

PHASE III FLIGHT SAFETY DATA PACKAGE FOR THE ALPHA MAGNETIC SPECTROMETER-02 (AMS-02)

Engineering Directorate

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National Aeronautics and
Space Administration

Lyndon B. Johnson Space Center
Houston, Texas

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PHASE III FLIGHT SAFETY DATA PACKAGE
FOR THE
ALPHA MAGNETIC SPECTROMETER-02 (AMS-02)

NASA/JSC APPROVAL



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HOUSTON, TEXAS

April 18, 2011

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FOR THE

ALPHA MAGNETIC SPECTROMETER-02 (AMS-02)

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ACRONYMS AND ABBREVIATIONS

α	Absorptivity
A	Amp or Amps
ACC	Anti-Coincidence Counters
AFD	Aft Flight Deck
AHP	Accumulator Heat Pipe
AI	Action Item
Al	Aluminum
AMICA	Astro Mapper for Instrument Check of Attitude
AMS	Alpha Magnetic Spectrometer
APCU	Assembly Power Converter Unit
APO	AMS Program Office
arc-sec	Arc-Second
ASTC	AMICA Star Tracker Camera
ASTS	AMICA Star Tracker Support
atm	atmosphere
AWG	American Wire Gauge
BFS	Backup Flight System
BMS	Battery Management System
BOL	Beginning of Life
BD	Burst Disk or Bursting Disk
Bps	Bits per second
μCi	micro Currie
C	Celsius
CAB	Cryomagnet Avionics Box
CALT	China Academy of Launch Vehicle Technology
CAN	Controller Area Network
CAS	Common Attach System
cc	Cubic Centimeter
CCD	Charged Coupling Device
CCEB	Cryocooler Electronics Box
CCR	Crew Consensus Report
CCS	Cryomagnet Current Source
CFRC	Carbon Fiber Reinforced Composite

ACRONYMS AND ABBREVIATIONS

CFRT	Carbon Fiber Reinforced Thermoplastic
CGS	Carlo Gavazzi Space
CLA	Capture Latch Assembly
cm	Centimeter
CMG	Control Moment Gyro
CO ₂	Carbon Dioxide
CPU	Central Processing Unit
CRES	Corrosion Resistant Steel
CRISA	Computadoras, Redes e Ingeniería SA
CSR	Customer Support Room
CU	Copper
DC or dc	Direct Current
DDRS	Digital Data Recording System
DOE	Department of Energy
DOL	Discrete Output Low
DV	Digital (on/off) Valve
DX	Double X Structure, Permanent Magnet to VC Integration Structure
ϵ	Emissivity
E	Energy
e ⁺	positron
e ⁻	electron
EA	Engineering Directorate
EBCS	External Berthing Camera System
ECAL	Electromagnetic Calorimeter
EHV	ECAL High Voltage
ELV	Expendable Launch Vehicle
EMC	Electromagnetic Compatibility
EMI	Electromagnetic Interference
ESCG	Engineering and Sciences Contract Group
ESMD	Exploration Systems Mission Directorate
EOL	End of Life
ETH	Eidgenossische Technische Hochschule
EVA	Extravehicular Activity

ACRONYMS AND ABBREVIATIONS

F	Fahrenheit
FoV	Field of View
FPGA	Field Programmable Gate Array
FRGF	Flight Releasable Grapple Fixture
γ	Gamma Ray
G	Gauss
GeV	Giga Electron Volts
GFE	Government Furnished Equipment
GN&C	Guidance, Navigation and Control
GND	Ground
GPC	General Purpose Computer
GPS	Global Positioning System
G_{rms}	Gravity Root Mean Square
GSE	Ground Support Equipment
HBE	Hans Bieri Engineering
He	Anti-helium
HP	Heat Pipe
HR	Hazard Report
HRDL	High Rate Data Link
HV	High Voltage
Hz	Hertz
ICD	Interface Control Document
ID	Inside Diameter
I/F	Interface
IFM	In-flight Maintenance
IR	Infra-Red
ISS	International Space Station
ISSP	International Space Station Program
ITS	Integrated Truss Segment
JMDC	AMS-02 Main DAQ Computer
JS	Jacobs Sverdrup
JSC	Johnson Space Center

ACRONYMS AND ABBREVIATIONS

K	Kelvin
KeV	Kilo Electron Volts
kg	Kilograms
kN	Kilo Newton
KSC	Kennedy Space Center
kW	Kilowatt or Kilowatts
L	Liter (also l)
LBBX	Laser Beamport Box
LCC	Launch Commit Criteria
LCC	Launch Control Center
LCL	Latching Current Limiter
LCTL	Laser Control Box
LDDR	Laser Diode Driver
LED	Light Emitting Diode
LFCR	Laser Fiber Coupler
LRDL	Low Rate Data Link
LTOF	Lower Time of Flight
μm	Micrometer
m	meter
mm	millimeter
MAGIK	Manipulator Analysis, Graphics and Integrated Kinematics
Mbps	Megabits per second
MCA	Multi-Channel Analyzer
MCC	Mission Control Center
MCC	Main Control Computer
MDC	Main Data Computer
MDP	Maximum Design Pressure
MDP	Maximum Dynamic Pressure
MET	Mission Elapsed Time
MIT	Massachusetts Institute of Technology
MJ	Megajoule
MLI	Multi-layer Insulation
MMOD	Micro-Meteoroid and Orbital Debris

ACRONYMS AND ABBREVIATIONS

MOSFET	Metal-Oxide-Silicon Field Effect Transistor
MV	Manually-actuated Valve
NaF	Sodium Fluoride
NASA	National Aeronautics and Space Administration
NBL	Neutral Buoyancy Laboratory
NbTi	Niobium Titanium
NSTS	National Space Transportation System
OD	Outside Diameter
OFHC	Oxygen Free High Conductivity
OIU	Orbiter Interface Unit
P	Photon
p^+	proton
p^-	anti-proton
P&I	Process and Instrumentation
PAS	Payload Attach System
PCS	Portable Computer System
PDA	Payload Disconnect Assembly
PDIP	Payload Data Interface Panel
PDS	Power Distribution System
PEDS	Passive Electrical Disconnect System
PEEK	Polyetheretherketone
PFR	Portable Foot Restraint
PFTE	Teflon TM
PGSC	Payload and General Support Computer
PGT	Pistol Grip Tool
PIP	Payload Integration Plan
PLB	Payload Bay
PM	Permanent Magnet
PMMA	Polymethyl Methacrylate (Plexiglas TM)
PMT	Photo Multiplier Tube
PO	Payload Organization
POCC	Payload Operations Control Center
PRLA	Payload Retention Latch Assembly

ACRONYMS AND ABBREVIATIONS

PSE	Payload Safety Engineer
psi	Pounds per Square Inch
psia	Pounds per Square Inch, Absolute
psid	Pounds per Square Inch, Differential
PSRP	Payload Safety Review Panel
PVGF	Power Video Grapple Fixture
ρ	Density
RHV	RICH High Voltage
RICH	Ring Imaging Cerenkov Counter
RITF	Receiving Inspection Test Facility
ROEU	Remotely Operated Electrical Umbilical
RPCM	Remote Power Control Module
RWTH	Rheinisch-Westfälischen Technischen Hochschule (University of Technology)
μ sec	microsecond
S3	Starboard 3 (Truss Designation)
SDP	Safety Data Package
SFHe	Superfluid Helium (He^{II})
SHV	TOF/ACC High Voltage
SiO_2	Silicon Dioxide
Si_3N_4	Silicon Nitride
SOC	State of Charge
SRMS	Shuttle Remote Manipulator System
SSP	Space Shuttle Program
SSP	Standard Switch Panel
SSPC	Solid State Power Controller
SSPF	Space Station Processing Facility
SSRMS	Space Station Remote Manipulator System
STA	Structural Test Article
STADCO	Standard Tool & Die Company
STD	Standard
STS	Space Transportation System
SVP	Structural Verification Plan

ACRONYMS AND ABBREVIATIONS

TAS	Tracker Alignment System
TBD	To Be Determined
TCS	Thermal Control System
Te	Tellurium
TeV	Tera Electron Volts
Ti	Titanium
Tm ²	Tesla-Meter Squared
TMP	Thermo-Mechanical Pump
TPG	Thermal Prolytic Graphite
TOF	Time Of Flight Counters
TRD	Transition Radiation Detector and associated Gas System
TTCB	Tracker Thermal Control Box
TTCE	Tracker Thermal Control Electronics
TTCS	Tracker Thermal Control System
UMA	Umbilical Mechanism Assembly
UPS	Uninterruptible Power Supply
USCM	Universal Slow Control Module
USS-02	Unique Support Structure-02
UTOF	Upper Time of Flight Counters
V	Volt or Volts
VC	Vacuum Case
VME	VERSAmodule Eurocard
W	Watt or Watts
WIF	Worksite Interface Fixture
WSA	Worksite Assessment
Xe	Xenon

APPLICABLE SAFETY DOCUMENTS

NSTS 1700.7B	Safety Policy and Requirements for Payloads Using the Space Transportation System
NSTS 1700.7B ISS Addendum	Safety Policy and Requirements for Payloads Using the International Space Station
NSTS/ISS 13830C	Payload Safety Review and Data Submittal Requirements for Payloads Using the Space Shuttle/International Space Station
NSTS/ISS 18798B	Interpretations of NSTS/ISS Payload Safety Requirements
JSC 26943	Guidelines for the Preparation of Payload Flight Safety Data Packages and Hazard Reports for Payloads Using the Space Shuttle

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1. INTRODUCTION

This Phase III Flight Safety Data Package for the Alpha Magnetic Spectrometer-02 (AMS-02) is submitted in response to the safety requirements of NSTS 1700.7B, "Safety Policy and Requirements for Payloads Using the Space Transportation System", and NSTS 1700.7B, ISS Addendum, "Safety Policy and Requirements for Payloads Using the International Space Station. This safety package has been prepared in accordance with NSTS/ISS 13830C, "Payload Safety Review and Data Submittal Requirements for Payloads Using the Space Shuttle/International Space Station". Also, JSC 26943, "Guidelines for the Preparation of Payload Flight Safety Data Packages and Hazard Reports for Payloads Using the Space Shuttle", was used as a guideline document.

2. SCOPE

This safety data package contains the safety analysis performed for the AMS-02 Payload flight hardware and the flight operations of the AMS-02 mission. The major subsystems of the AMS-02 included in this safety analysis are listed below. Each subsystem and the operational scenarios will be discussed in detail in Section 5 of this safety data package.

- Permanent Magnet (PM)
- Unique Support Structure – 02 (USS-02)
- Vacuum Case (VC) (Non pressurized/evacuated) with “DX” (Double X) support structure.
- Transition Radiation Detector and associated Gas System (TRD)
- Time-of-Flight (TOF) Scintillator Assemblies
- Silicon TrackerTracker Alignment System (TAS)
- Anti-Coincidence Counters (ACC)
- Ring Imaging Cerenkov Counter (RICH)
- Electromagnetic Calorimeter (ECAL)
- Star Tracker
- Global Positioning System (GPS)

- Data and Interface Electronics
- Thermal Control System (TCS)
- Micrometeoroid and Orbital Debris (MMOD) Shields
- Payload Attach System (PAS) (Passive Half)
- Digital Data Recording System – 02 (DDRS-02)
- Space Shuttle Program (SSP) and ISS Program (ISSP) Provided Hardware
 - Flight Releasable Grapple Fixture (FRGF) SSP
 - Remotely Operated Electrical Umbilical (ROEU) SSP
 - Power Video Grapple Fixture (PVGf) ISSP
 - Umbilical Mechanism Assembly (UMA) (passive half) ISSP
 - External Berthing Camera System (EBCS) ISSP

The AMS-02 Payload also requires the use of the Shuttle Remote Manipulator System (SRMS) and the Space Station Remote Manipulator System (SSRMS) for removing the payload from the Orbiter Payload Bay and berthing it on the station. The payload requires an active PAS and an active UMA, which are ISS hardware and part of the Integrated Truss Segment (ITS). The safety analyses for the SSP and ISS provided hardware are not included in this data package. However, the safety of the use and interfaces of the SSP and ISS provided hardware with the AMS-02 Payload is a part of this AMS-02 safety data package.

NOTE: The AMS-02 has changed its magnetic field source from a superfluid helium cooled superconducting magnet (Cryomagnet) to a solid state permanent magnet. Graphics in this document may show some features that were unique to the Cryomagnet design that will not be present in the Permanent Magnet configuration, typically in a background sense to the focal point of the graphics.

3. PURPOSE

The purpose of this safety analysis is to identify potential flight hazards associated with the AMS-02 Payload design and operation; to evaluate their cause and impact on the Space Shuttle, Orbiter, ISS, and flight crews; to define methods for eliminating or controlling the hazards; to verify the

elimination or control methods; and to document the status of the verification methods. This safety package is intended to provide the information necessary for a Phase III review of the AMS-02 Payload by the JSC Payload Safety Review Panel (PSRP). A Verification Tracking Log of all open verifications at the time of this submittal is provided to document all open verification work at the time of the submittal.

4. AMS-02 PROJECT OVERVIEW

The AMS-02 experiment is a state-of-the-art particle physics detector being designed, constructed, tested and operated by an international team organized under United States Department of Energy (DOE) sponsorship. The AMS-02 experiment will use the unique environment of space to advance knowledge of the universe and potentially lead to a clearer understanding of the universe's origin. Specifically, the science objectives of the AMS are to search for antimatter (anti-helium and anti-carbon) in space, to search for dark matter (90% of the missing matter in the universe) and to study astrophysics (to understand Cosmic Ray propagation and confinement time in the Galaxy).

4.1 AMS-02 EXPERIMENT

The AMS-02 experiment utilizes a large permanent magnet (PM) to produce a strong, uniform magnetic field (~1400 Gauss) within the interior of the magnet, the primary Silicon Tracker sensing volume. The experiment has planes of detectors above (Plane 1N), in the center of (Planes 1-5), and below (Plane 6) the PM (Figures 4.1-1, 4.1-2) to track the particles trajectory. Electrically charged particles will curve when they pass through the magnetic field created by the PM. Due to the differences in electrical charge, particles made of matter will curve in one distinctive manner, and the same particles of antimatter will curve the opposite way. The various interactions and signatures of transient particles with the AMS-02 detectors will be electronically recorded (Figure 4.1-3). Physicists will be able to study the trajectory of curvature and these signature characteristics and determine the charge of the particles from the direction of curvature, the mass of the particles from the amount of curvature and whether it was matter or antimatter.

An Implementing Arrangement (IA) between NASA and DOE signed in September 1995 established two flights for AMS: an Engineering Test on Shuttle (STS-91 – June 1998) and a 3-year Science Mission on ISS (Launch Ready for STS-134, July 2010). The flight of AMS-01 was a precursor flight of the detectors proposed for AMS-02. The purpose of the precursor flight was

to verify proper on-orbit operation of the various AMS detectors, verify command and data communications, collect thermal data for the ISS flight, determine actual accelerations on some AMS internal instruments and establish experimental background data.

The AMS-02 will be transported to the International Space Station (ISS) in the cargo bay of the Space Shuttle (Figure 4.1-4 and 4.1.5) for installation on the external truss of the ISS (Figures 4.1-6 and 4.1-7). Once on-orbit the AMS-02 will remain in place for the duration of the ISS mission, AMS-02 will not be return to Earth prior to ISS safe disposal.

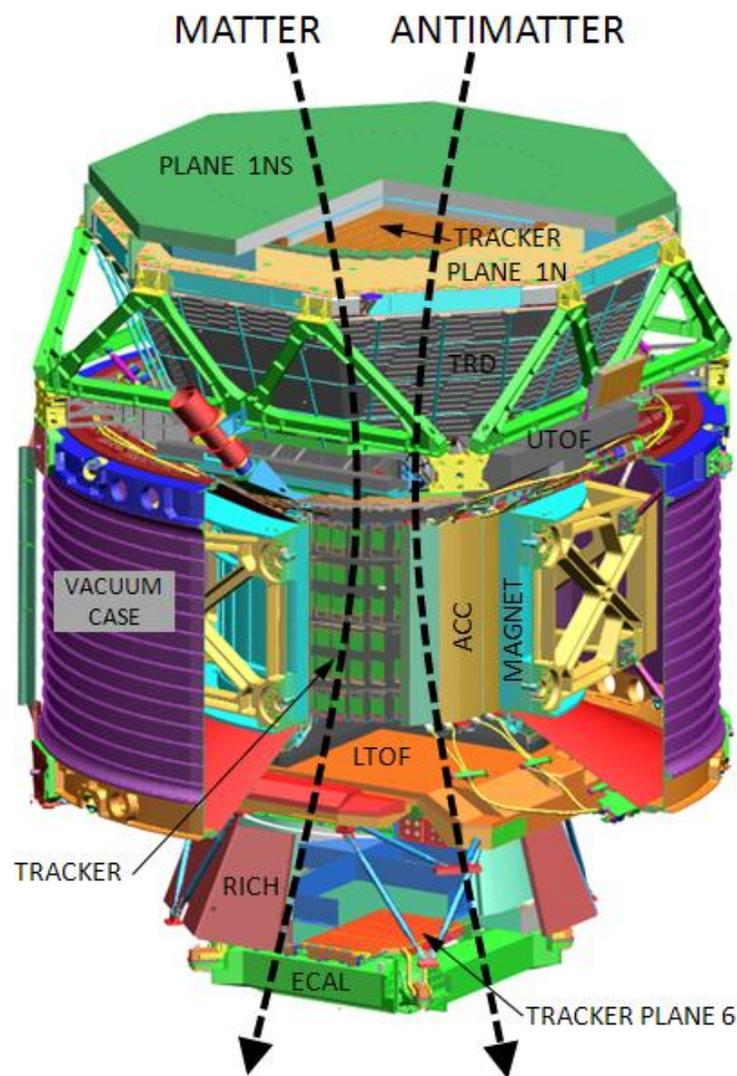


Figure 4.1-1 The AMS-02 Experiment

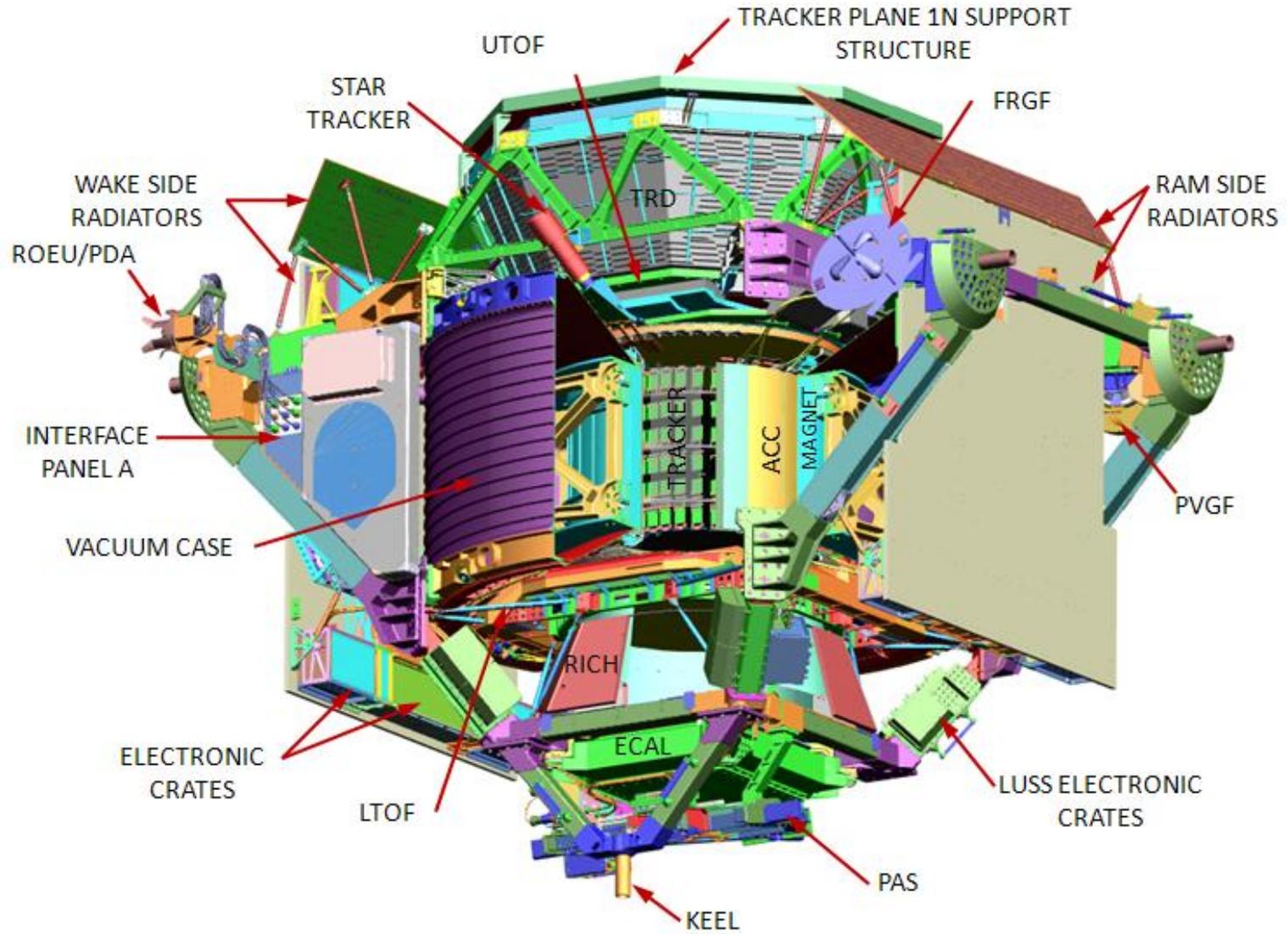
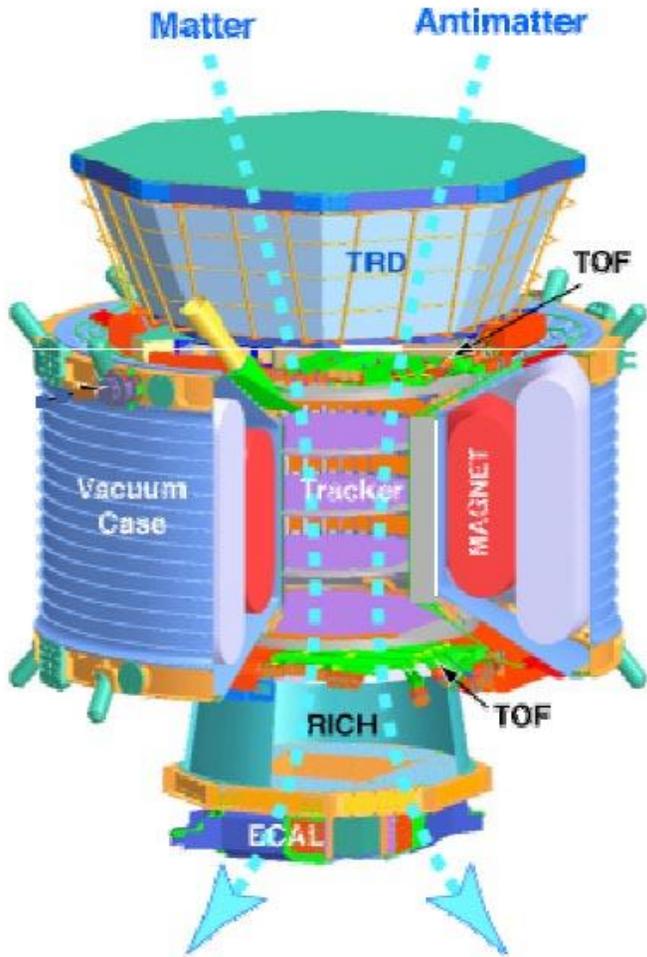


Figure 4.1-2 The AMS-02 Payload (Shown in Cryomagnet Configuration)

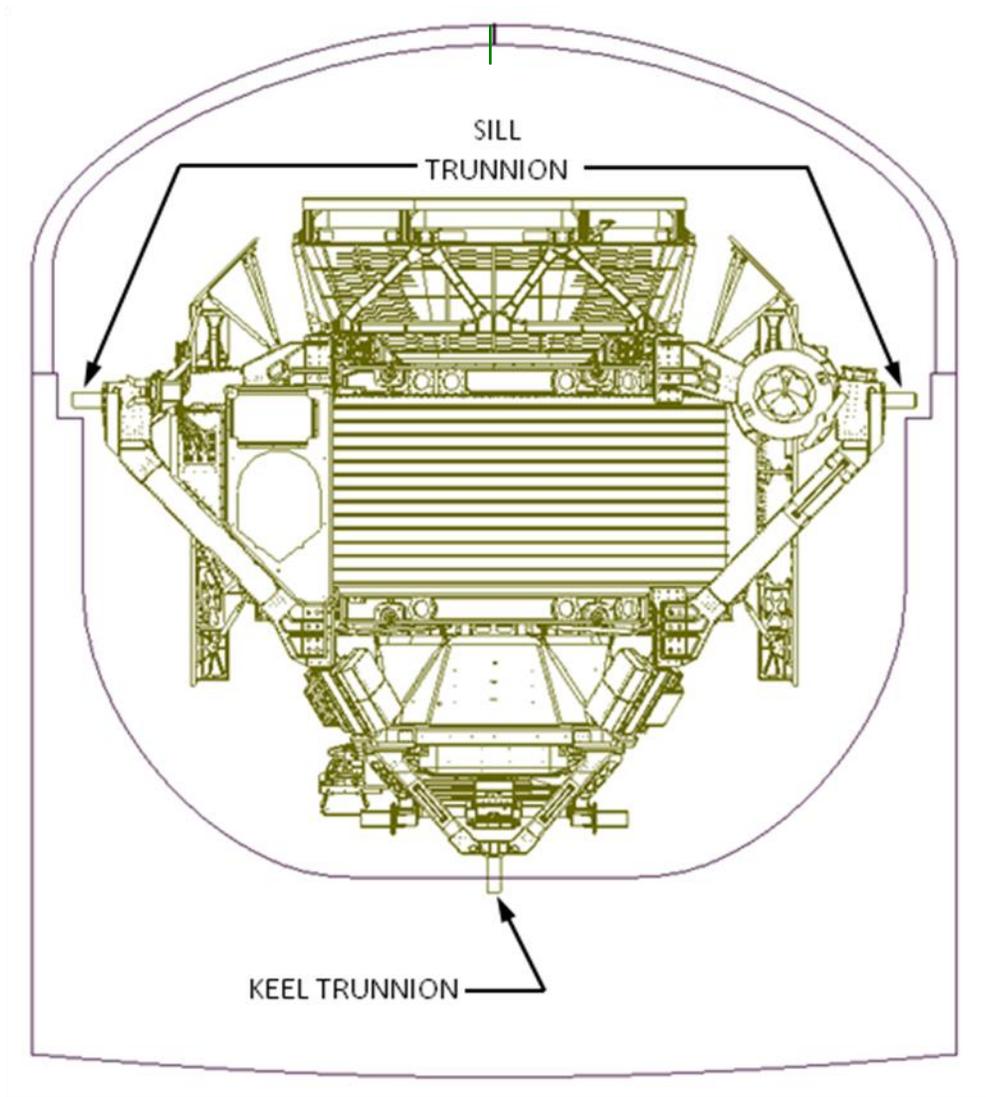
AMS: A TeV Magnetic Spectrometer in Space



	e^-	P	Fe	e^+	\bar{P}	\bar{He}
TRD						
TOF						
Tracker + Magnet						
RICH						
ECAL						
Physics example	Cosmic Ray Physics Strangelets			Dark matter		Antimatter

300,000 channels of electronics $\Delta t = 100$ ps, $\Delta x = 10\mu$

Figure 4.1-3 AMS-02 Detector Signatures



**Figure 4.1-4 AMS-02 in the Space Shuttle Orbiter Cargo Bay
(From forward bulkhead looking aft.)**

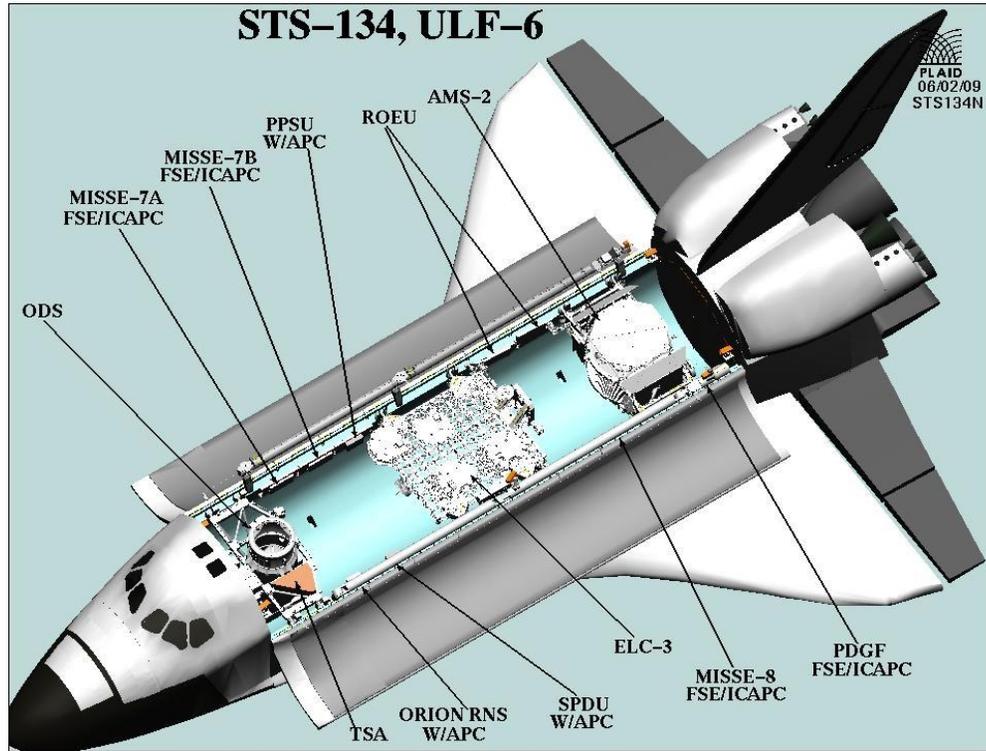


Figure 4.1-5 STS-134, ULF-6 Mission Payload Bay Cargo

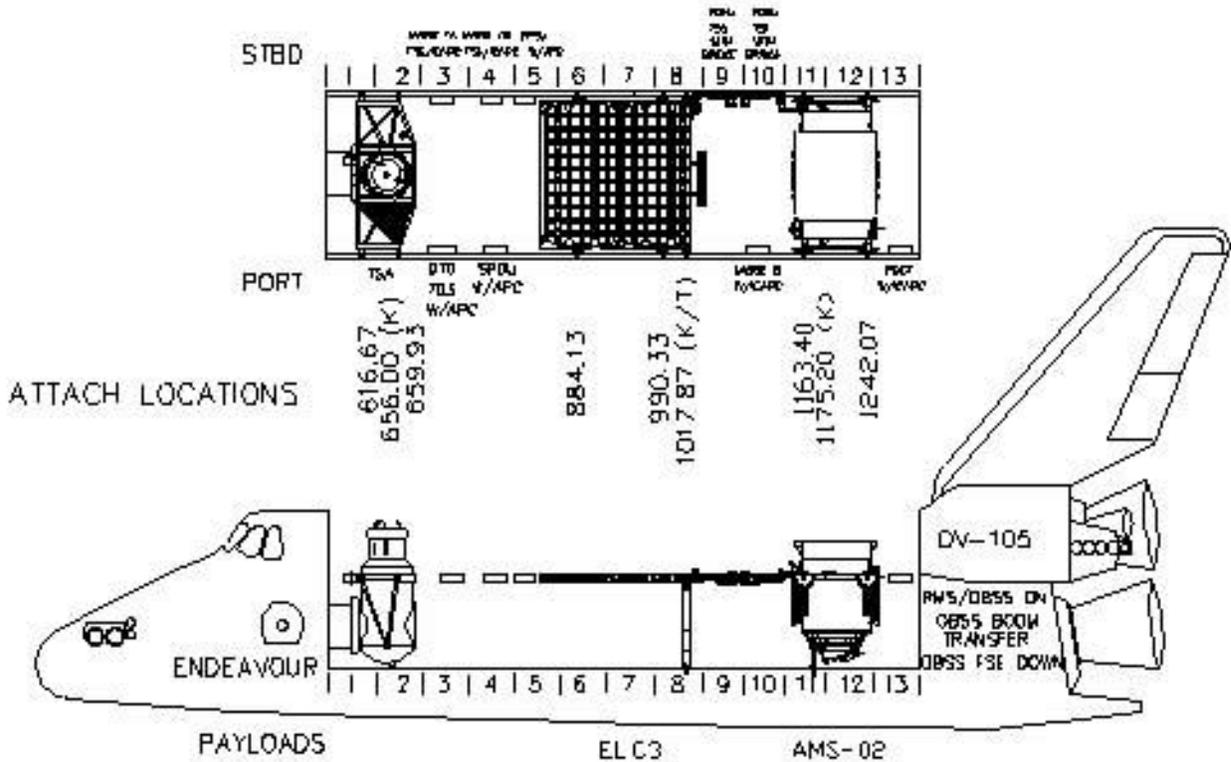
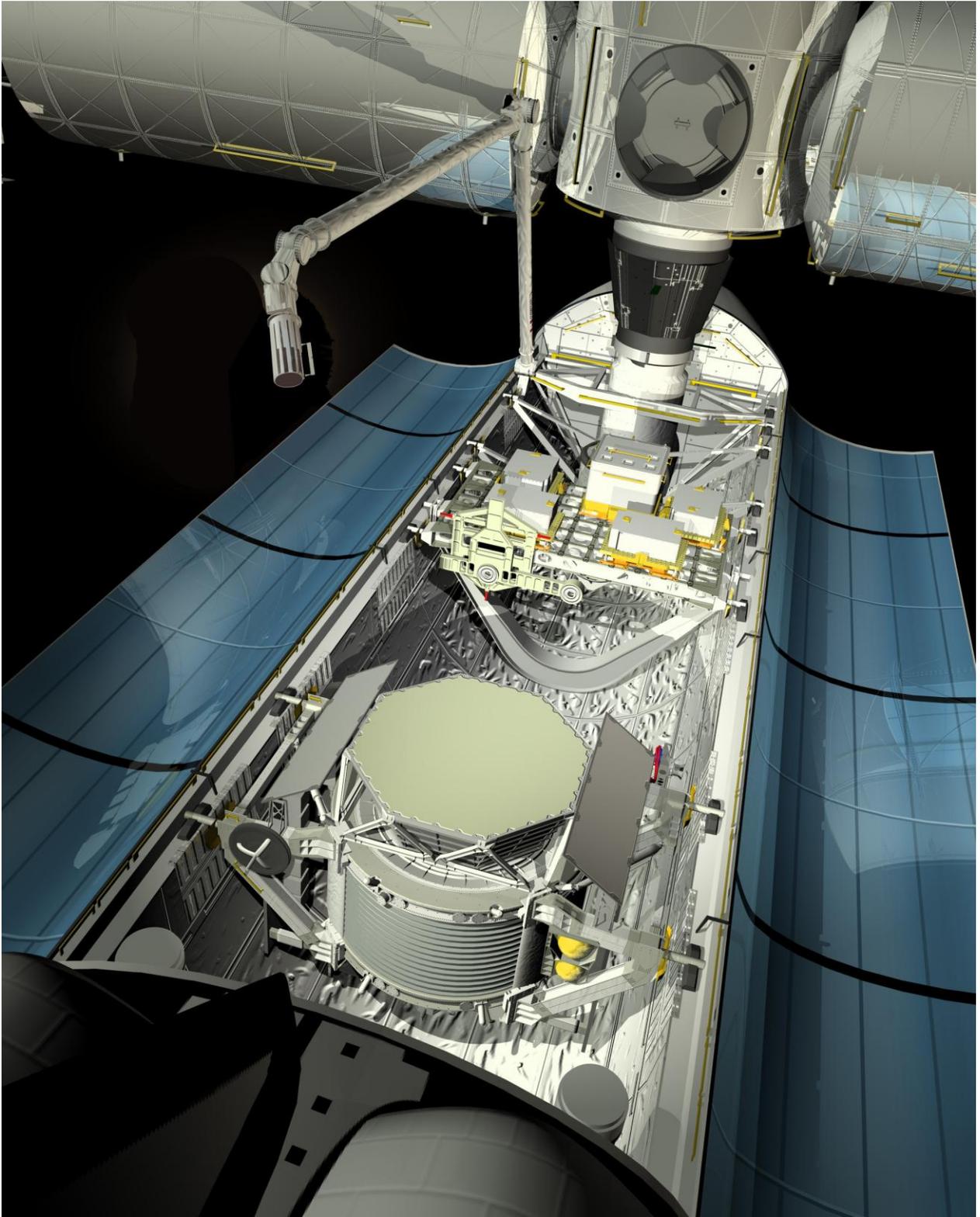


Figure 4.1-6 STS-134 Cargo Bay Layout



**Figure 4.1-7 AMS-02 (Simplified) in the Space Shuttle Orbiter Cargo Bay
(From above looking forward.)**

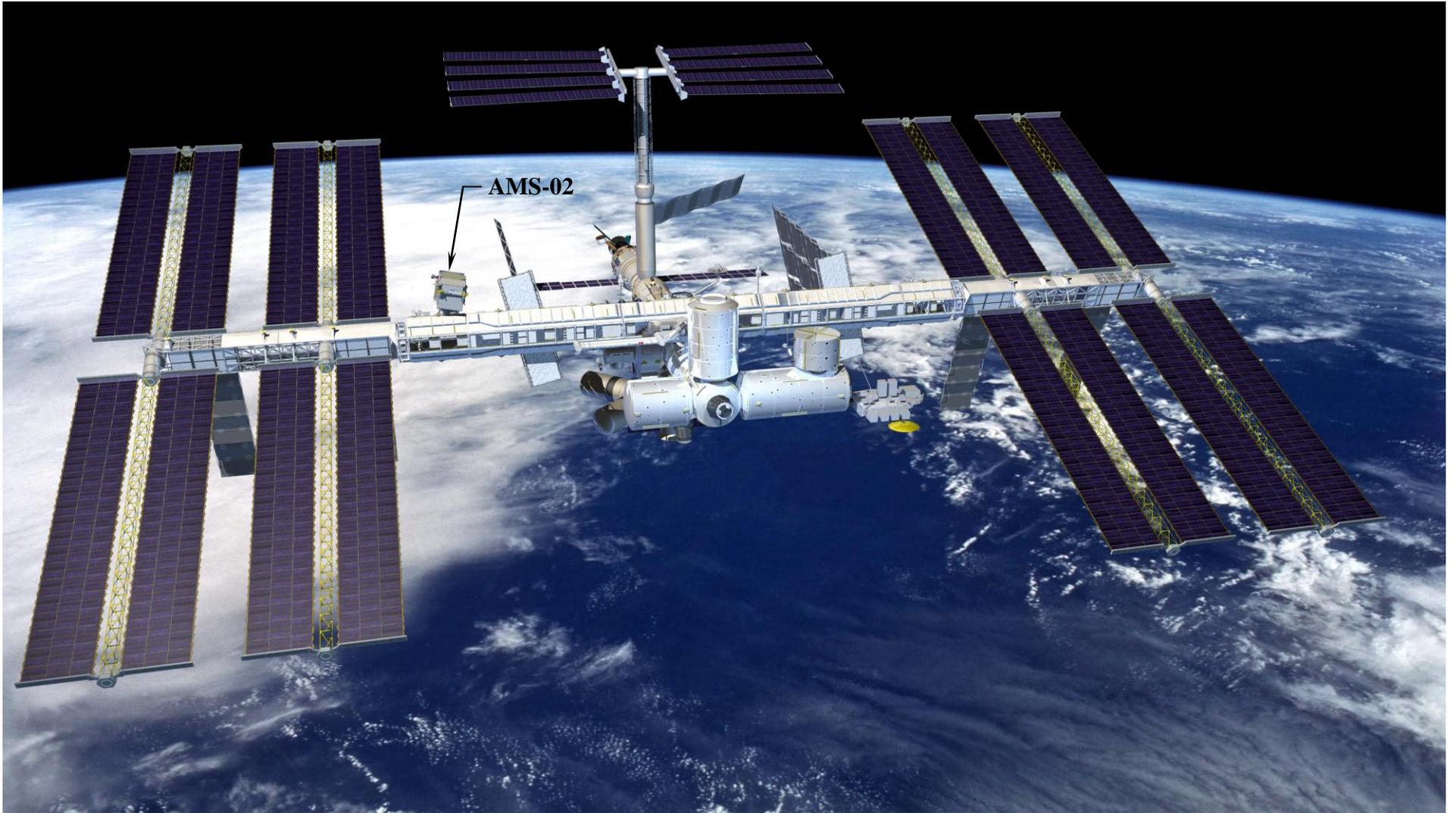


Figure 4.1-8 AMS-02 on the ISS

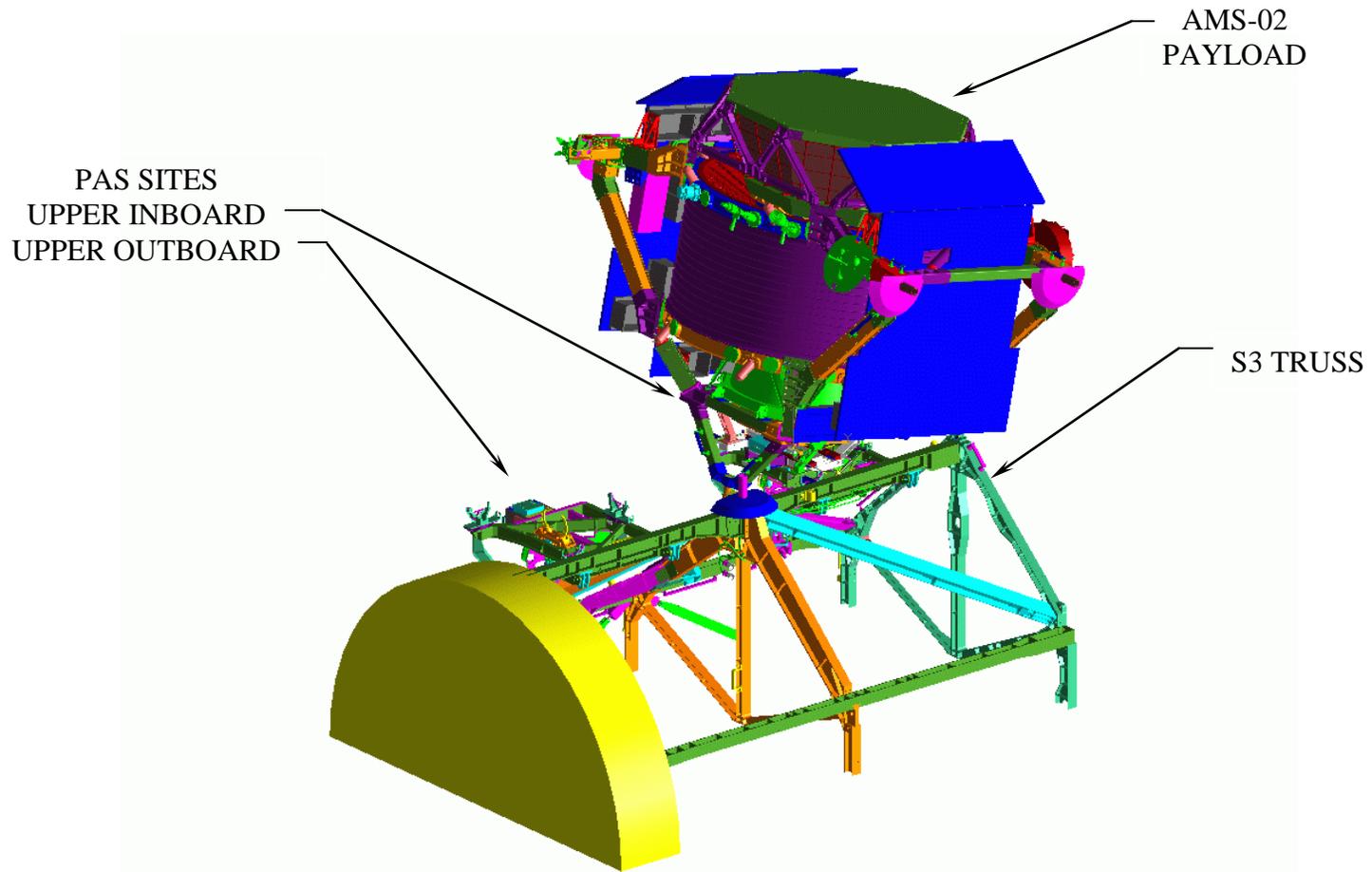


Figure 4.1-9 AMS-02 Payload Assembly on ISS S3 – Z Inboard PAS Site

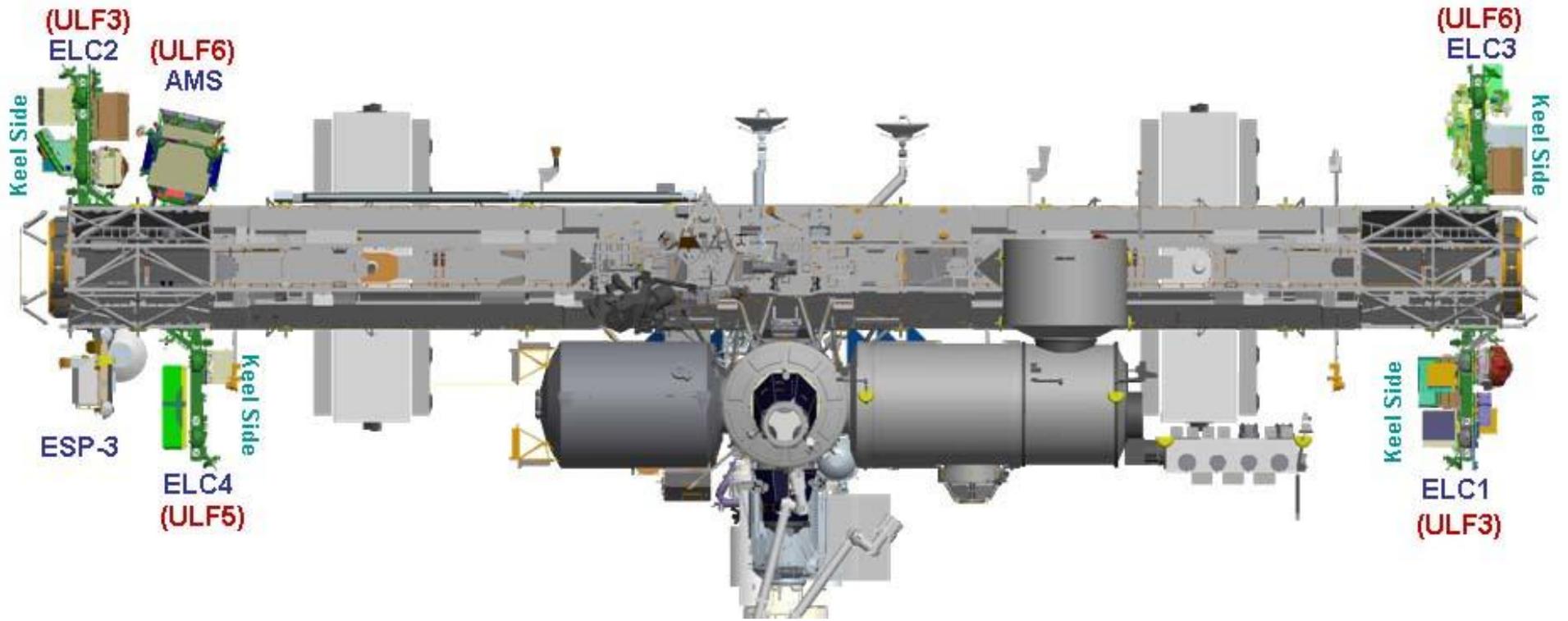


Figure 4.1-10 ISS Truss with Attachments

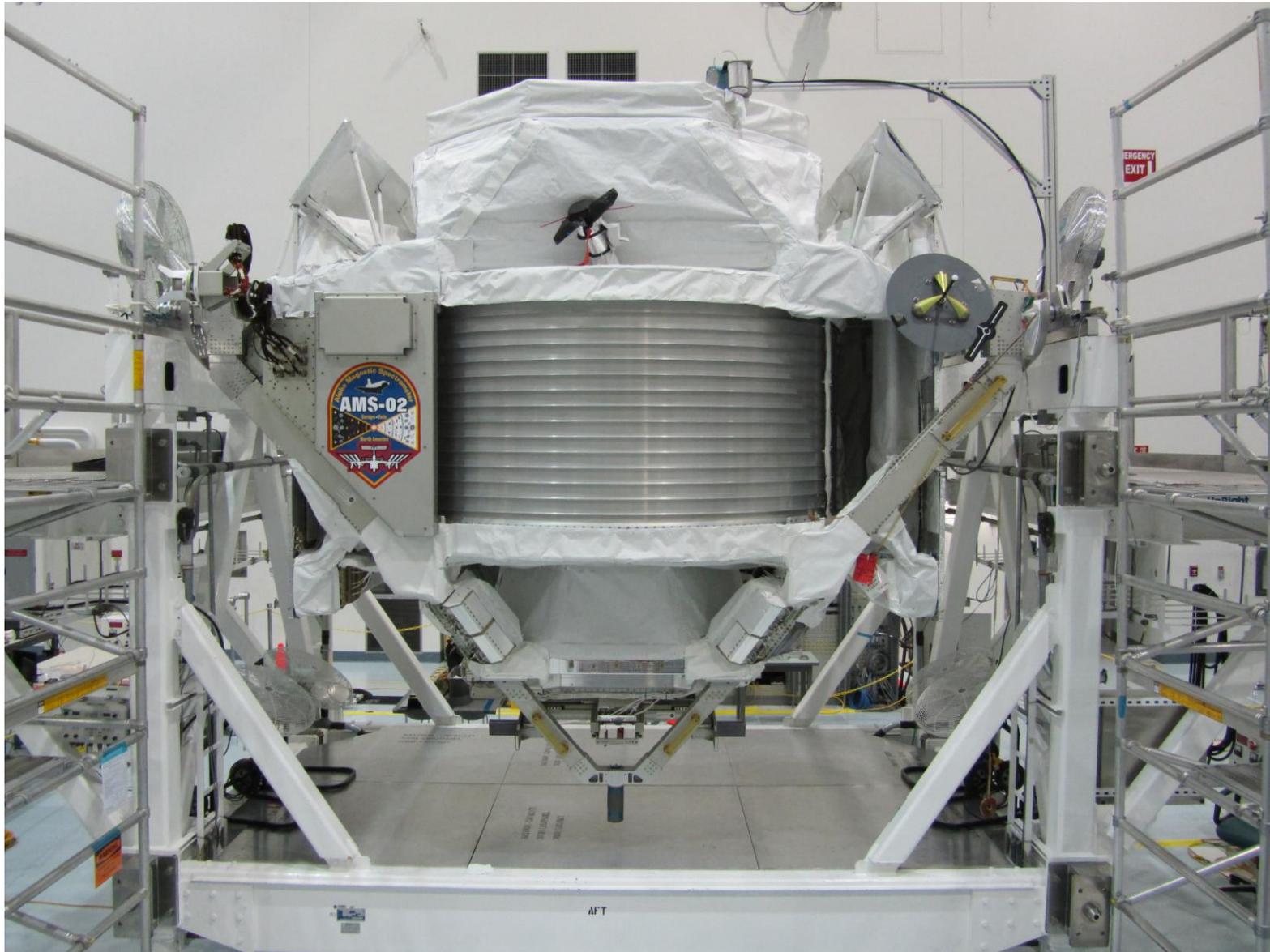


Figure 4.1-11 The AMS-02 at Assembly Complete at KSC SSPF

4.2 AMS-02 ROLES AND RESPONSIBILITIES

The Implementing Arrangement between the Department of Energy (DOE) and the National Aeronautics and Space Administration (NASA) establishes the roles and responsibilities of DOE and NASA with respect to the Alpha Magnetic Spectrometer (AMS) Program.

4.2.1 NASA Responsibilities

NASA Headquarters is responsible for the overall NASA management of the AMS Program interface activity between NASA and DOE and for overall program management of the NASA activities required to support the implementation of the flight of AMS-02 (Figure 4.2.1-1). The AMS Project Office (APO) of the Engineering Directorate (EA) at JSC has been assigned responsibility for implementing the AMS Program. The APO serves as the AMS representative and acts as the single point of contact between the AMS Program and the Shuttle and ISS Programs. The APO reports and is responsible directly to NASA Headquarters and is the AMS NASA representative to all other NASA organizations providing equipment, materials, and services to the AMS Program.

In order to implement the AMS Program, NASA will perform or provide the following:

- Fly the AMS-02 on the ISS as an external attached payload, and provide accommodation on the ISS; all necessary services, AMS-to-carrier integration, AMS transfer to and installation on the ISS. NASA shall include the AMS-02 in the Space Station utilization planning process.
- Provide mission-peculiar interface hardware and software for the AMS-02 on the ISS.
- Perform AMS-to-carrier integration support, payload certification, and payload safety certification.
- Provide necessary facilities and perform related services for the AMS-02 final assembly, testing and checkout at the launch site, as well as control center accommodations for AMS-02 operation and monitoring as required for the launch and transfer-to-ISS phases.

- Provide AMS-02 housekeeping, science (unprocessed) and carrier-ancillary data products to the DOE-sponsored team at the designated NASA data handling/distribution center.
- Perform a mission management function consisting of the following tasks in support of AMS:
 - Representation of the AMS to the Shuttle Program, the ISS Program, and to various supporting NASA organizations involved in the integration and flight of AMS.
 - Design and operations consulting and guidance to the AMS Program to minimize the potential for incorporation into the AMS design of features or characteristics which could result in functional and/or safety incompatibilities with either the Shuttle or the ISS or with ground systems at the launch or landing sites.
 - Performance of detailed engineering analyses (e.g. stress, loads, etc.) to ensure compatibility of the AMS with the Shuttle and ISS through its launch, operational, and return environments.
 - Systems engineering for the development of mission-peculiar interface hardware and software needed to analytically, physically, and operationally integrate the AMS into the Shuttle and ISS system.
 - Management of the physical integration of the AMS and mission-peculiar interface hardware onto the Shuttle and ISS carriers.
 - Guidance, identification and control of hazards, and lead role in development of Safety Compliance Documentation, and representation of AMS to the Shuttle, ISS, and KSC Safety Panels.
 - Guidance in the development of requirements levied on the Shuttle and ISS and lead role in negotiation of those requirements through the Shuttle Payload Integration Plan, (PIP), the ISS PIP, the associated annexes, and required Interface Control Documents (ICDs).
 - Provision of training related to Shuttle and Station operations, including the development of training requirements.
 - Provision of documentation required for payload verification of AMS compliance with Shuttle and ISS program requirements.
 - Representation of the AMS Program at KSC and support of testing, AMS-to-carrier integration, and flight operations.
 - Real-time mission support for the delivery flight to the ISS, through AMS deployment, installation, checkout, and verification of proper operation.

AMS Project Functional Organization Chart

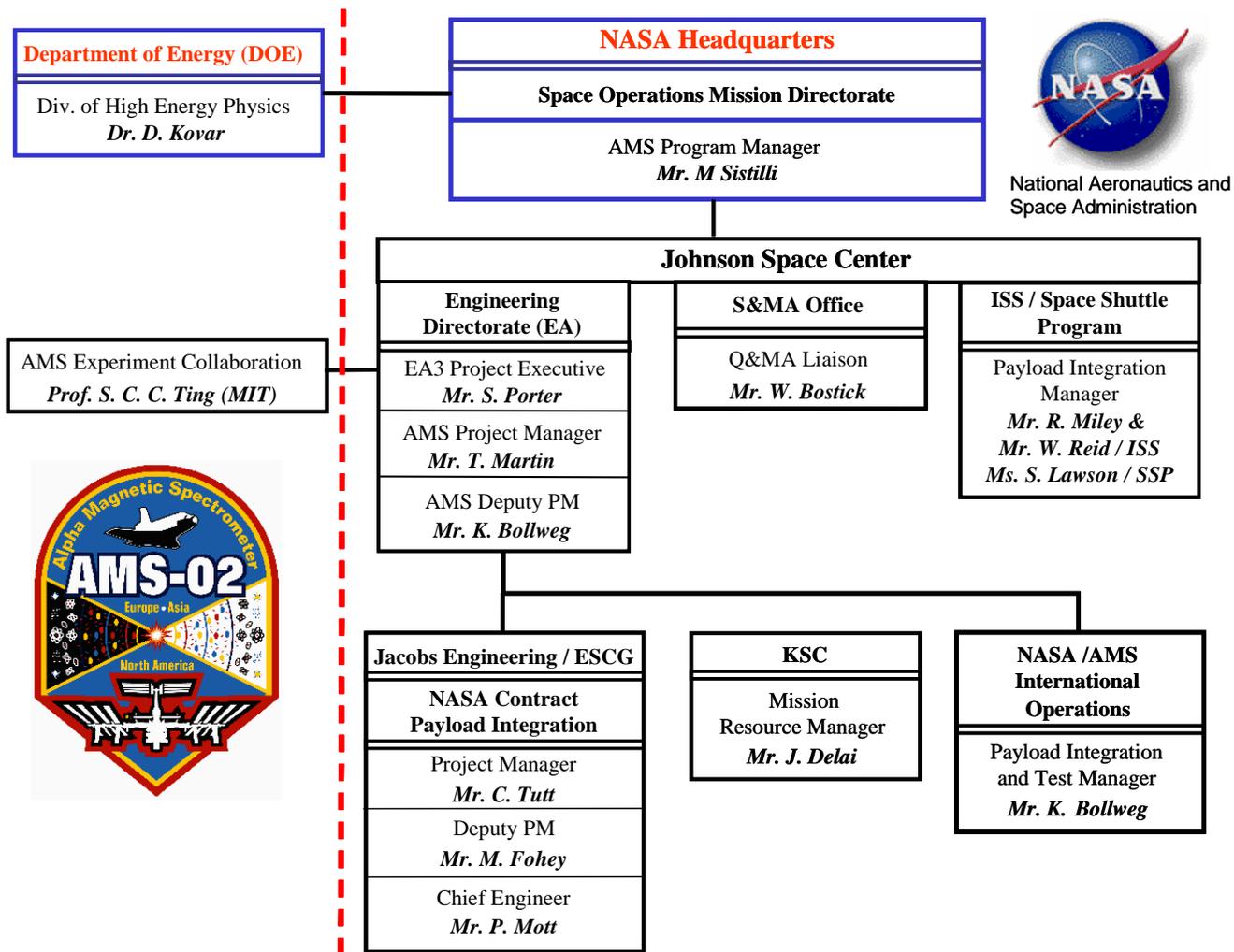


Figure 4.2.1-1 AMS Project Functional Organization

Flight hardware to be provided by NASA/APO is listed in Table 4.2.1-1.

TABLE 4.2.1-1 NASA/APO PROVIDED FLIGHT HARDWARE

ITEM	UNITS
* External Berthing Camera System (EBCS), w/cables and brackets	1
* EVA (Extravehicular Activity) Handrails/ Tether Attach Points	9
* Flight Releasable Grapple Fixture (FRGF), w/cables and brackets	1
* Portable Foot Restraint (PFR) Worksite Interface Fixture (WIF)	1
* Power Video Grapple Fixture (PVGf), w/cables and brackets	1
* Remotely Operated Electrical Umbilical (ROEU)/Payload Disconnect Assembly (PDA), w/cables and brackets	1
* Umbilical Mechanism Assembly (UMA) (Passive Half), w/cables and brackets	1
Vacuum Case (VC) (Flight Article, Flight Spare)	2
Micrometeoroid and Orbital Debris (MMOD) Shields	3
Payload Attach System (PAS) (Passive Half)	1
EVA Interface Panel (Interface to UMA)	1
Interface Panel A (Interface to ROEU)	1
Power and data cabling from interface panels to J-Crate, PDS, etc.	13
Cabling for T0 connections (PDIP)	1
DDRS-02 and associated cabling/interface cards	1
Trunnion scuff plates for deployable payload	4 (Part of USS-02)
Thermal Blankets	6
Unique Support Structure-02 (USS-02)	1

* Items (excluding brackets) supplied by NASA SSP or ISSP and integrated into AMS Payload by NASA/APO.

4.2.2 DOE Responsibilities

The DOE Headquarters Division of High Energy Physics, under the Department's Office of Energy Research is responsible for the administration of a Cooperative Agreement with the Massachusetts Institute of Technology (MIT) for a basic science program in particle physics. Under this agreement, the MIT Principle Investigator for the AMS Program has organized, and is the spokesman for, the AMS International Collaboration, currently consisting of over 500 physicists and engineers from 16 countries representing over 56 institutions, to implement its part in the AMS Project (Figure 4.2.2-1). The DOE or, as appropriate, its MIT Cooperative Agreement Principle Investigator, will be responsible for: the definition, design, and development of the AMS hardware and related ground support equipment (GSE); delivery to and return from a location to be specified at the Kennedy Space Center (KSC) for integration or de-integration in the NASA processing system; and establishment of the science mission requirements. These responsibilities will include:

- All necessary interagency coordination and obtaining necessary concurrences within the U.S. Government for the AMS Project regarding international arrangements among the DOE Program Collaborators involved in the definition, design, development, fabrication, assembly, test, checkout, and operation of the AMS.
- Management of all international transfer and shipment, unless otherwise agreed. This includes, but is not limited to, customs clearances, import and export licenses required for AMS systems, subsystems, or components, or, as mutually agreed, for any NASA tests, integration, or mission-peculiar equipment or technical data that is required to be shipped abroad.
- Establishment of the AMS science plan, including science requirements, definition of data requirements, and definition of mission success criteria.
- Provision, when requested by NASA, of DOE technical and management support for all formal NASA reviews involving AMS (Safety Reviews, Cargo Integration Reviews, Ground Operations Reviews, Flight Operations Reviews, etc.) and other related NASA reviews and activities.
- Development and management of an AMS implementation schedule consistent with NASA program milestone schedules and provision of updates to keep NASA advised of AMS schedule status.

- Provision of technical and management data required by NASA to complete programmatic requirements (e.g. Safety, ICDs, MIP, reviews, material lists, etc.).
- Provision of all transport equipment (shipping containers, other AMS handling ground support equipment) required for AMS transport to and from NASA KSC.
- Management of: (1) All AMS science and engineering team activities, including travel, visa issuances, and related in-country logistical expenses; (2) support for science operations before, during, and after AMS flights; and (3) science data analysis, distribution, and publication.

Flight hardware to be provided by DOE/MIT is listed in Table 4.2.2-1.

TABLE 4.2.2-1 DOE/MIT PROVIDED FLIGHT HARDWARE

ITEMS	UNITS
Permanent Magnet System	1
Transition Radiation Detector (TRD)	1
TRD Gas System	1
Upper and Lower Time-Of-Flight (TOF) Scintillator Assembly	1 each
AMS-02 Silicon Tracker Assembly <ul style="list-style-type: none"> ○ Plane 1N ○ Plane 9 	1
Tracker Alignment System (TAS)	1
Anti-Coincidence Counters (ACC)	1
Ring Imaging Cerenkov Counter (RICH)	1
Electromagnetic Calorimeter (ECAL)	1
Thermal Control System (TCS) including Tracker TCS	1
Thermal Blankets	14
Star Tracker	2
Global Positioning System (GPS) Receiver	1
Micrometeoroid and Orbital Debris (MMOD) Shields	1

5. AMS-02 FLIGHT HARDWARE DESCRIPTION

5.1 AMS Permanent Magnet

The Permanent Magnet (PM) is at the heart of the AMS-02 experiment, shown in Figure 5.1-1. Trajectories of incoming particles are bent by the magnetic field to provide differentiation between particles and anti-particles. The Silicon Tracker detects this trajectory, which allows AMS-02 to identify the magnitude and sign of the particles' electrical charge. The bending strength of the PM comes from its use of neodymium-iron-boron (Nd-Fe-B) rare earth magnets, magnetized and arranged to create a Halbach Ring, a known, uniform field in the interior bore and a magnetic field externally that diminishes rapidly with distance from the centerline creating a small magnetic torque.

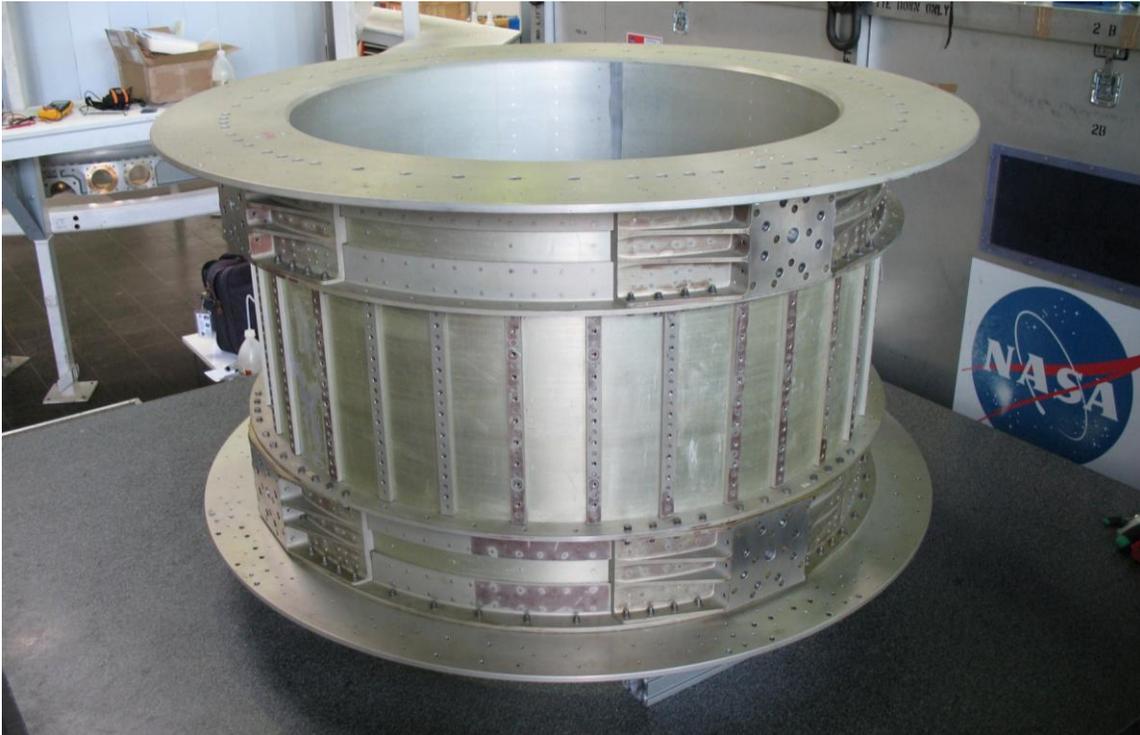


Figure 5.1-1 AMS Permanent Magnet (PM)

The PM individual magnets were manufactured by Vacuumschmelze GmbH & Co and magnetized to their individual orientation by the Beijing Institute of Electrical Engineering (BIEE). The construction of the complete PM was accomplished by China Academy of Launch Vehicle Technology (CALT). Originally design to interface with

the AMS-01 unique support structure, the PM interfaces with the Double X (DX) structure which is suspended by 16 struts along the same force vectors used for suspending the original AMS-02 Cryomagnet mass by way of non-linear straps. The Upper and Lower flanges of the PM are bolted to the upper and lower conical flanges of the Vacuum Case (VC). The VC was designed originally for use with a cryogenically cooled superconducting magnet by Lockheed Martin and was built at the Standard Tool and Die Company (STADCO) in Los Angeles and subsequently modified by the AMS-02 Collaboration to carry the permanent magnet. The entire system is currently estimated to weigh 7048 lbs (3197 Kg), equivalent to the Cryomagnet mass with superfluid helium filled tank.

5.1.1 Magnetic Construction

The PM, shown in Figure 5.1.1-1, is constructed of neodymium-iron-boron (Nd-Fe-B) rare earth magnets arranged in a cylindrical structure weighing approximately 4200 lbs and capable of producing a uniform 1400 Gauss field in the interior bore. The magnet is constructed of stacked Nd-Fe-B magnets, positioned as columns in the PM structure to form a Halbach Ring, with each individual magnet's field oriented to contribute to the alignment and field uniformity. Figure 5.1.1-2 shows the magnetic field orientation of the magnets within the ring.

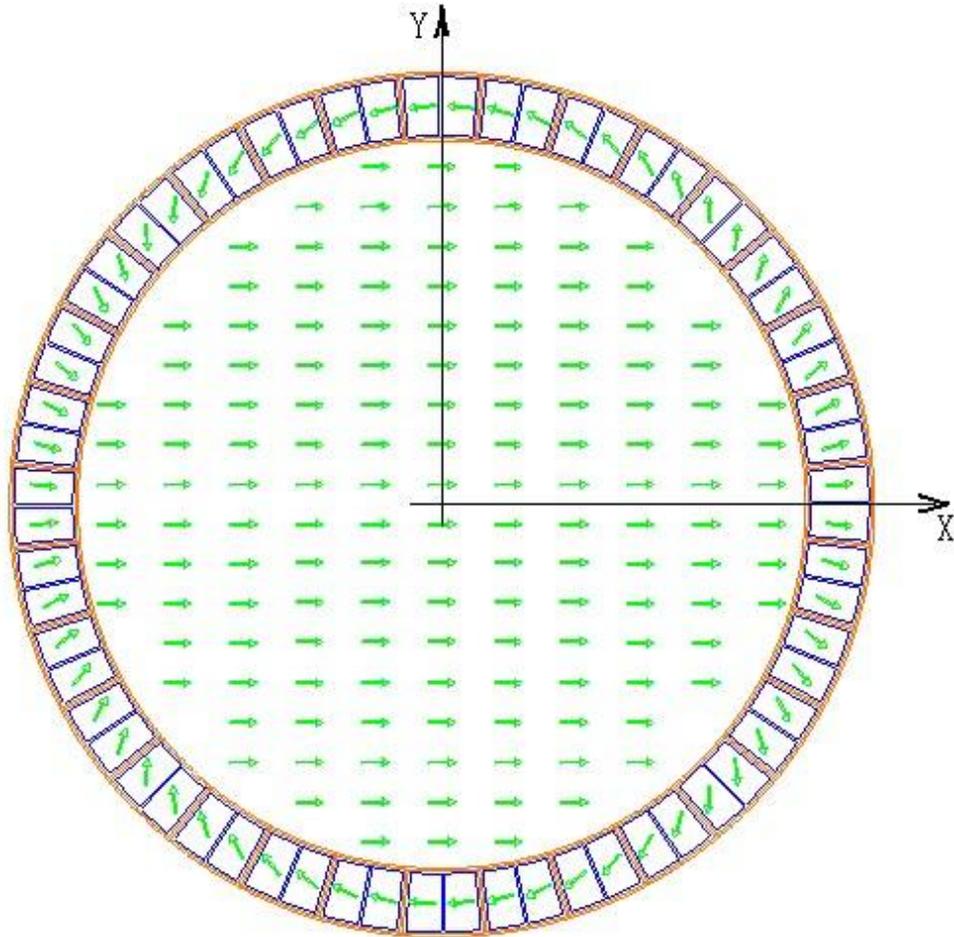


Figure 5.1.1-2 Magnetic Field Orientation, Halbach Ring

Each magnet is approximately 1 inch x 2 inch x 2 inch weighing approximately 0.492 kg each. There are 64 columns of magnets with 32 magnets per column.

The structure of the PM is made of a welded aluminum inner cylinder (1115mm inner diameter, 800 mm tall, 3 mm thick) and a riveted outer cylinder (1298 mm outer diameter, 4 mm thick), with the two joined by a series of 32 “Z” stringers (2.5 mm thick) that form cavities in which one (Figure 5.1.1-3) or two columns (Figure 5.1.1-4) of magnets are inserted and restrained. Rings are in place around the outer cylinder to further reinforce the cylinders and provide structural interface blocks for attachment to the DX structure. Flanges are attached to the top and bottom of the PM by “L” bracket.

The flanges extend across the magnet cavities closing off the cavities and will contain the magnets if the glue were to fail. The magnet's construction is bolted and riveted and has a single weld in the inner bore cylinder. Each of the eight structural tie blocks interface with the supporting structure by shear pins and bolts.

Magnet blocks (not yet magnetized) are formed into composite "column" that are glued together. These columns are then magnetized as a group before being placed into the Z-stringer defined volume, a step is provided in the magnets to offset magnetically induced loading on the Z-stringers, and the position of the Z-stringers are such as the magnetically induced loads compress and not pull on the Z-stringer countersunk rivets Figure 5.1.1-4.

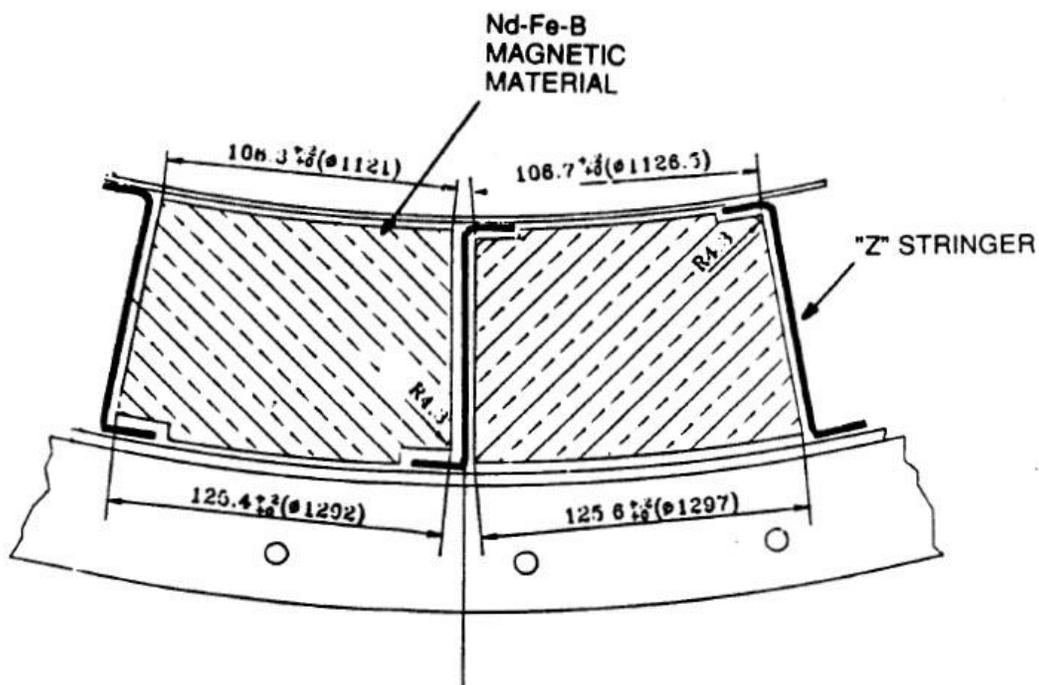
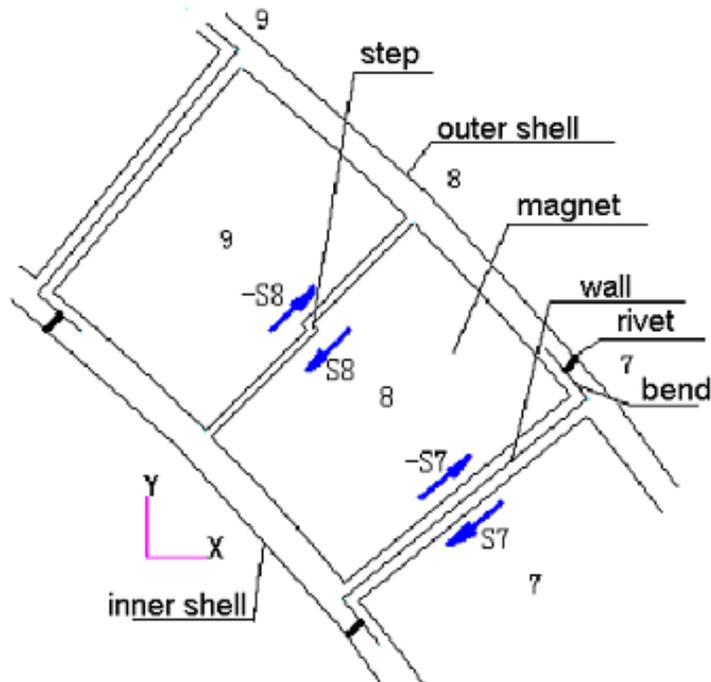


Figure 5.1.1-3 Z-stringer Construction



The magnetic shear pair $+/-S8$ are canceled each other with the step.
The magnetic shear pair $+/-S7$ don't load the rivet with the correct bend.

Figure 5.1.1-4 Z-stringer Construction

The cavities are vacuum filled with a glue to eliminate volumes in which the magnets may shift. The structural integrity of the PM was qualified without the glue so as to eliminate the concern of possible loss of glue integrity over time. The glue introduction process was qualified using a transparent mockup to assure full penetration of the adhesive. With the glue in place the Z-stringer volumes are enclosed by the flanges of the PM structure, further confining and containing the magnets within the toroidal volume.

The PM is supported inside the VC by way of the DX structure and sixteen struts. The DX structure is constructed of milled AL 7075-T7351 with an alodine finish. Four identical DX components are bolted and shear pinned together to form the structural interface that surrounds the PM, Figure 5.1.1-5. The DX interface to the PM is made with shear pins and bolts with shims used to account for any gapping. A clevis and spherical bearing joint is the interface to the titanium struts that connect to the VC by way of the VC fittings (Figure 5.1.1-7) that are bolted in place (previously the thermal isolating straps utilized Bellville washer stacks to provide a required preload, this

interface is simply bolted in place.) A minimum of preload is created during the installation of the struts.

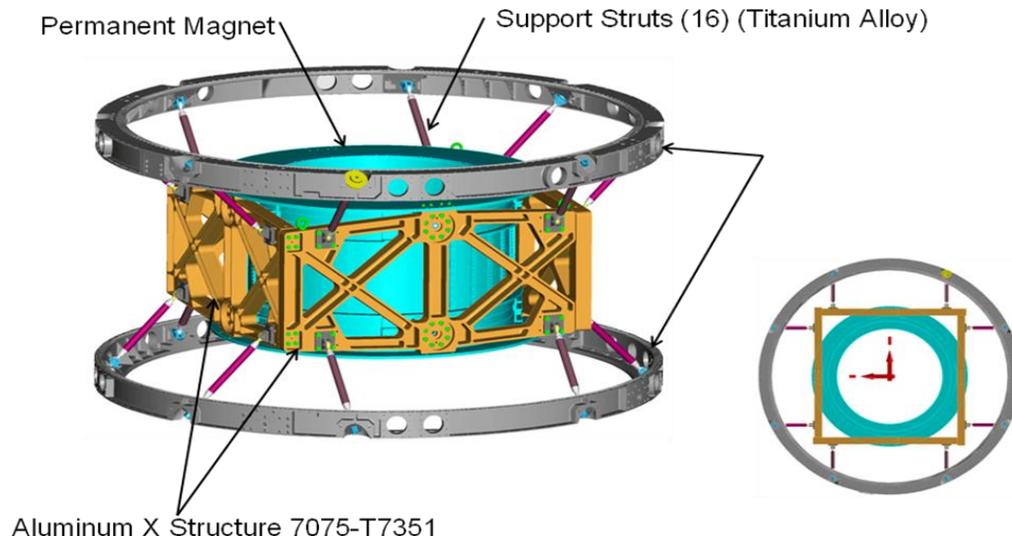


Figure 5.1.1-5 – Double X Structure, Struts and VC Upper and Lower Rings

The locking nuts for each adjustable strut is positively precluded from releasing by the use of “ears” that bend over the nut and preclude nut rotation. This is shown, with the DX structure interface, in Figure 5.1.1-6. Figure 5.1.1-7 shows the interface of the struts to the VC.

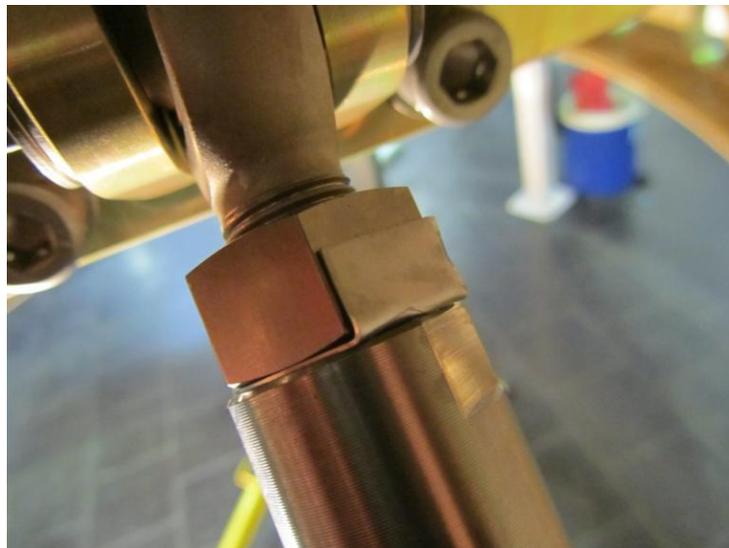


Figure 5.1.1-6 DX Strut Locking Nut and Locking Feature, Shown attaching to DX Structure

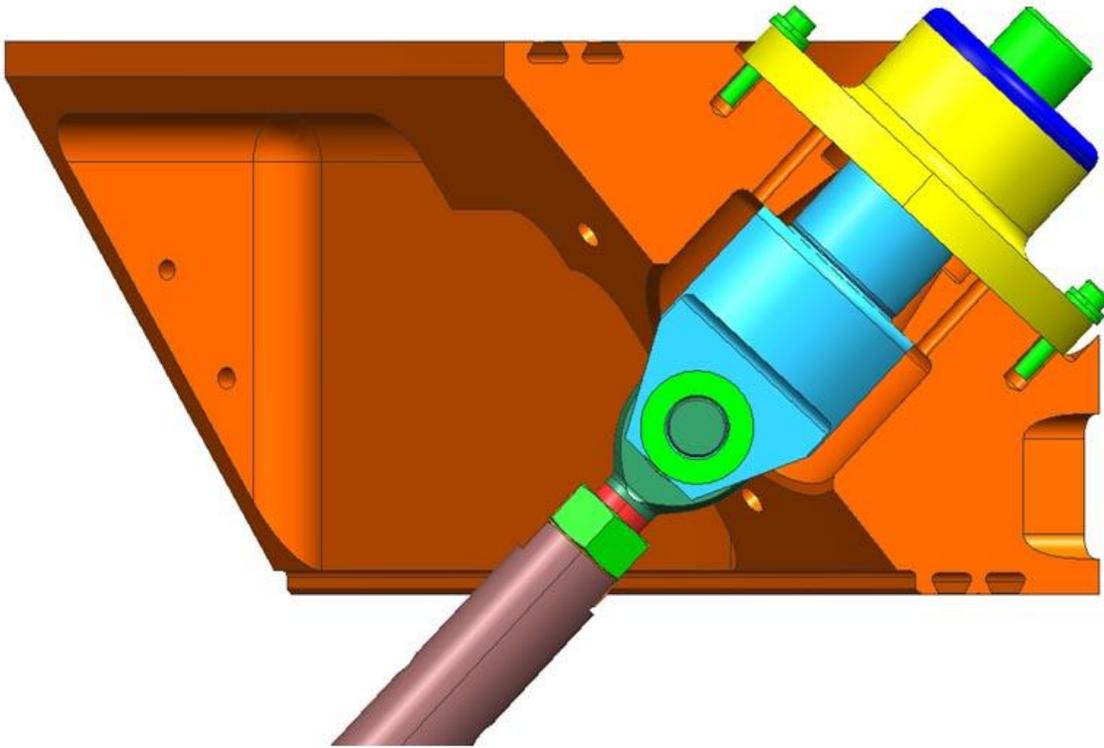


Figure 5.1.1-7 DX Strut Interface (Clevis) to VC

In all cases, the AMS-02 magnetic field would not interfere with the proper operation of any equipment located within the field, including robotic operations of the SSRMS, SPDM and MT (10 Gauss Field). The field was found to be within acceptable limits and would not present a hazard to astronauts or their equipment (300 Gauss Field).

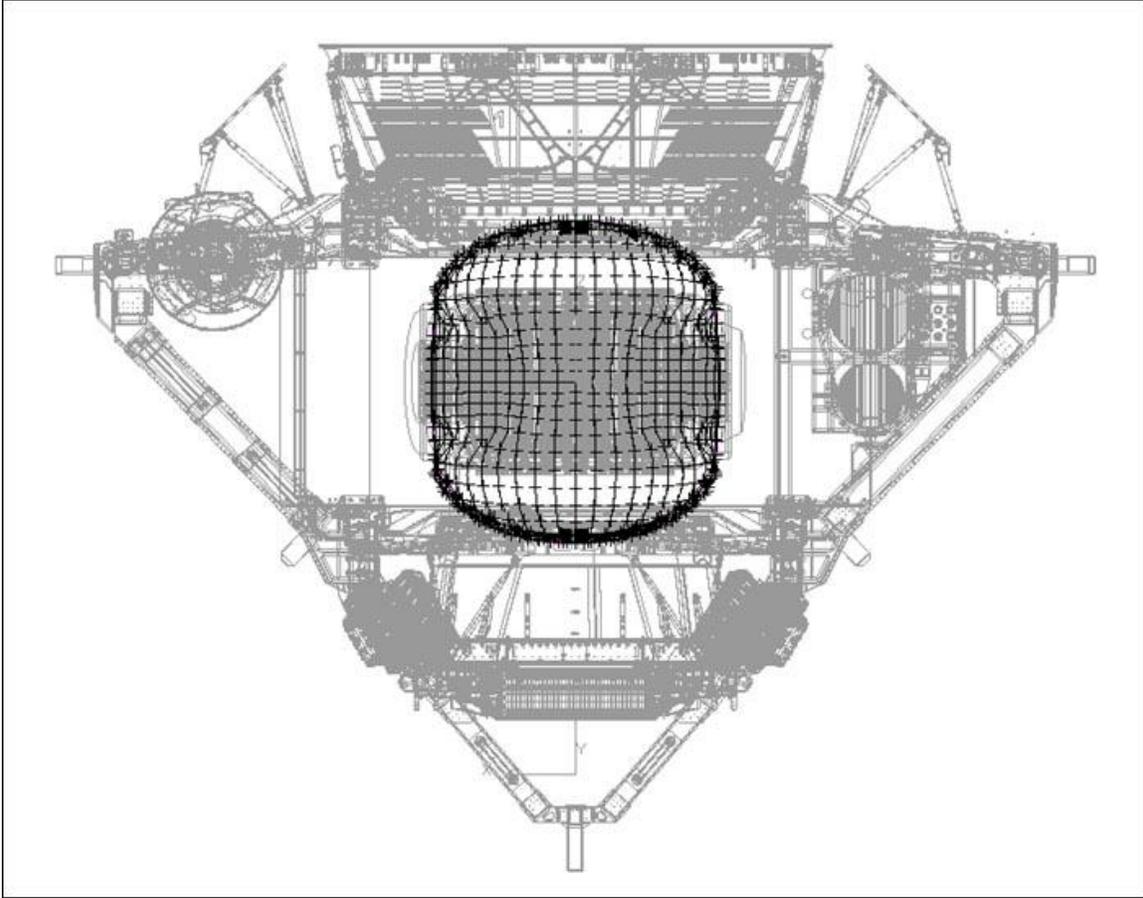


Figure 5.1.1-7 300 Gauss Magnetic Field (interior to the VC structure)

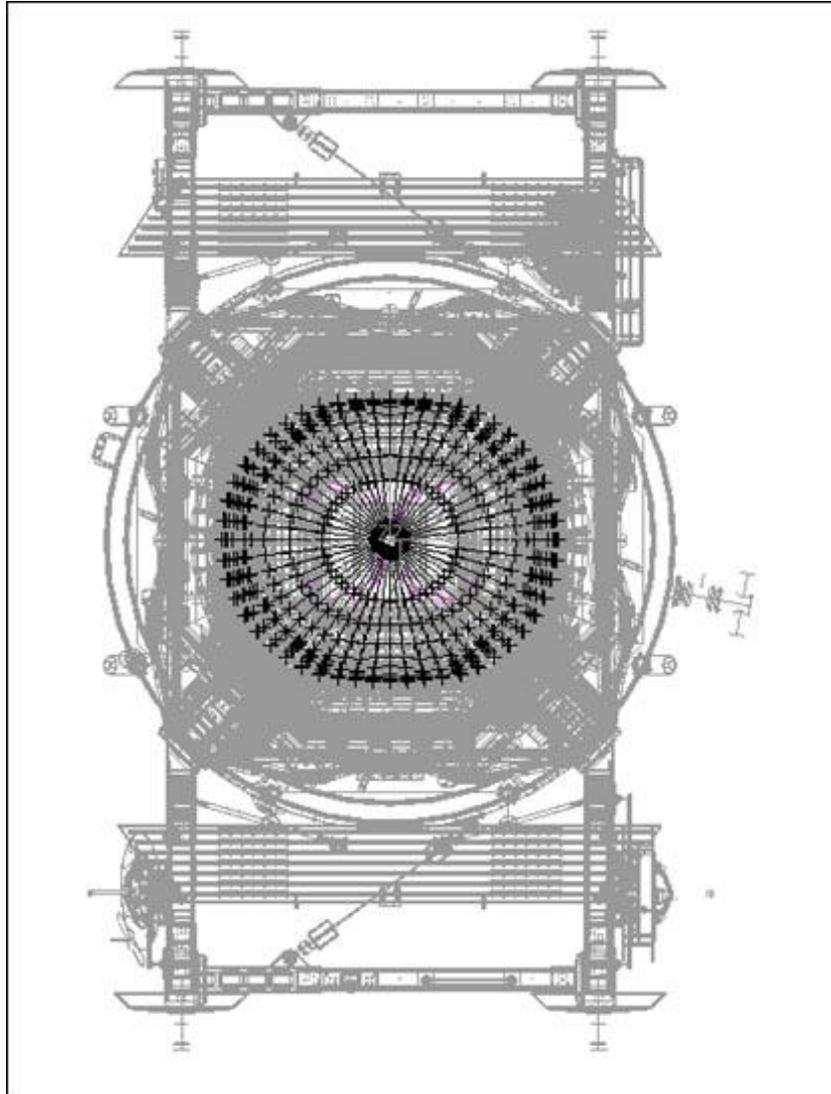


Figure 5.1.1-8 300 Gauss Field (Top View)

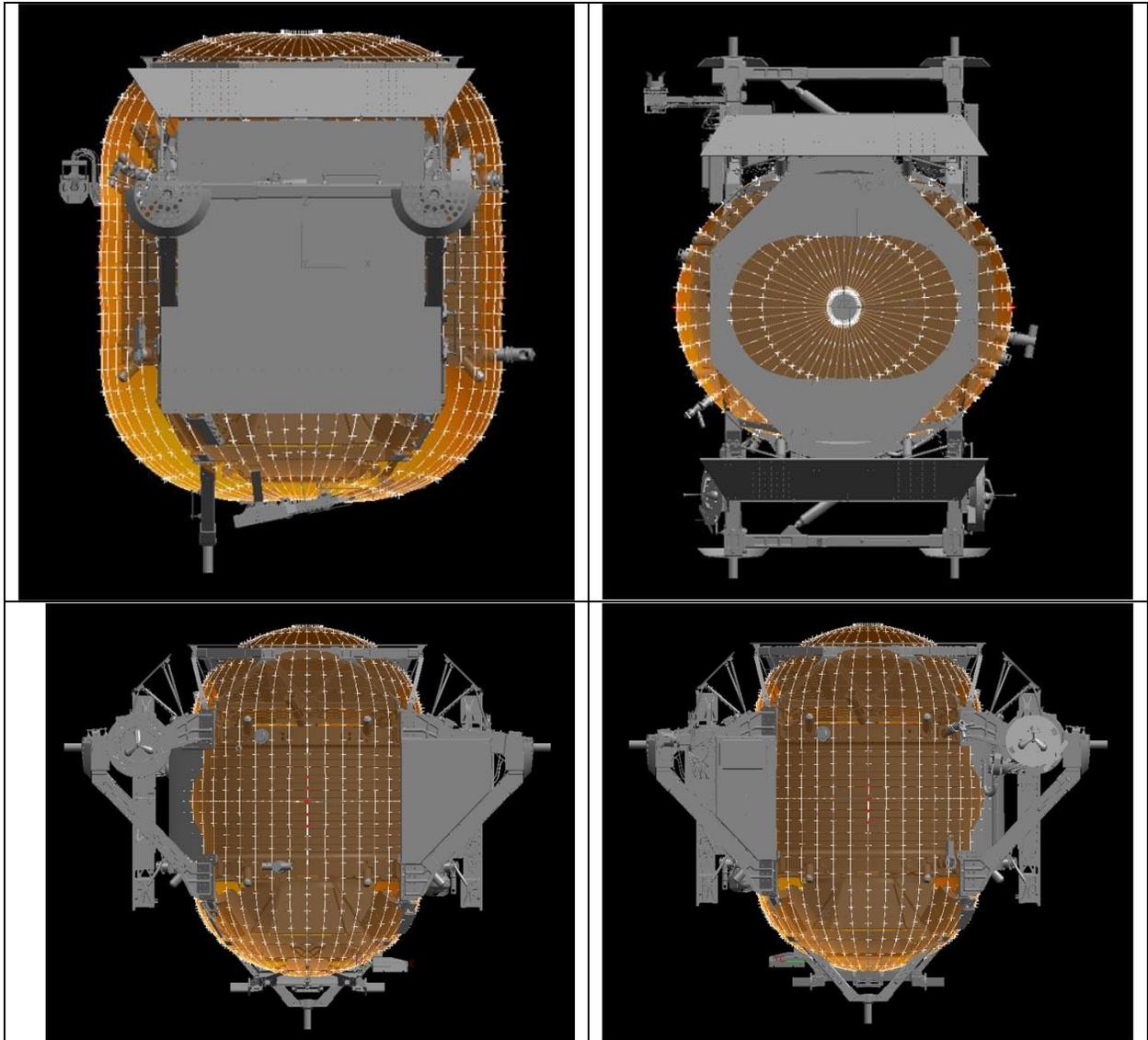


Figure 5.1.1-9 10 Gauss Field (Note, Removed Cryosystem components still visible in silhouette graphic of AMS Structure)

The overall magnetic field will interact with the Earth's magnetic field and create a constant torque input to the station. The ISS Guidance, Navigation and Control (GN&C) Team provided the AMS-02 Project maximum magnetic dipole moment levels which would ensure that this torque would not be beyond the ISS ability to control. Measured value of the far field dipole moment of the AMS-02 was 11.55 kA/m^2 in the AMS-02 X-Axis, zero in the other two axes. As the AMS-02 coordinates must be translated to the ISS due to the different orientations and the 12 degree installation tilt of the AMS-02, the translated dipole moment value is shown in the following table:

ISS Axis	AMS-02 Value	ISS Provided Allowables
X	0	100 kA/m ²
Y	11.3 kA/m ²	40 kA/m ²
Z	2.4 kA/m ²	190 kA/m ²

The values show that the AMS-02 is substantially below the maximum allowable that the ISS CN&C Team has provided.

5.1.2 Structural Support

The DX structure is the primary structural interface between the permanent magnet and the titanium struts coming from the Vacuum Case. The design of this system and the struts is intended to minimize the amount of modification required on previously tested and accepted flight hardware. Because this system has not had a dedicated static test, it has been designed to a factor of safety of 2.0 to yield and 3.0 to ultimate.

The DX hardware consists of four large frames built up of alodined 7075-T3751 aluminum which are then bolted to each other at the corners. This system is bolted to the magnet at eight different locations. These locations and fasteners are the same ones used to attach the permanent magnet to the original AMS-01 support structure. Also at the corners are a series of 16 clevises, four in each corner, where the titanium struts (Figure 5.1.2-2) connect. These have been arranged to replicate the line of action of the magnet support strap assemblies in the previous, Cryomagnet design.

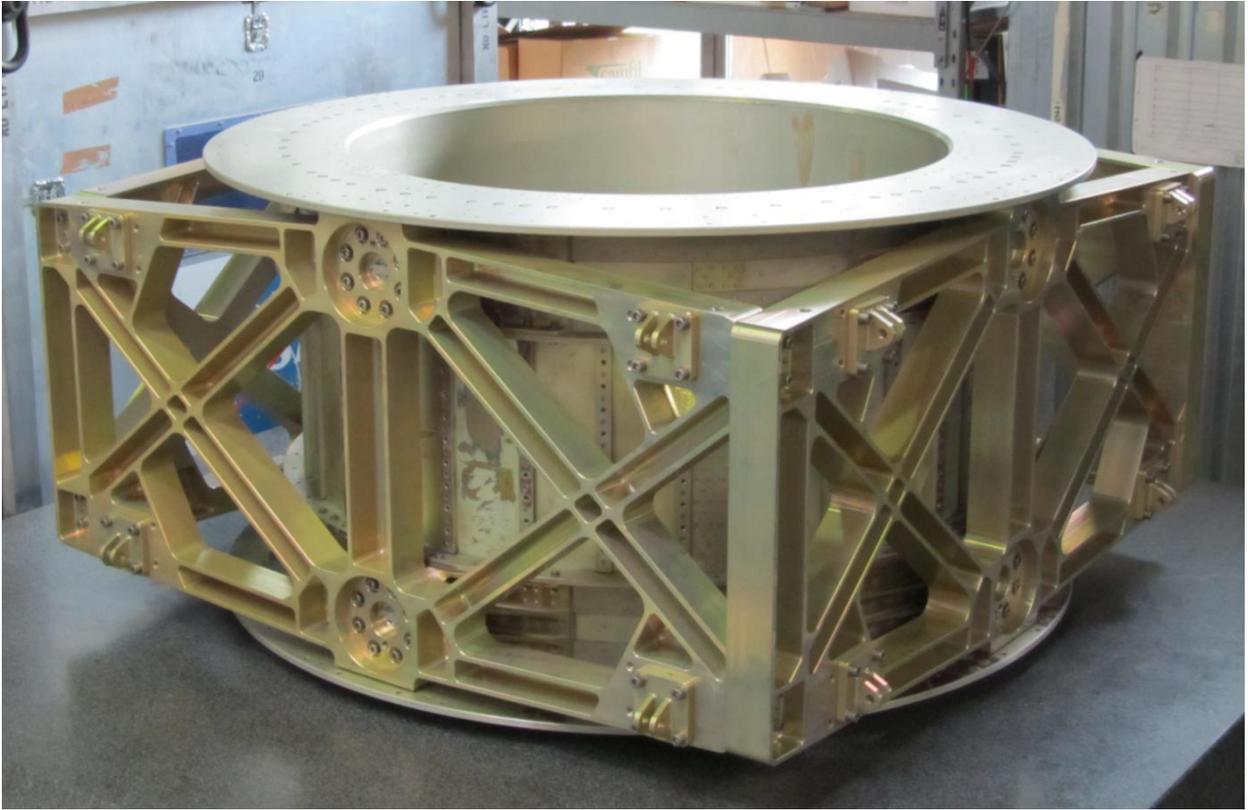


Figure 5.1.2-1 The Double-X Structure

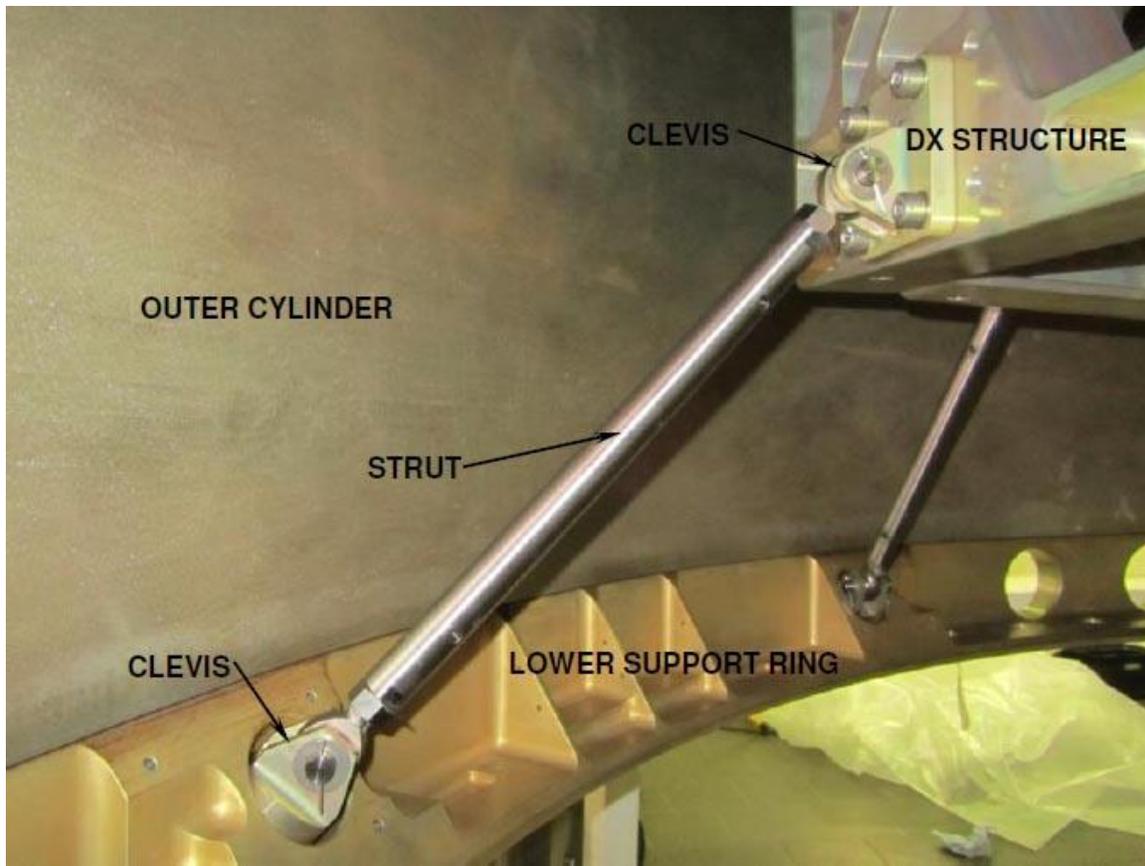


Figure 5.1.2-2 Struts

5.1.3 Vacuum Case (VC)

The design and analysis for the Vacuum Case (VC) is provided by the Engineering & Sciences Contract Group (ESCG) in Houston and fabrication is being performed by Standard Tool & Die Company (STADCO) in Los Angeles with oversight by ESCG personnel. The VC originally served a dual purpose; it is a primary structural support that works in conjunction with the USS-02 to form the foundation structure of the AMS-02 and serves as a vacuum jacket for the superfluid helium tank and Cryomagnet. With the use of the fixed PM, the VC has been left open to vent and no longer provides a vacuum jacket. The Vacuum Case assembly and cross section is shown in Figure 5.1.3-1 and 5.1.3.1-2.

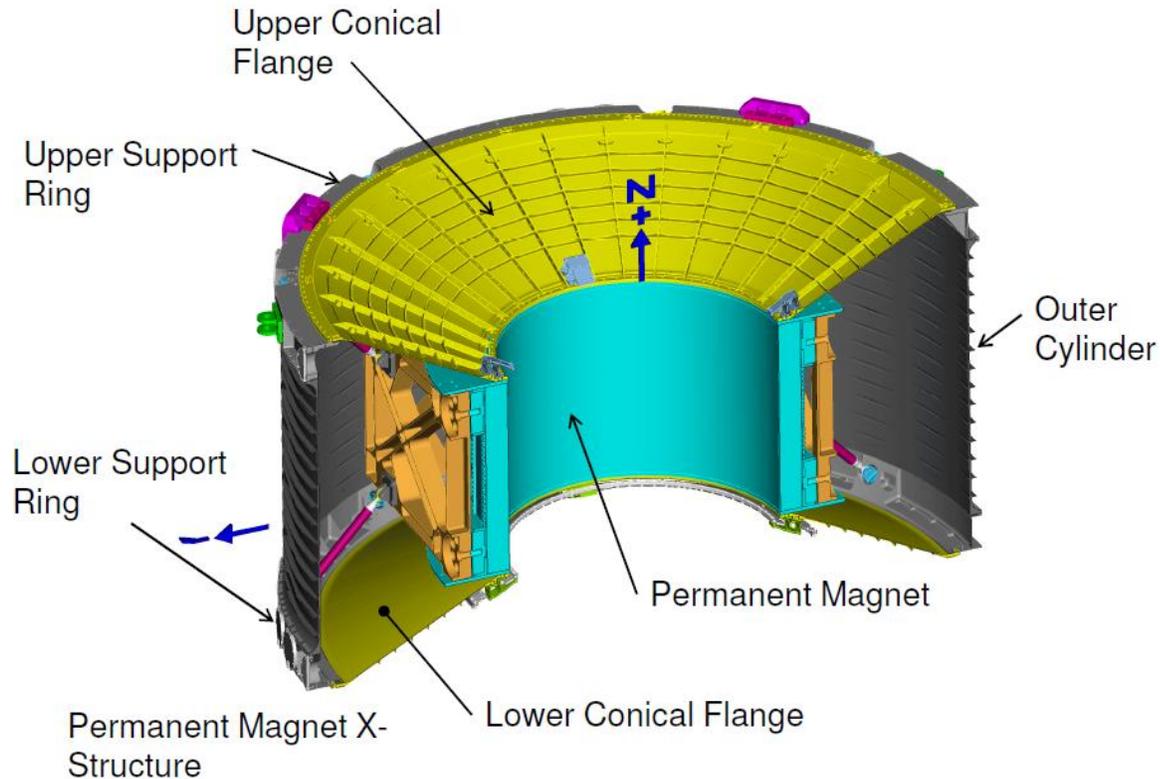


Figure 5.1.3-1 Vacuum Case

5.1.3.1 Vacuum Case Structural Components

The main structural components of the VC are described in the following paragraphs.

5.1.3.1.1 Conical Flanges

The Upper and Lower Conical Flanges are made of spin formed Al 2219-T62. The Conical Flanges start as an annealed plate (T0) and spin formed to rough shape using two dies. They are then solution heat treated and quenched (T42) followed by aging to final condition (T62) to complete a spin form blank. One blank was cut up through the entire thickness along the entire cone for tensile test samples to qualify this process. The remaining blanks are qualified by tensile samples along the inner and outer diameters. All blanks must meet the design requirements for Aluminum 2219-T62 in MIL-HDBK-5 and all samples are tested per ASTM B557. The blanks are then machined to final dimensions.

5.1.3.1.2 Support Rings

The Upper and Lower Support Rings are made of a rolled ring forged Al 7050-T7451. The forgings are qualified to AMS 4108 and inspected per NASA/JSC PRC-6504, Class A. In addition to this qualification, additional tensile samples are removed from both ends of the forging and tested per ASTM B557. The forging is then machined to final dimensions. The Support Rings contain all of the ports for the support struts along with ports previously used as electrical/plumbing feed-throughs and cyrocooler interfaces. All surfaces are machined to the standard 125 or better micro-inch finish. All exterior surfaces, with the exception of sealing surfaces, are anodized. All interior surfaces, sealing surfaces, and O-ring grooves (O-rings no longer used), are chemical filmed to prevent corrosion.

5.1.3.1.3 Outer Cylinder

The Outer Cylinder is milled from a rolled ring forging of Al 7050-T7451. The forgings are qualified to AMS 4108 and inspected per NASA/JSC PRC-6504, Class A. In addition to this qualification, additional tensile samples are removed from both ends of the forging and tested per ASTM B557. The forging has been machined to provide reinforcing ribs along the height of the cylinder. The ribs are spaced approximately 3.0 inches apart and are .10 inch thick. The recessed O-ring grooves, which help prevent inadvertent damage, are machined to a 16 micro-inch finish. All other surfaces are machined to the standard 125 or better micro-inch finish. All exterior surfaces, with the exception of sealing surfaces, are anodized. All interior surfaces, sealing surfaces, and O-ring grooves, are chemical filmed to prevent corrosion. The chemical film process does not affect the sealing capability of the O-ring.

5.1.3.1.4 Clevis Plates

The Clevis Plates are fabricated from CRES A286 and are used to attach the diagonal struts from the USS-02 to the Upper Support Ring

5.1.3.1.5 Interface Plates

The Upper and Lower Interface Plates are fabricated from Al 7050-T7451 plate and are the main interface with the USS-02 at 8 locations.

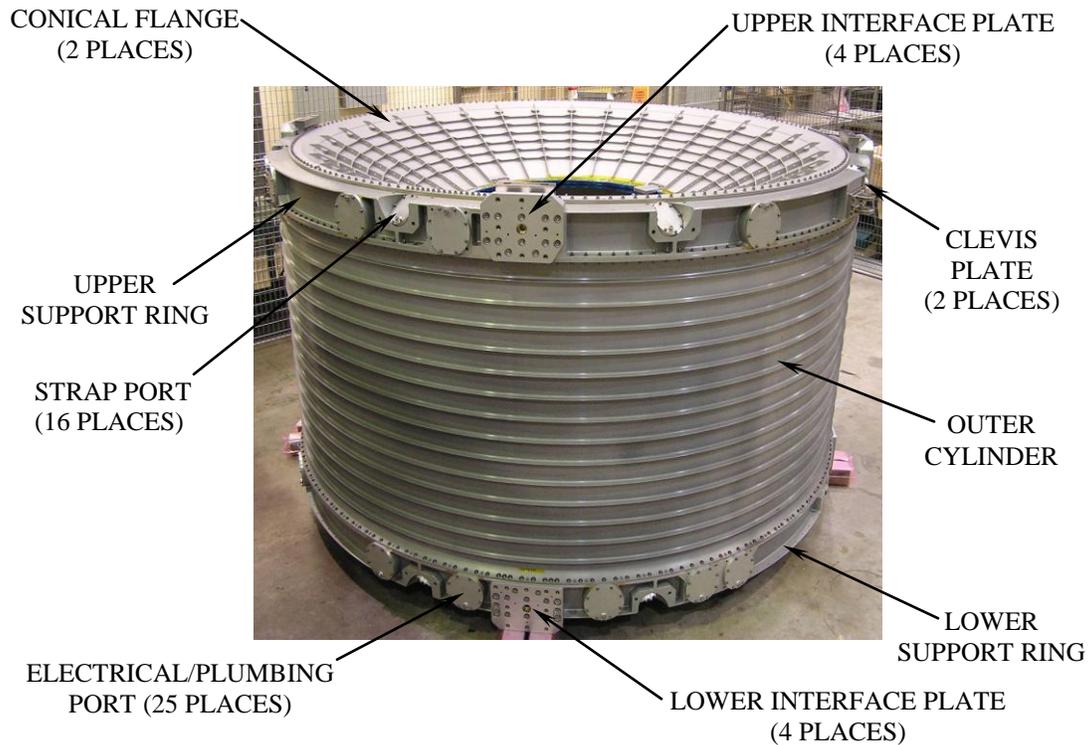


Figure 5.1.3.1-1 Vacuum Case Assembly

The weight of the VC is 1626 lbs (738 kg). The VC attaches to the USS-02 at the 8 Interface plates and the 2 Clevis Plates. Since the VC is an integral part of the primary structure with the USS-02, a Structural Test Article (STA) was developed and fabricated at the same time as the Flight VC and is a flight backup. The STA VC was used for much of the AMS-02 structural testing. The Flight unit and the STA unit are identical. The PM has been mounted in the STA VC and that configuration will be flown as shown. The original flight VC remains integrated with the Cryomagnet system.

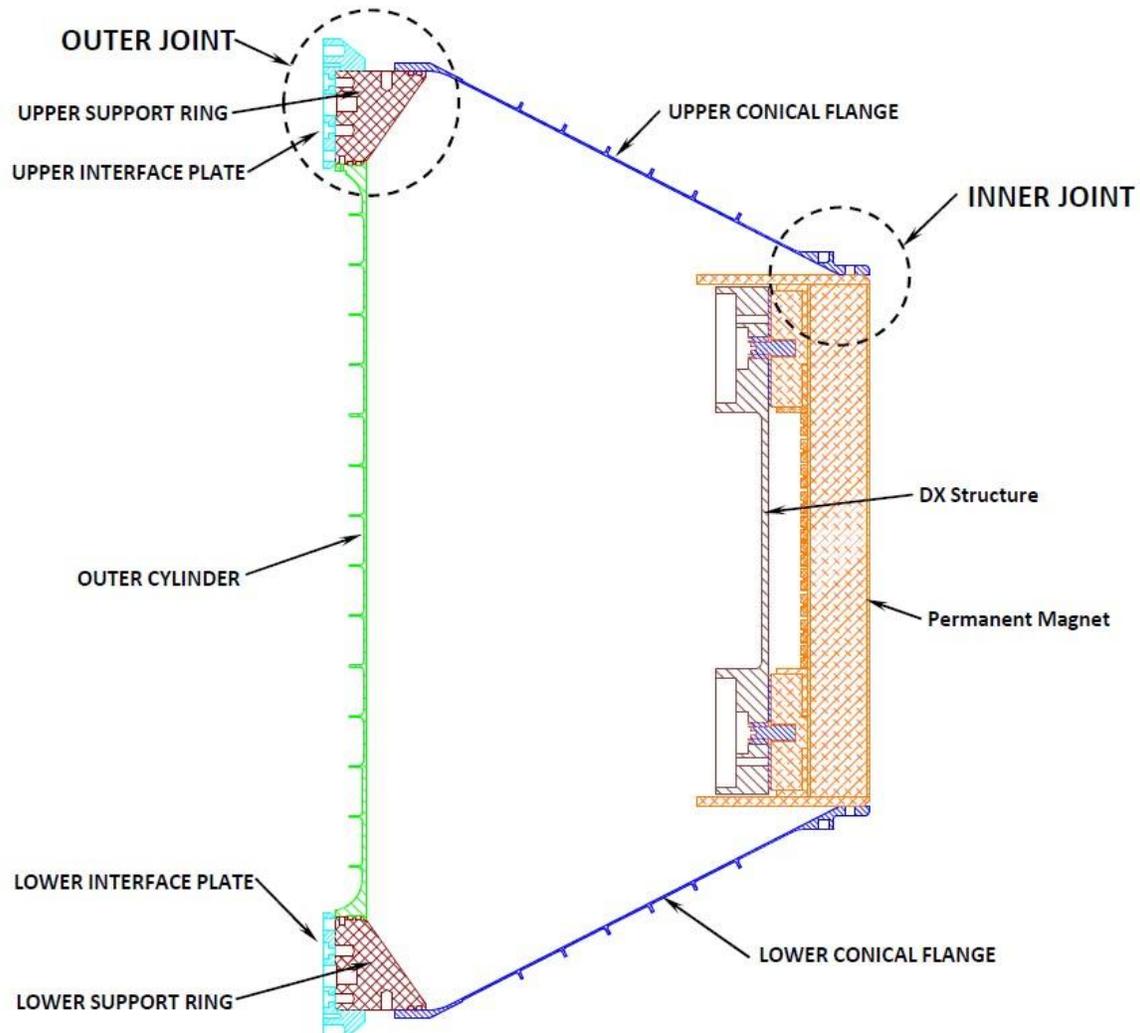


Figure 5.1.3.1-2 Vacuum Case Cross Section

5.1.3.2 Vacuum Case Assembly Details

The VC Inner Joint consists of the Upper or Lower Conical Flange bolted directly to the Permanent Magnet flange as shown in Figure 5.1.3.2-3, using 56 #10 bolts at each joint.

The VC Outer Joint, which consists of the Upper or Lower Conical Flange to the Upper or Lower Support Ring and the Outer Cylinder to the Upper or Lower Support Ring, is bolted using 1/4 and 5/16 inch fasteners at each location (Figure 5.1.3.2-2, 5.1.3.2-3). All fasteners meet the requirements of the JSC Fastener Integrity Testing Program, JSC 23642. The O-rings were removed between the Conical Flanges and the Support Rings since the flanges were removed during PM integration but the o-rings between the Outer

Cylinder and the Support Rings remain in place since this joint was not disassembled. The O-ring material is Viton and is an off-the-shelf item. These O-rings are also coated with Dow Corning High Vacuum Grease prior to installation.

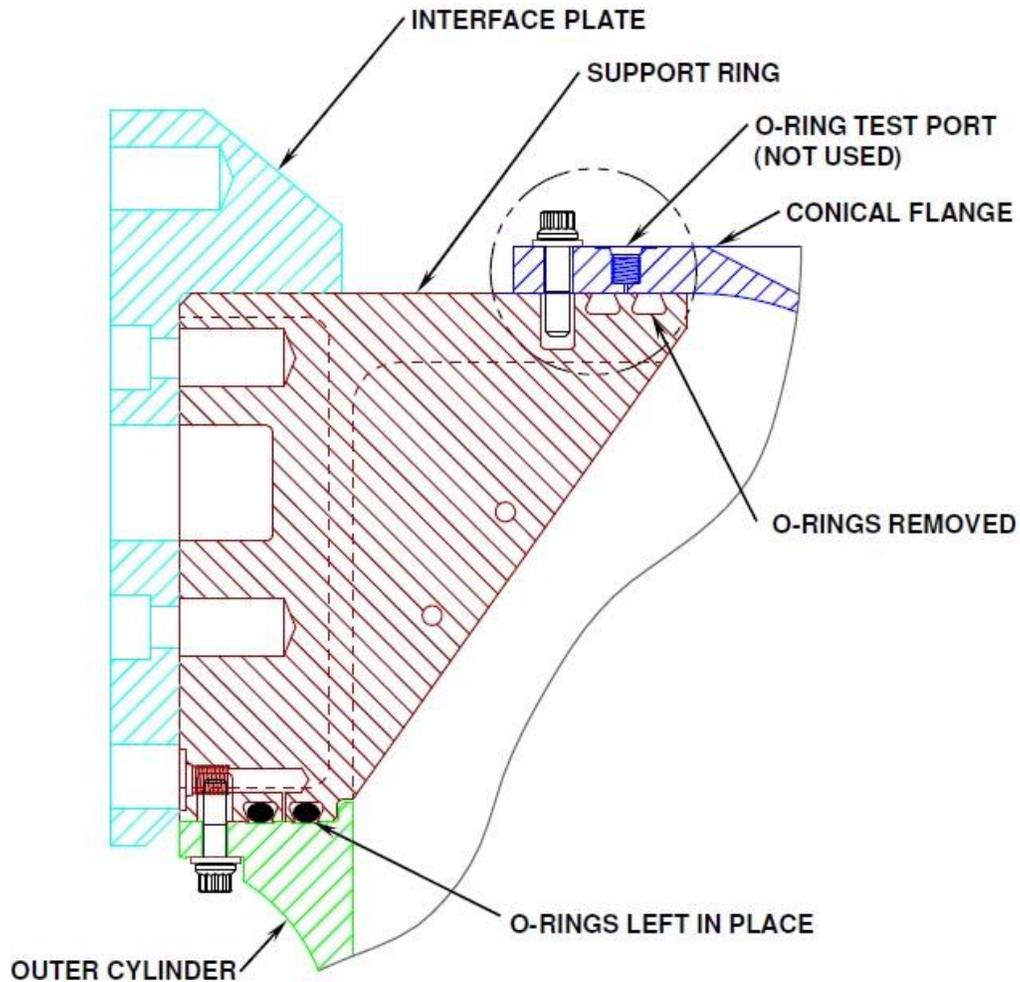


Figure 5.1.3.2-2 Outer Joint Assembly Detail

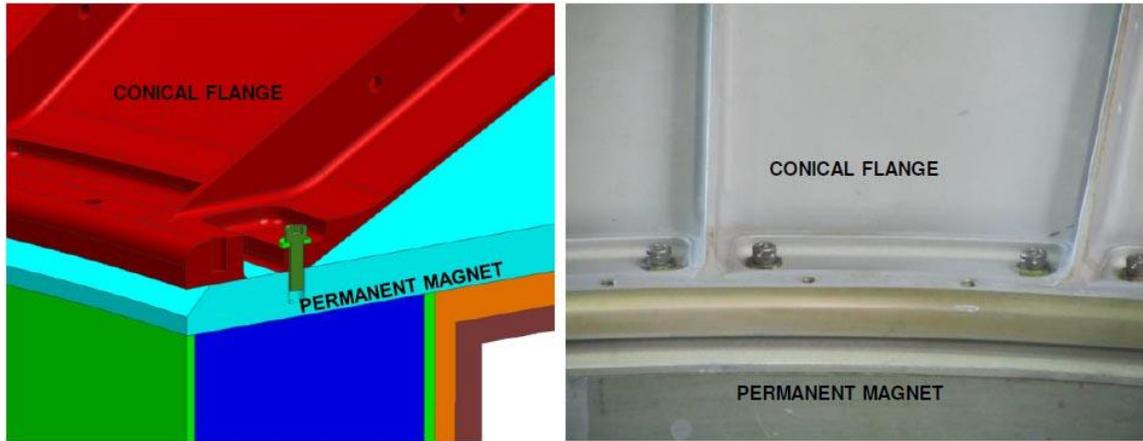


Figure 5.1.3.2-3 Conical Flange to PM Interface

5.1.3.3 Feed Thru Ports

There are 41 ports on the Vacuum Case. Sixteen ports are for the Cryosystem support straps and 25 ports were previously used for plumbing lines and electrical connections in the Cryomagnet configuration (Figures 5.1.3.3-1 and 5.1.3.3-2). Note that many graphics in this package will show Cryomagnet Support Strap covers and other VC mounted components that are not part of the flight PM configuration.

The Feed Thru ports on the +/- X sides will be covered with a lightweight aluminum cover to keep sunlight from penetrating the VC. The Feed Thru ports on the +/- Y sides are blocked by the radiators and electronics crates. These open ports provide venting for the VC internal volume.

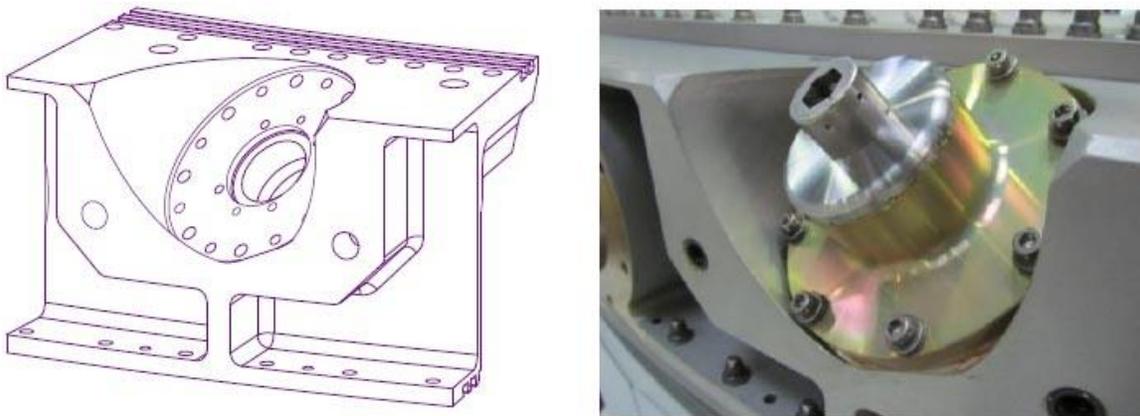


Figure 5.1.3.3-1 Strut Port ISO Views

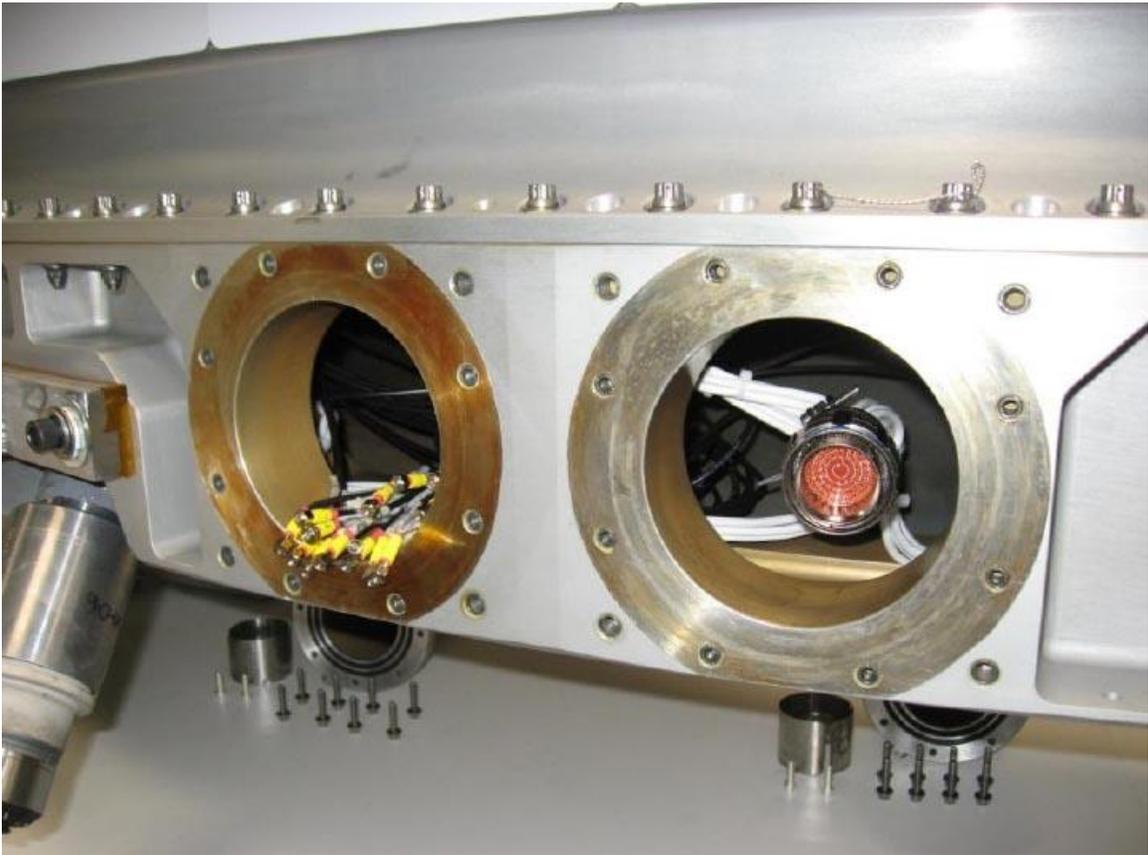


Figure 5.1.3.3-2 Feed Thru Ports

5.2 UNIQUE SUPPORT STRUCTURE-02 (USS-02)

The Unique Support Structure – 02 (USS-02) is the primary structural element of the AMS-02 Payload (Figure 5.2-1). Its purpose is to structurally support the Permanent Magnet and the AMS-02 Experiment during launch, landing, and on-orbit loading and integrates them with Shuttle and ISS. The total weight of the AMS-02 is 15,250.97 lbs (6917.72 kg).

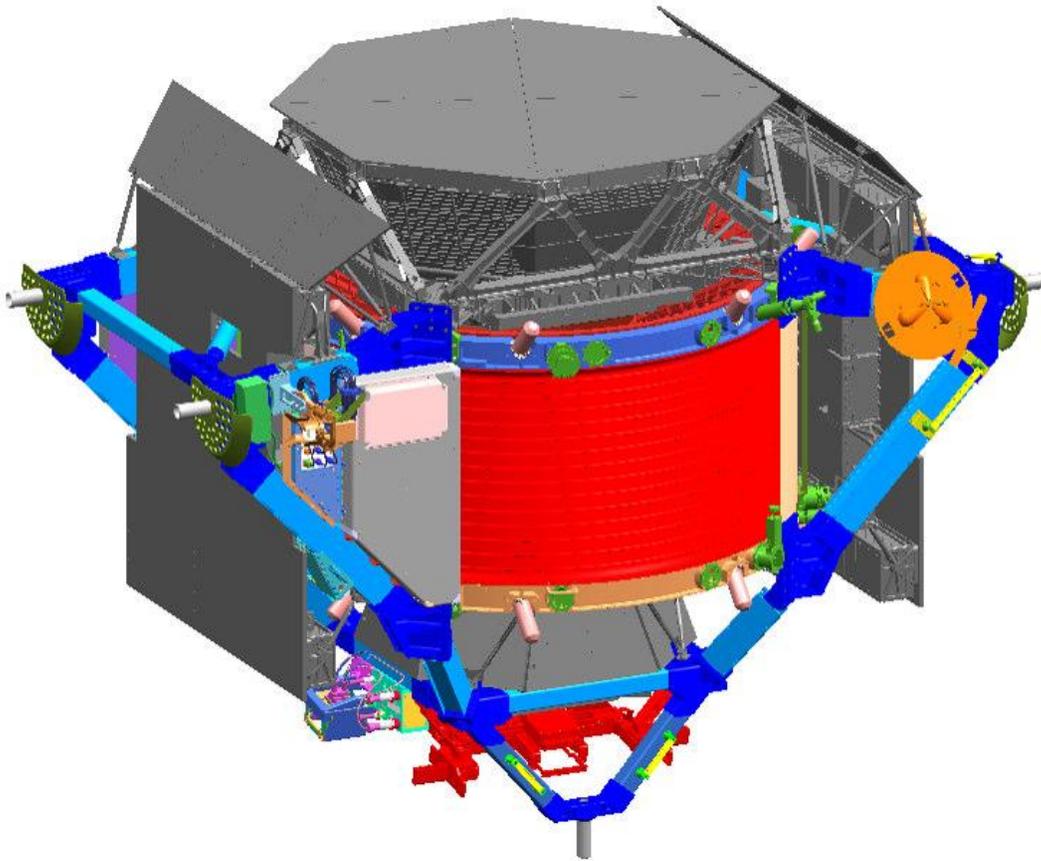


Figure 5.2-1 Alpha Magnetic Spectrometer (AMS) – 02 Payload

The USS-02 (Figures 5.2-2 and 5.2-3) consists of five primary subassemblies – the Upper USS-02, Vacuum Case (VC), Lower USS-02, Keel, and the AMS Payload Attach System (PAS). Each of these subassemblies is bolted together to form the top-level USS-02.

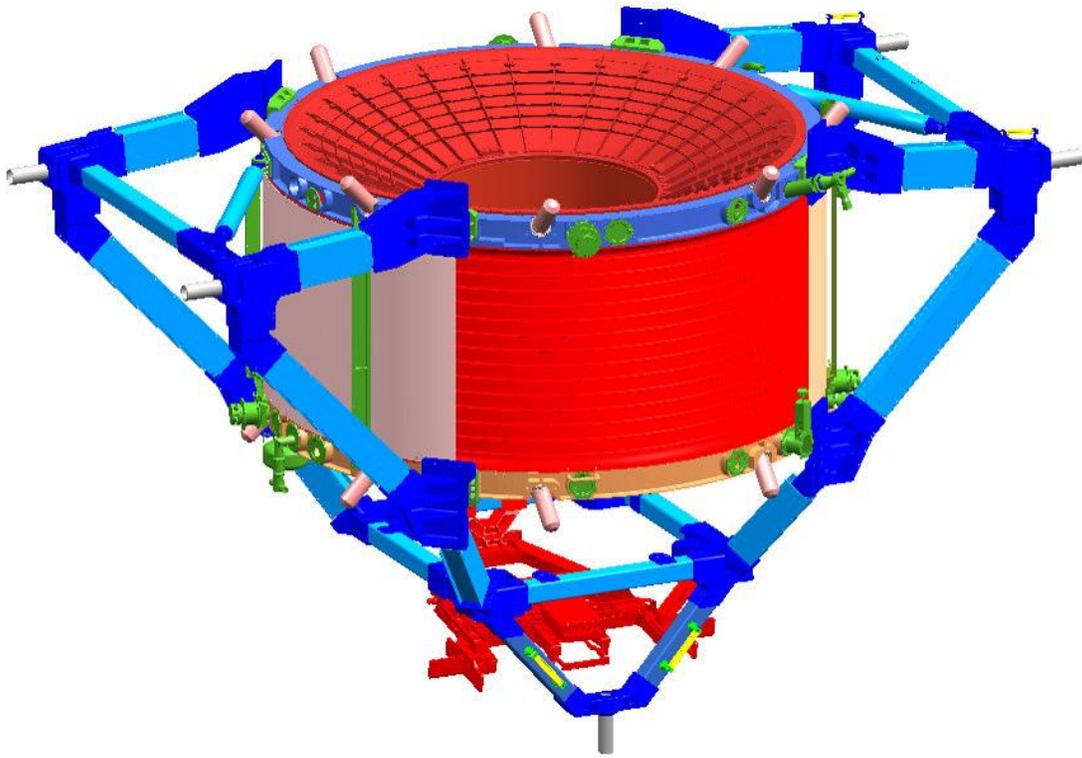


Figure 5.2-2 Unique Support Structure (USS) - 02

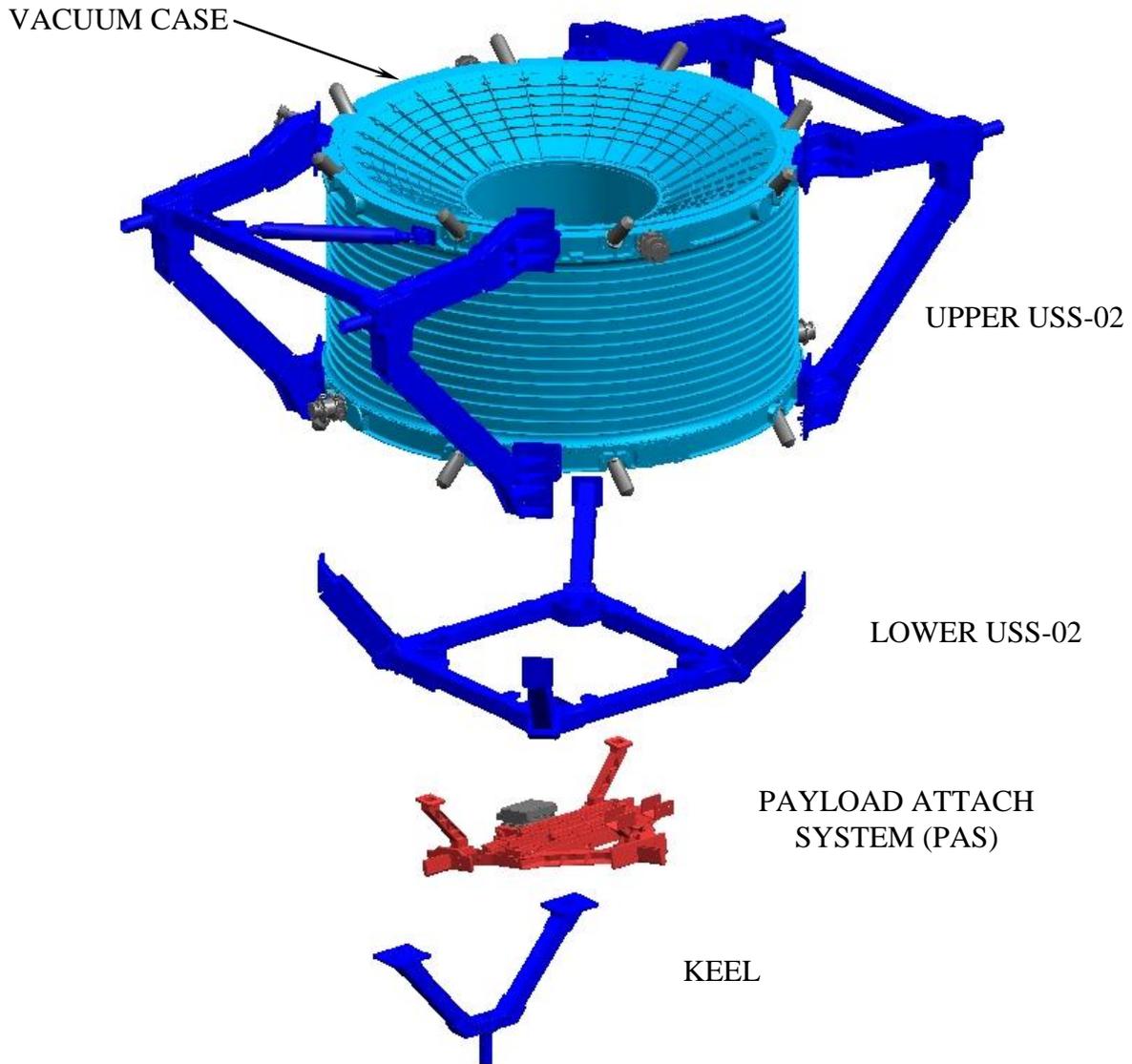


Figure 5.2-3 Subassemblies of the Unique Support Structure (USS) – 02

The Upper USS-02, Lower USS-02 and Keel are comprised of joints riveted to hollow tubes Figure 5.1-4. The joints are made of machined aluminum alloy 7050-T7451 plate and the hollow tubes are made of machined aluminum alloy 7075-T73511 extrusions.

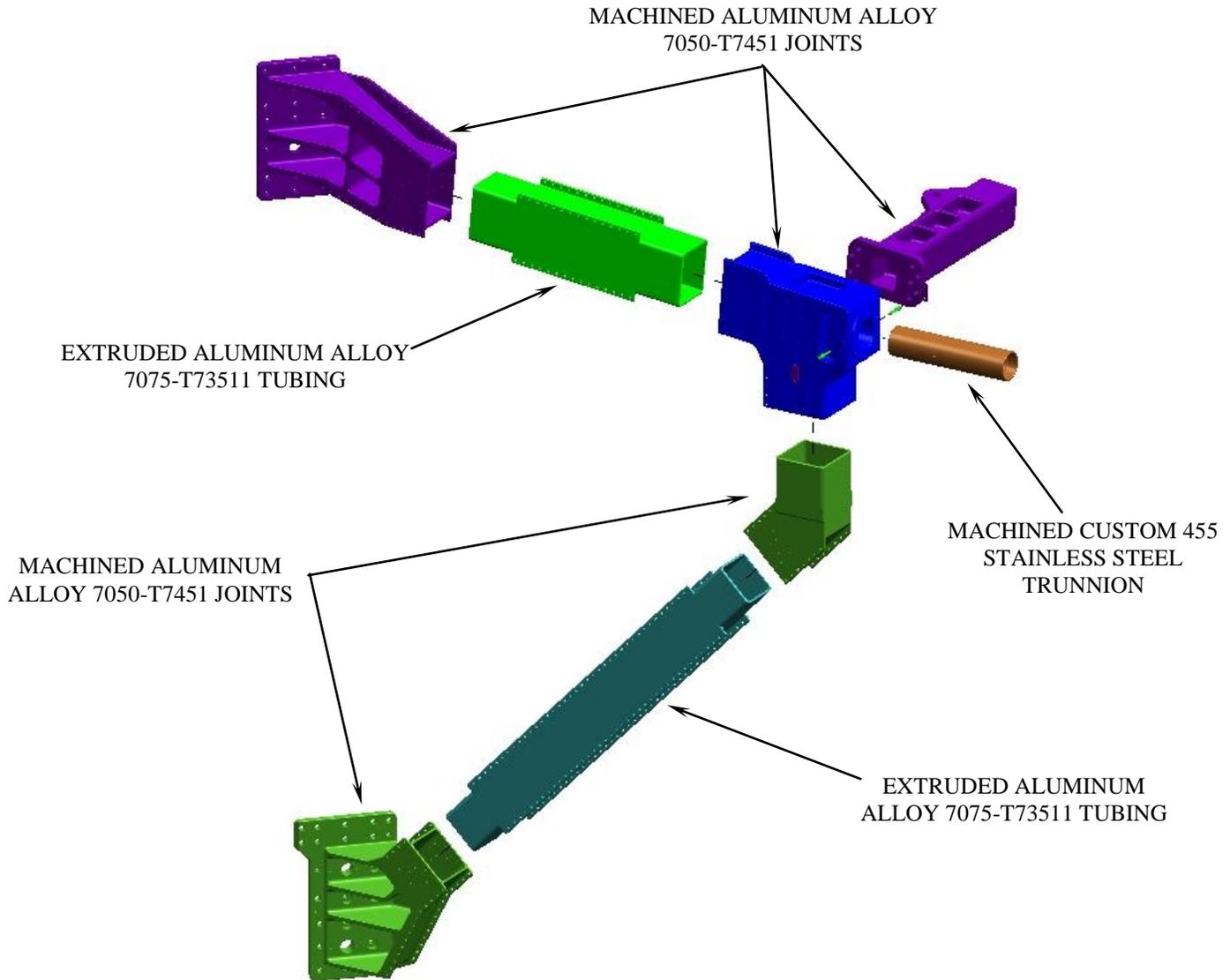


Figure 5.2-4 USS-02 Construction with Aluminum Tubes and Machined Joints

The Upper USS-02 includes two struts (Figure 5.2-5). The struts are made from machined 6061-T6511 extruded tubing, machined end fittings that are riveted to the tube, and rod-end bearings that are threaded into the end fittings. The struts are pinned to the Upper USS-02 at both ends using custom made custom 455 stainless steel shear pins.

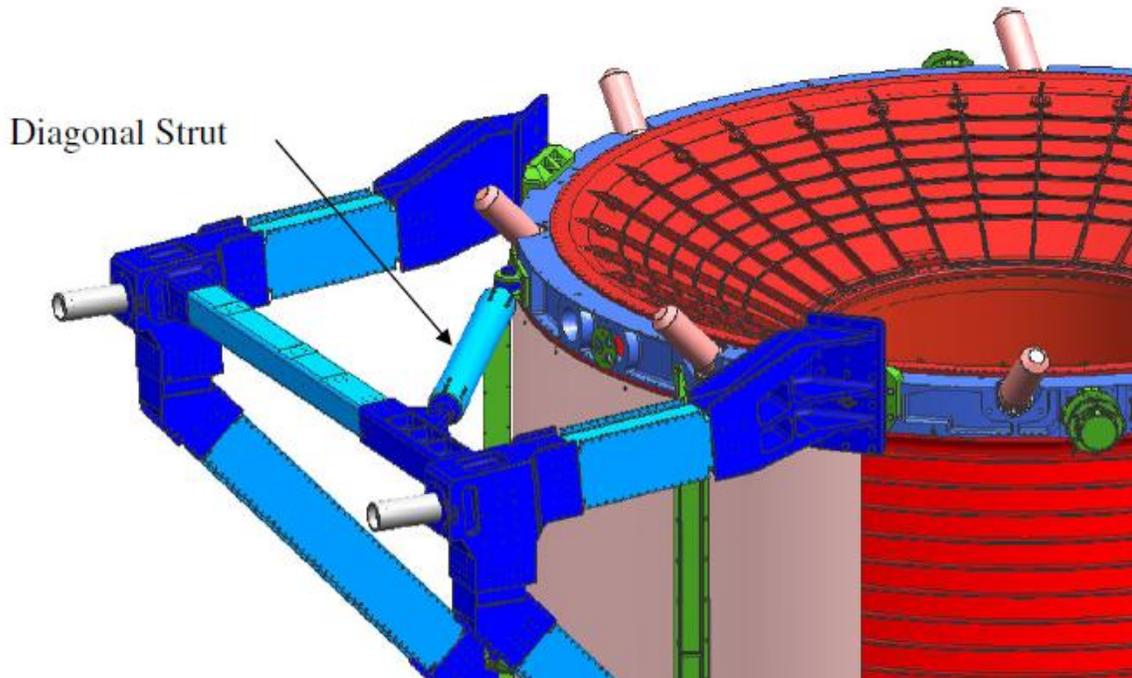


Figure 5.2-5 Location of the Diagonal Strut on the USS-02

The VC is comprised of machined parts made of aluminum alloy 7050-T7451 ring forgings and plate; aluminum alloy 2219-T7351 spin-formed plate, and A-286 stainless steel plate.

The AMS-02 PAS is comprised of components machined from 7075-T7351 plate, 7050-T7451 plate, A286 stainless steel bar, and spherical bearings made from stainless steel with self-lubricating Teflon liners.

All threaded fasteners are made from A-286 stainless steel ranging in strength from 180 to 200 KSI. All structural threaded fasteners are tested and certified per the NASA/JSC Fastener Integrity Program by the NASA/JSC Receiving Inspection Test Facility (RITF) lab. All installed structural threaded fasteners have a secondary means of back-out prevention including locking inserts, locking nuts, self-locking bolts, or lock wire (in non-EVA accessible areas only).

Shear pins are made from Custom 455 stainless steel. Portions of the shear pins fit inside aluminum bronze bushings that fit inside holes in the aluminum alloy USS-02 joints. All

shear pins are secured by machined aluminum alloy 6061-T651 block-off plates that are secured to the USS joints with two screws per plate.

All USS-02 parts except the aluminum bronze bushings have corrosion resistant metal finish. The aluminum bronze bushings are inherently corrosion resistant and do not require additional metal finish. Exposed aluminum surfaces are anodized. Stainless steel parts are passivated. Aluminum faying surfaces that require electrical conductivity are Alodined or nickel-plated.

Many of the Joints and all of the tubes that make up the USS-02 have .25 inch (nominal, ¼ inch bolts use 0.280 inch) thru holes or 0.190 inch inserts for hardware mounting. These holes are referred to as the “generic holes” of the USS.

The riveted components of the USS-02 are electrically bonded together via the large number of conductive rivet connections. Resistance of each riveted joint will be verified after assembly. Non-conductive bolted interfaces will be bonded using bonding straps secured to the USS-02 generic hole pattern. Anodize around the holes used will be removed and the resulting surfaces will be Alodined prior to installation of the bonding strap. The resistance across each bonding strap will be verified to be in compliance with Space Station Electrical Bonding Requirements (SSP30245) class “S.”

All of the AMS-02 Experiment components bolt to the USS-02 per JSC 29095, Alpha Magnetic Spectrometer - 02 (AMS-02) Experiment/Payload Integration Hardware (PIH) Interfaces (Part II). The USS-02 has unique interfaces for the TRD/Upper TOF, Tracker, Lower TOF, RICH, ECAL, and Permanent Magnet. All other AMS Experiment Hardware subcomponents bolt to generic holes on the USS-02 and VC.

The VC supports the Permanent Magnet by 16 struts and through bolted interface to the conical flanges. Details of the VC design are covered in Section 5.1.3 of this Safety Data Package.

The Shuttle interfaces consist of four sill trunnions and scuff plates, one keel trunnion, and one Remotely Operated Electrical Umbilical (ROEU) Payload Disconnect Assembly (PDA). The ROEU and PDA are GFE from the Shuttle Program. Shuttle Program

provided hardware is discussed in Section 5.4. The PDA is mounted to the ROEU Bracket. .

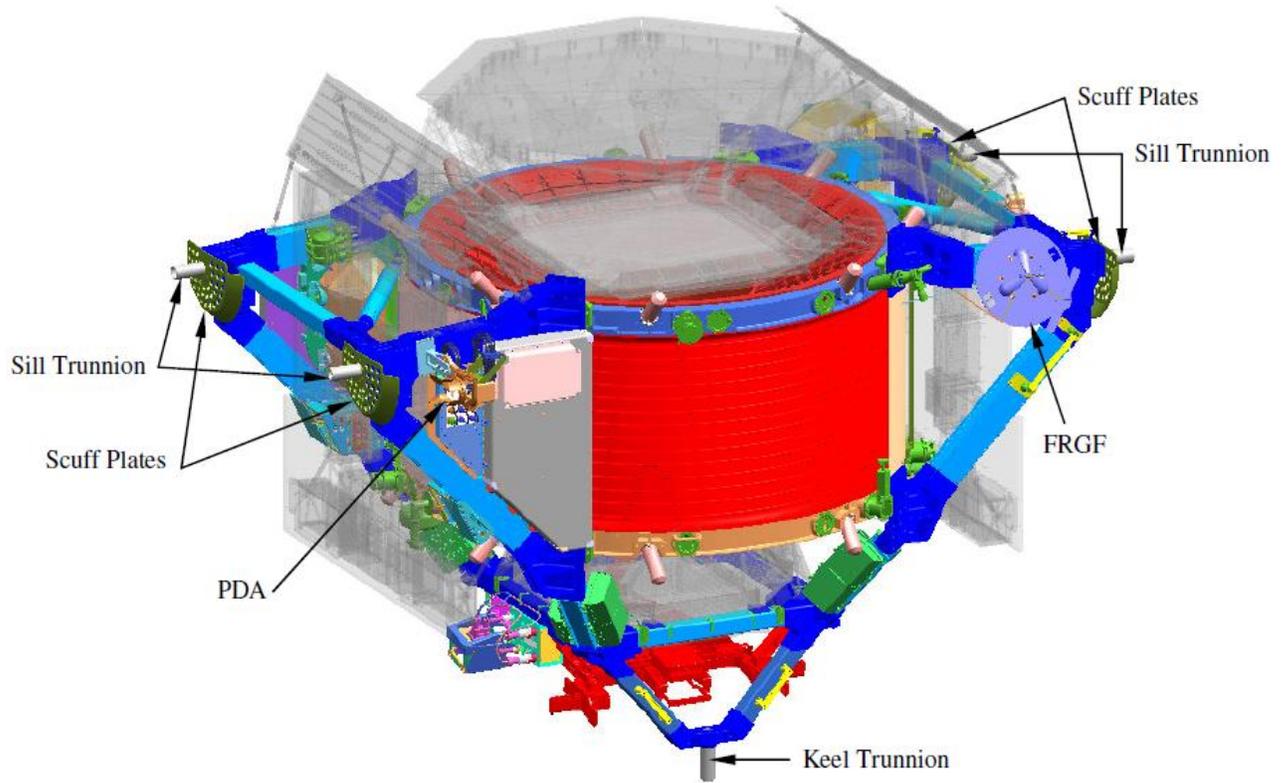


Figure 5.2-6 AMS-02 Shuttle Interfaces

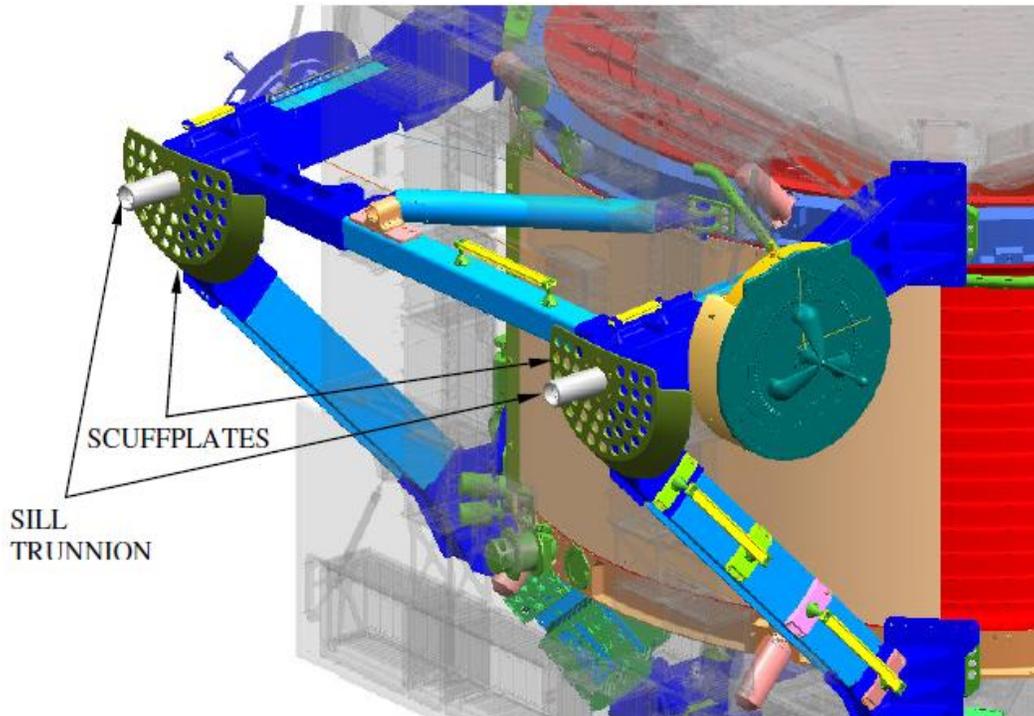


Figure 5.2-7 AMS-02 Shuttle Interfaces – Sill Trunnions and Scuff Plates

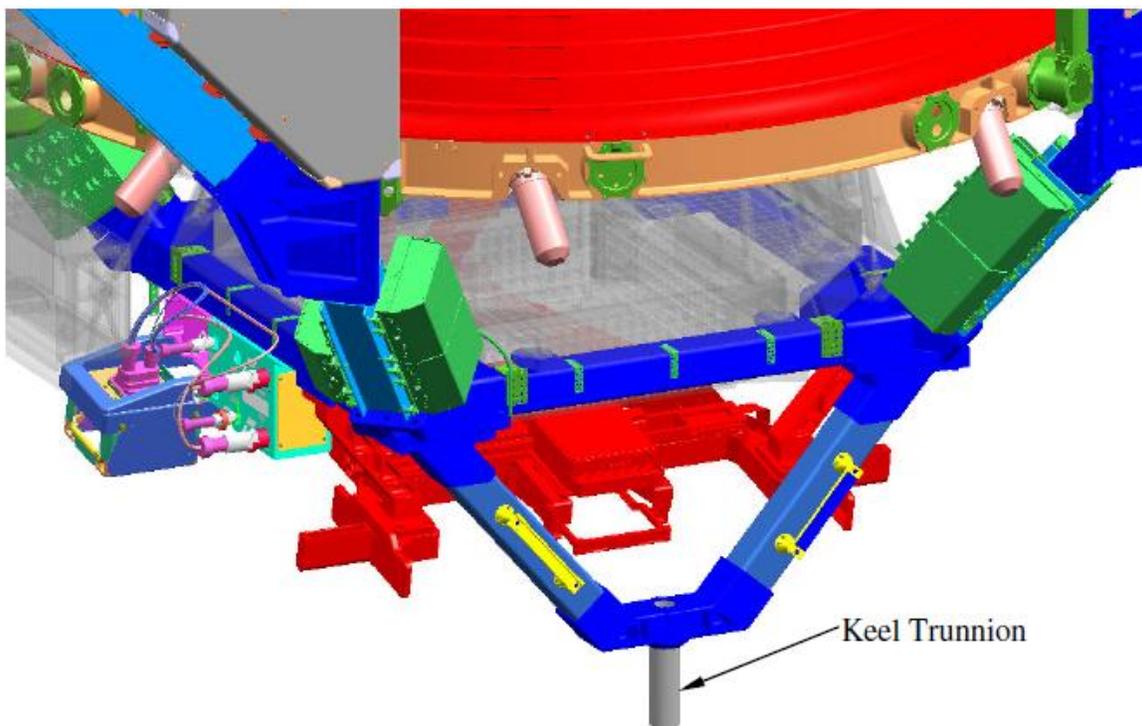


Figure 5.2-8 AMS-02 Shuttle Interfaces – Keel Trunnion

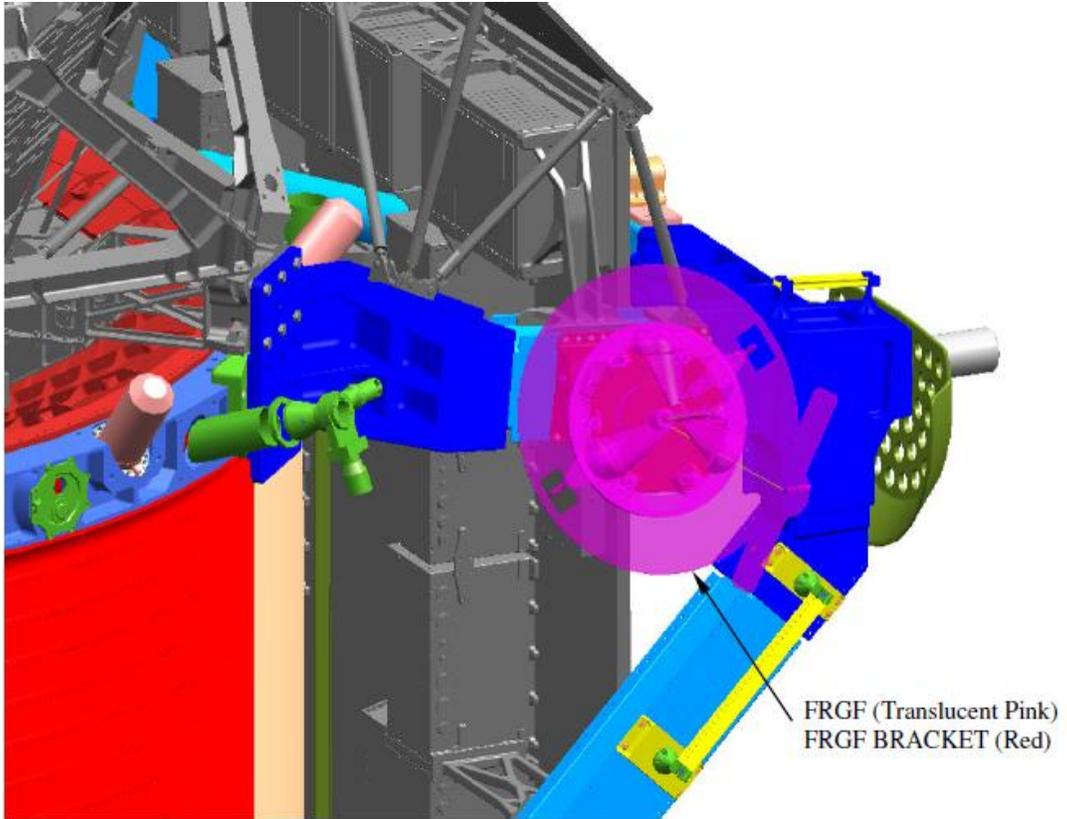


Figure 5.2-9 AMS-02 Shuttle Interfaces – FRGF

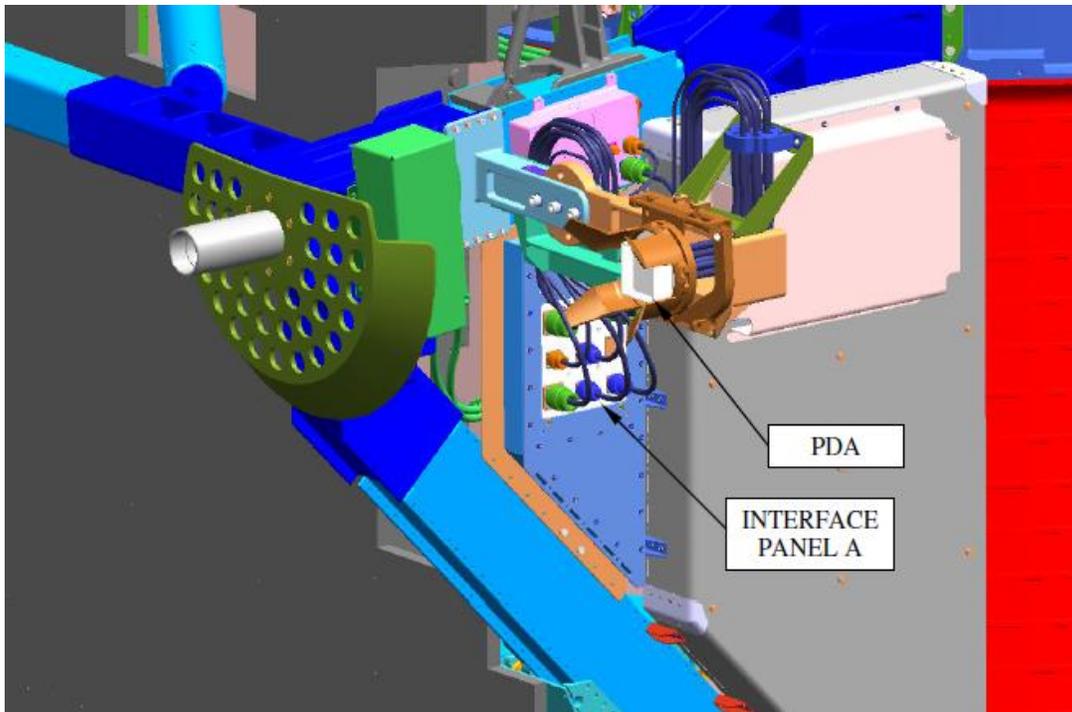


Figure 5.2-10 AMS-02 Shuttle Interfaces – PDA

The ISS interfaces include the AMS-02 Payload Attach System (PAS), UMA, and the PVGF. The AMS-02 PAS interfaces with the ISS at the three Guide Pins, the Capture Bar, and the ISS provided passive Umbilical Mechanism Assembly (UMA) per the ISS Attached Payload ICD (SSP 57003). The PAS has a mechanism to allow for an EVA crewmember to unload and release the capture bar so that the Payload can be removed from ISS in the event of a failure. Details of the AMS-02 PAS are covered in Section 5.3 of this SDP. The UMA is the power and data interface to ISS. It is GFE that is bolted to the Payload per SSP57003. The Power Video Grapple Fixture is the SSRMS interface used to berth the payload to ISS. It is bolted to the payload via a custom designed, machined 6061-T651 aluminum alloy bracket. The PVGF has the capability to provide power, video and data interfaces via the ISS SSRMS; however, the AMS-02 payload will only utilize the video (for EBCS operations) and power interfaces.

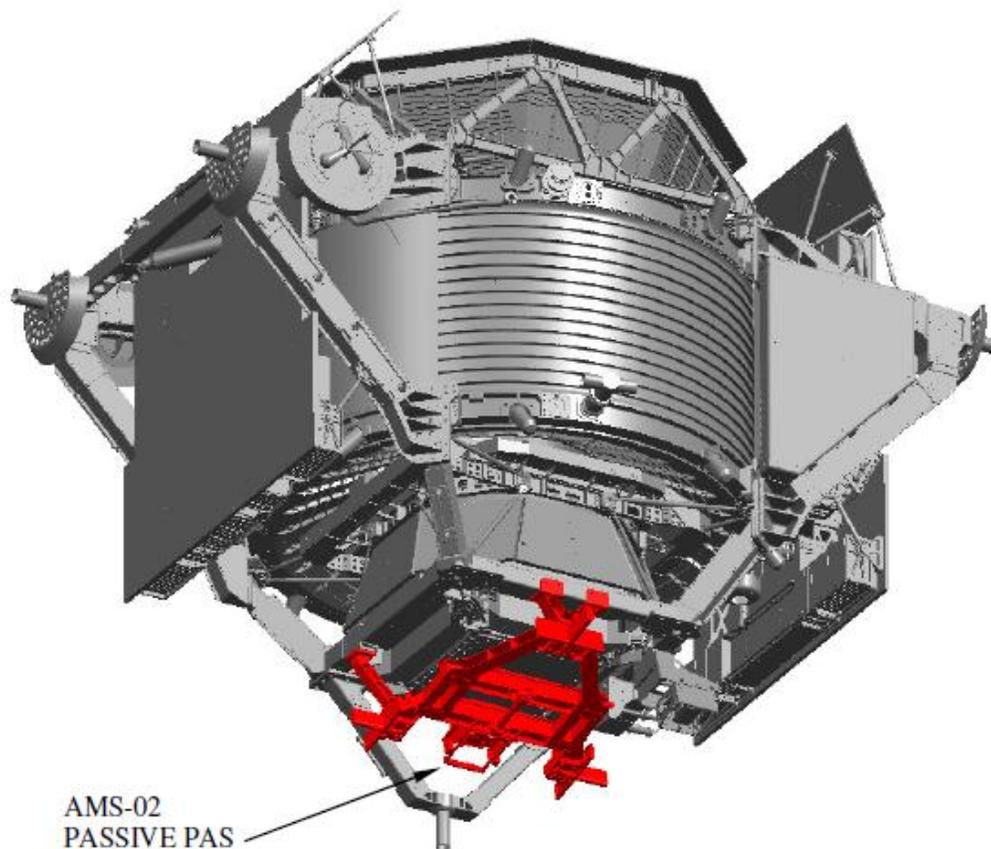


Figure 5.2-11 ISS Interfaces – Passive PAS

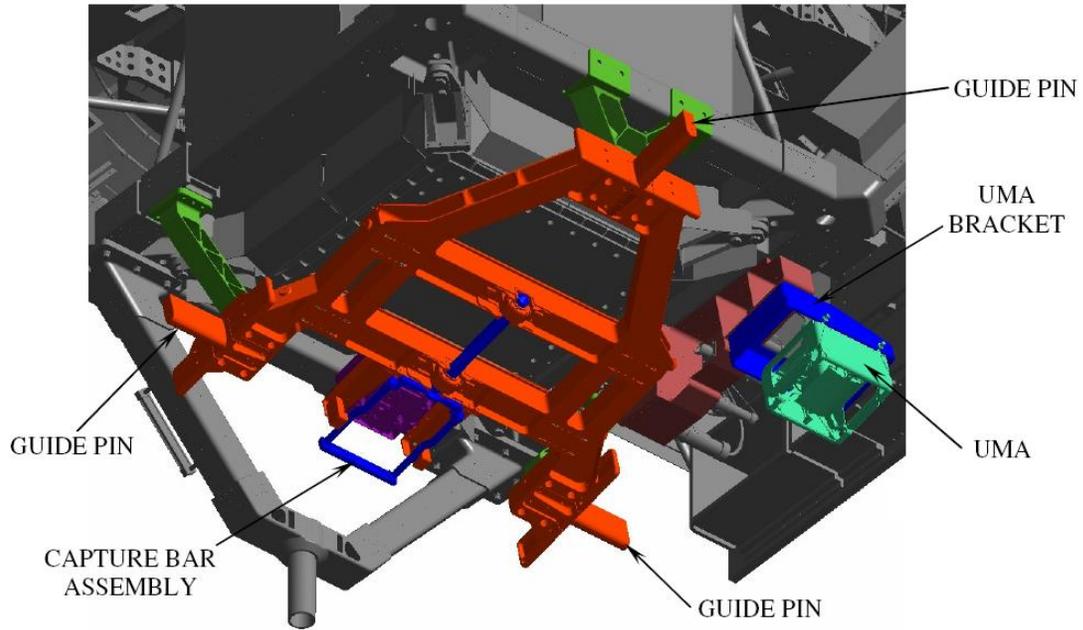


Figure 5.2-12 ISS Interfaces – Passive PAS

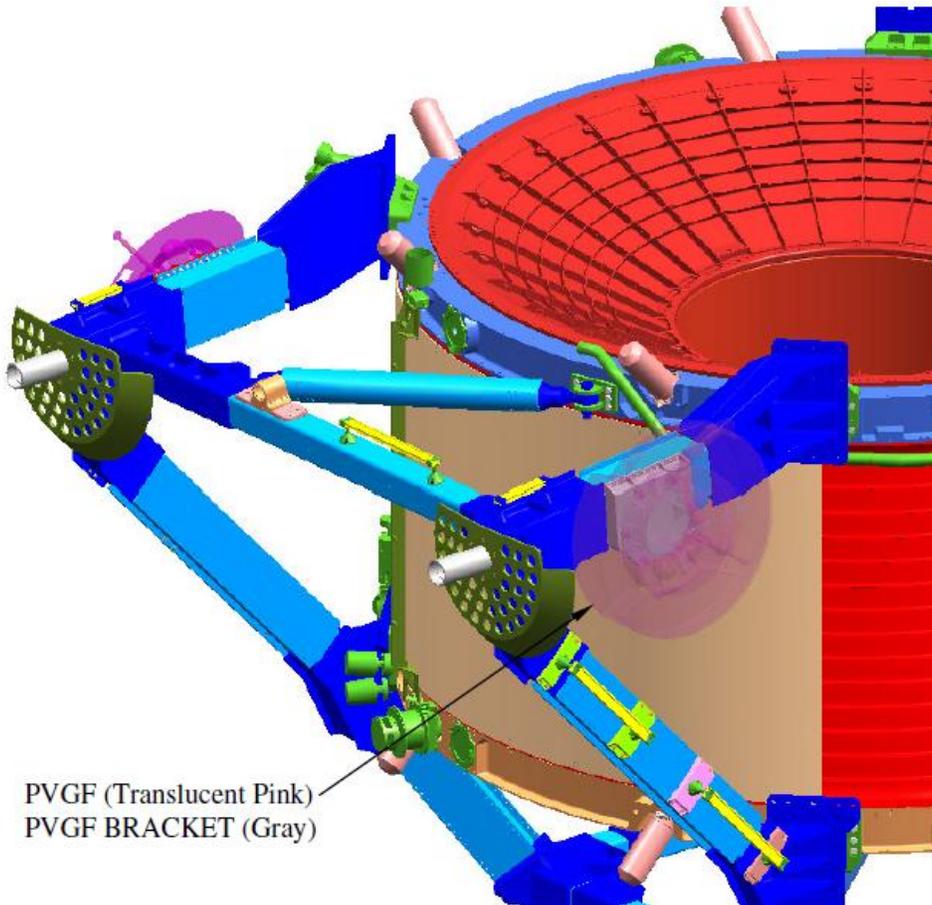


Figure 5.2-13 ISS Interfaces – PVGF

EVA interfaces include nine handrails, one WIF interface, two sets of grapple release bolts on the PVGF and FRGF, two PAS unload bolts, and one Capture Bar Release Handle. All but three of the handrails are mounted to the USS-02 generic hole pattern via aluminum alloy 6061-T651 adapter brackets. The other three handrails are bolted to the aluminum alloy 7075-T73511 square tube extrusions. The WIF is mounted to an aluminum alloy 6061-T651 adapter bracket that is mounted to a square tube extrusion. The PAS unload bolts and the Capture Bar Release Handle are discussed in Section 5.3.2.

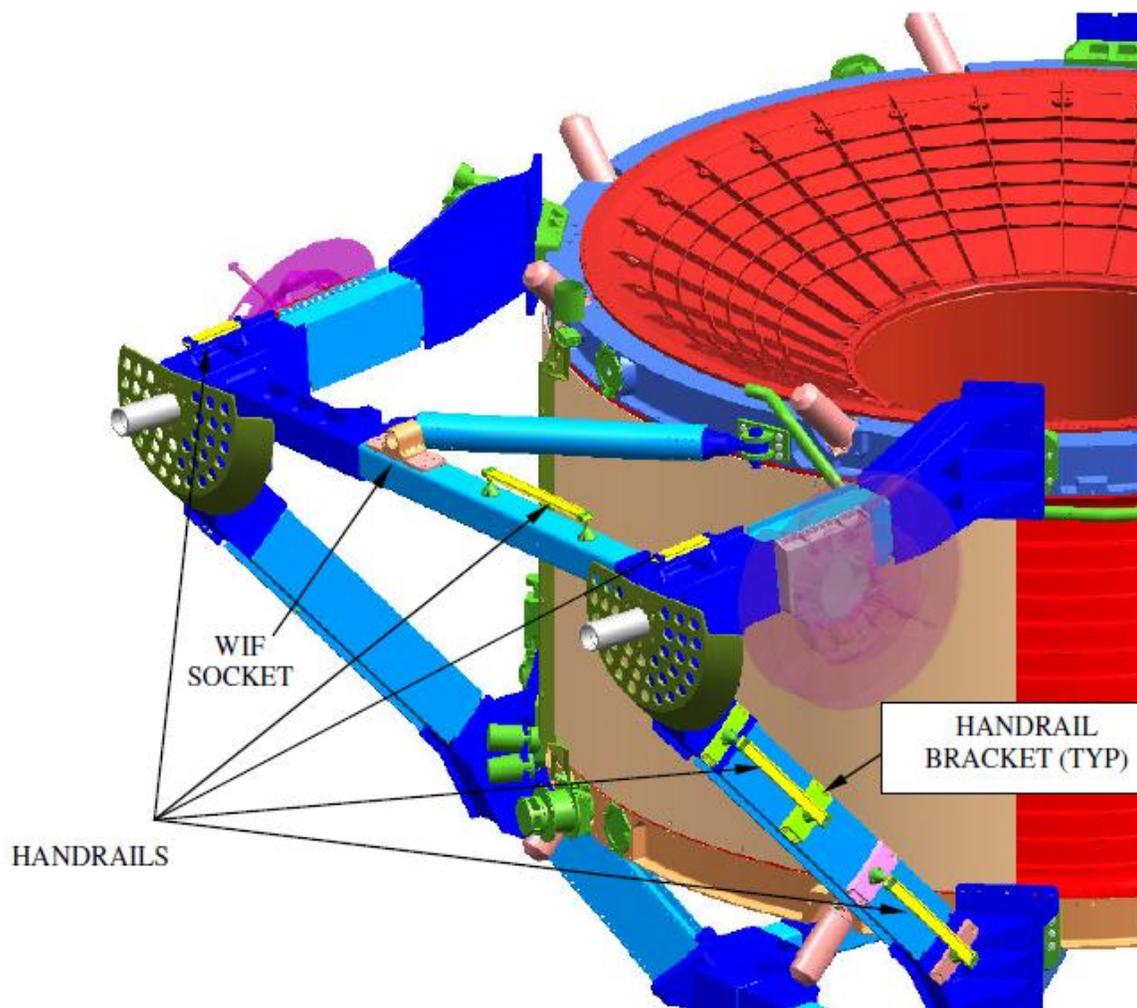


Figure 5.2-14 EVA Interfaces – WIF Socket and Handrails

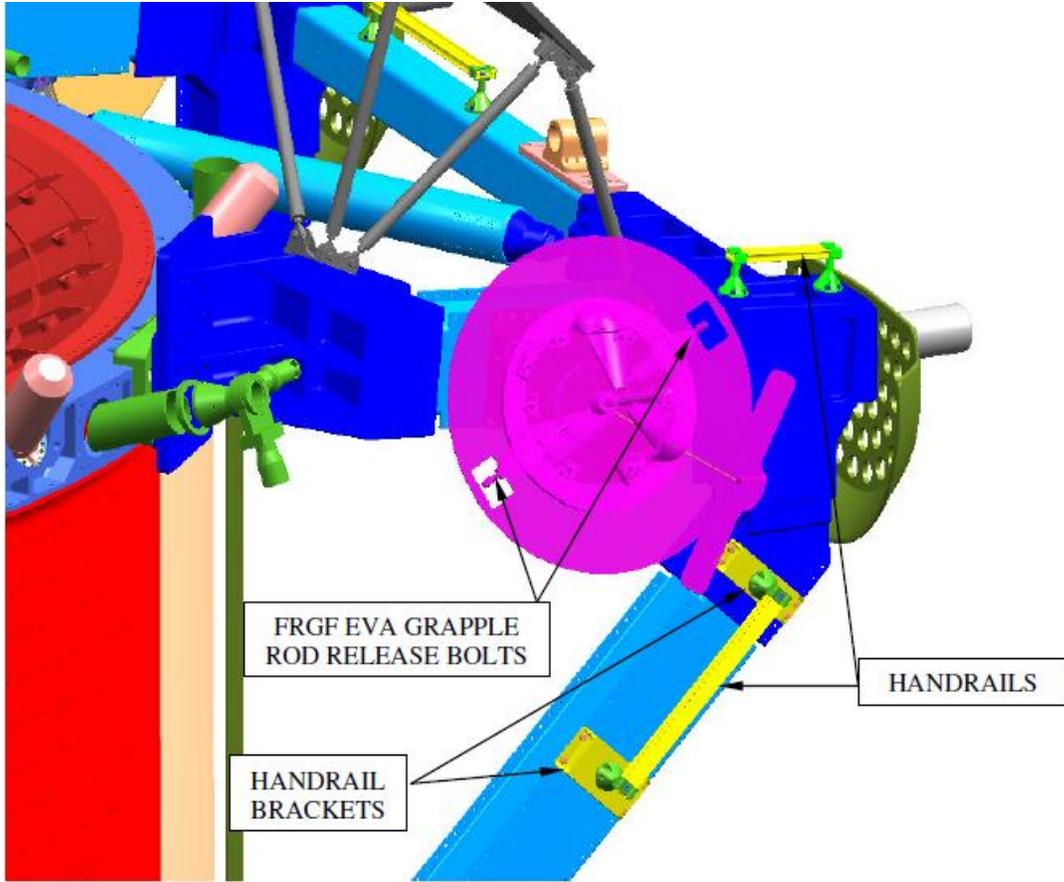


Figure 5.2-15 EVA Interfaces – Handrails and FRGF Release Bolts

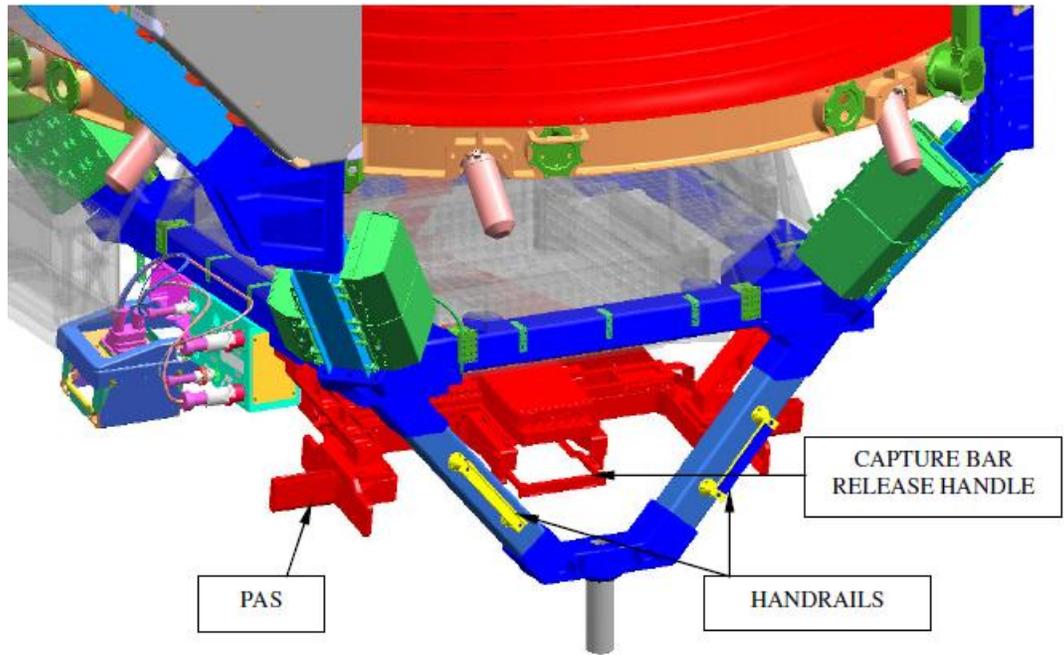


Figure 5.2-16 EVA Interfaces – Handrails and PAS Capture Bar Handle

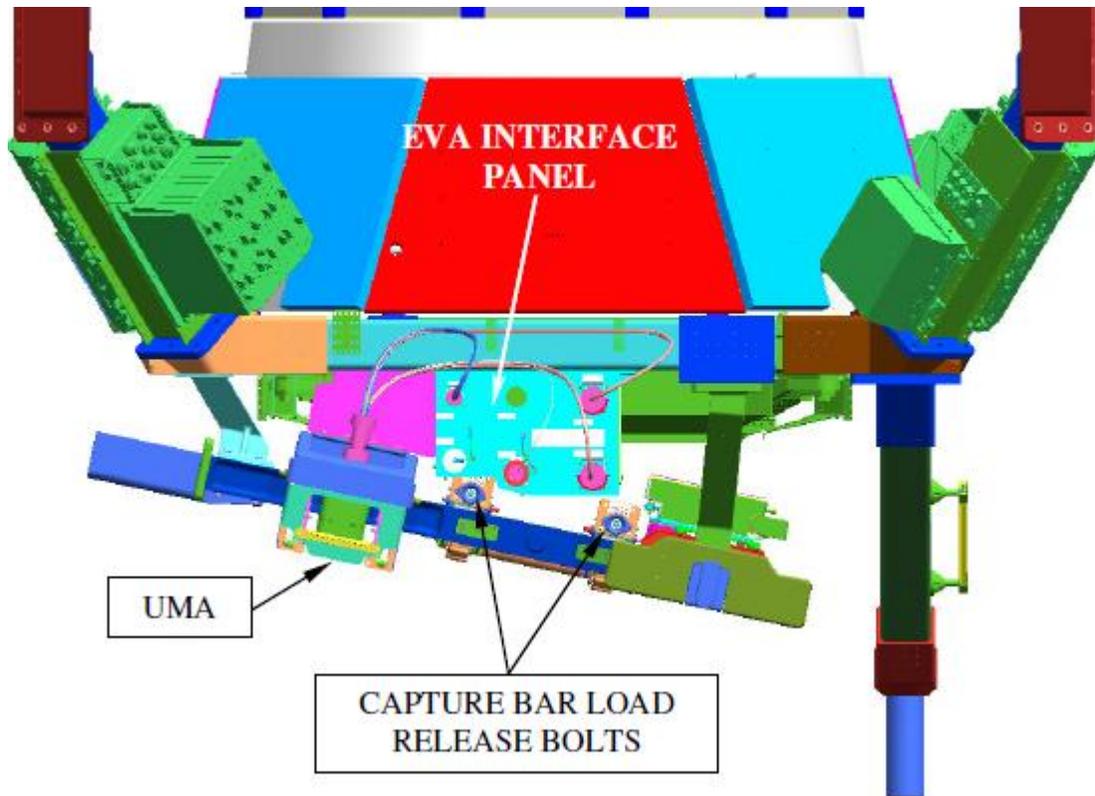


Figure 5.2-17 EVA Interfaces – PAS Capture Bar Handle

A single USS-02 will be built to completion and a number of significant subassemblies of a second USS-02 are available. The Lower USS-02 also has a single unit built to completion for flight and testing purposes with significant assemblies available..

The USS-02 underwent structural testing. Structural testing was performed per JSC 28792, AMS-02 Structural Verification Plan (SVP). This testing included a full static test to 1.1 x limit load and a modal test.

5.3 PASSIVE PAYLOAD ATTACH SYSTEM (PAS)

The AMS-02 Payload interfaces with the ISS S3 truss via the Payload Attach System (PAS) (Figure 5.3-1). The PAS is comprised of two halves, the active and passive halves. The active half is an integral part of the truss. The passive PAS is an integral part of the Payload (Figures 5.3-2 & 5.3-3). The AMS-02 PAS Assembly was developed by the AMS-02 Project specifically for the AMS-02 Payload per SSP57003.

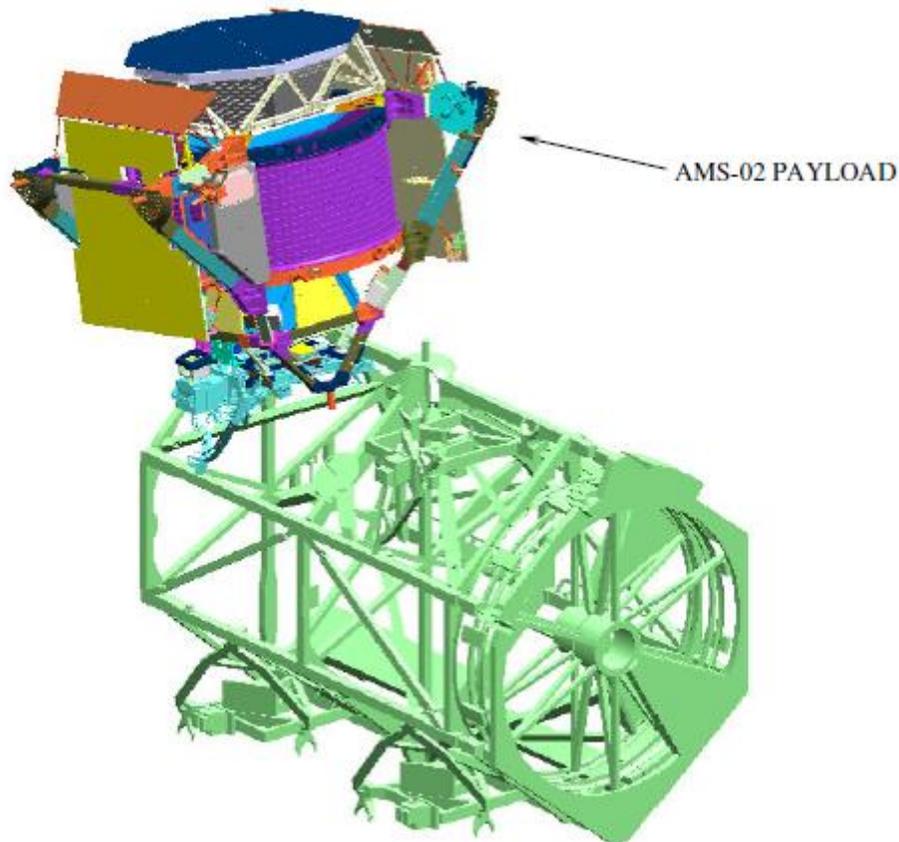


Figure 5.3-1 The AMS-02 Payload on the ISS Starboard 3 (S3) Truss

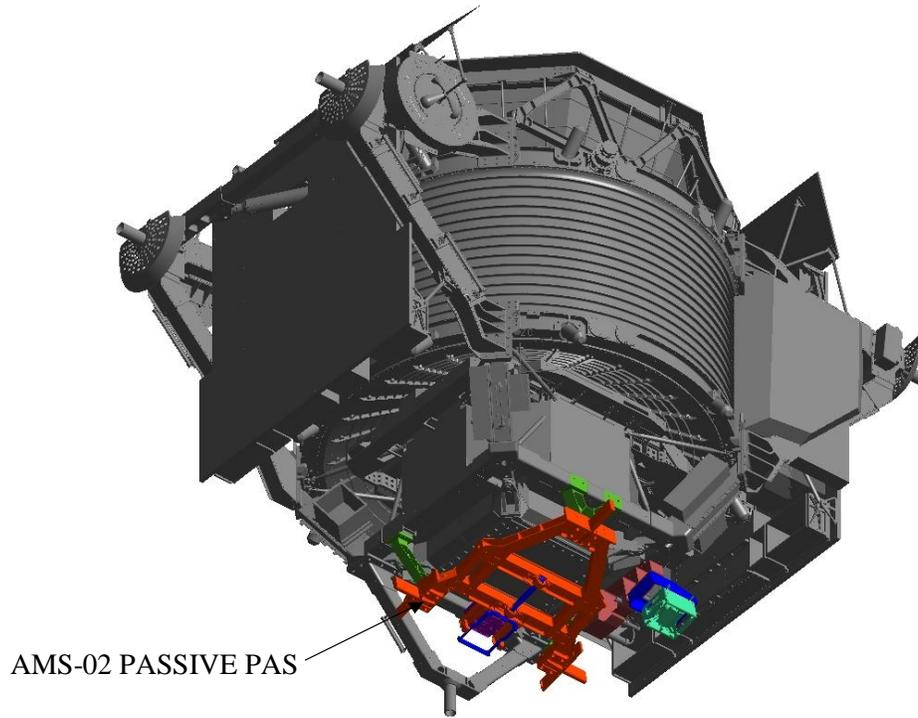


Figure 5.3-2 The Passive PAS on the bottom of the AMS-02 Payload (1 of 2)

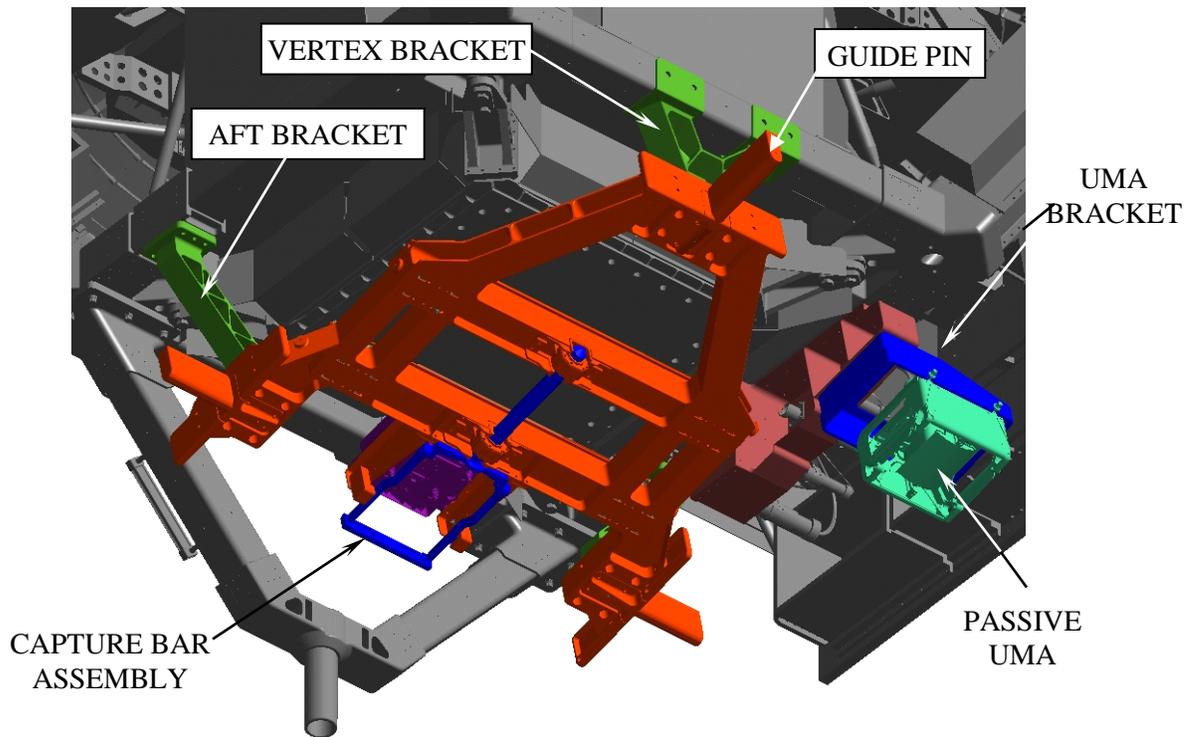


Figure 5.3-3 The Passive PAS on the bottom of the AMS-02 Payload (2 of 2)

The PAS (active and passive) consists of three basic pairs of components that interact to mate the payload to the ISS (Figures 5.3-4 thru 5.3-6): the active half Capture Claw and passive half Capture Bar, the three active half Guide Vanes and the passive half Guide Pins, and the active Umbilical Mechanism Assembly (UMA) and the passive UMA. The Capture Claw, Capture Bar, Guide Vanes, and Guide Pins provide the structural attachment for the Payload to ISS and the active and passive UMA provide power and data connection from ISS to the Payload.

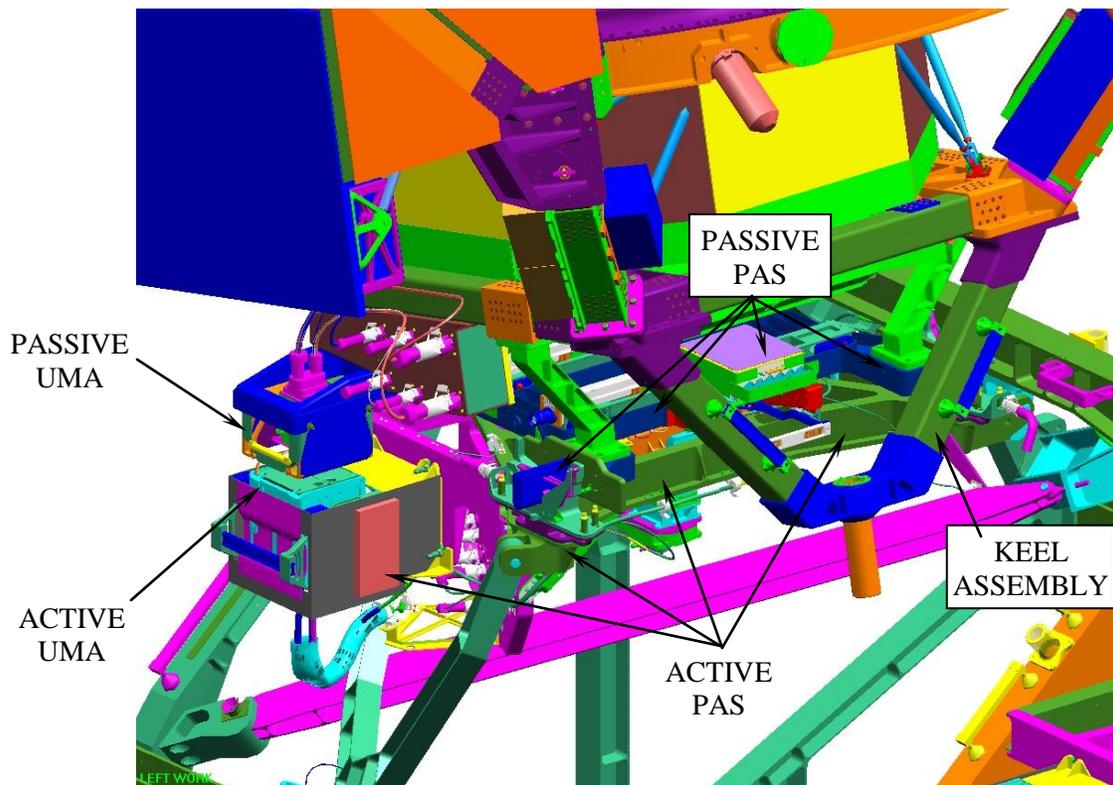


Figure 5.3-4 The AMS-02 Passive PAS attached to the ITS3 Active PAS (1 of 3)

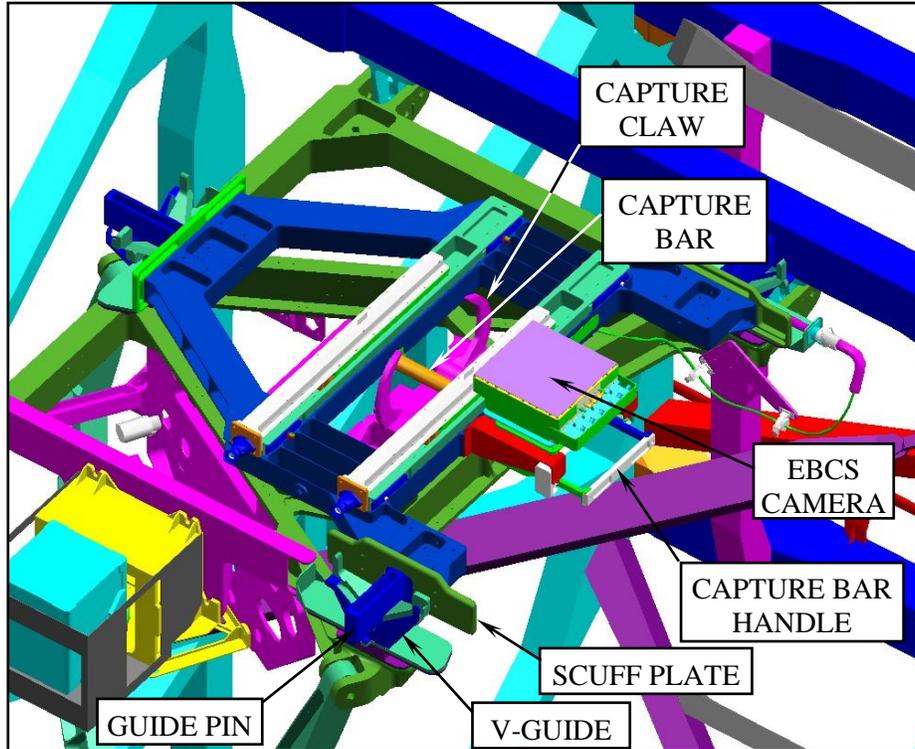


Figure 5.3-5 AMS-02 Passive PAS attached to the ITS3 Active PAS (2 of 3)

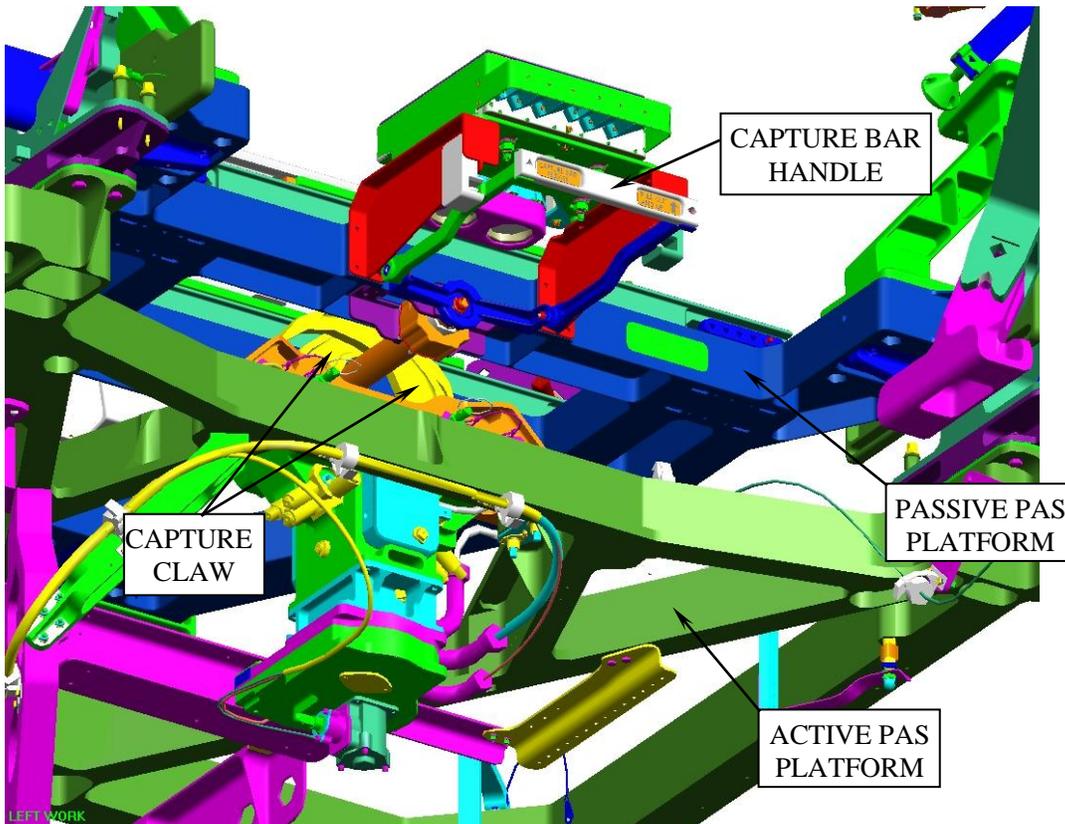


Figure 5.3-6 AMS-02 Passive PAS attached to the ITS3 Active PAS (3 of 3)

The Capture Claw latches onto and pulls down on the Capture Bar. This induces a load in the system that is reacted via the Guide Vane / Guide Pin interface. When the Capture Claw is fully closed, it is required to impart a 6430 lb maximum and a 4900 lb minimum load into the system thus clamping the two halves together. This load holds the payload to the ISS. Once the Payload is structurally mounted to ISS the active UMA is driven into the passive UMA. The passive UMA is GFE from ISS. The Payload only provides structural mounting and power and data connectors to the passive UMA.

5.3.1 EVA Releasable Capture Bar

Per SSP 57003, the AMS-02 PAS incorporates a mechanism to unload the capture bar and release the Payload from the ISS (Figure 5.3.1-1). To unload and release the AMS-02 Payload from ISS, an EVA crewmember first unloads the capture bar, by driving two EVA bolts using the Pistol Grip Tool (PGT). Turning the bolts a defined number of turns and alternating between the two lowers the Capture Bar and relieves any load in the system. The crewmember then retracts the capture bar by reaching thru the AMS-02 Keel structure, grasping the Capture Bar Assembly handle, and pulling the capture bar out towards the keel and up towards the Payload. Once the capture bar is retracted, the Payload is free from the PAS and the ISS.

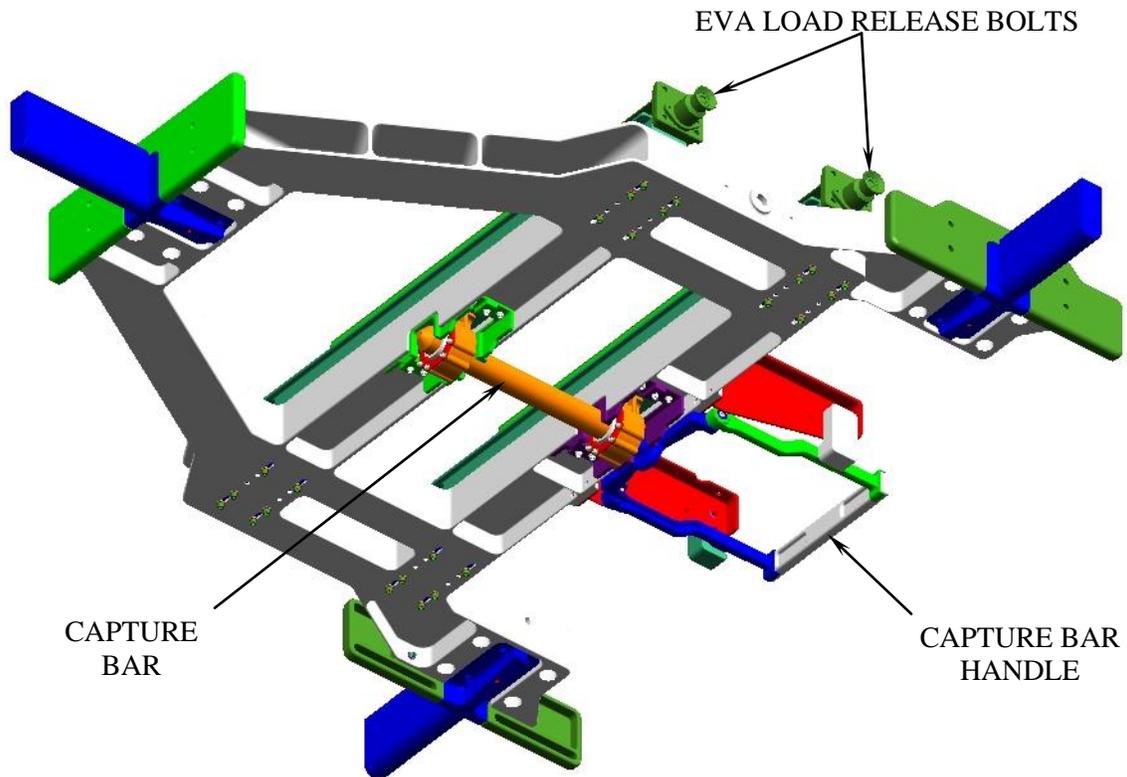


Figure 5.3.1-1 PAS EVA Releasable Capture Bar

The AMS-02 PAS Assembly is bolted to the Lower USS-02 via four brackets, the Vertex Bracket, two Aft Brackets and the UMA Bracket. The AMS-02 PAS Assembly (Figure 5.3.1-2) consists of five bolted subassemblies, the PAS Base Assembly, EVA Extension Assembly, PAS Bridge Assembly, Capture Bar Assembly, and EBCS Avionics Assembly. All bolts used in the AMS-02 PAS Assembly are certified by the NASA/JSC Fastener Integrity Program and utilize locking nut or inserts or self-locking bolts as a secondary method of back-out prevention.

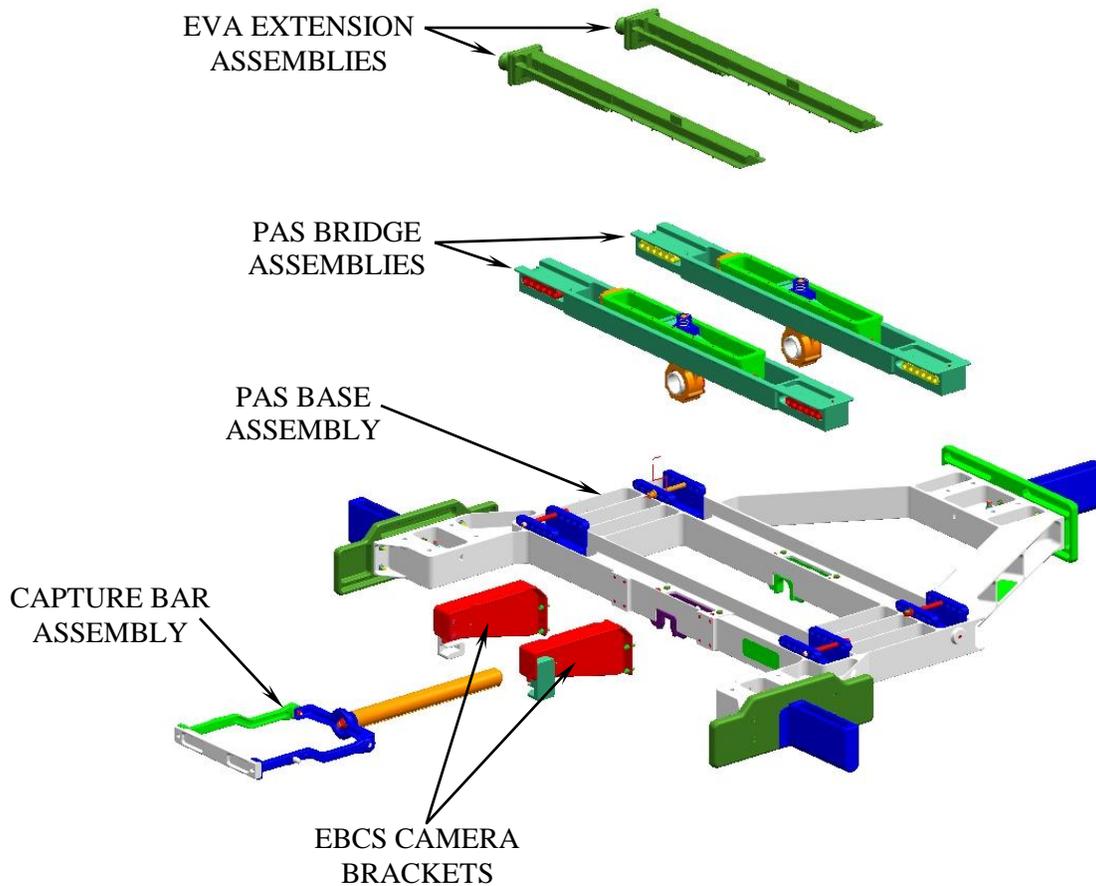


Figure 5.3.1-2 AMS-02 PAS Component Detailed Description

The PAS Base Assembly is the overall structural member of the PAS Assembly. All other subassemblies are supported by it. The PAS Bridge Assembly supports the Capture Bar Assembly and houses the Capture Bar Release Mechanism. The EVA Extension Assembly provides a standard 7/16" EVA socket interface, a locking feature to prevent back out of the Capture Bar Release Mechanism and a cover for the PAS Bridge Assembly. The EBCS Avionics Assembly locates and supports the EBCS Camera and provides brackets to retain Capture Bar Handle.

The PAS Base Assembly is composed of the PAS Platform, Guide Pins, Scuff Plates, and Capture Bar Retainer Brackets as show in Figure 5.3.1-3. The PAS Platform is a single piece of machined 7050-T7451 aluminum plate. It is the structural element that ties all the PAS components to the brackets that attach it to the Lower USS-02 and the rest of the

Payload. The aluminum Guide Pins, Scuff Plates, and stainless steel Capture Bar Retainer Brackets are all bolted to the PAS Platform.

PAS BASE ASSEMBLY COMPONENTS

- PAS PLATFORM
- GUIDE PINS
- SCUFF PLATES
- CAPTURE BAR RETAINER BRACKETS

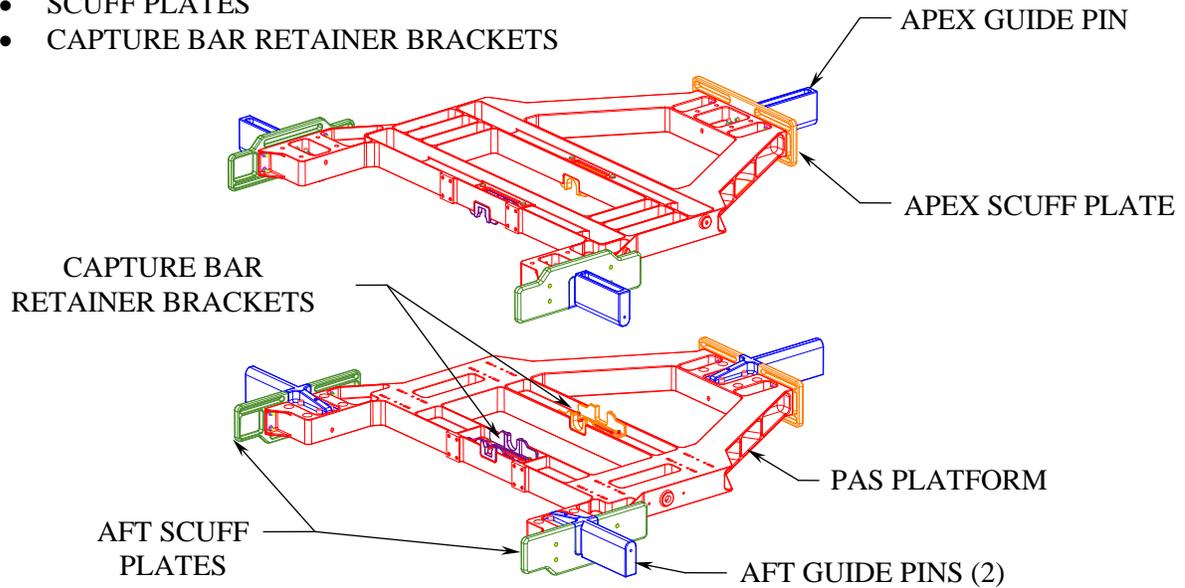


Figure 5.3.1-3 PAS Base Assembly

The EVA Extension Assembly is composed of the EVA Screw Extension, Screw Locking Housing, Lock Retractor, Compression Spring, and Release Mechanism Cover. The EVA Screw Extension, Compression Spring, Locking Retractor and Locking Mechanism Base are all made from A286 stainless steel. The Release Mechanism Cover is made from 7075 aluminum alloy. The EVA Extension (Figure 5.3.1-4) has an internal hex on one end and an external EVA tool compatible hex on the other end. Just below the external hex is a flange that prevents the extension from passing thru the Release Mechanism Cover. The Compression Spring and Locking Retractor stack on top of the flange. The Locking Mechanism fits over and retains the assembly with two screw threaded into the Release Mechanism Cover.

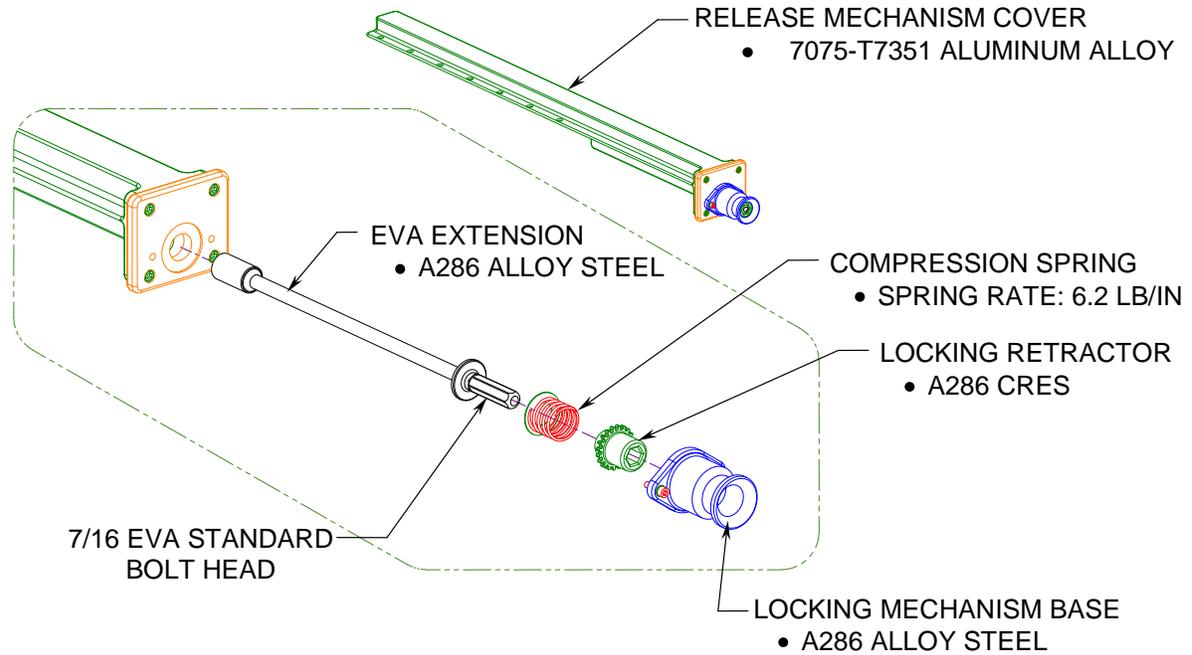


Figure 5.3.1-4 EVA Extension Assembly

The PAS Bridge Assembly (Figure 5.3.1-5) is composed of the Bridge, Load Release Mechanism and the Bearing Assembly. The Bridge is machined from one piece of 7075 aluminum alloy. The Release Mechanism Assembly is bolted onto the Bridge with four bolts. The Bearing Assembly's threaded shaft passes thru a hole in the Bridge and Release Mechanism Housing and thru a slot in the Wedge and is retained by a nut and mating wedge shaped washer. This washer is held against the Wedge by a compression spring that bears up against the EVA Extension Assembly Cover.

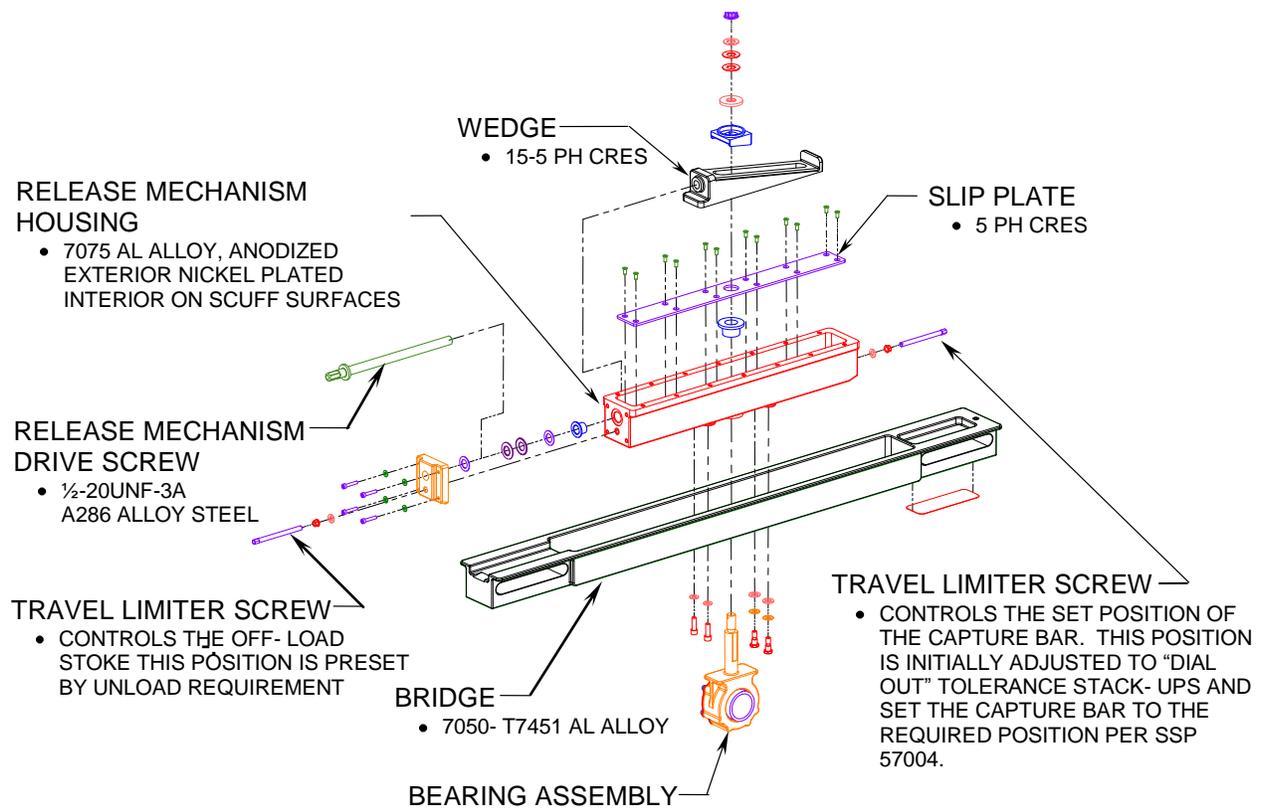


Figure 5.3.1-5 PAS Bridge Assembly and Load Release Mechanism

The Load Release Mechanism is composed of the Release Mechanism Housing, the Release Mechanism Drive Screw and Wedge, and Travel Limiter Screws. The Release Mechanism Drive Screw is made from A286 stainless steel and is sandwiched between the 7075 aluminum alloy Release Mechanism Housing and an aluminum alloy retainer bracket. Its threaded shaft passes thru the housing and threads into the Wedge. The 15-5PH stainless steel Wedge has a threaded hole on one end for the Release Mechanism Drive Screw, and a slot along its length for the Bearing Assembly rod to pass thru. The A286 stainless steel Travel Limiter Screws thread into and pass thru the Release Mechanism Housing. A nut on the inside of the Release Mechanism Housing provides as secondary locking feature for the Travel Limiter Screws. The limiter screw on the same side as the thick portion of the Wedge sets the unloaded limit of the Bearing Assembly. The opposite limiter screw sets the loaded position of the Bearing Assembly.

The Bearing Assembly is comprised of a 15-5PH stainless steel Bearing Housing, a stainless steel, PTFE lined spherical bearing and an A-286 stainless steel retainer plate. The spherical bearing is pressed into the Bearing Housing and is retained by the retainer plate. The retainer plate is secured using 5 screws threaded into the Bearing Housing.

The primary components of the Capture Bar Assembly (Figure 5.3.1-6) are the Capture Bar, Capture Bar Removal Handle and Capture Bar Handle Base, Handle Extensions and Handle Pins. The Capture Bar is a dry film lubricated A286 stainless steel bar with a closed ended slot machined down the side and a threaded boss on one end. The slot interfaces with a key in the Spherical Bearing Assembly to retain the Capture Bar with the PAS Assembly. The 6061 aluminum alloy Capture Bar Removal Handle bolted to two 6061 aluminum alloy Handle Extensions. The Handle Extensions are bolted to the 15-5PH stainless steel Handle Base with two screws and aluminum bronze bushing which allow the handle to pivot. The Capture Bar Handle Base is fixed to the Capture Bar by a nut and prevented from rotating using a boss and a hole in the bar onto a boss machined into Capture Bar. The handle base has a groove machined into it that interfaces the Capture Bar Retainer Bracket in two locations to retain the Capture Bar Assembly while in the nominal position.

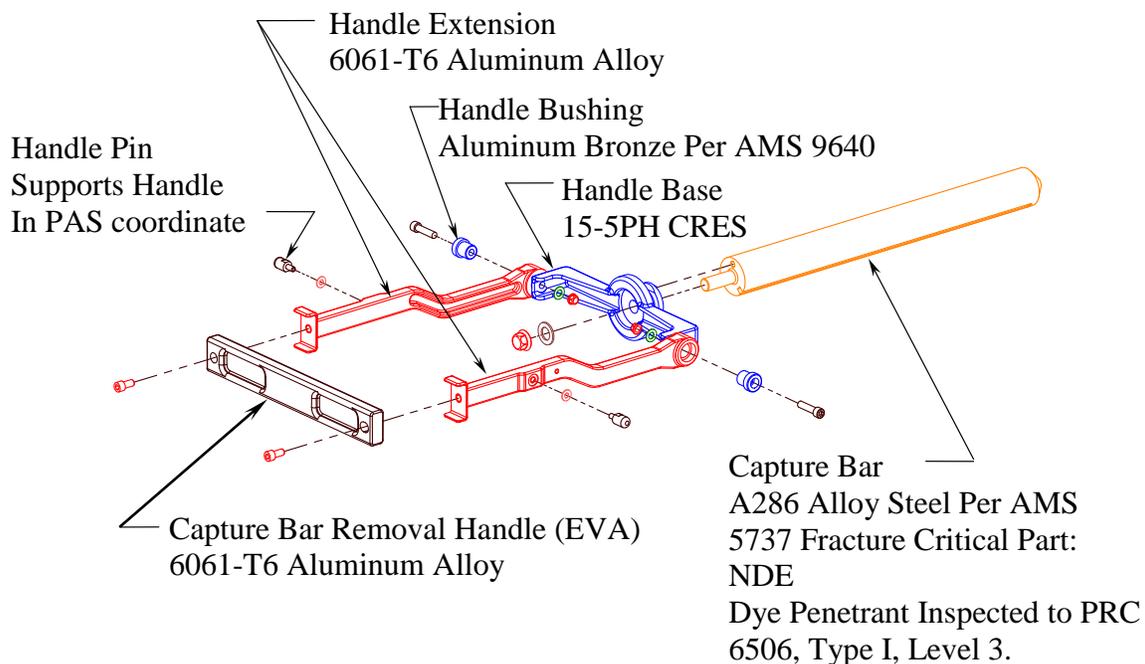


Figure 5.3.1-6 Details of the PAS Capture Bar

The EBCS Avionics Package (Figure 5.3.1-7) consists of the EBCS Camera and the EBCS Camera mounting Brackets. The 7075-T7351 aluminum alloy EBCS Camera Mounting Brackets bolt to the PAS Base Assembly with four screws per bracket. Each bracket contains another bracket to hold the Capture Bar Assembly Handle. The EBCS Avionics Package is bolted to the EBCS Camera Mounting Brackets.

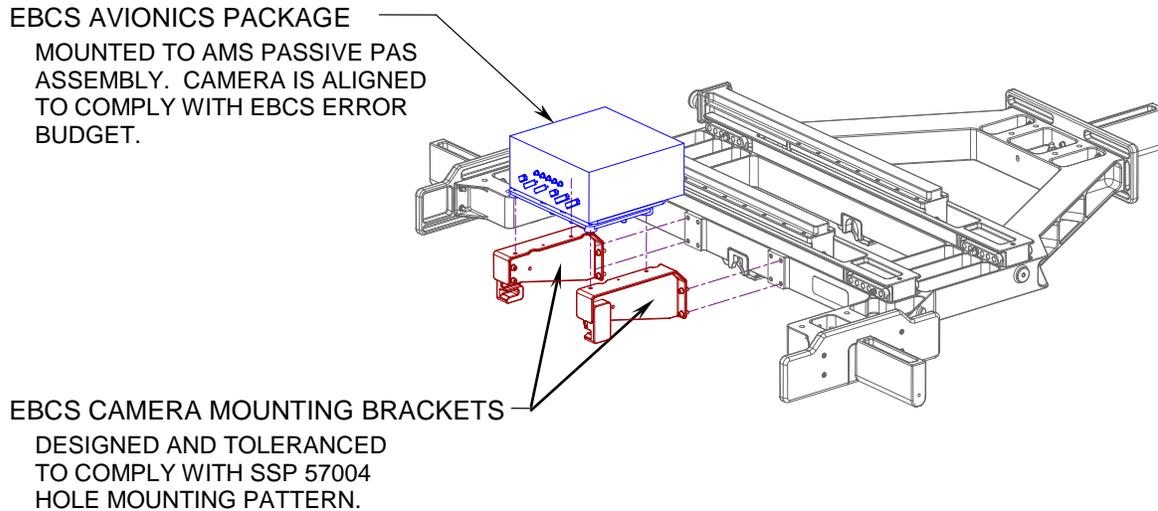


Figure 5.3.1-7 EBCS Avionics Package mounting to the PAS

5.3.2 EVA Release Mechanism

The EVA bolt head that the crewmember drives with the PGT to unload the AMS-02 PAS is machined into one end of the EVA Extension (Figure 5.3.2-1). The other end is mechanically coupled to the Release Mechanism Drive Screw that is captured by the Release Mechanism Housing and threaded into the Wedge. When the EVA Extension is turned, the Wedge translates along the axis of the drive screw as a nut would on a threaded rod. On top of the Wedge is another wedge shaped block that supports the spherical Bearing Housing that, supports the Capture Bar Assembly. When the Wedge translates, the inclined plane of the Wedge forces the Capture Bar Assembly up or allows it translate down depending on the direction of the Wedge translation. The torque required to drive the EVA unload mechanism is approximately 2.25 ft-lbs.

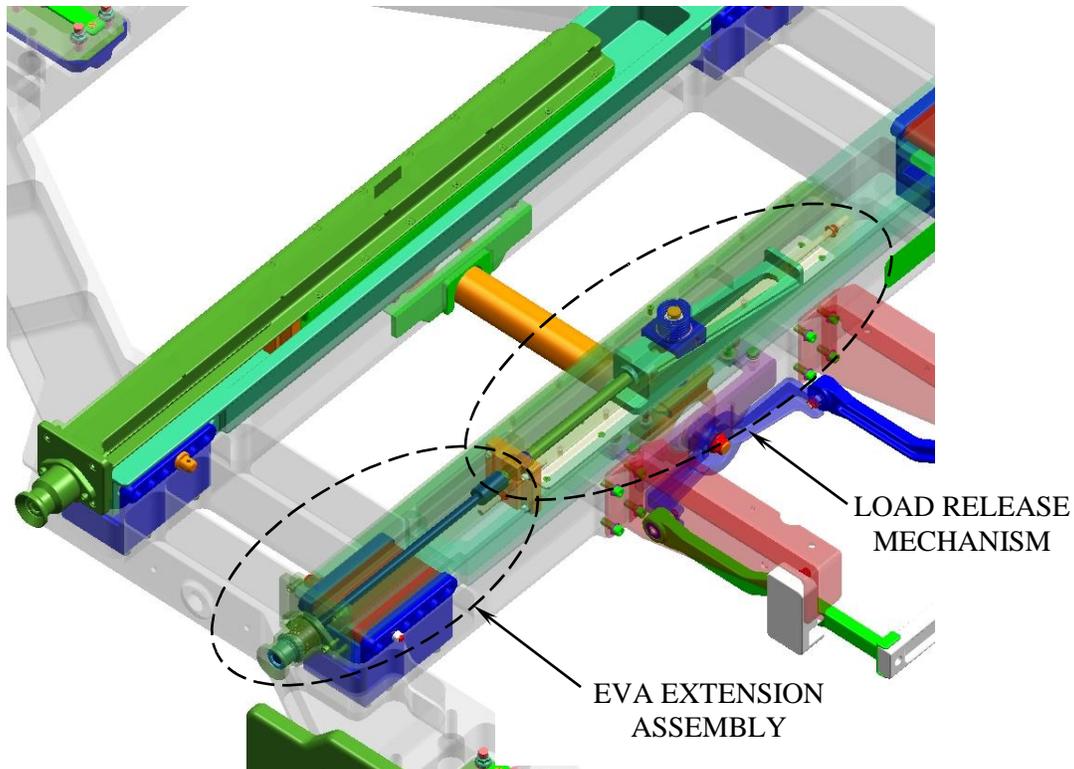


Figure 5.3.2-1 PAS Load Release Mechanism

In the nominal flight configuration, the EVA Extension is captured and prevented from turning by a locking mechanism (Figures 5.3.2-2 & 5.3.2-3) that is part of the EVA Extension Assembly. This assembly contains the Locking Retractor that has a hex shaped thru hole that fits around the hex of the EVA Extension bolt head and external teeth that mesh with teeth machined in the Locking Mechanism Base. The Locking Retractor is held up against the inside of the Locking Mechanism Base by spring force imparted by the compression spring. The Locking Mechanism Base is held in place by two screws that mount it to the EVA Extension Assembly. Locking Retractor must be pushed inward to disengage its locking teeth with the teeth in the Locking Mechanism Base. The force required to overcome the spring force of the compression spring and disengage the locking teeth is approximately 5 lbs.

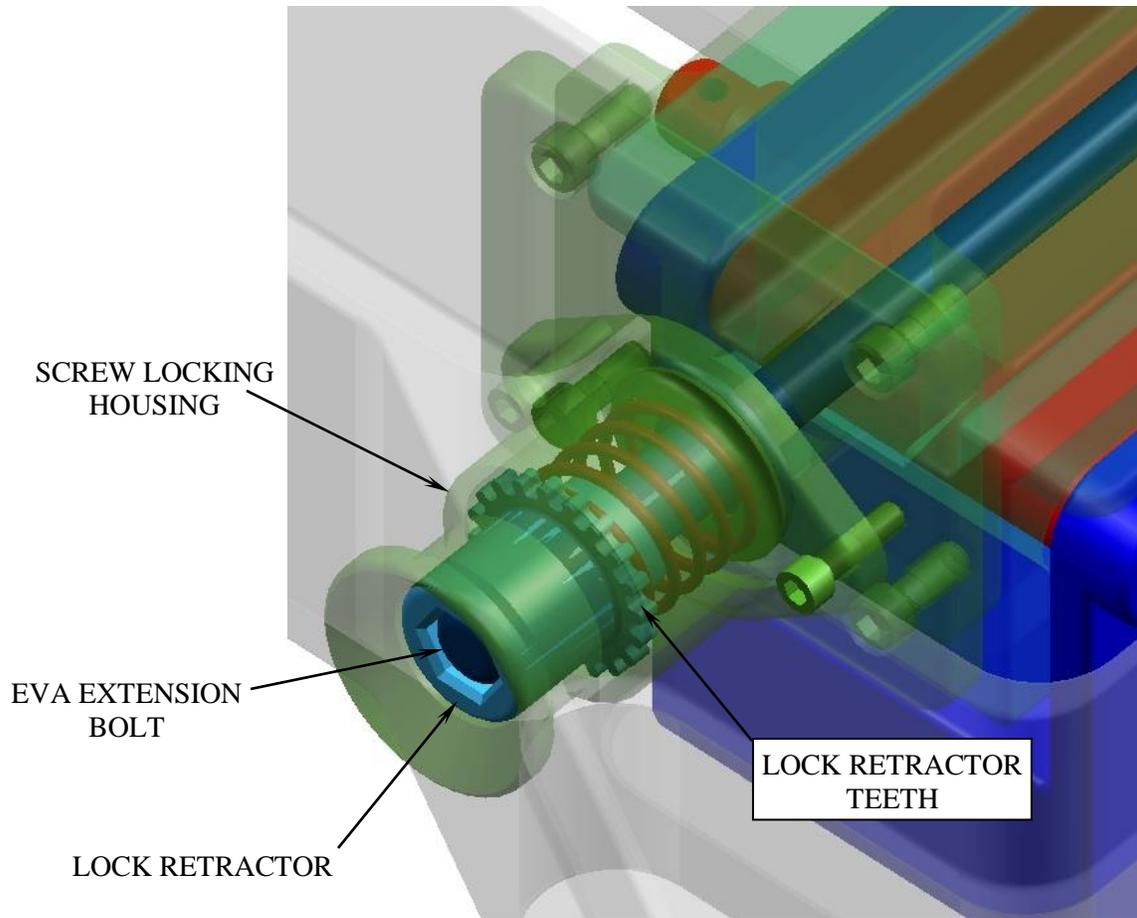


Figure 5.3.2-2 EVA Extension Locking Mechanism

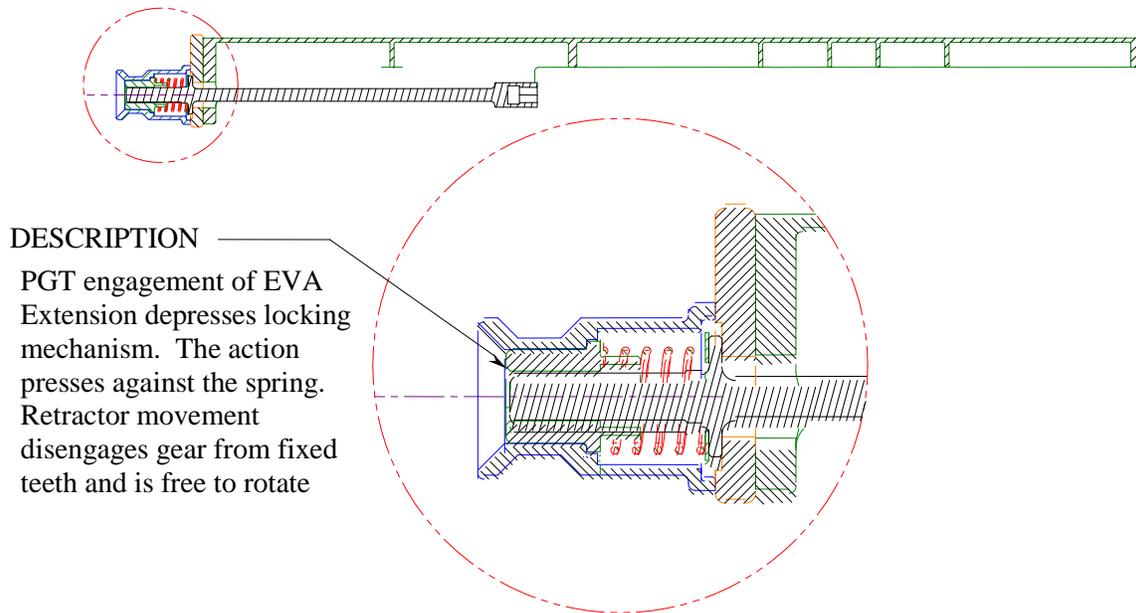


Figure 5.3.2-3 EVA Extension Locking Mechanism

Travel Limiter Screws are threaded into the Release Mechanism Housing that controls the Wedge translation limits. They provide a hard stop for the Wedge and set the height limits of the Capture Bar when the Wedge is at the ends of its stroke.

When the AMS-02 PAS is in the nominal flight configuration, the Wedge is butted up to the upper limit Travel Limiter Screw (Figure 5.3.2-4). This configuration positions the Bearing Housings closest to the PAS Base. Turning the EVA bolt interface of the EVA Extension clock-wise pulls the Wedge out from underneath the Bearing Housing wedge, allowing the Bearing Housing to drop, thus relieving the load imposed on the Capture Bar by the ISS Capture Claw. A compression spring forces the bearing housing down in case there is no load on the Capture Bar.

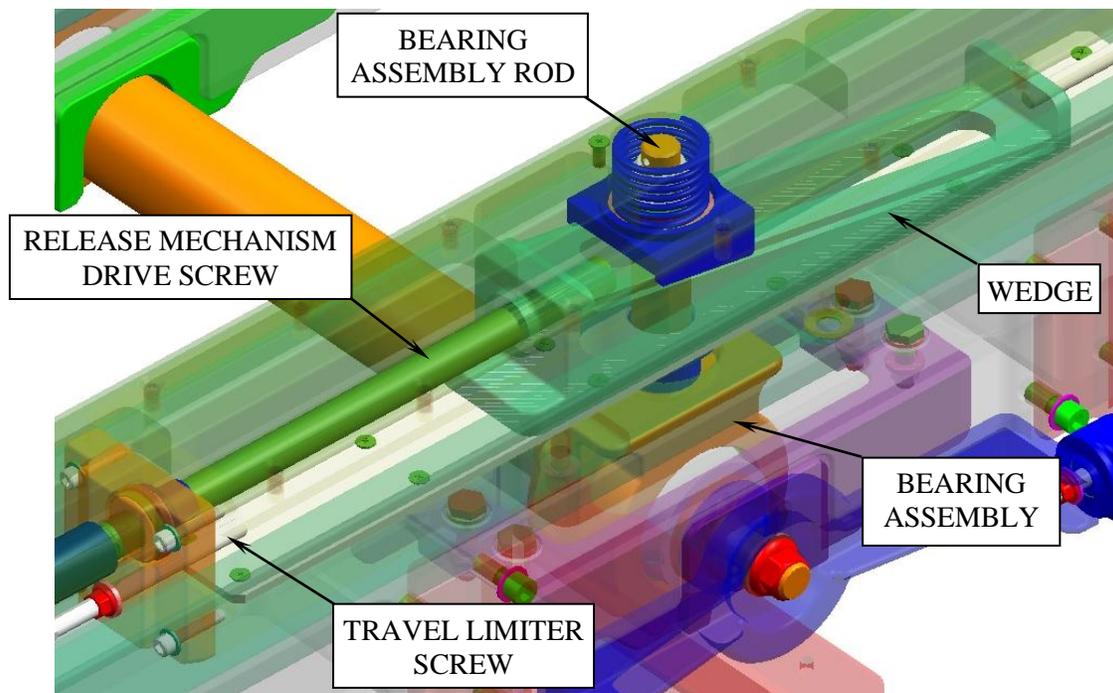


Figure 5.3.2-4 Load Release Mechanism Details

The Capture Bar Assembly (Figures 5.3.2-5 & 5.3.2-6) contains the Capture Bar and the Capture Bar Removal Handle. The Capture Bar is supported by the spherical bearings in the Bearing Assemblies and the Removal Handle is held in place by slots in EBCS Camera Brackets. In the nominal flight configuration, the Capture Bar Assembly is locked in place by mating grooves in the Capture Bar and Capture Bar Retainer Bracket. Four bolts secure the Capture Bar Retainer Bracket to the PAS Base. Once the Capture Bar is unloaded and driven fully down, where the Wedge is against the lower limit Travel Limiter Screw, it will clear the slots in the retainer brackets and it can be slid out of one of the spherical Bearing Housing by pulling the Capture Bar Removal Handle. The Capture Bar Assembly is prevented from sliding free of the PAS by means of a key that fits into a close-ended groove machined into the Capture Bar. The key is fixed to the Bearing Housing nearest to the Capture Bar Removal Handle.

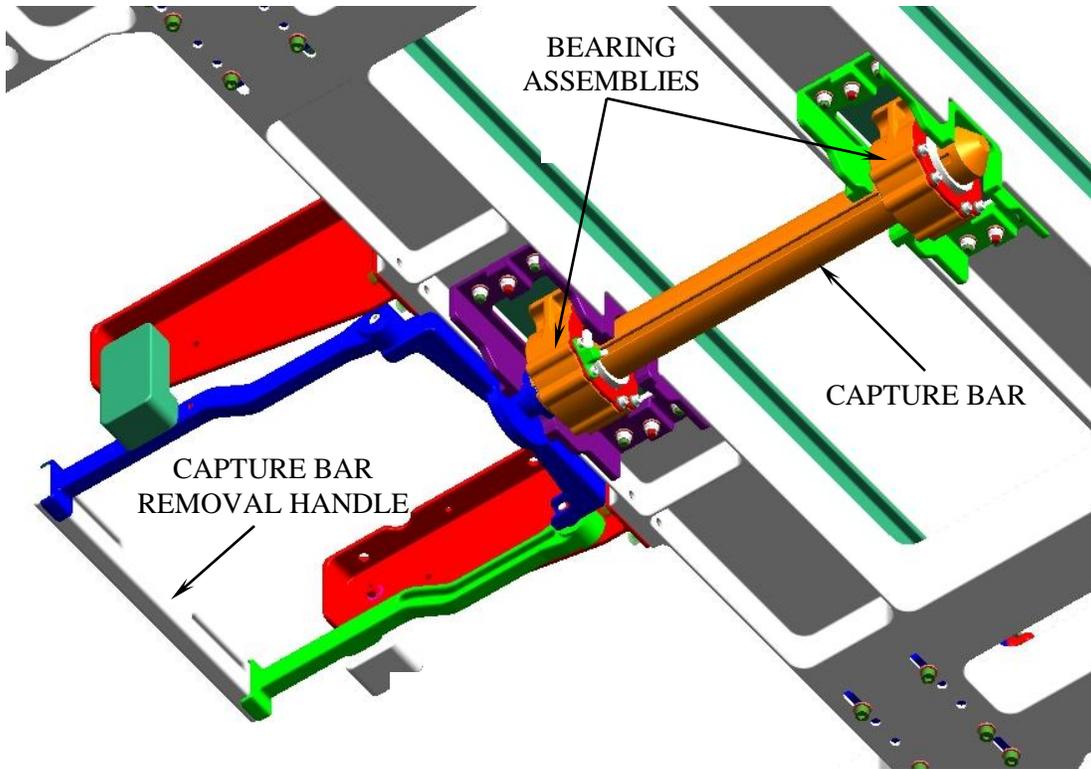


Figure 5.3.2-5 EVA Removable Capture Bar Assembly (1 of 2)

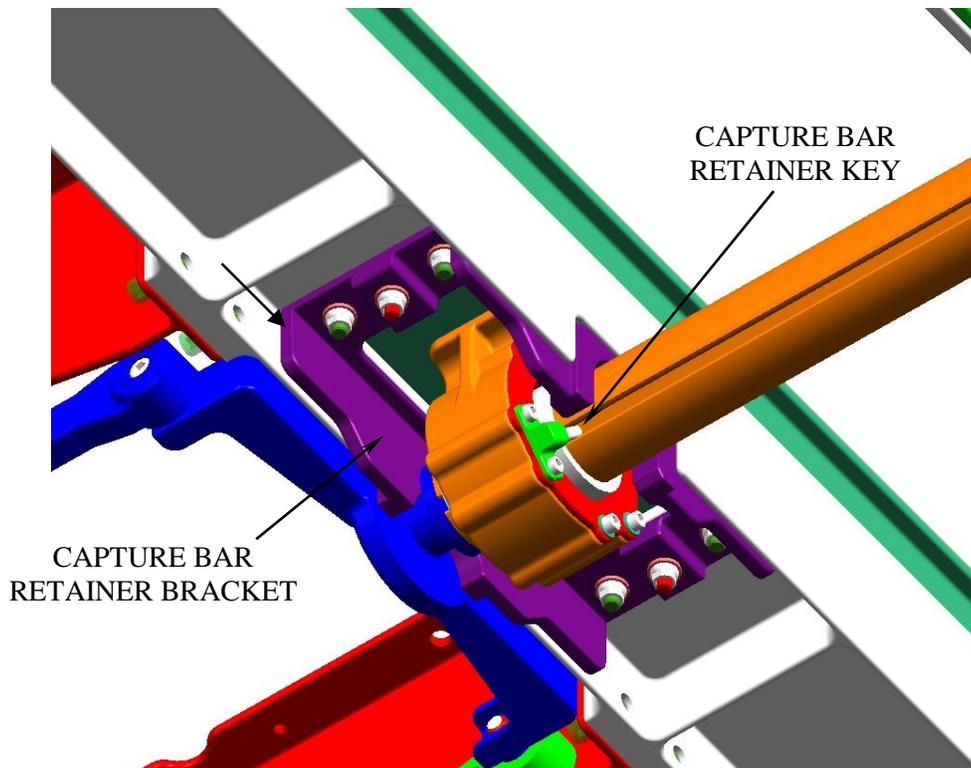


Figure 5.3.2-6 EVA Removable Capture Bar Assembly (2 of 2)

5.3.3 PAS Testing

Static and Interface Verification tests were performed on the AMS-02 PAS. Thermal extreme testing of the EVA release mechanism and vibration testing are completed on the flight hardware.

5.3.3.1 Static Test

The Static Test (Figures 5.3.3.1-1 & 5.3.3.1-2) was performed to:

- Correlate the NASTRAN model with the flight hardware
- Demonstrate the maximum preload capability
- Set the PAS stiffness as close as possible to the required stiffness per SSP 57003
- Demonstrate the ability to off-load the Capture Bar Preload using the Capture Bar Release Mechanism
- Use the adjustability of the spring system to level the Capture Bar
- Determine the final configuration of the hardware

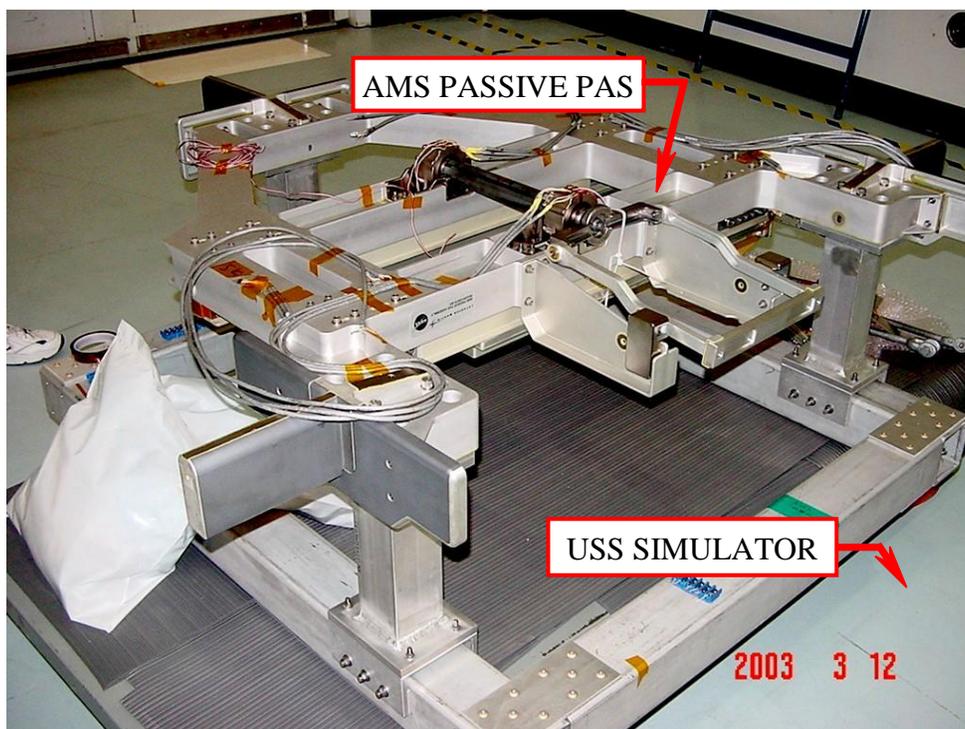


Figure 5.3.3-1 AMS Passive PAS with USS Simulator – Test Configuration

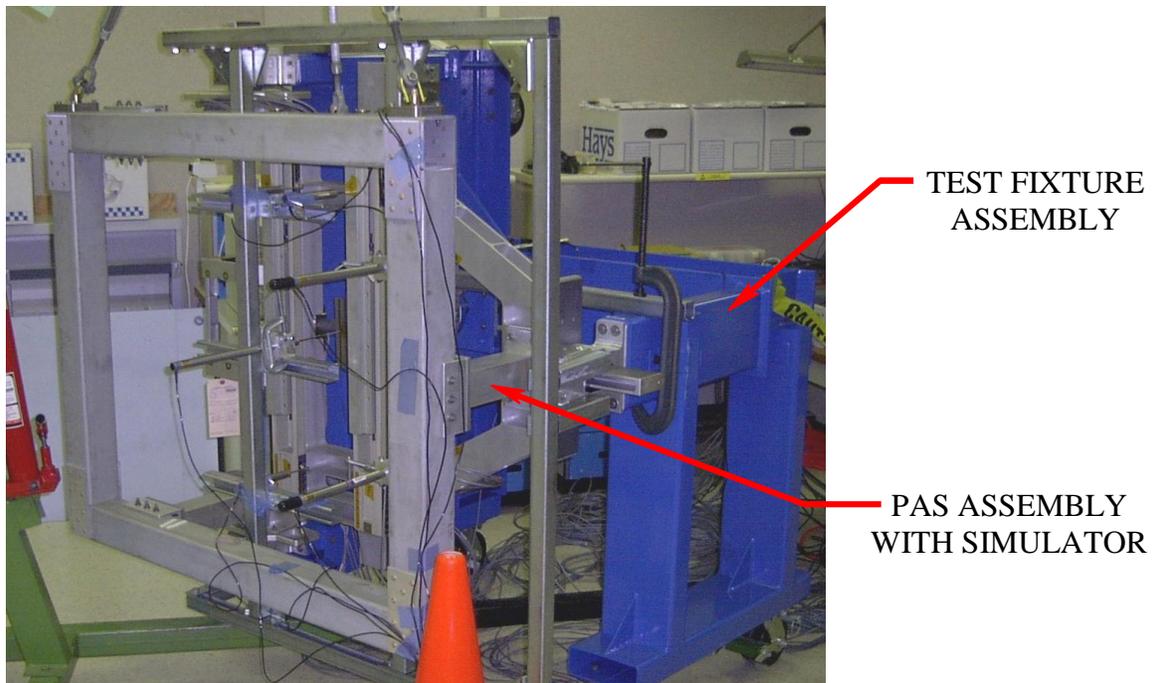
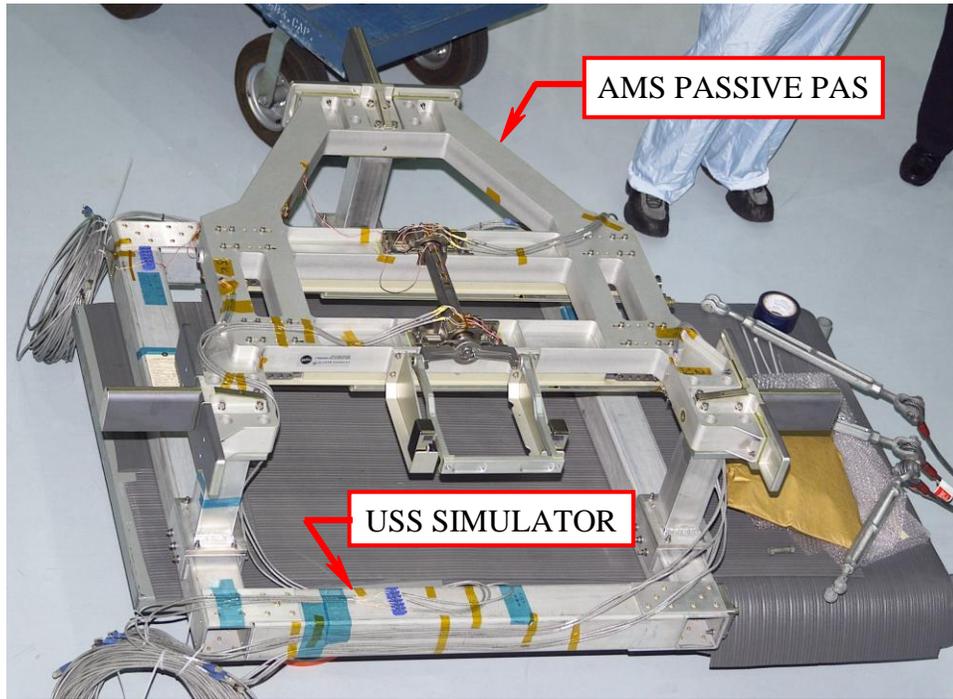


Figure 5.3.3-2 AMS Passive PAS/USS Simulator Assembly On Test Stand

5.3.3.2 Interface Verification Test

The Interface Verification Test was performed to verify the AMS-02 PAS interfaces with the actual ISS active PAS hardware (Figure 5.3.3.2-1). The AMS Passive PAS was lifted to the Upper Inboard PAS number 2 Active PAS site (Figure 5.3.3.2-2), the actual flight location for the AMS-02. The PAS 2 Capture Claw was then closed on the AMS PAS Capture Bar (Figure 5.3.3.2-3). Once the capture claws were closed, the preload at full closure was measured. The proximity of the PAS Capture Bar mounting hardware to the EBCS Target Assembly was measured at loaded condition. The AMS Passive PAS Release Mechanism was used to unload the Capture Claw Preload (Figure 5.3.3.2-4). Proximity to Target was measured in unloaded condition. The Capture Bar was removed demonstrating the required contingency capability to unload and remove the payload.

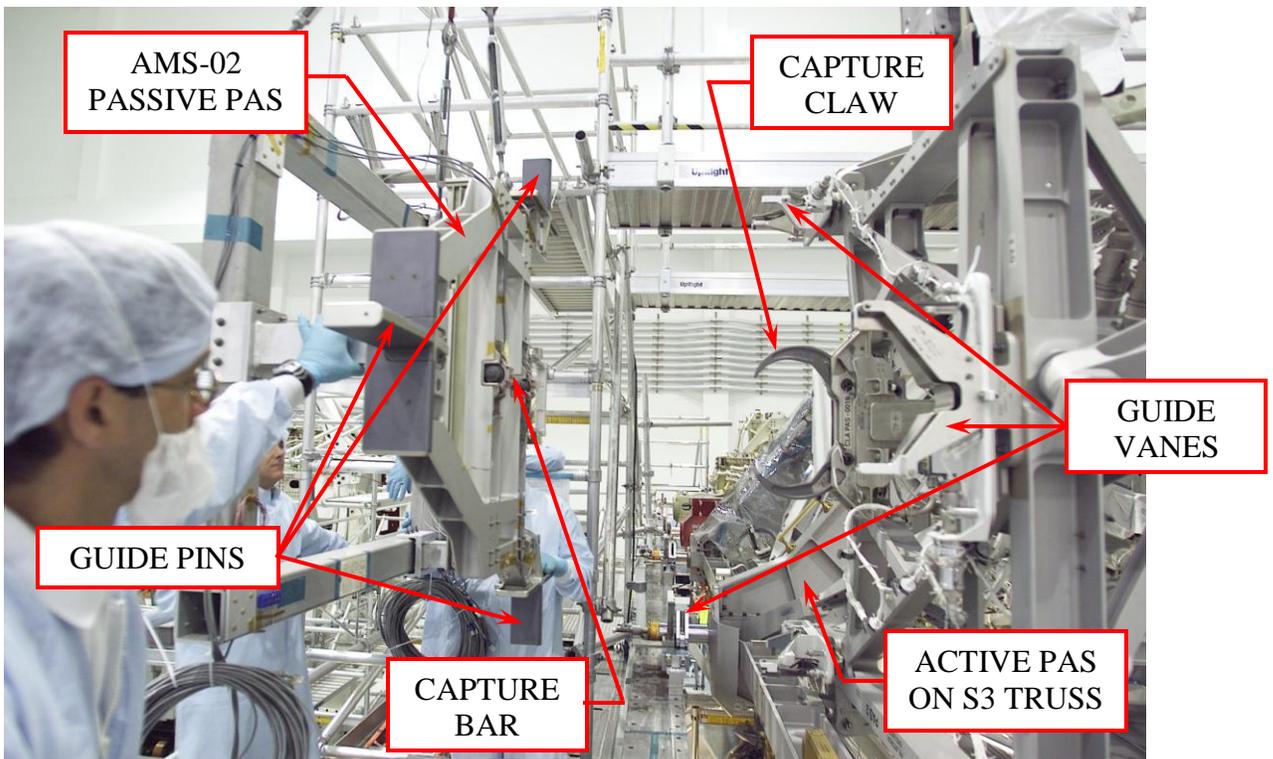


AMS PASSIVE PAS

USS SIMULATOR

Figure 5.3.3.2-1 IVT Test Configuration

(NOTE: The IVT Configuration was identical to the AMS PAS Static Test)



AMS-02
PASSIVE PAS

CAPTURE
CLAW

GUIDE
VANES

GUIDE PINS

CAPTURE
BAR

ACTIVE PAS
ON S3 TRUSS

Figure 5.3.3.2-2 The AMS Passive PAS on Berthing Approach to PAS site 2

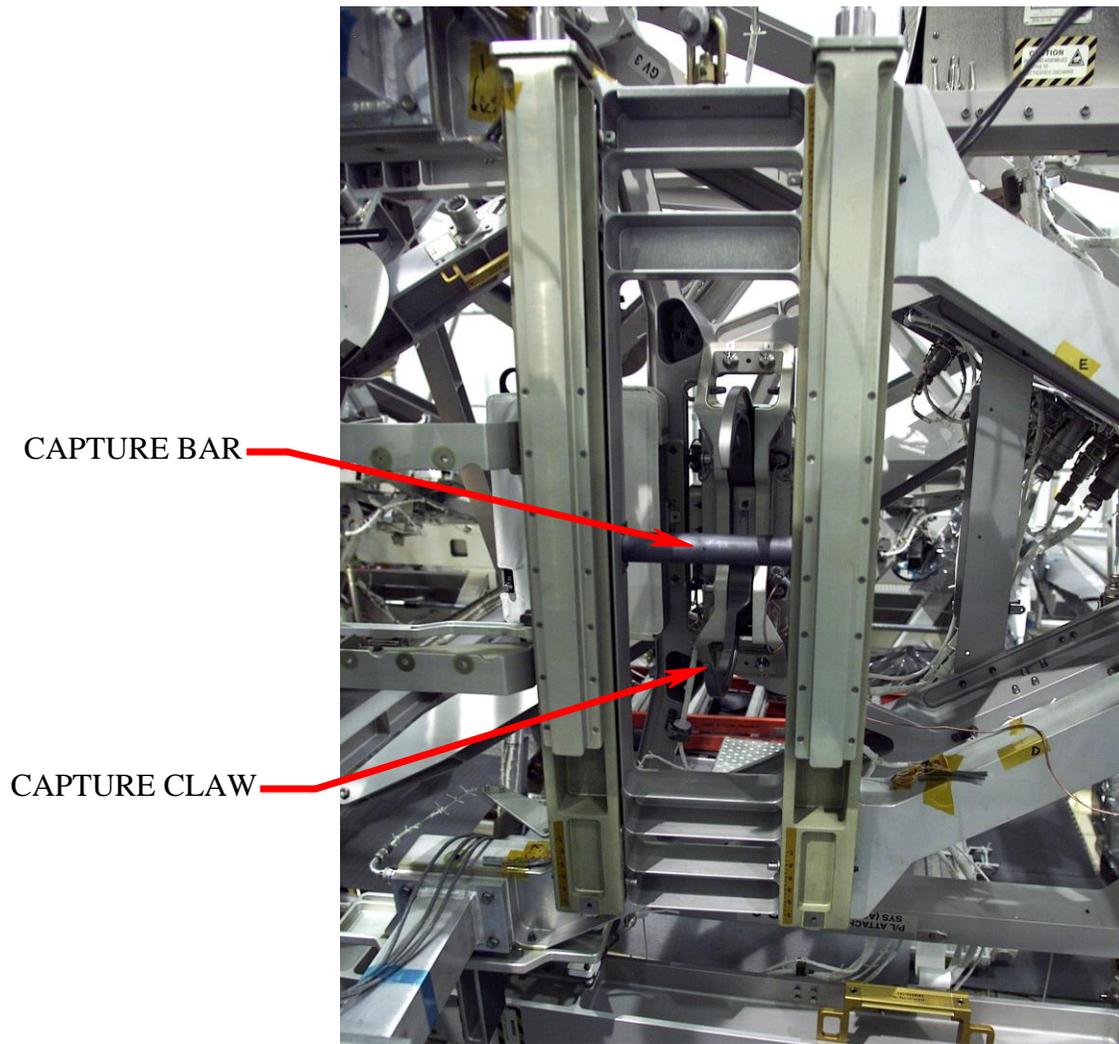


Figure 5.3.3.2-3 AMS Passive PAS Berthed to the S3 Active PAS 2



Figure 5.3.3.2-4 Removing the Preload with the EVA Release Mechanism

5.3.3.3 PAS Vibration Test

The vibration test was performed to verify that the PAS mechanism was not affected by the vibration loads seen at launch. A functional test was performed prior to testing in all 3 axis and after the tests were completed. There was no change in the performance of the EVA Release Mechanism. Pictures of the three setups are shown in Figures 5.3.3.3-1, 5.3.3.3-2 and 5.3.3.3-3.

For each test axis, the shaker excitation will be a random vibration environment from 20 Hz to 2000 Hz as defined in Table 7.2-1.

TABLE 7.2-1 VIBRATION TEST ENVIRONMENT

Random Vibration Specification		
Magnitude definition		
FREQ(Hz)	ASD(G ² /Hz)	Tol dB
20	0.01	+3,-3
80	0.04	+3,-3
500	0.04	+3,-3
2000	0.01	+3,-3

The test duration is 60 seconds per axis. The test can be performed in any sequence.

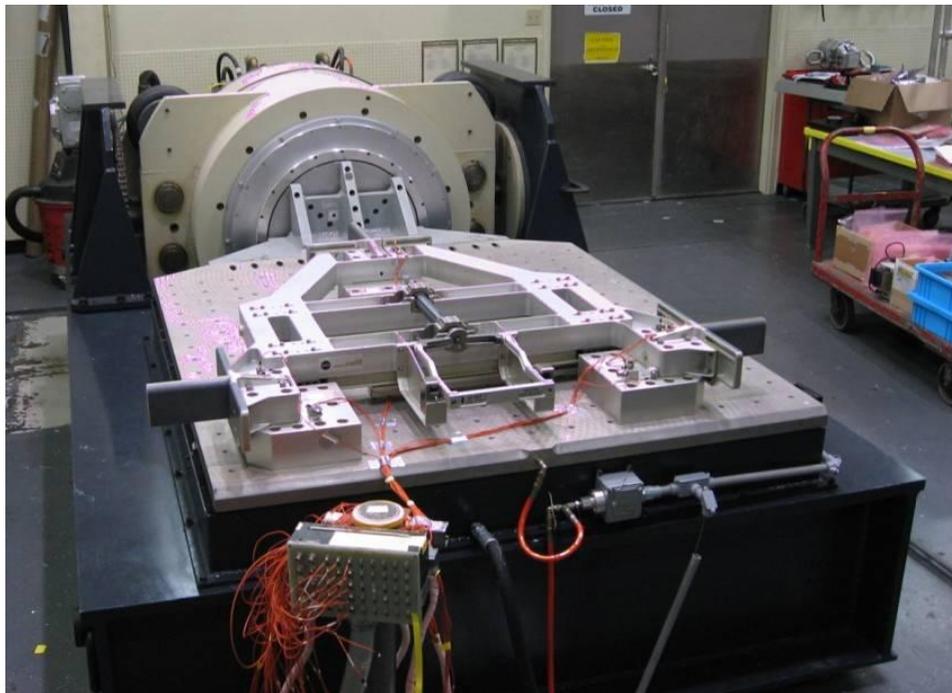


Figure 5.3.3.3-1 PAS Vibration Test X-Axis Setup

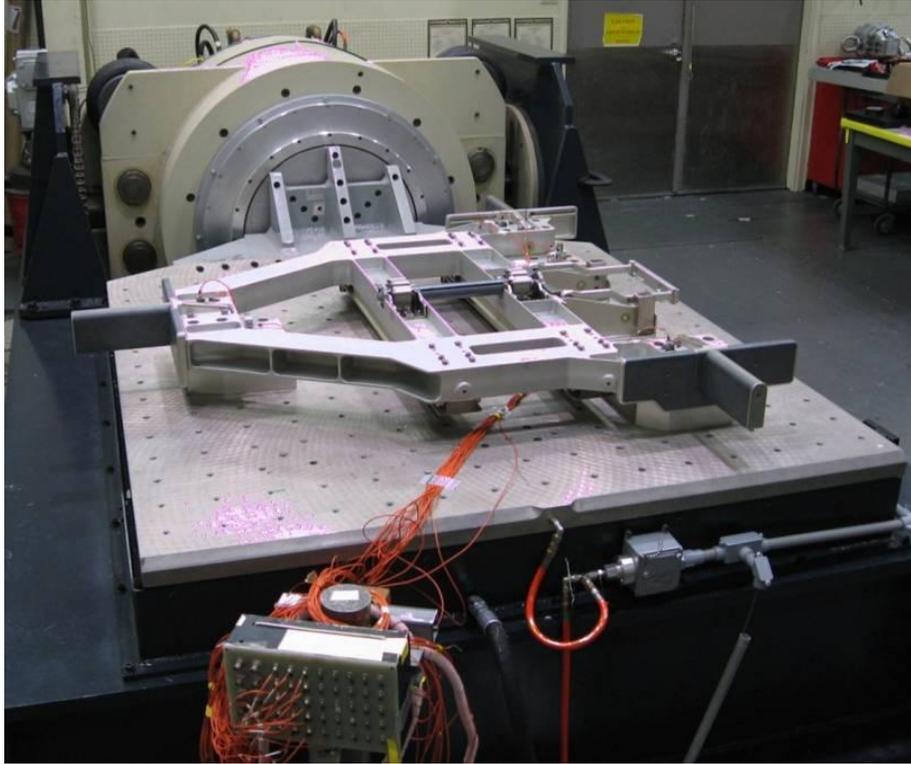


Figure 5.3.3.3-2 PAS Vibration Test Y-Axis Setup

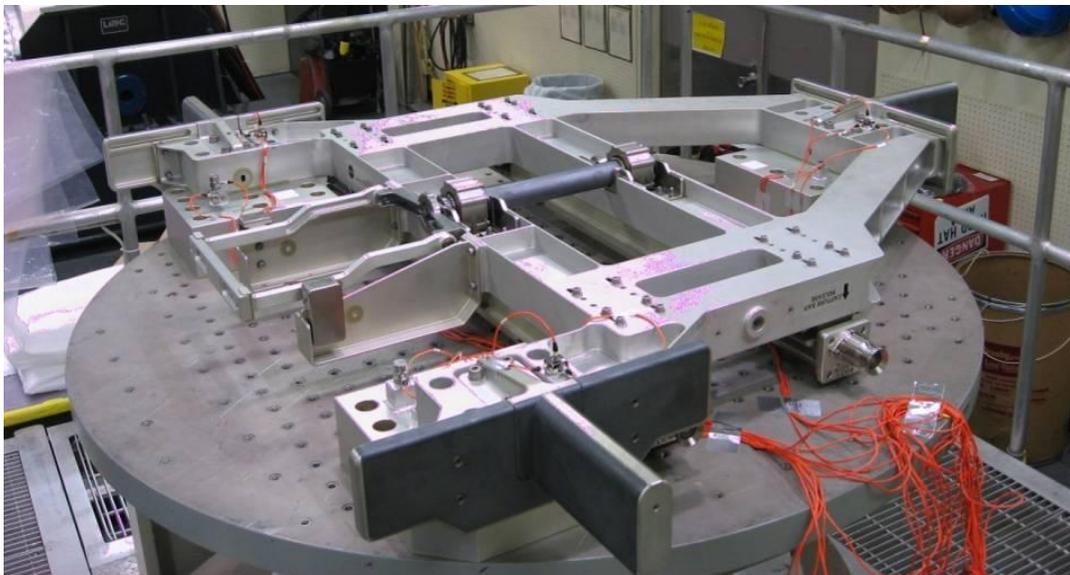


Figure 5.3.3.3-3 PAS Vibration Test Z-Axis Setup

5.3.3.4 PAS Thermal Test

The thermal test was performed to show that the PAS EVA Release mechanism performed per the requirements at the thermal extremes. The PAS was loaded with the nominal load of 5850 lbs. The cold phase was performed first with a cold soak of a minimum of an hour at -130 °F. The cold case had an issue with the mechanism icing up at the cold thermal extreme but was able to show that the mechanism worked at a warmer cold temperature. There was also an issue with the test setup in that the full torque could not be applied to the release screws because of the distance and tool extension that were required to reach the mechanism inside the thermal chamber. The ISS mechanism group accepted the higher cold temperature and the mechanism test with no changes to the hardware. There was no issue with the hot extremes (+200 °F) during testing. The mechanism performed within the EVA requirements both during the test and post test. Figures 5.3.3.4-1 through 5.3.3.4-3 show the test set up; two access doors/ports were required to function, one to turn the release mechanisms and one to withdraw the capture bar.



Figure 5.3.3.4-1 PAS Thermal Test Setup in the Thermal Chamber

Note that in Figure 5.3.3.4-1, this photograph was shot through door the operator is to access the release mechanism through via tool extensions. The operator can be seen working through this door's access ports in Figure 5.3.3.4-2.



Figure 5.3.3.4-2 Unloading of PAS Capture Bar by turning the EVA Release Screws

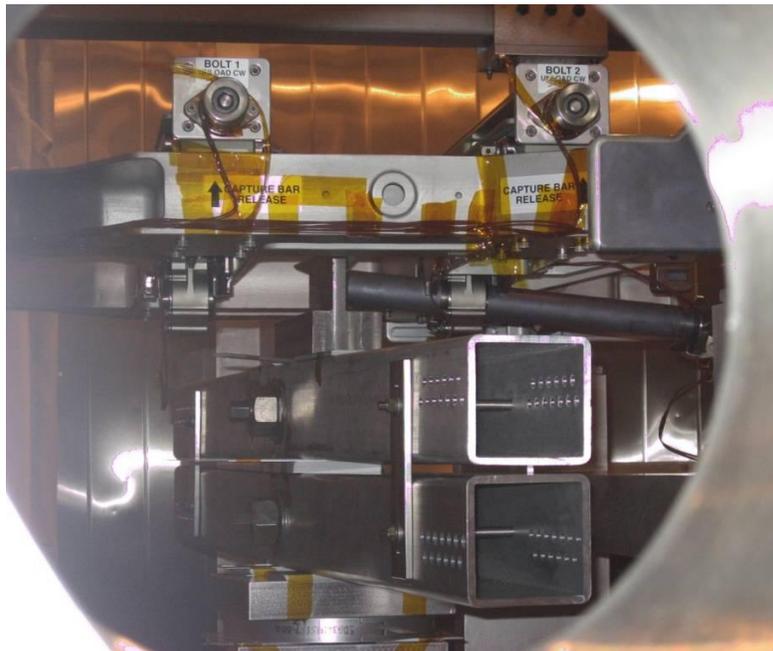


Figure 5.3.3.4-3 PAS Capture Bar shown unload after the hot case

5.4 SPACE SHUTTLE PROGRAM (SSP) AND ISS PROGRAM PROVIDED HARDWARE

All Shuttle and ISS Program supplied hardware is being utilized consistent with the hardware ICDs and certifications.

5.4.1 Shuttle Program Hardware

The AMS-02 will utilize a number of Space Shuttle Program (SSP) supplied components.

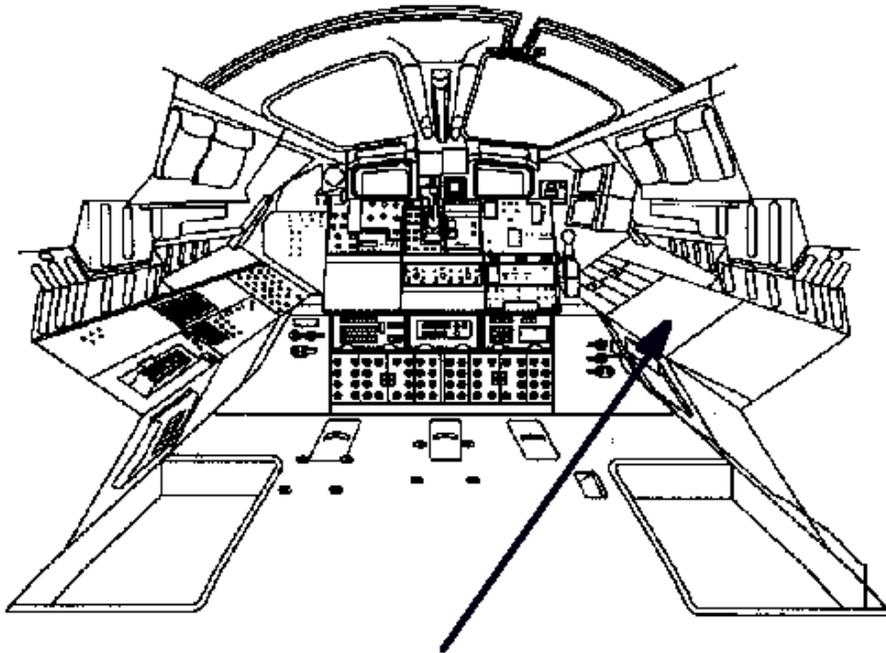
This hardware includes:

- Two Orbiter Interface Units (OIUs)
- One Payload General Support Computer (PGSC), (a.k.a AMS Laptop),
- One middeck locker,
- One Flight Releasable Grapple Fixture (FRGF)
- One Payload Disconnect Assembly (PDA) for the Remotely Operated Electrical Umbilical (ROEU).

The AMS-02 will interface structurally with the Shuttle cargo bay by way of four Payload Releasable Latch Assemblies (PRLAs), one Keel Latch, and the ROEU.

5.4.1.1 Orbiter Interface Units

The two OIUs (one will be a backup) will be used as 1553 bus controllers and will serve as the uplink/ downlink interface for housekeeping data and commands. The OIUs will be mounted in the Payload Station L11 Console in the Orbiter aft flight deck, as designed as shown in Figure 5.4-2. The OIUs provide an interface between PGSC and the ROEU connected payload.



**OIU prime and OIU backup
(mounted in Payload Station Console L-11)**

Figure 5.4-2 Orbiter Interface Unit Location on Console L-11

5.4.1.2 Middeck Locker

The middeck locker will be used for stowage of the Digital Data Recorder System (DDRS-02) hardware which includes the PGSC and cables. In addition for return from orbit the PDIP cable, installed for launch, will be stowed in the Middeck Locker with the DDRS cables and hardware.

5.4.1.3 Flight Releasable Grapple Fixture (FRGF)

A FRGF, mounted to the AMS-02 payload, will be used by the SRMS to lift the AMS-02 out of the Orbiter payload bay. The FRGF is mounted to the FRGF Bracket using 6 high strength (200 ksi ultimate) $\frac{3}{8}$ " diameter bolts. The FRGF Bracket is bolted to the forward face of the port Upper Trunnion Bridge Beam using 24 high strength (180 ksi ultimate) $\frac{1}{4}$ " diameter bolts. The FRGF placement on the USS-02 is shown in Figure 5.4-3. An exploded view of the attachment hardware is shown in Figure 5.4-4.

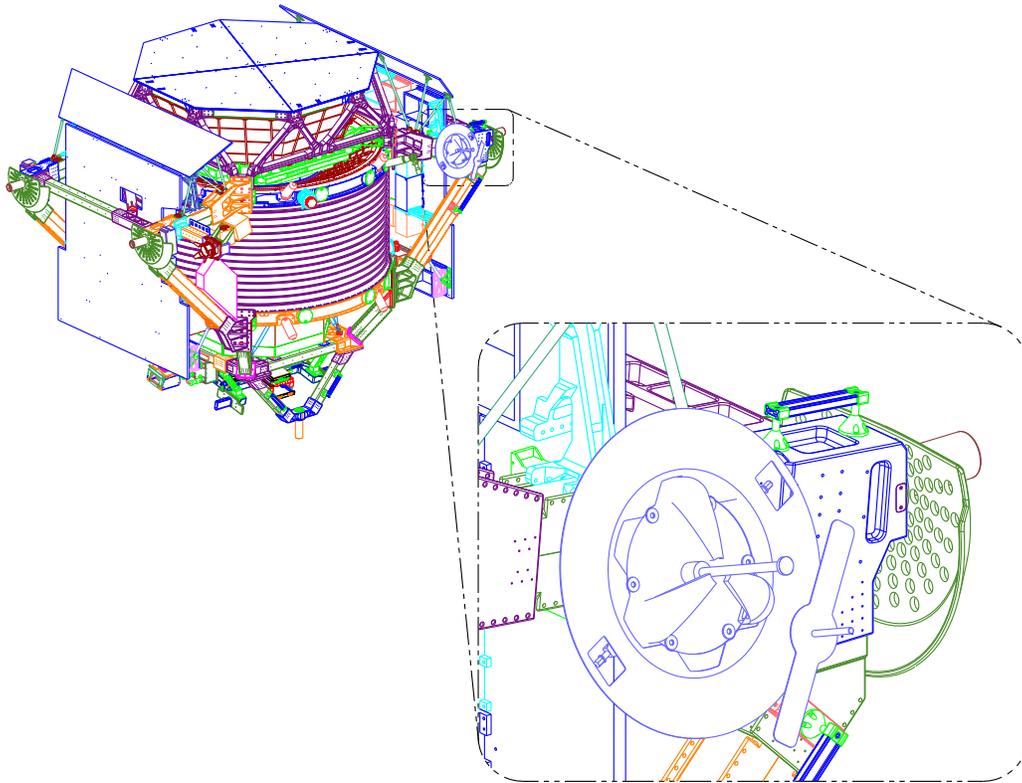


Figure 5.4-3 The FRGF Mounted to the Upper Trunnion Bridge Beam USS-02

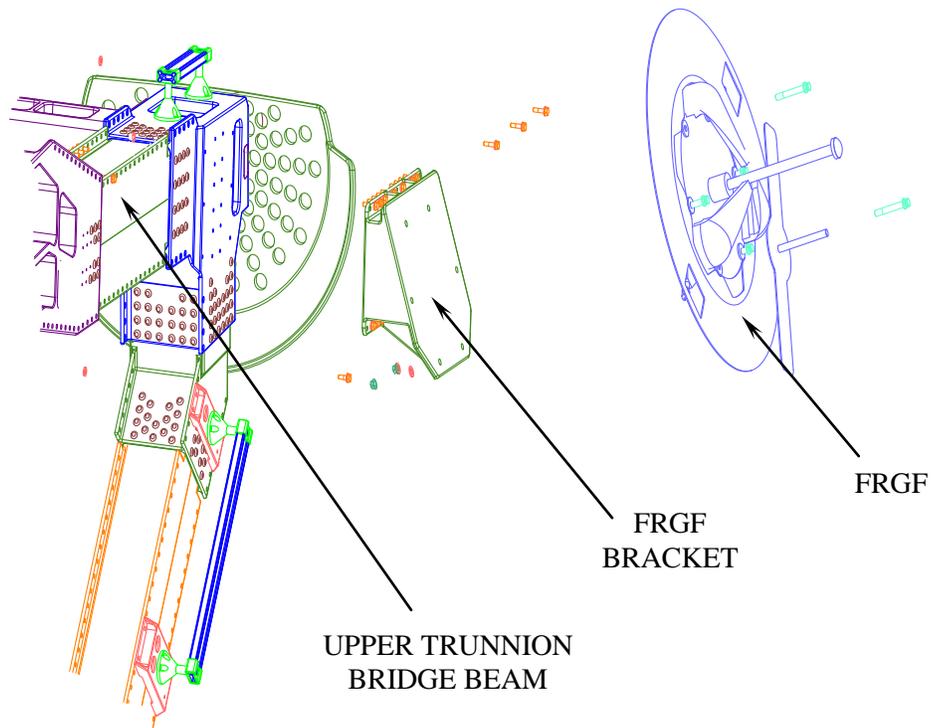


Figure 5.4-4 The FRGF to USS-02 Mounting Hardware

5.4.1.4 Payload Disconnect Assembly (PDA)

The PDA for the ROEU is the AMS-02 half of the ROEU system. This will be used to make the electrical interface between the Shuttle and the AMS-02 payload. The PDA will be mounted to the ROEU bracket that is attached to both the Primary Sill Joint and the Upper Trunnion Bridge Beam with 12 high strength (180 ksi Ultimate Strength) ¼” diameter bolts. The PDA mounted to the ROEU Bracket Assembly is shown in Figure 5.4-5. Pip Pins show in older graphics have been replaced with fixed bolts (Figure 5.4-5).

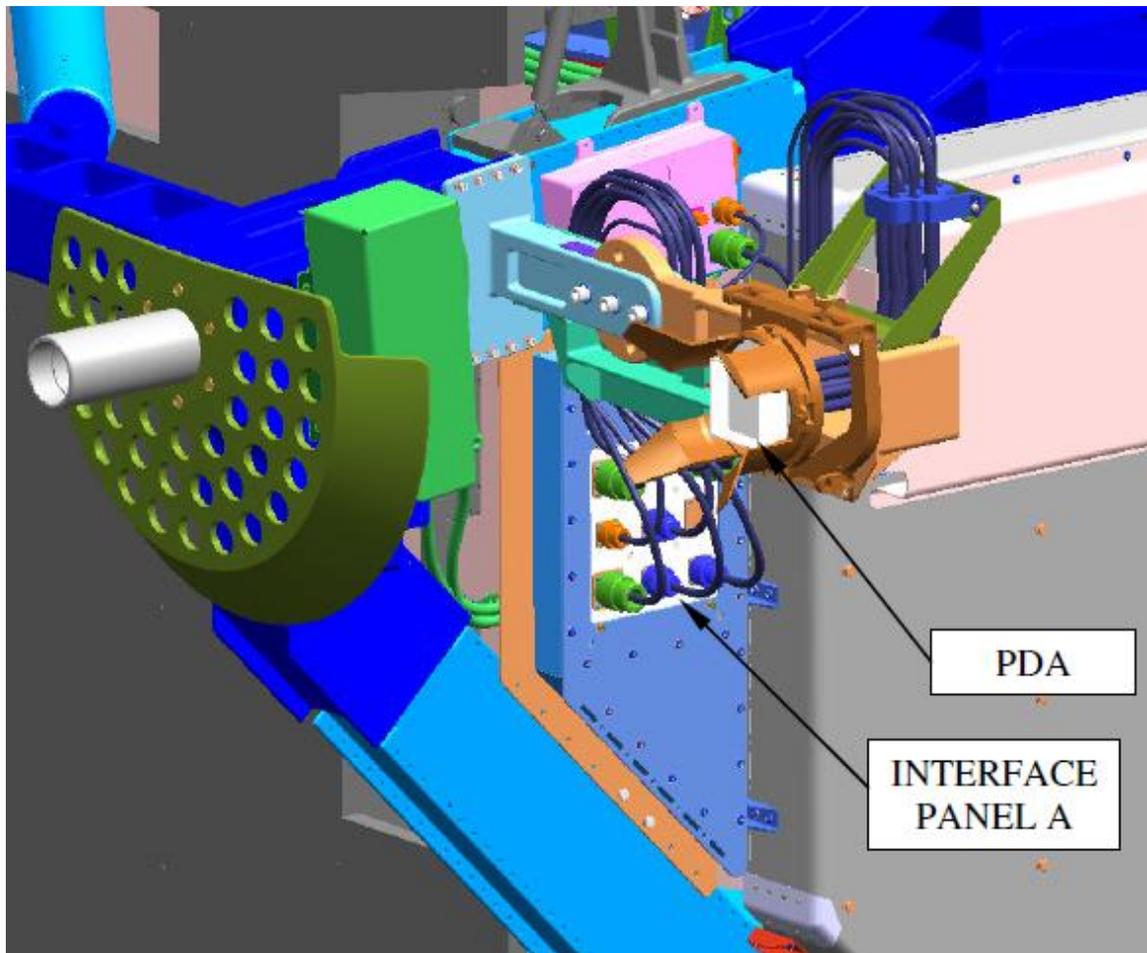


Figure 5.4-5 PDA Mounted on the Upper USS-02

5.4.1.5 Scuff Plates

The scuff plates are manufactured from aluminum and mount to the front face of the Sill Trunnion Joints, as shown in figure 5.4-6. The scuff plates are meant to preclude excessive port/starboard motion for berthing/unberthing operations using the SRMS and SSRMS operations. The scuff plates are designed to meet the requirements specified NSTS-21000-IDD-ISS.

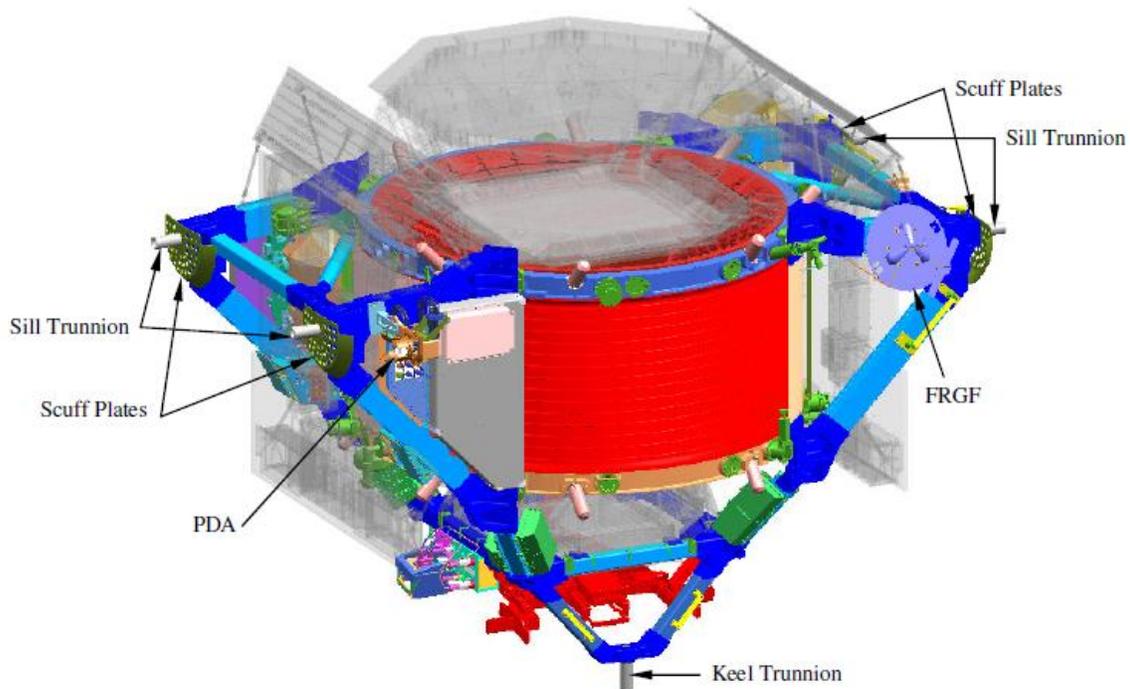


Figure 5.4-6 Scuff Plate Locations on AMS-02

5.4.2 ISS Provided Hardware

The ISS Program provided hardware that will be used with the AMS-02 includes:

- Two Shuttle installed Assembly Power Converter Units (APCUs),
- One Power Video Grapple Fixture (PVGF)
- One passive Umbilical Mechanism Assembly (UMA)
- One External Berthing Camera System (EBCS)

The AMS-02 payload will also require the use of the SSRMS. The SSRMS attaches to the Power Video Grapple Fixture and moves AMS-02 from the SRMS to the upper inboard payload attach site two, located on the ISS S3 truss shown in Figure 5.4-7.

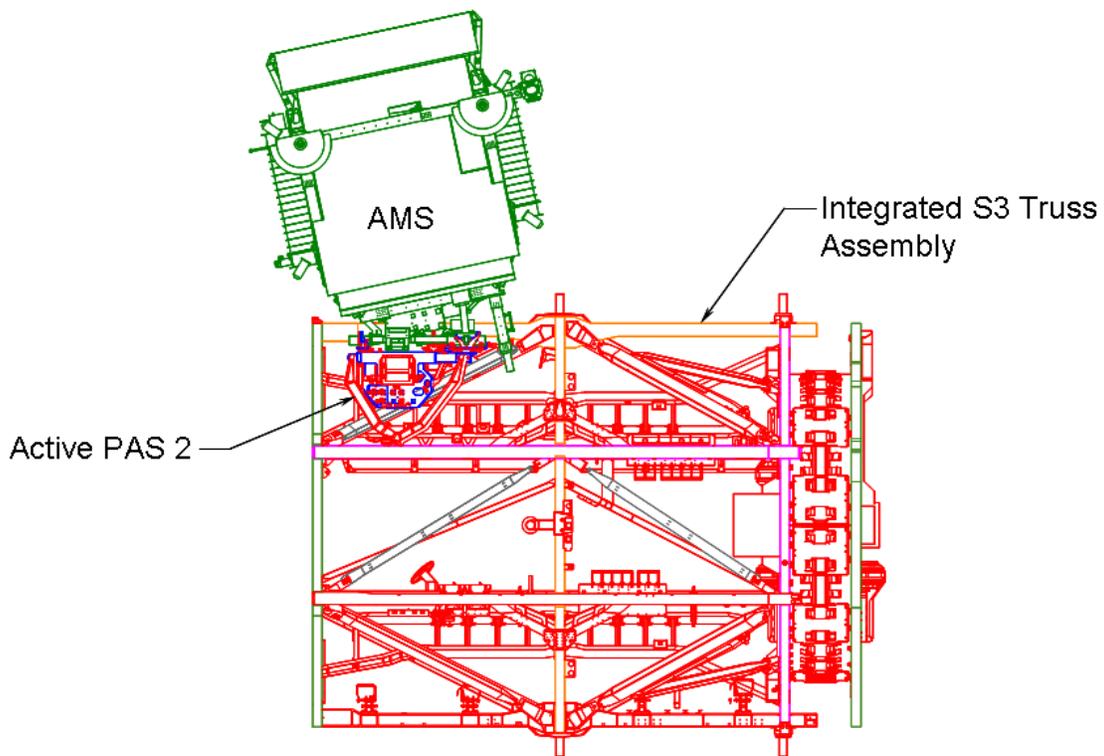


Figure 5.4-7 AMS Mounted to ISS S3 Truss

5.4.2.1 Assembly Power Converter Units

The APCUs will be used to supply 120v DC power to the AMS while operating on the Orbiter. Two APCUs are being used interconnected to provide adequate power. They will be mounted in bay 5 on the port side of the Orbiter, as designed, per the APCU Interface Control Document (ICD).

5.4.2.2 Power Video Grapple Fixture (PVGF)

A PVGF, mounted on the aft port side of the Upper Trunnion Bridge Beam of the AMS-02 payload, provides an additional structural/mechanical interface with the Mobile Servicing System allowing the SSRMS or the Payload/Orbiter Replacement Unit (ORU) Accommodation to grapple the payload. The PVGF mounts to the PVGF Bracket using 6 high strength (200 ksi ultimate) $\frac{3}{8}$ " diameter bolts. The PVGF Bracket is mounted to the Upper Trunnion Bridge Beam with 24 high strength (180 ksi ultimate) $\frac{1}{4}$ " diameter bolts. The PVGF attachment location on AMS-02 is shown in figure 5.4-8. An exploded view of the attachment hardware is shown in Figure 5.4-9. Electrically the PVGF will supply power but not data communication to AMS-02. Power supplied to AMS-02 during this operation is for heater operations only.

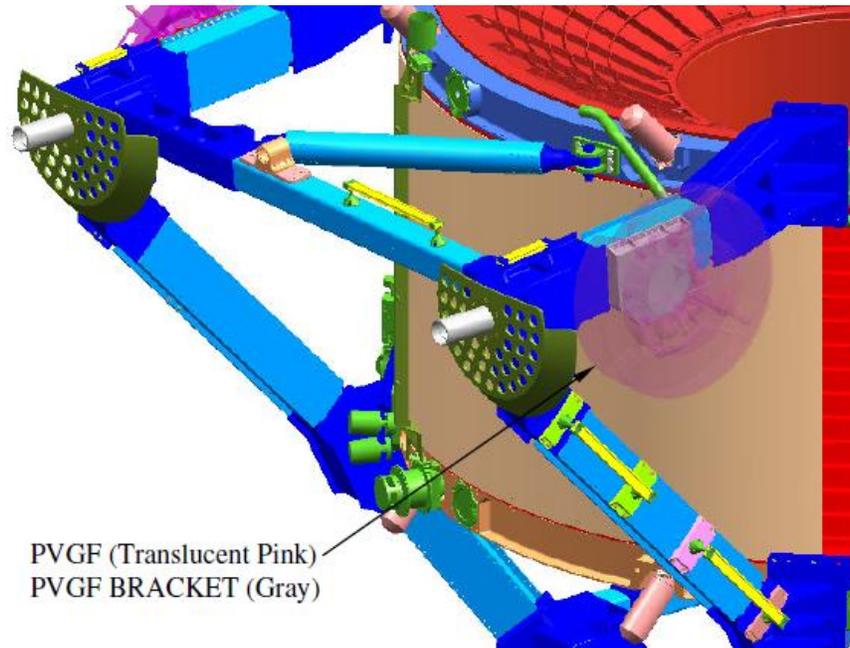


Figure 5.4-8 PVGF Mounted to the Upper Trunnion Bridge Beam USS-02

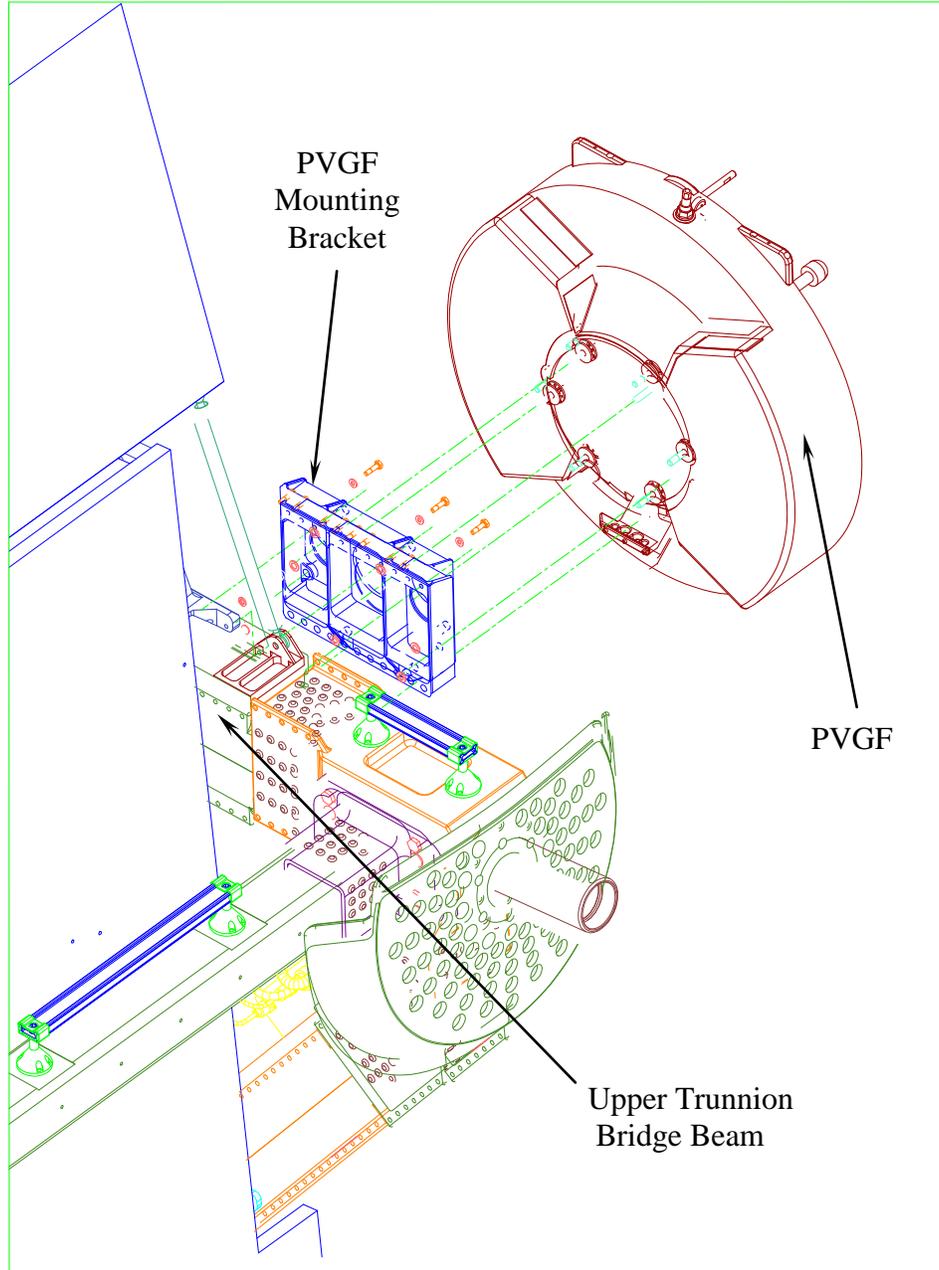


Figure 5.4-9 The PVGF to USS-02 Mounting Hardware

5.4.2.3 Passive Umbilical Mechanism Assembly (UMA)

The passive UMA will be used to electrically connect the AMS-02 payload to the ISS truss attach site. The UMA attaches to the lower USS-02, as shown in figure 5.4-10, and will interface with the active UMA mounted to the ISS PAS site as per SSP-57003.

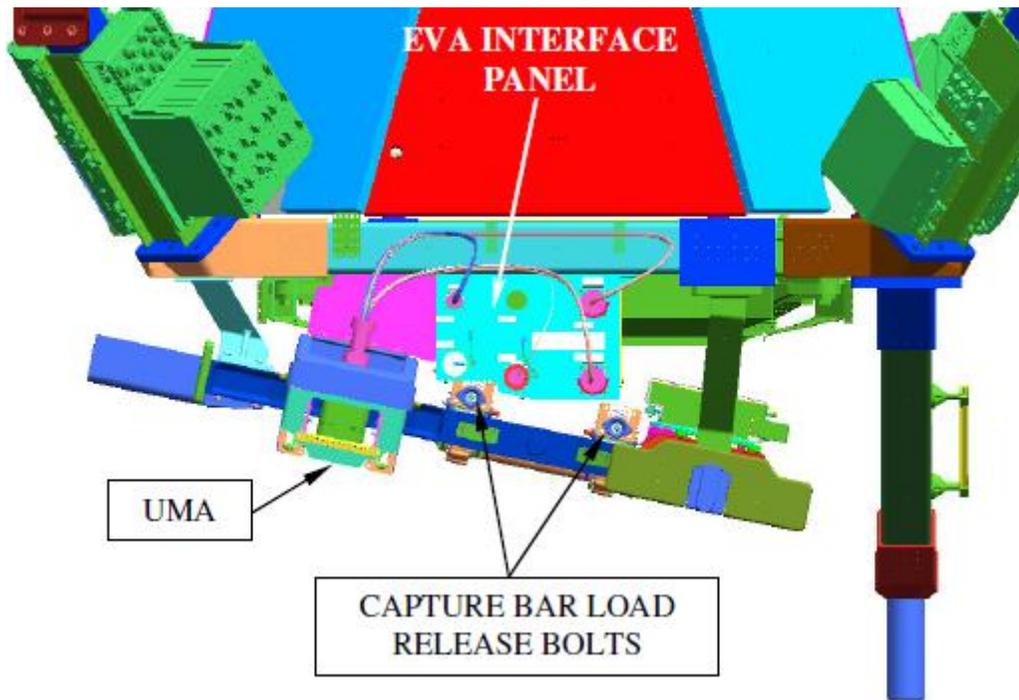


Figure 5.4-10 The UMA Mounted to the EVA Connector Panel

5.4.2.4 External Berthing Camera System (EBCS)

The EBCS is a camera and avionics package provided by the ISS Program that is electrically connected to the PVGF and structurally mounted to the passive PAS assembly on the AMS-02. The EBCS provides visual cues to robotic workstation monitors to assist ISS Mobile Servicing System operators in berthing AMS-02. The system is comprised of an avionics package which contains both a primary and secondary video camera and an EBCS Target which is mounted on the PAS site. The electrical services of EBCS include video, power, heater power and AMS-02 heater power. The EBCS Avionics mounting is the responsibility of AMS-02. The mounting requirements are defined in SSP 57003 Section 3.7.6.1, SSP 57004 Figures 3.1.2.2-1 and SSP 57004 Figures 3.7.1-1. Additional mounting data is contained in MDR-BCS-TM-7498, EBCS Avionics Package Detailed Installation Instructions produced by MD Robotics per NASA contract NAS9-00089.

The EBCS mounting location positions it within the Permanent Magnet field such that it does not exceed the 15 Gauss limit that was provided by MDA for the threshold limit for safe accurate operations.

Refer to Figure 5.4-11 for the location of the EBCS mounted on the PAS Assembly.

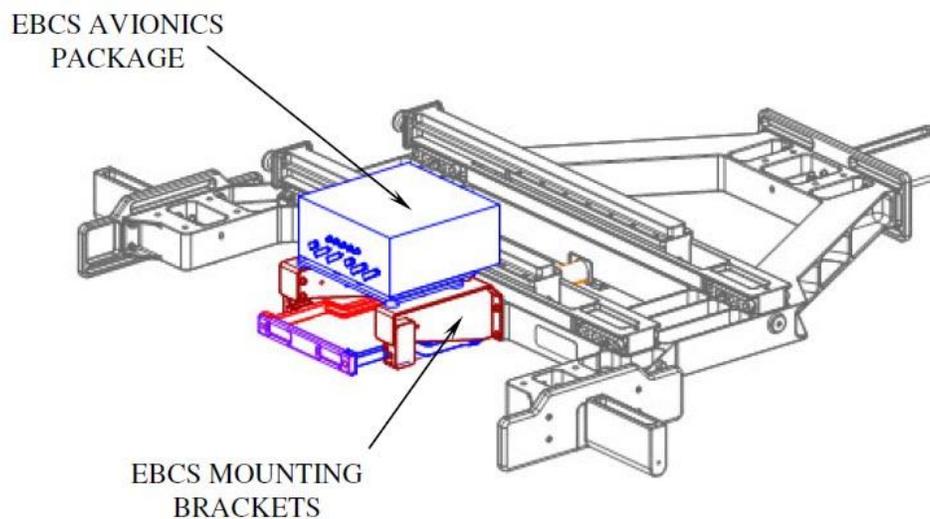


Figure 5.4-11 The EBCS Mounted on the AMS-02 Passive PAS

5.4.3 EVA Hardware

The AMS-02 has been designed to support contingency EVAs to the AMS-02. These potential contingency EVAs include:

- ROEU Manual Release/Mate
- UMA Manual Release/Mate
- FRGF Release
- PVGF Release
- PAS Capture Bar Release
- EVA Connector Panel Operation

Each of the above EVAs may include multiple EVA work locations. These sites have been identified and work site aids have been positioned to facilitate EVA operations. Payload hardware associated with these EVA operations is described and shown in the sections that follow.

5.4.3.1 UMA EVA Bolts

In the event that the passive and active UMA halves cannot be nominally separated, the passive UMA can be released from the AMS-02 by cutting the unpowered between the UMA and the USS mounted cable clamp, then releasing the four EVA bolts shown in Figure 5.4-12.

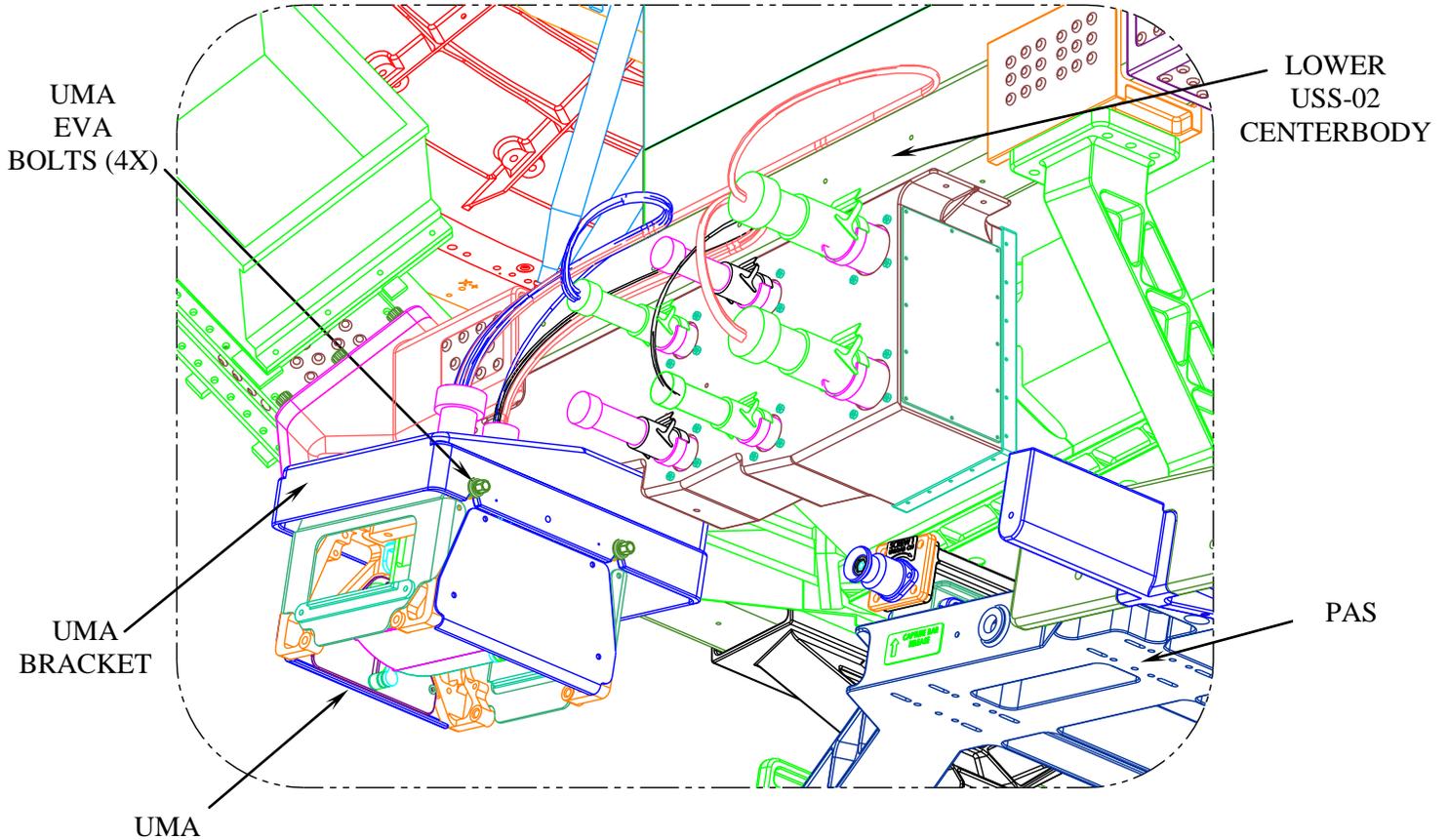


Figure 5.4-12 UMA EVA Bolt Locations

5.4.3.2 FRGF Release

The AMS-02 payload can be manually released from the FRGF by way of the Rod Release. The Rod Release is a standardized ISS EVA process which AMS-02 is compatible with. The locations of the EVA bolts and Rod Release are shown in figure 5.4-13.

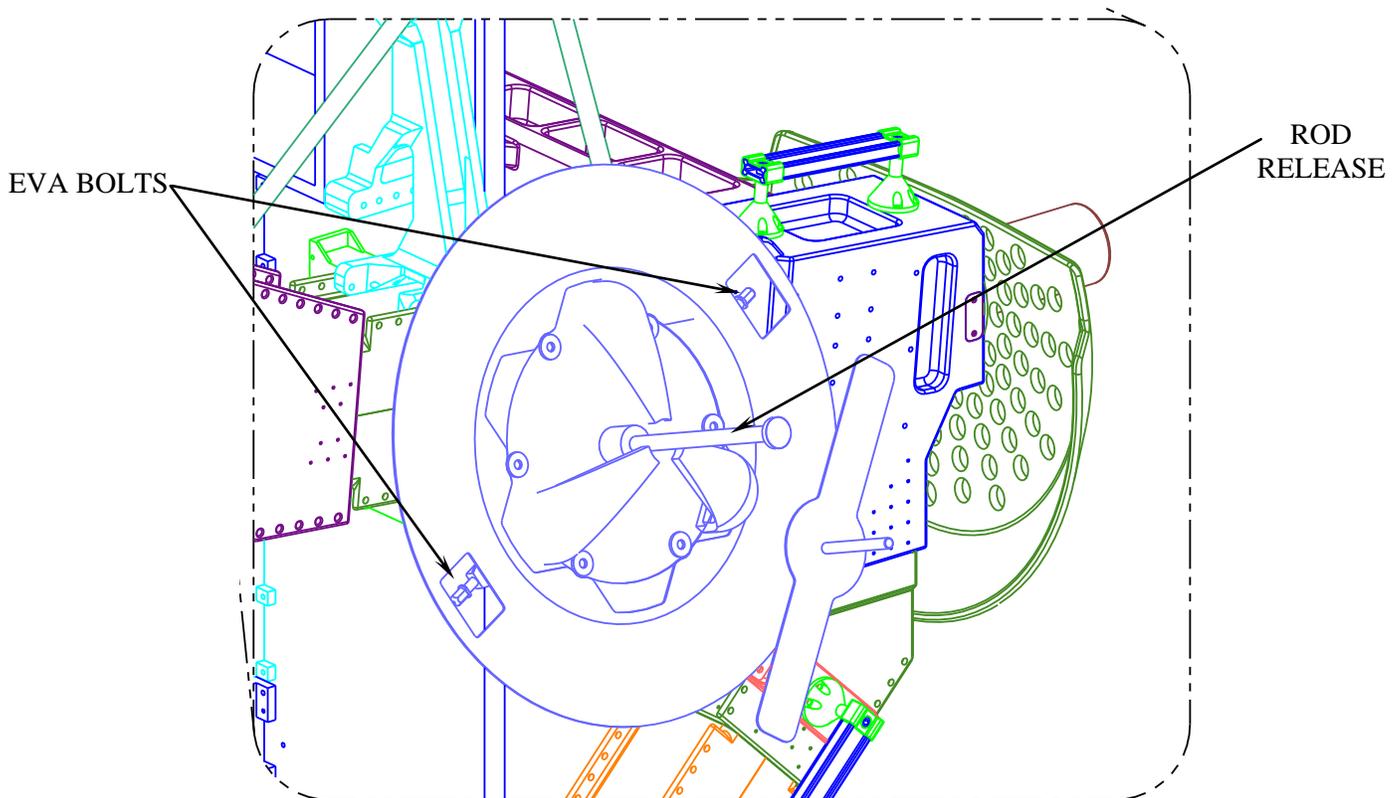


Figure 5.4-13 FRGF Rod Release Location

5.4.3.3 PVGF Release

The AMS-02 payload can be manually released from the SSRMS by removing the Rod Release from the PVGF bracket. The Rod Release is a standard shuttle program EVA process that the AMS-02 is compatible with. Locations of the PVGF EVA bolts and Rod Release are shown in figure 5.4-14.

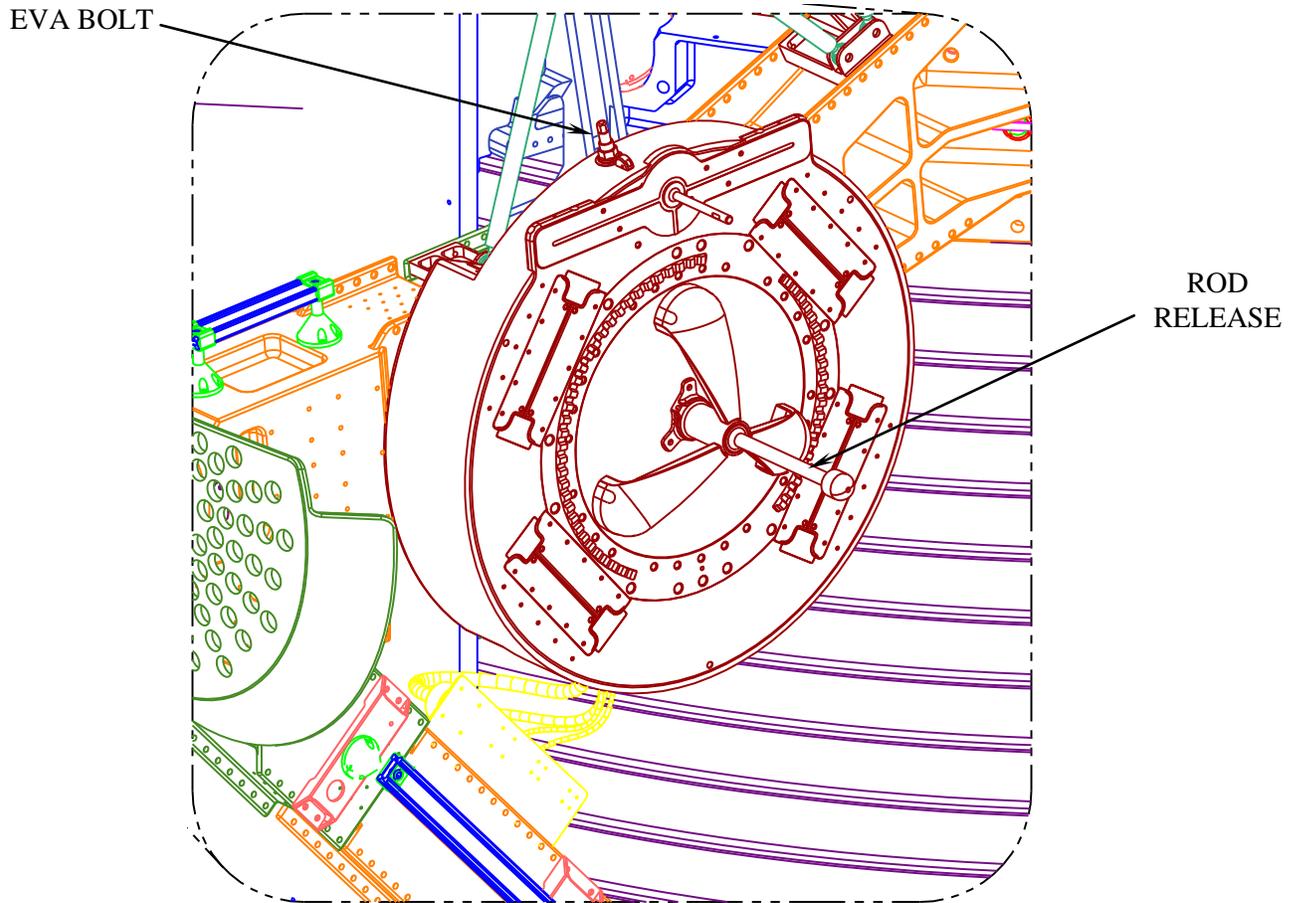


Figure 5.4-14 PVGF Rod Release Location

5.4.3.4 The PAS Capture Bar Release Mechanism

The PAS Capture Bar Assembly's preload is released mechanically by unloading the two Drive Screws using an EVA PGT. After the Capture Bar is unloaded and lowered the crew member pulls the Capture Bar Assembly out from the Bearing Assemblies using the Capture Bar Removable Handle. Figure 5.4-15 shows the location of the PAS Assembly mounted to AMS-02. Figure 5.4-16 shows the location of the drive screw interface on the PAS. Labels indicating the location of the release mechanisms and the direction required to release the capture bar are noted with the appropriate decals. The Capture Bar Assembly's removal from the PAS Assembly is shown in Figure 5.4-17.

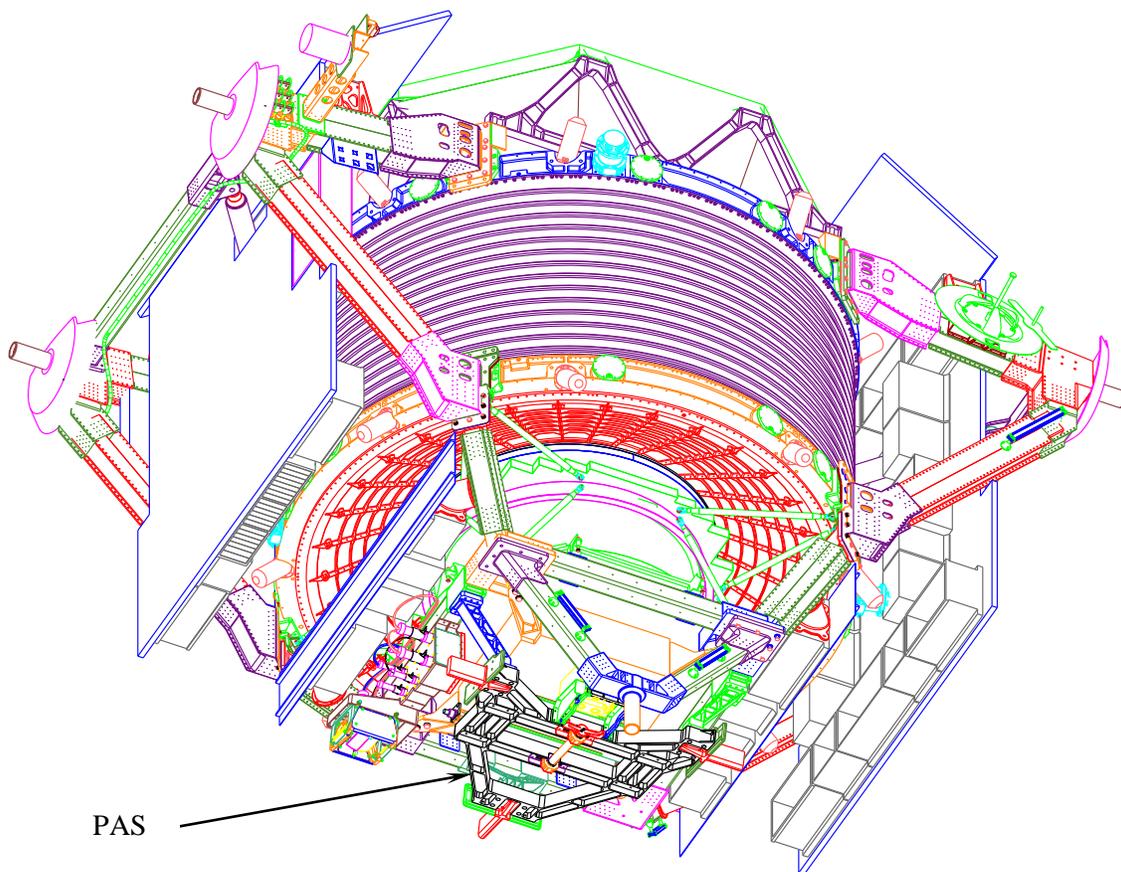


Figure 5.4-15 PAS Location on AMS-02

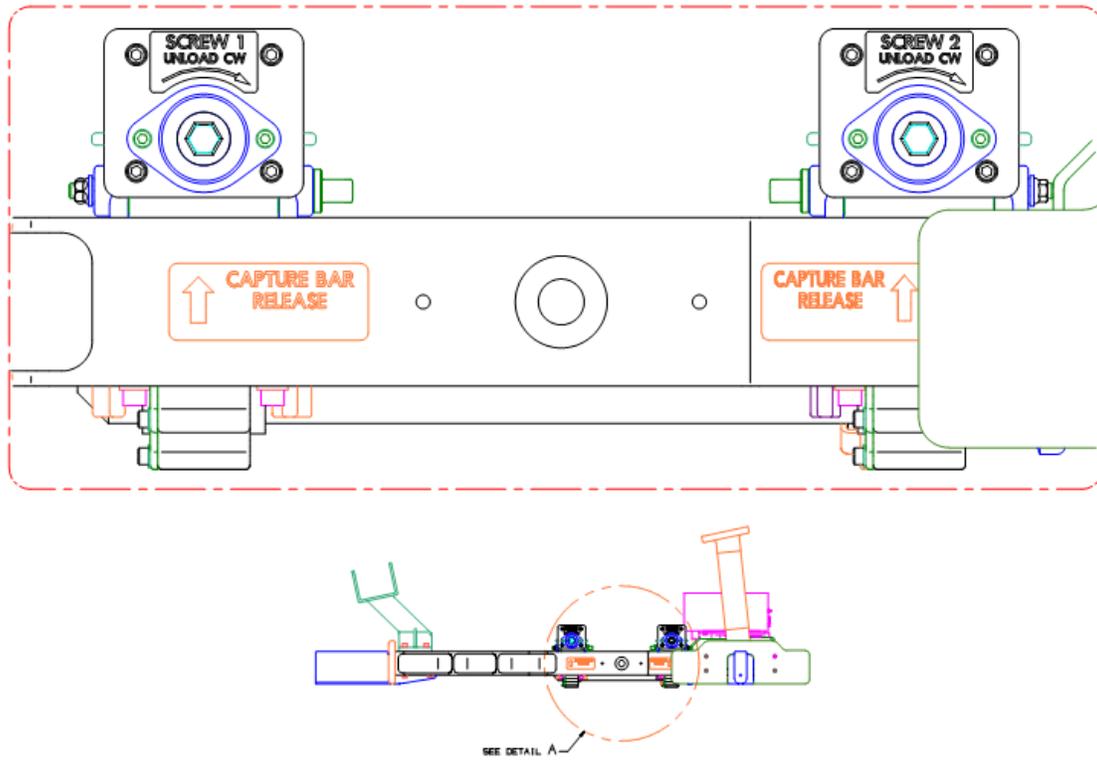


Figure 5.4-16 Drive Bolt Location on the PAS
(Note: Label “SCREW” will be replaced with “BOLT”)

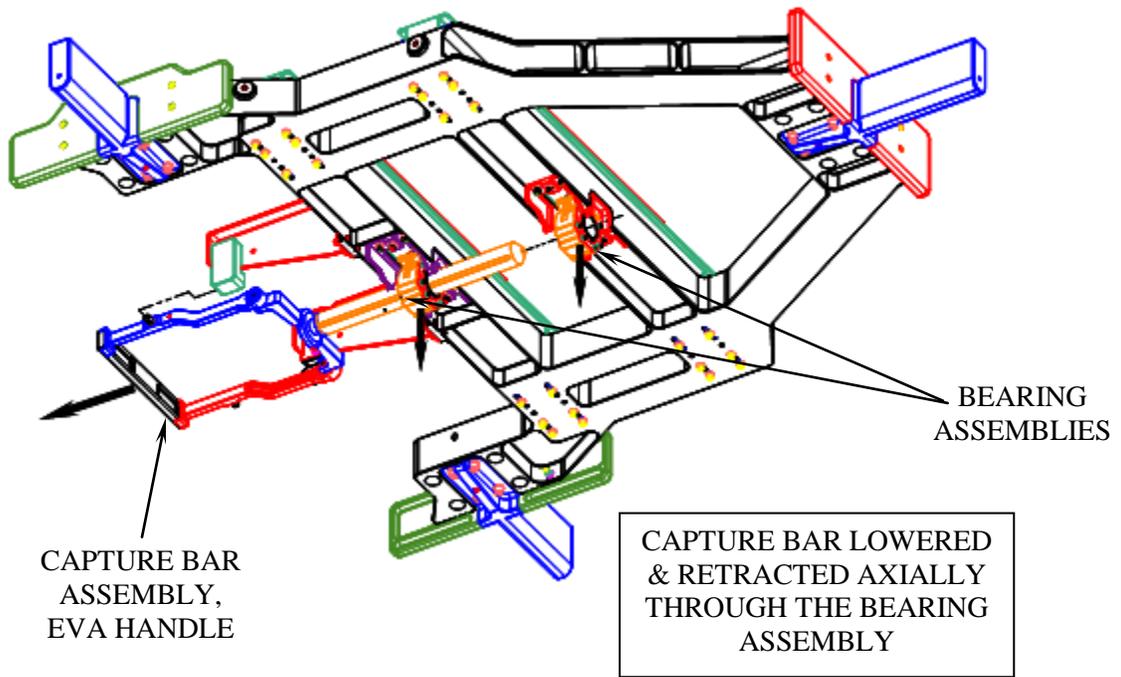


Figure 5.4-17 Capture Bar Assembly from AMS-02 Passive PAS

5.4.3.5 EVA Compatible Electrical Connectors

The connectors used to connect to the EVA panel are EVA compatible lever-actuated connectors per SSG-21635. The unused connectors on the EVA panel are protected by connector caps that are tethered to the panel. The power and data cables connect the UMA to the EVA panel with sufficient length to be routed to either channel A or channel B. The EVA Panel Assembly is bolted to the Lower Centerbody of the USS-02 with 16 ¼" high strength fasteners (160 ksi ultimate) as shown in figure 5.4-18.

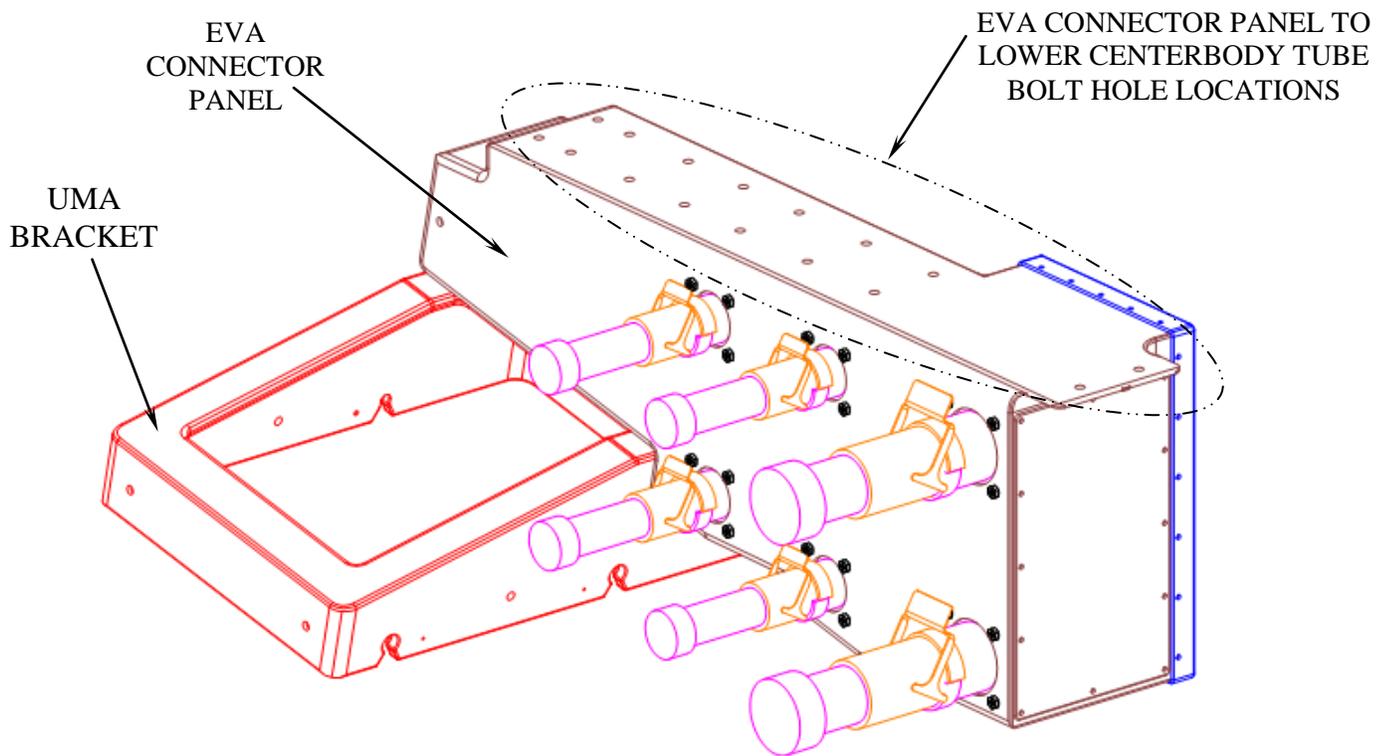


Figure 5.4-18 EVA Connector Panel with UMA Bracket

5.4.3.6 Worksite Interface Fixture (WIF) Socket

A standard WIF socket is mounted to the starboard Sill Tube with 8 high strength (160 ksi ultimate) $\frac{1}{4}$ " fasteners, as shown in figure 5.4-19. This work site location will be used during the EVA operations to release either the FRGF from the SRMS or the PVGF from the SSRMS.

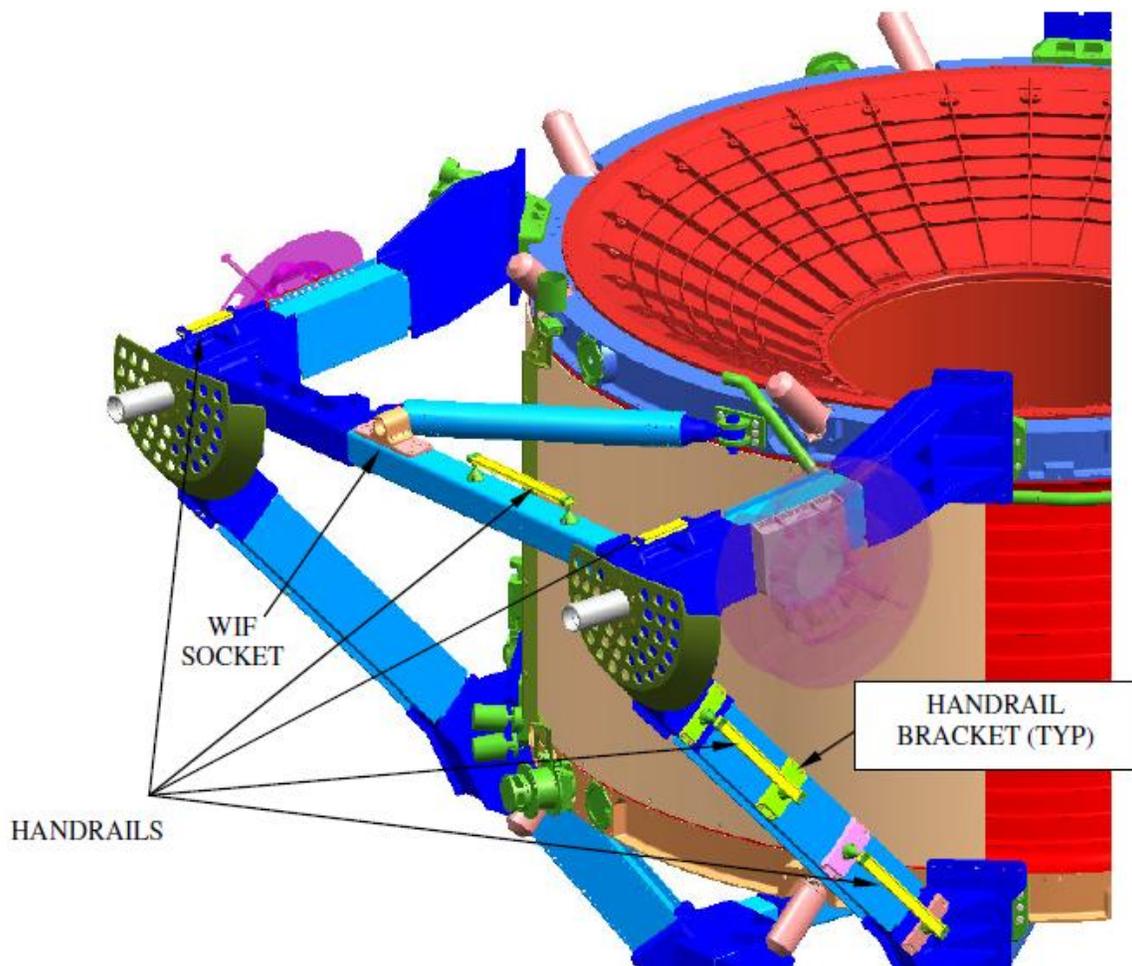


Figure 5.4-19 WIF Socket Location on Sill Tube

5.4.3.7 ROEU Bracket Assembly

The ROEU Bracket Assembly had been designed to fold to increase clearances with adjacent payloads. Further review indicated that this function was not necessary and the folding mechanism of the bracket has been secured with bolts to preclude folding (Figure 5.4-5). This bracket is now considered standard structure that supports the AMS-02 ROEU PDA. There are no EVA operations associated with the current configuration of the ROEU Bracket Assembly.

5.4.3.8 EVA Handrails

EVA handrails are mounted to the USS-02 as shown in figures 5.4-20 through 5.4-225. The EVA handrails provide a crew member access to the WIF socket used as a worksite to release the grapple fixtures. EVA handrails will also be used for crew translation during contingency EVA operations on AMS-02. The locations of the handrails were assessed by either an EVA simulation by computer or weightless environment exercises. The locations of additional EVA handrails for on-orbit ROEU access would be determined by performing a WSA. All handrails and the WIF interface are provided by the JSC Extravehicular Activity Office (XA) to the AMS-02 Project for installation on the USS-02.

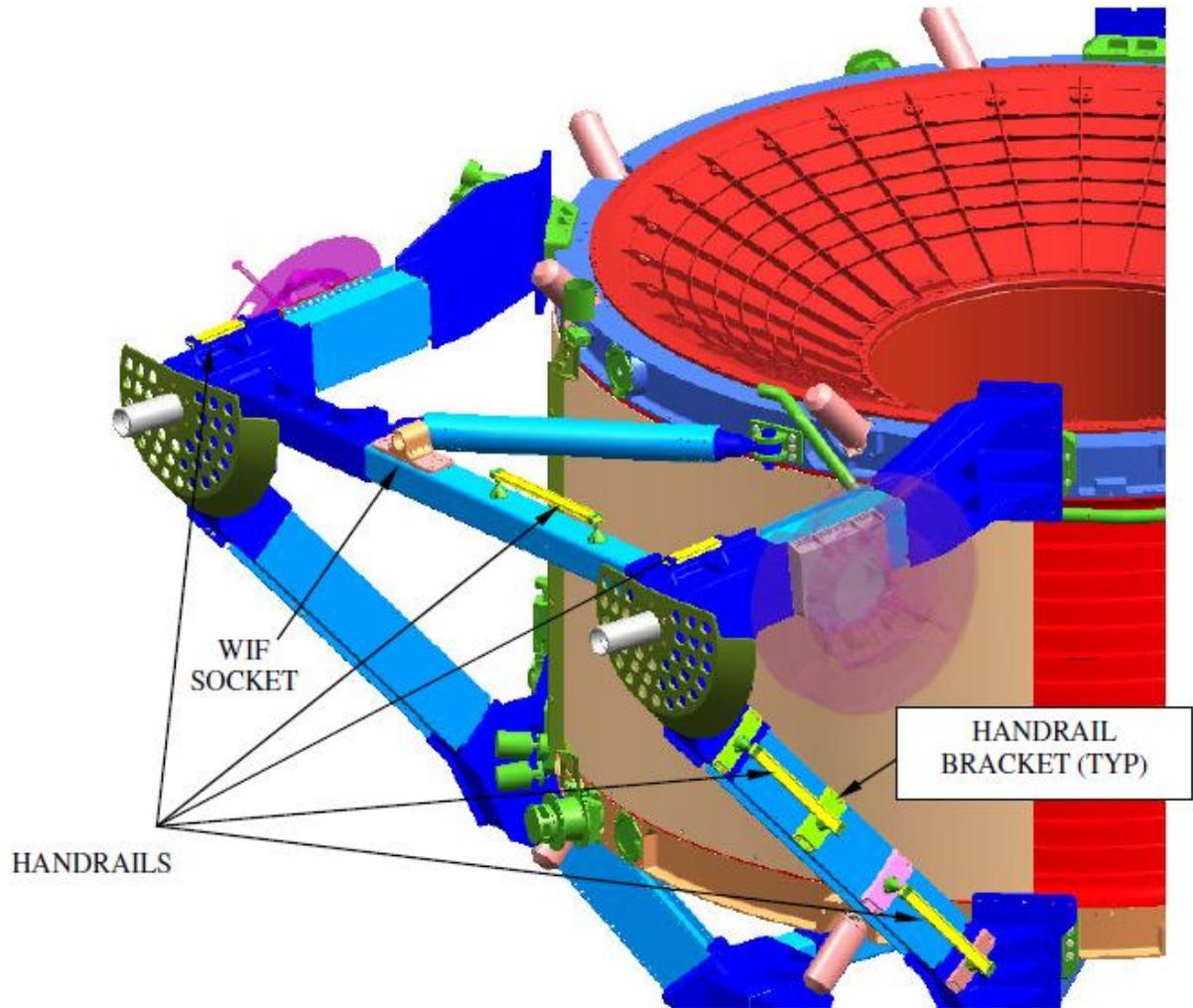


Figure 5.4-20 EVA Handrails Used To Access WIF Socket On-Orbit

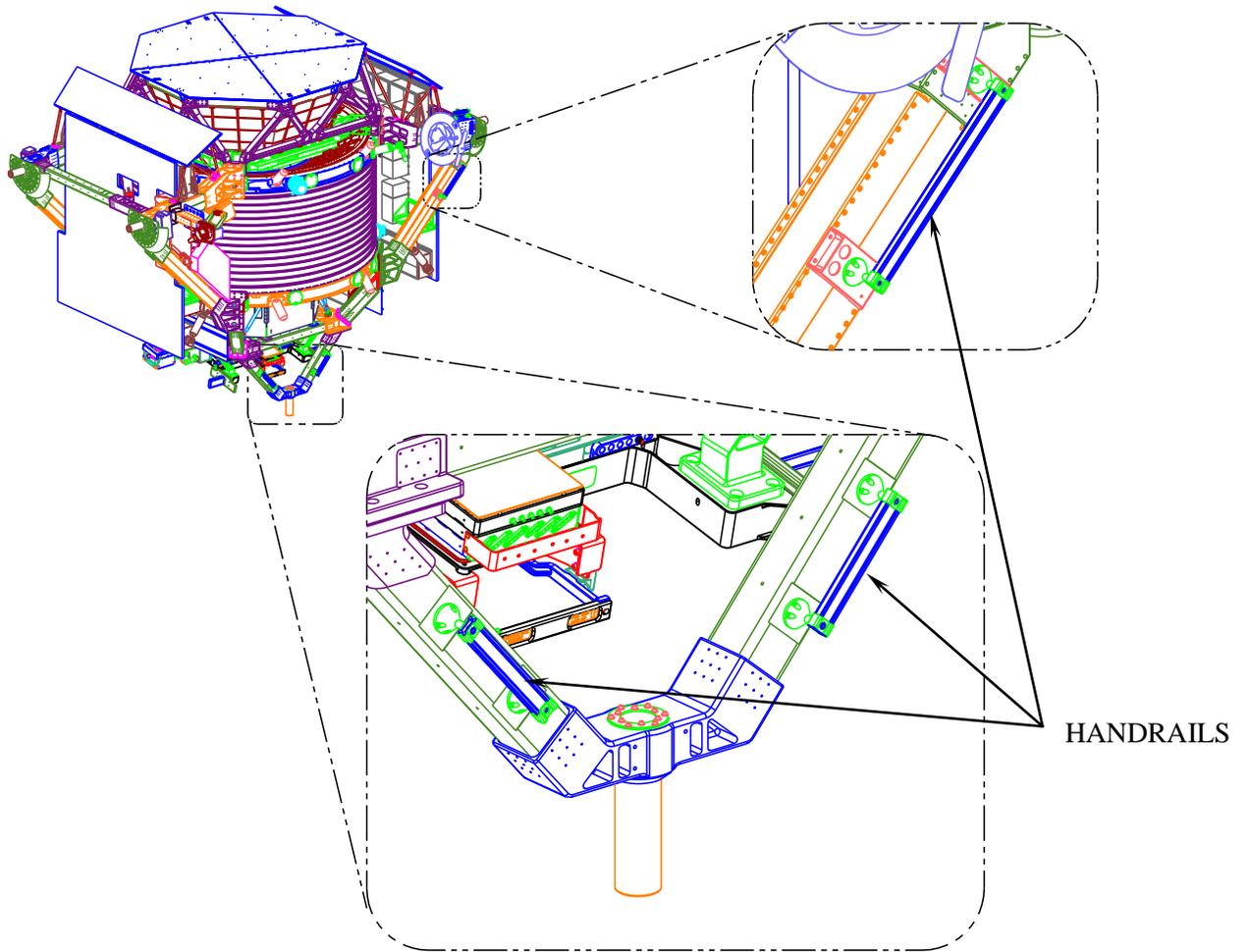


Figure 5.4-21 EVA Handrails for PAS Capture Bar Removal and FRGF Access

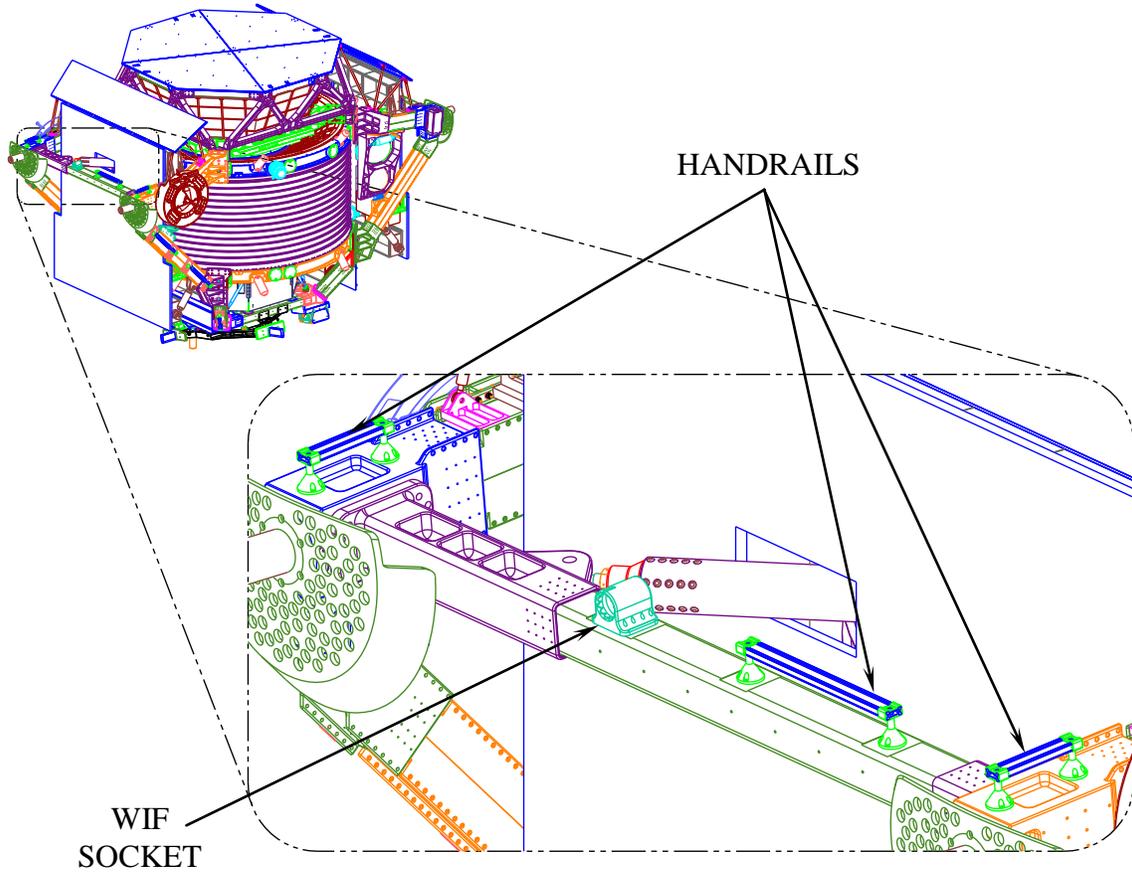


Figure 5.4-22 EVA Handrails Used for WIF Access

5.5 TRANSITION RADIATION DETECTOR (TRD) AND ASSOCIATED GAS SYSTEM

The role of the TRD (Figure 5.5.1-1) is to discriminate between electrons/anti-protons (e^-/p^-) and positrons/protons (e^+/p^+) over the Energy (E) range $E = 1 - 500$ GeV. This is accomplished by detecting X-ray photons emitted by highly energetic electrons and positrons when they pass through a radiator. For heavier particles such radiation is strongly reduced. The radiation is detected in tubes filled with Xe and CO₂ gas in an 80:20 ratio. Xenon gas ionizes very easily and is thus very sensitive to the passage of photons.

5.5.1 TRD Structure

The TRD detector is composed of 5248 proportional tubes which are made from a multi-layer wound composite structure. The composite includes layers of polyurethane, carbon-polyimide, aluminum, and Kapton (Figure 5.5.1-2). The straw tubes are grouped into 10 separate segments which are connected through active and passive gas manifolds. The straws have an inner diameter of 0.24 inch (6.02 mm), a wall thickness of 0.003 inches (72 microns), and vary in length from 31.5 inches (0.8m) to 78.7 inches (2.0m).

A straw module (Figure 5.5.1-3) consists of 16 straws glued together with 6 stiffeners running alongside the straws. Every 3.94 inches (10 cm), additional stiffeners are glued across the module for extra rigidity. The straw ends are glued into polycarbonate endpieces. The endpieces contain the wire fixation pieces (wire: gold plated tungsten, 0.001 inch (30 microns) diameter; wire fixation pieces (Cu/Te alloy)), the gas distributor, and the gas seal.

The TRD is constructed from 20 layers of the straw modules where a gap of 0.91 inch (23 mm) between the layers is filled with a radiator material (polypropylene fleece). The upper 4 layers (72 modules) and the lower 4 layers (56 modules) are oriented in the X-direction and the 12 middle layers (200 modules) in the Y-direction (Figures 5.5.1-4 and 5.5.1-5).

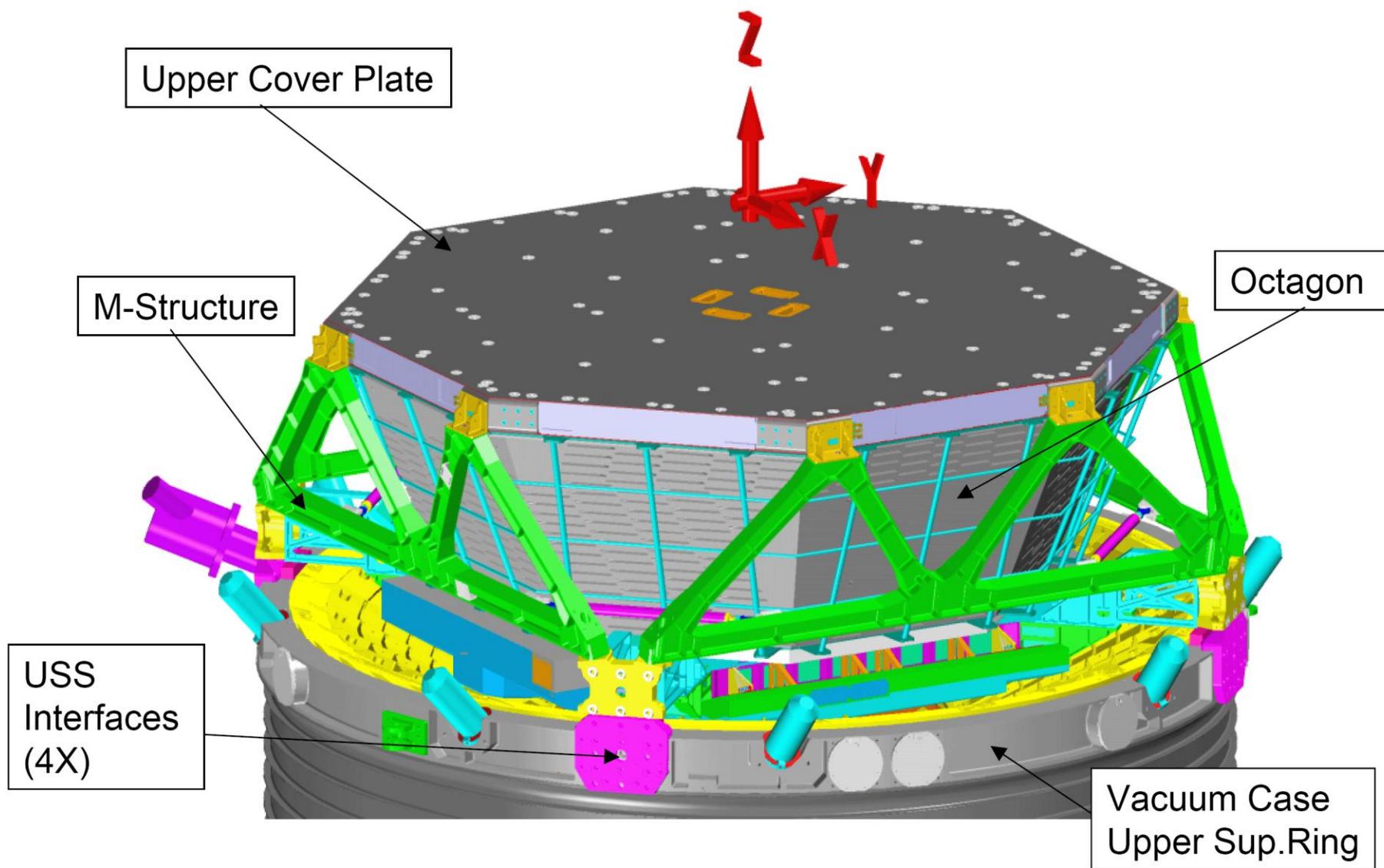


Figure 5.5.1-1 TRD Structure

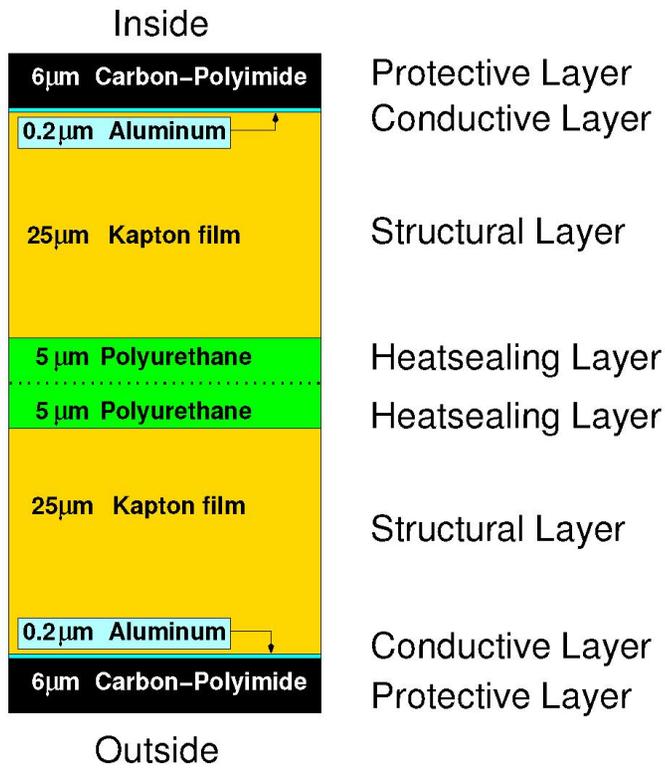


Figure 5.5.1-2 Composition of Straw Wall

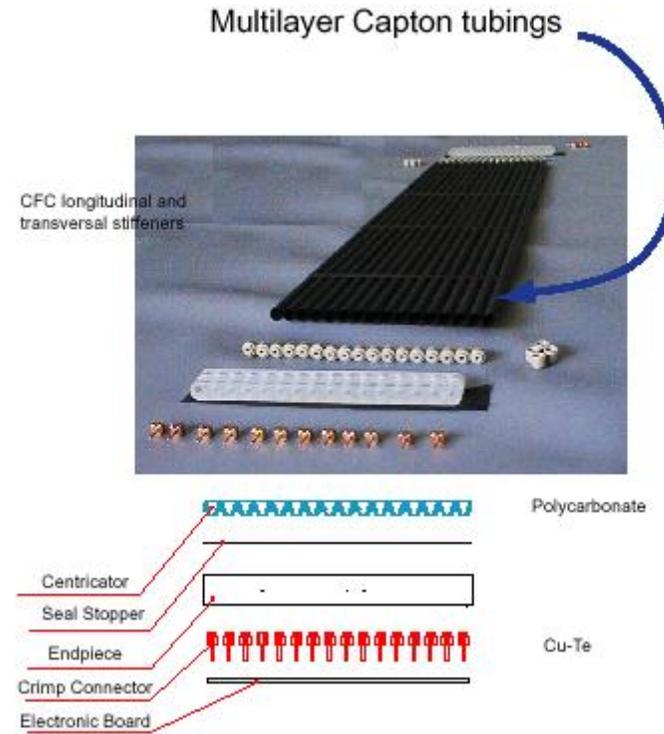
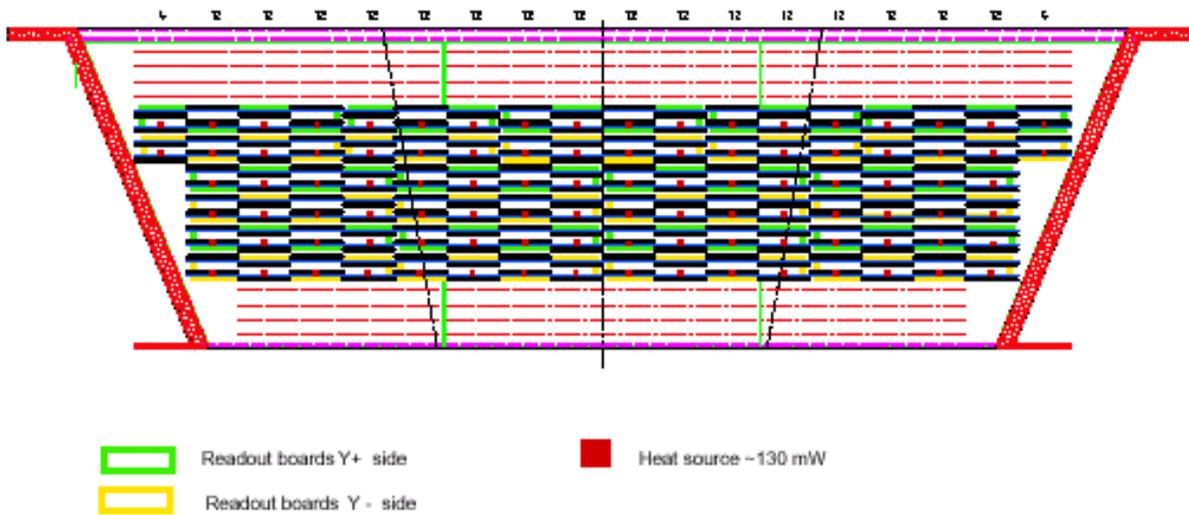
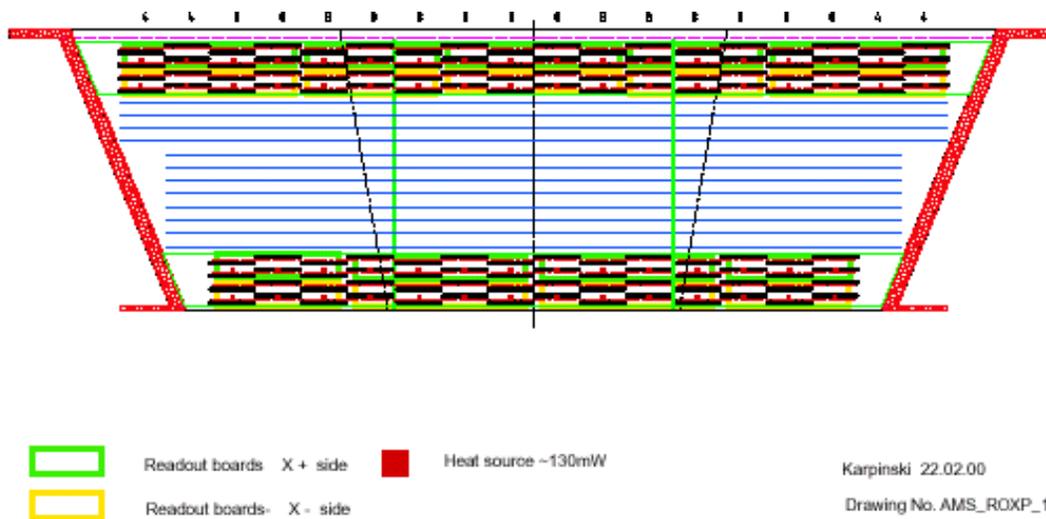


Figure 5.5.1-3 Straw Module Production



Karpinski 22.02.00
DRAWING No.: AMS_ROYP_10

Figure 5.5.1-4 TRD X-Z Cross Section



Karpinski 22.02.00
Drawing No. AMS_ROXP_10

Figure 5.5.1-5 TRD Y-Z Cross Section

The 20 layers of straw modules and radiators are mounted in an octagon structure which consists of 8 honeycomb side panels (1.18 inches (30 mm) thickness), a lower honeycomb support plate, and an upper honeycomb plate. The size of the octagon structure is 91 inches x 24.5 inches (height) (2.3 m x 0.6 m). The combined weight of the TRD is 728 lbs (330.4 kg). Inside the octagon structure, the straw modules are further supported by 6 bulkheads (0.1 inch (3 mm) thick), 2 in the Y-direction and 2 times 2 smaller ones in the X-direction (Figure 5.5.1-6).

The TRD is located at the top of the experiment stack above the Upper TOF. The Octagon Structure is supported by the M-Structure, which is mounted to the USS-02 at 4 locations, just above the vacuum case interface. The TRD corner joints are hard-mounted to the corner joints on the upper USS-02 (Figure 5.5.1-1).

The front-end readout electronics and the High Voltage (HV) distribution boards are mounted on special boards close to the straw module end pieces. The gas distribution system is also mounted close to the ends of the straw modules on the opposite side of the electronics.

The TRD M-Structure is equipped with resistive heaters to keep the TRD side panel temperatures above 0°C to assure gas tightness of the O-ring seals in the TRD gas tubing and allow switching of the manifold flipper valves at all times. Each of the redundant heater systems consists of four resistor heaters mounted on the M-structure and are wired in parallel to the PDS supplied 120VDC with a nominal power consumption of 70W.

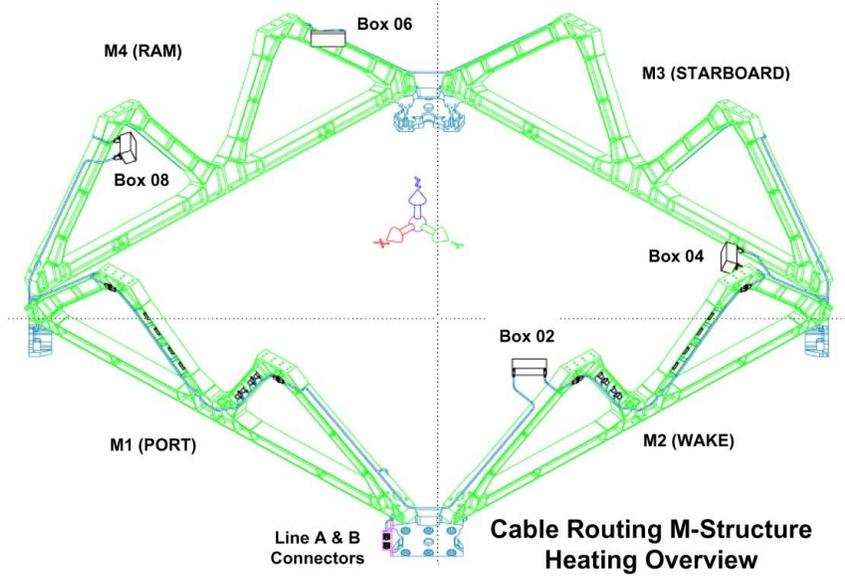


Figure 5.5.1-6 TRD M-Structure Heater Locations

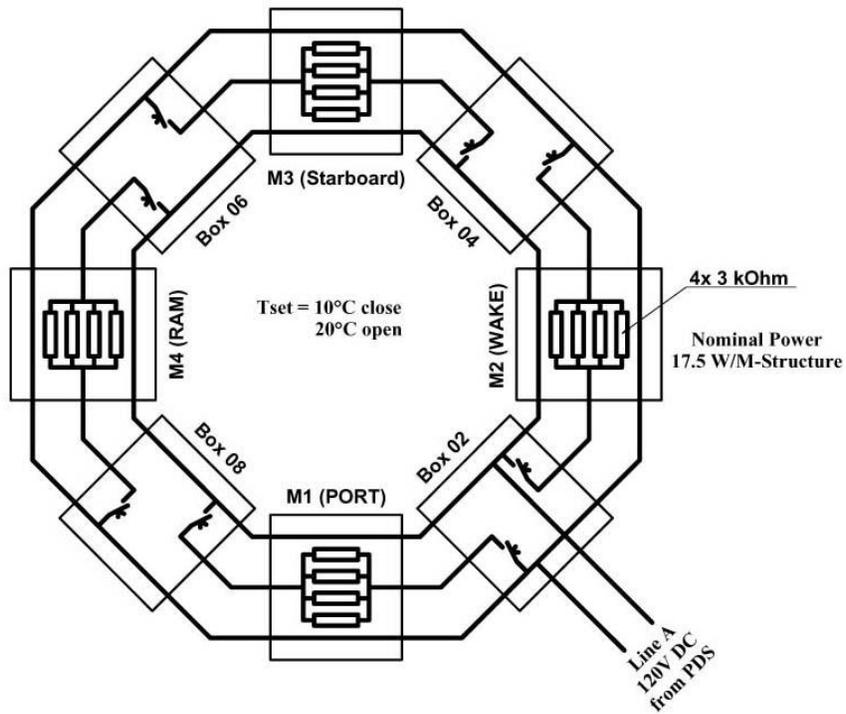


Figure 5.5.1-7 TRD M-Structure Heater Schematics

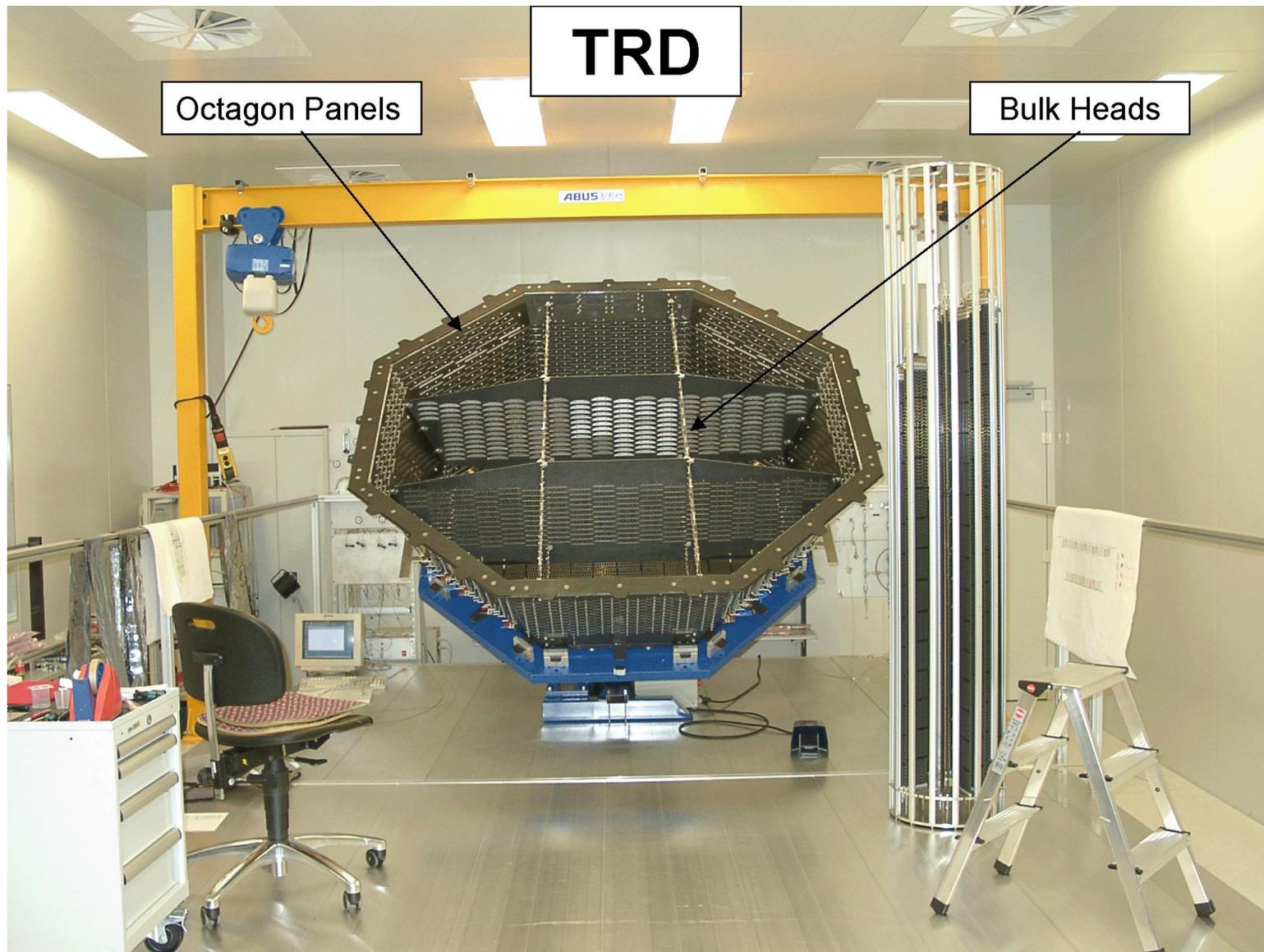


Figure 5.5.1-8 TRD Bulkheads Inside the Octagon (Full Scale TRD Mockup)



Figure 5.5.1-9 TRD Integrated Flight Module

5.5.2 TRD Gas Supply System

The TRD Gas Supply System supplies a mixture of 80% Xenon (Xe) and 20% Carbon Dioxide (CO₂). The density and purity of the gas mixture is monitored and adjusted to ensure efficient photon detection. The gas supply system includes three tanks, one for the Xe, one for the CO₂, and one mixing tank (Figures 5.5.2-1 and 5.5.2-2). These tanks are mounted to a support bracket and covered by shields to protect them from orbital debris. The support bracket is mounted to the wake side of the USS-02 (Figure 5.5.2-3), which also helps protect them from debris.

The Xe tank is a composite over-wrapped stainless steel tank that is designed and built by Arde, Inc. This tank is the same design as one that is used on the Plasma Contactor Unit for ISS. It has a maximum design pressure (MDP) of 3000 psid with a minimum temperature rating of -60°F and a maximum temperature rating of 150°F. The tank was designed with a minimum proof test factor of 1.5 x MDP and a minimum burst factor of 3.1 x MDP. It has an outside diameter of 15.4 inches (390 mm) and a volume of 1680 cubic inches (27.5 liters). It carries up to 109 lbs (49 Kg) of Xe at launch and has been tested to 8.9 G_{rms} at 0.08 g²/Hz.

The CO₂ tank is also a composite over-wrapped stainless steel tank designed and built by Arde, Inc. This tank was designed for use on the X-33 vehicle and also has a maximum design pressure of 3000 psid with a minimum operating temperature of -100°F and a maximum operating temperature of 300°F (tank rating, AMS-02 qualification requires 150°F). The tank is designed with a proof test factor of 1.6 x MDP and a minimum burst factor of 2.1 x MDP. The outside diameter is 12.4 inches (315 mm) and it has a volume of 813 cubic inches (13.3 liters). The tank weighs 9.5 lbs (4.3 kg) and it can hold a maximum of 12.1 lbs (5.5 kg) of CO₂. A vibration test has been performed to 8.9 G_{rms} at 0.08 g²/Hz axially and 4.5 G_{rms} at 0.02 g²/Hz laterally.

The small mixing tank will also be manufactured by Arde, Inc. It will have a nominal operating pressure of 200 psia, a normal operating temperature of 77°F and an MDP of 300 psid established by dual pressure relief devices and the source gas supply control. A

proof test factor of 2.0 x MDP and a minimum burst factor of 4.0 x MDP will be used. The volume will be 61 cubic inches (1 liter).

The fittings and connections in the gas system include stainless steel tubing, welded joints, and numerous gas manifolds. The stainless steel tubing will range from 0.06 - 0.25 inch (1.6 - 6 mm) outer diameter. Connections in the supply system and the circulation system are made with welded joints. The low pressure connection between the supply system and the circulation system is made with metal sealed fittings. The connections between the gas manifolds and the TRD segments are made with 0.05 inch (12 mm) inner diameter stainless steel tubing and brazed metal connectors.

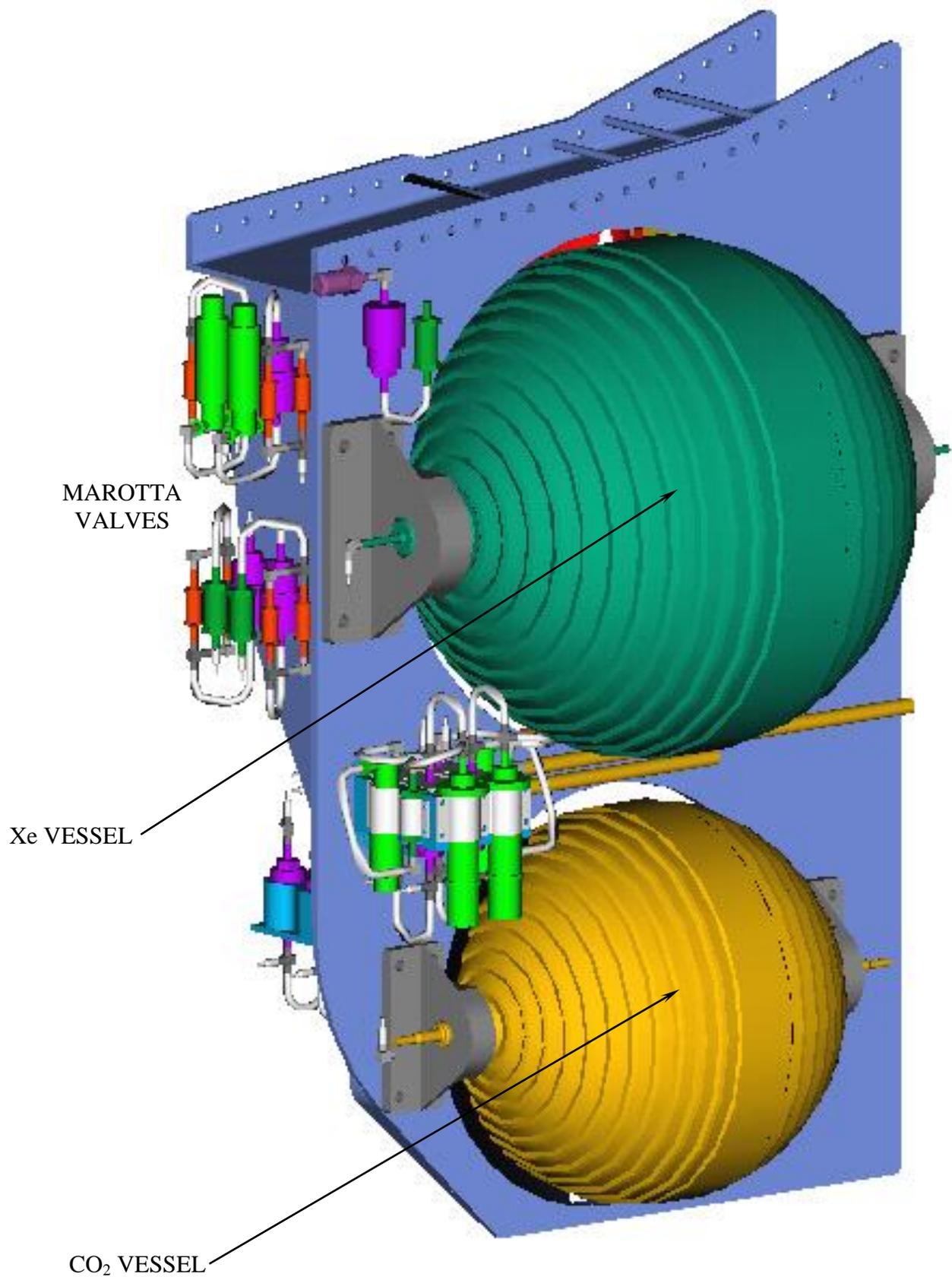


Figure 5.5.2-1 TRD Gas Supply System (Box S)

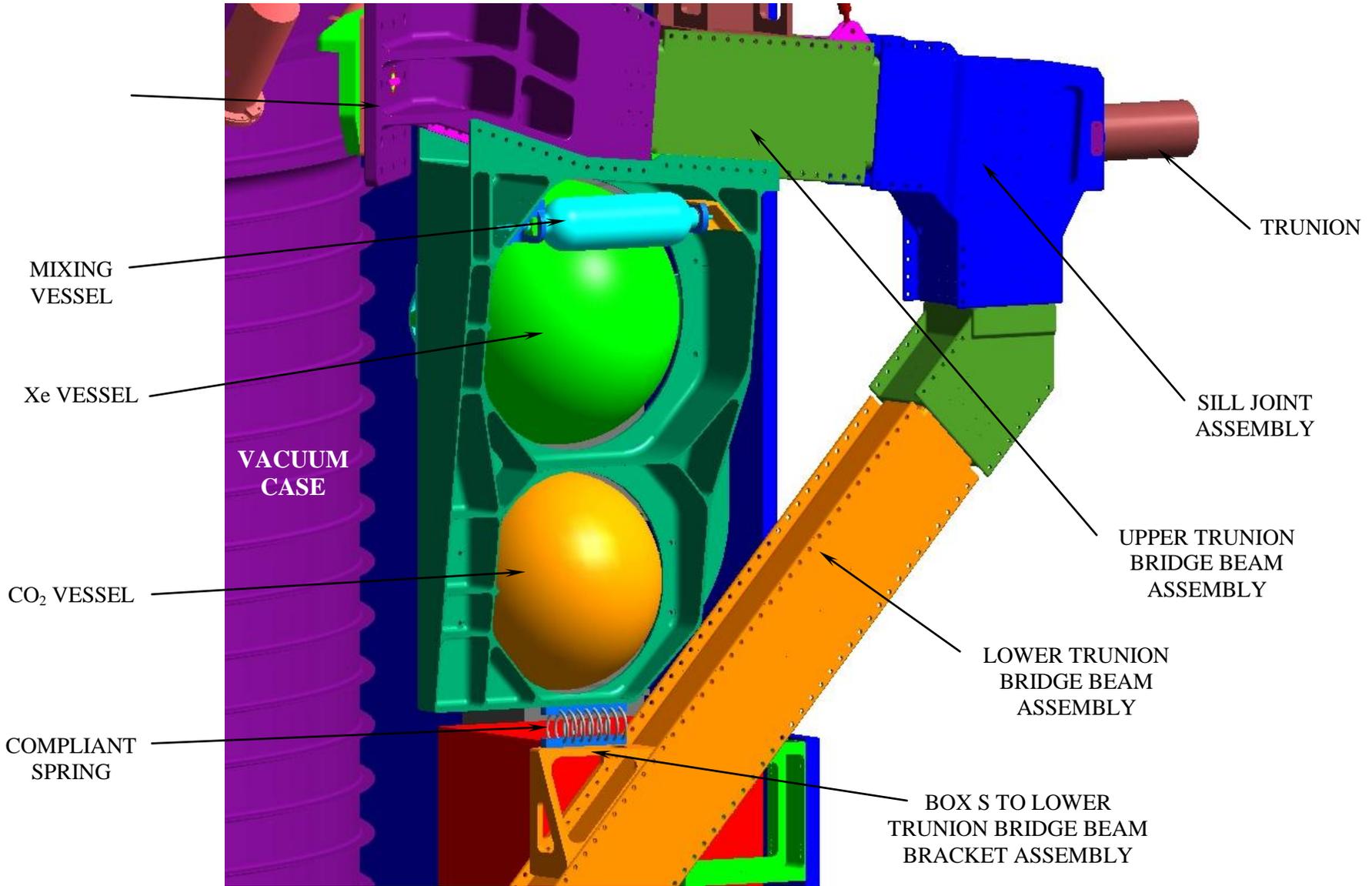


Figure 5.5.2-2 TRD Gas Supply System (Box S and Mixing Vessel) on the Upper USS-02 Structure (Wake Side – Port)

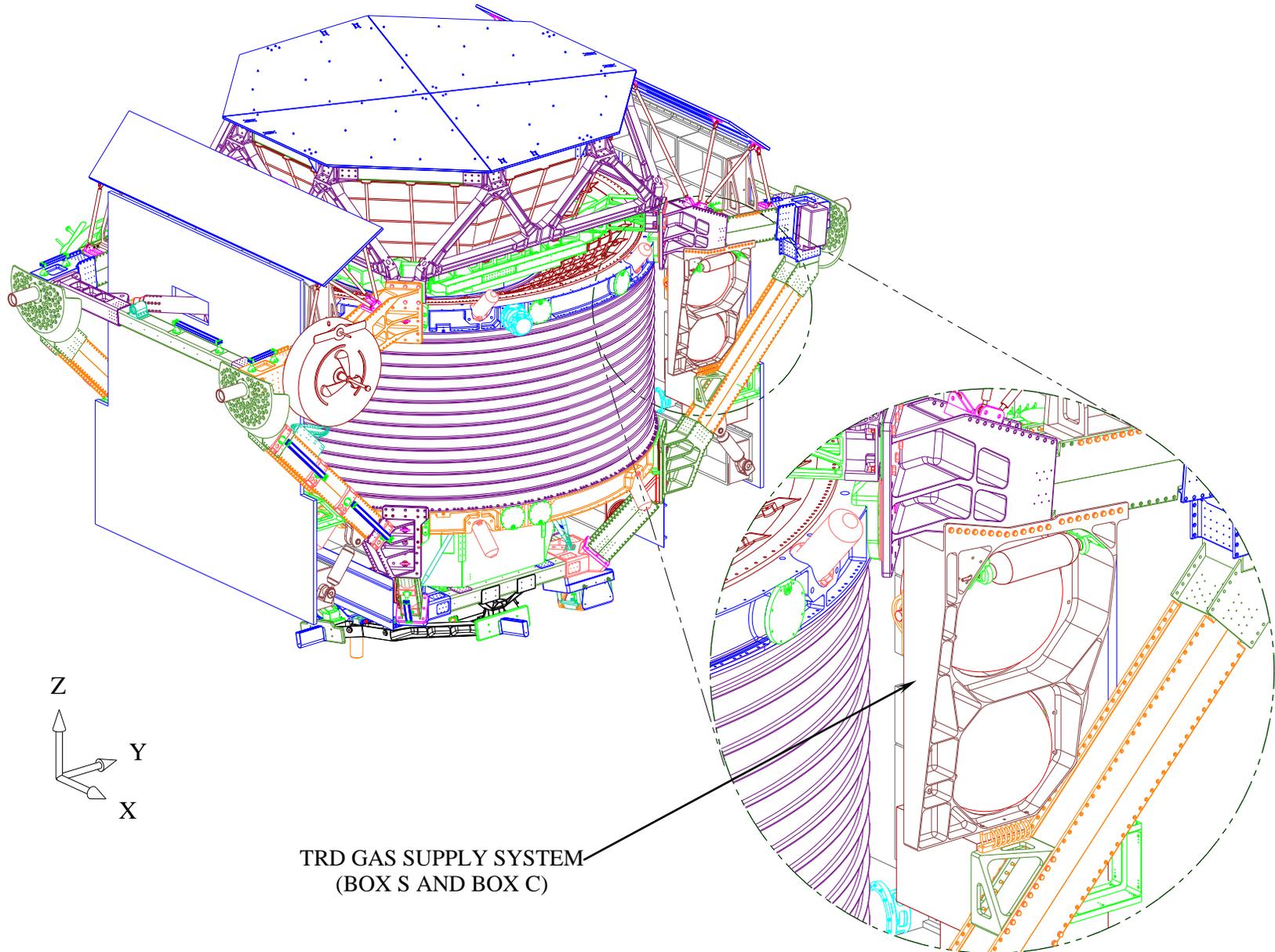


Figure 5.5.2-3 TRD Gas Supply System Mounted to the USS (Debris Shields Not Shown)

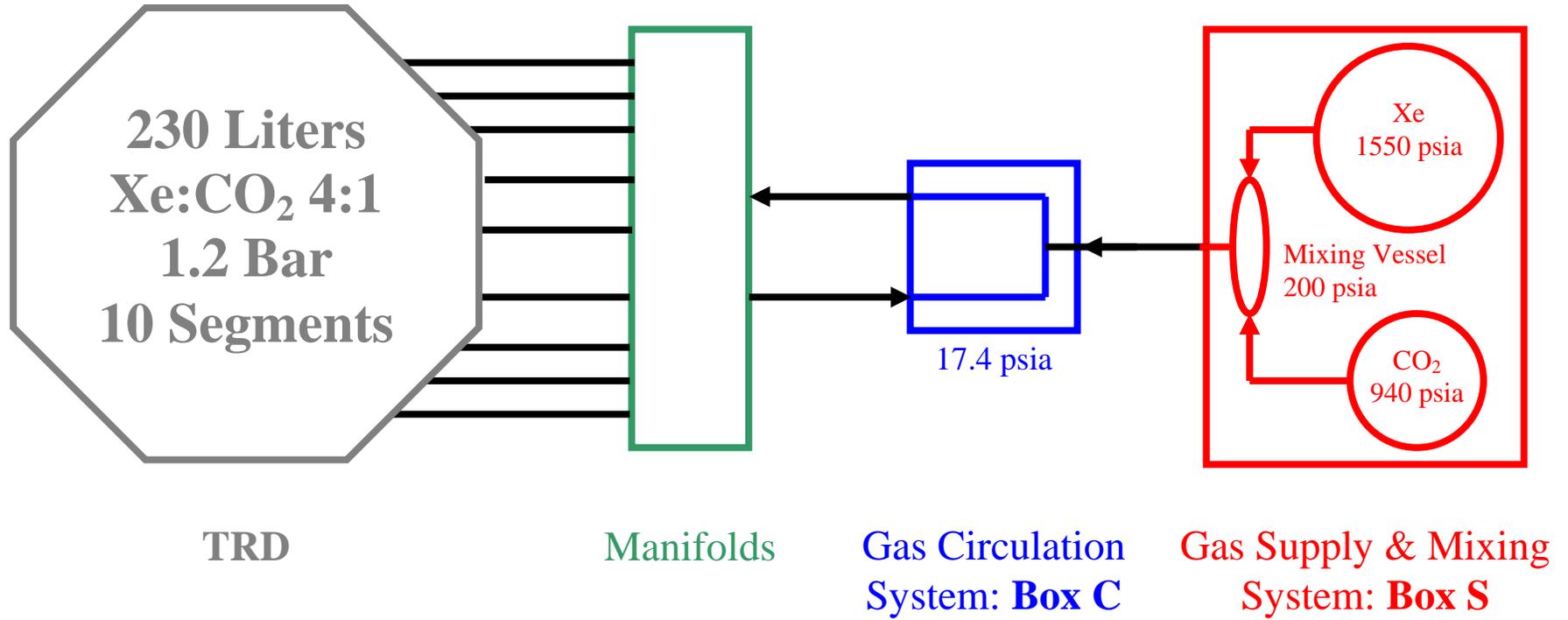


Figure 5.5.2-4 Schematic of the TRD Gas System [All pressures are at 77° F (25° C)]

The TRD straw tubes have a maximum design pressure of 29.4 psid. The minimum design temperature is 13.5°F and maximum design temperature is 105°F. Thermal/vacuum testing has been performed to verify these numbers. The relief valves will be set to 25 psia. The normal operating pressure is 11.6 to 17.4 psid on-orbit and 17.4 psid on the ground. The proof test factor of 1.5 x MDP will be employed and a minimum burst factor ≥ 2.0 x MDP will be employed. Each of the 10 separate segments contains 1200 - 1700 in³ (20-28 liters) of gas, for a total gas volume of 8.1 ft³ (0.23 m³). The nonflammable gas mixture is circulated through these tubes in a continuous loop. The density and purity of the gas mixture is monitored and corrected.

The 10 TRD segments are connected through active and passive manifolds to Box C, containing controls, monitors, and recirculation pumps. Box S provides Box C with pre-mixed gas from the gas supplies in a limited transfer volume (approximately 1 liter). A feed control between Box S and C is activated by computer when required (approximately once a week). The general layout is shown in Figure 5.5.2-4. The 10 sealed TRD segments of average 1400 in³. (23 liters) each are held at 17.4 psi. Box C has an estimated volume of 150 in³, held below 25 psi by relief valves.

During air transportation, ambient air pressure will drop during cruise and then rise back to standard sea level pressure upon landing. If the internal pressure within the straw tubes falls below atmospheric, the potential exists for structural damage to the tubes. To prevent this, a small ride-along tank will be attached to the ground handling and shipping fixtures to provide a constant source of 1.05 bar gas to the tubes. This tank will be removed prior to launch and the low pressure port will be capped.

5.5.3 Box S Description

Box S, shown in Figure 5.5.3-1, contains the gas reserves for the TRD. Gas is released from the two reservoirs into the mixing vessel (D), where it is combined in the required ratio and stored until such time as the straw tubes need to be refilled. Once needed, the combined gas is transferred to Box C for circulation.

The straw tubes are measured to lose approximately 0.25 liters of gas per week. At that rate, the mixing operation should take place once per week. For Xenon, valve V1a is

opened for 1 second, releasing gas into the 15 cc buffer volume between V1a and V2a. To avoid entrapping liquid gas in the buffer volume, the gas passes through a Pre-Heater of three times the buffer volume, and a thermal interlock is implemented in the firmware of the Slow Control Module (USCM) such that V1a can only be actuated to open, if the Pre-Heater temperature is measured to at least 91.4 °F (33 °C) in the 5 minutes before the open command. After V1a is closed, V2a is opened for 1 sec, releasing gas into the 60 cc buffer volume between V2a and V3a. After V2a is closed V3a is opened for 30 seconds transferring the small amount of pressurized gas from the 60 cc buffer volume into the 1 liter mixing vessel. By use of two buffered volumes at a gradual, controlled step down of pressure is achieved. The release of gas through this three stage (areas) process (called one cycle) occurs several times until the required quantity of Xenon gas is in the 1 liter mixing volume. Similarly CO₂ is released in the same three-stage (using the “b” indices for the “a”) into the 1 liter mixing volume.

Valves V3a or V3b are always closed at the end of the cycle and the gases are allowed to settle for 3 minutes to measure the pressure increase and to ensure good mixing. After the gases reach the correct quantity in the 1 liter vessel, and settled for at least 10 minutes, valves V4a can be opened to allow the gas to flow into Box C.

Box S Schematic

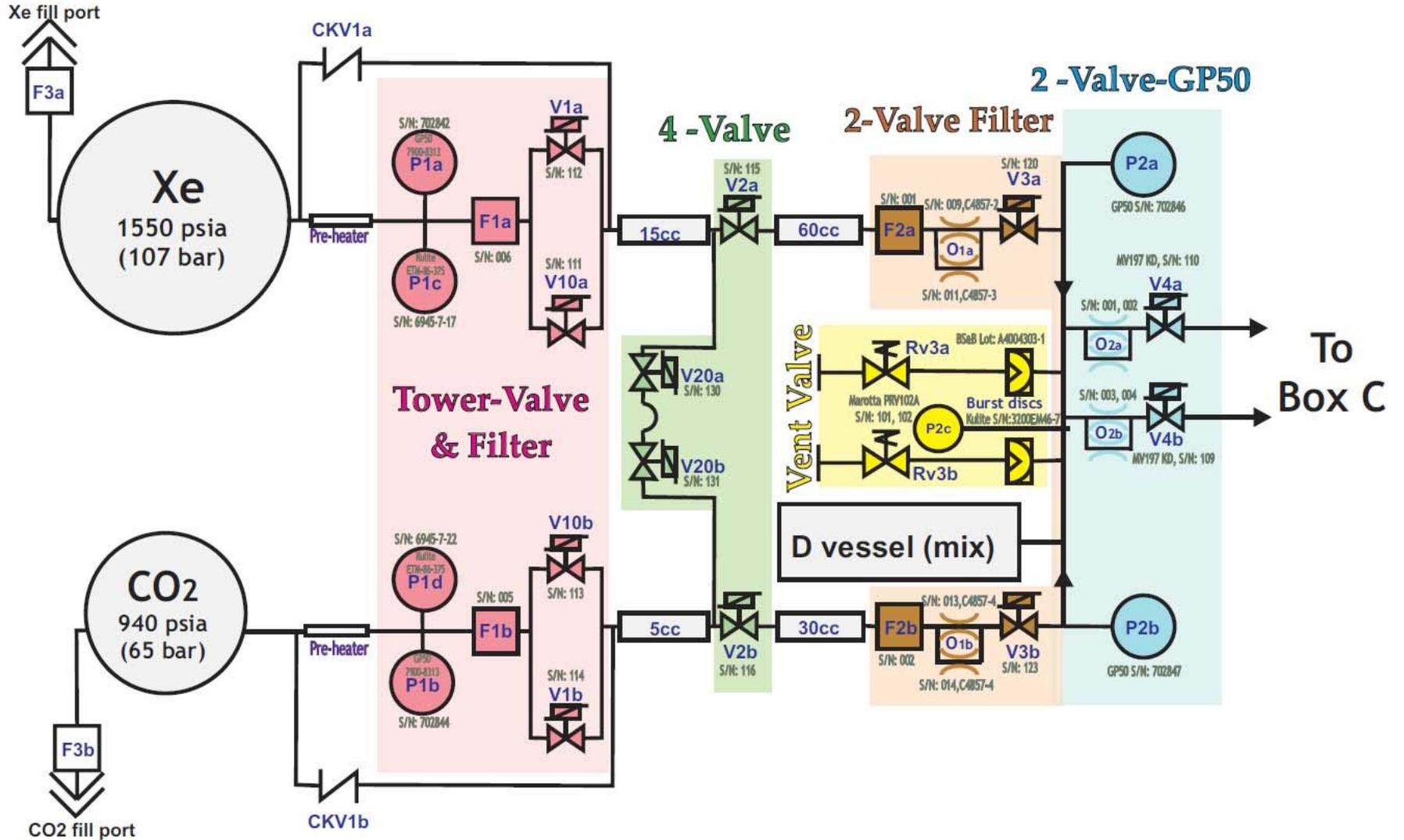


Figure 5.5.3-1 Box S TRD Gas Supply Detailed Schematic [PV pressures are at 77° F (25° C) with a nominal fill level]

The reservoirs are filled through the GSE fill ports equipped with recoil check valves. Valves V1a (V10a) and V1b (V10b) are closed (all Marotta MV 197 and MV100 valves are normally closed unless energized) and each tank is filled from a ground source. Temperature and pressure are then monitored for four hours. If performance is as desired, then the fill ports are capped with metal seals (2).

Several redundant valves have been included in the system to reduce the risk of mission failure, but are not required for safety:

- Valves V10a and V10b provide a secondary path from the reservoir to the first buffer volume in case of failure in valves V1a and V1b, respectively. (Each valve has Pre-Heaters and thermal interlocks are implemented.)
- Valves V20a and V20b provide a channel between the two reservoirs and the two sets of buffer volumes. If one of the valves V2a, V2b, V3a, or V3b were to fail closed, this allows each reservoir access to the buffer volumes on the opposite side.
- Flow restrictor O2b and valve V4b allow for a redundant path into Box C.

During launch and landing, all valves are closed and the mixing vessel will be at 1.2 bar. All pressure and temperature sensors will be monitored from the ground as long as possible prior to launch. There are no planned go-no go launch restrictions for this monitored value. Temperature sensors will also be monitored during all transfer and berthing operations by the global temperature network.

Maximum design pressure for the gas reservoirs, the buffer volumes, and the associated piping through valves V3a and V3b have been determined through thermal analysis and all items have been shown to have sufficient structural margin. MDP of the mixing vessel and all plumbing between V3a/V3b and V4a/V4b is set at 300 psi based on the redundant burst disks shown in Figure 5.5.3-1. This hardware has also been shown to have adequate margin through structural analysis.

5.5.4 Box C Description

Box C, shown in Figure 5.5.4-1, contains the pumps for the primary TRD gas circuit. By causing the gas to flow continuously throughout each of the TRD's 10 gas segments, the gas is not able to separate into pockets and uniform properties are ensured. Box C is

mounted on the USS-02 just above the main TRD Gas Supply, as shown in Figure 5.5.4-2.

Newly mixed gas from Box S arrives in Box C through valve V6a, where it merges with the gas circulating through the TRD. Gas coming out of the manifolds enters the canister, where two KNF Neuberger UNMP30 pumps provide the circulation through the system. These pumps operate in the open environment of the canister shown in Figure 5.5.4-1, with only one side of the pump connected directly to the plumbing. Only one pump is needed – a redundant pump is included for mission success purposes. Inside the Canister the gas flows through an ultrasonic spirometer, which measures the CO₂ content in the gas flow to check the Xe/CO₂ ratio. The gas then flows back into the manifolds and re-enters the straw tubes.

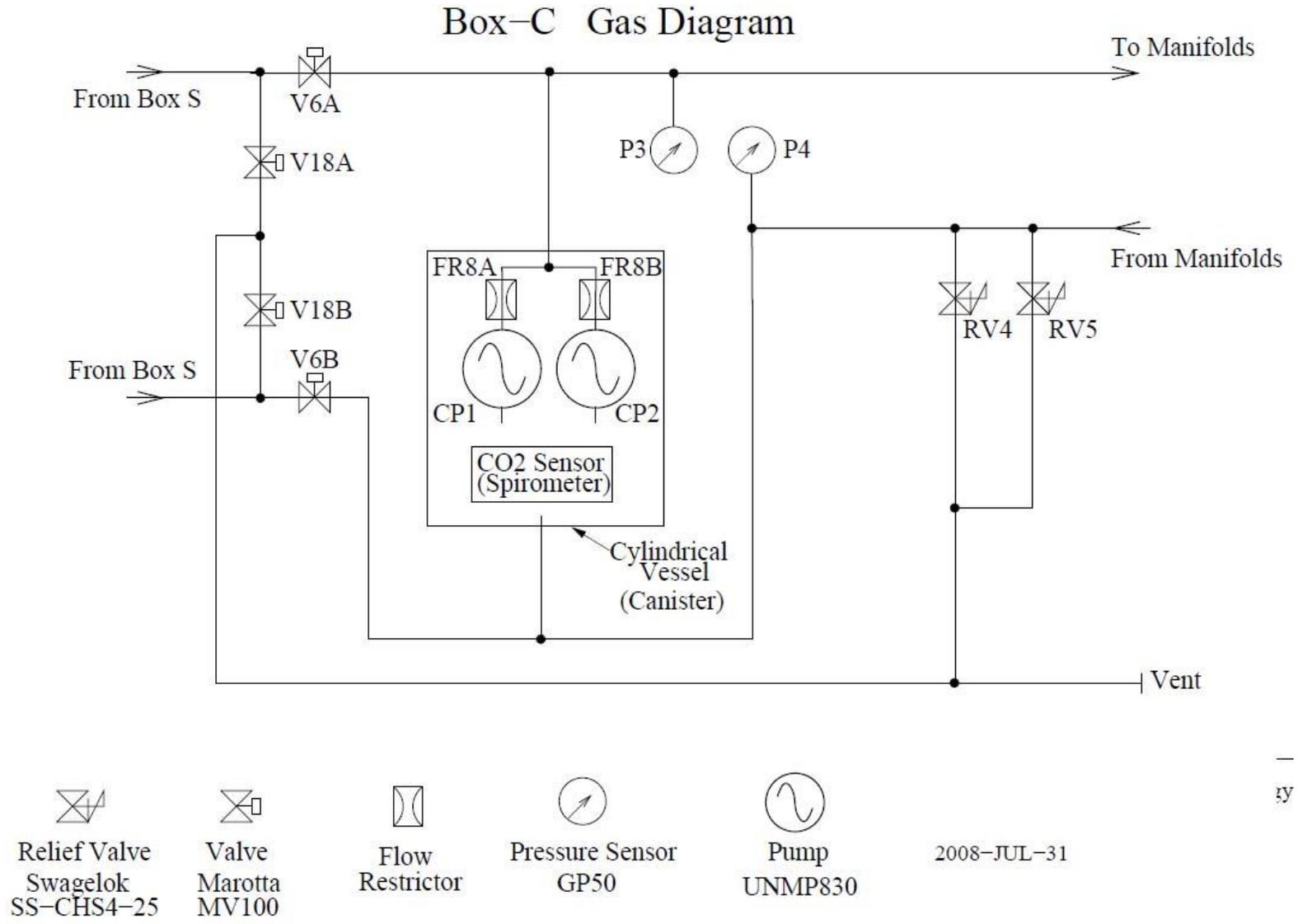


Figure 5.5.4-1 Box C TRD Gas Circulation System

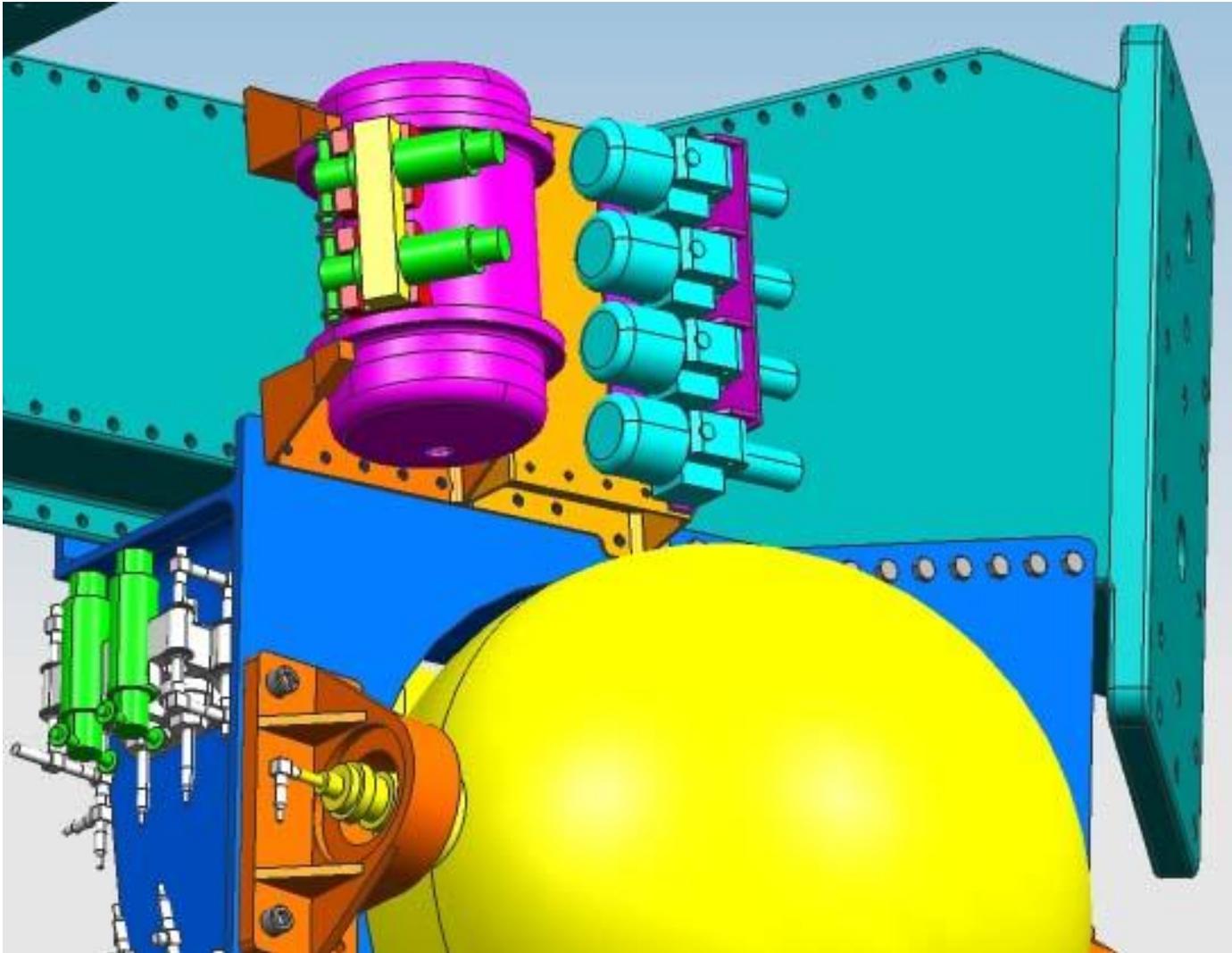


Figure 5.5.4-2 TRD Gas Circulation System (Box C) Mounted to the USS

As with Box S, several redundant valves have been included in the system to reduce the risk of mission failure, but are not required for safety:

- Valve V6b pairs with valve V4b in Box S and allows a redundant entry point for incoming gas.
- Valves V18a and V18b allow gas to be purged to space through a zero thrust vent in the case of incorrect gas mixing or contamination.

Note that flow restrictor FR8a and FR8b are used to restrict backflow through a pump where both internal check valves fail during ground filling operations.

5.5.5 Straw Tube Segments

From Box C, 3 mm stainless steel gas lines run to the top rim of the TRD, where input and output manifolds are located. The 5248 tubes of the TRD are grouped into 41 gas groups, each connecting eight modules with 16 straws in series. Nine of the ten passive manifolds connect four gas groups and one passive manifold connects five gas groups in parallel to form ten TRD gas segments, each separately attached to the active input and output manifolds. (Figure 5.5.5-1). Each segment is small enough so as not to be considered a pressure vessel ($1 \text{ bar} \times 28 \text{ liters} = 2.8 \text{ kJ}$). Each of the 10 TRD gas segments the manifolds utilizes computer controlled isolation valves. 0.06 inch (1.6 mm) steel tubing runs from the isolation valves to the passive gas distribution manifolds and from there to the segment inputs and outputs, where it is joined to the straws via RWTH Aachen designed special connectors. Where other connections need to be made, Cajon VCR fittings are used. Figure 5.5.5-2 shows the locations of the gas manifolds and the input and output connections to the straw modules (one of 41 gas-groups shown).

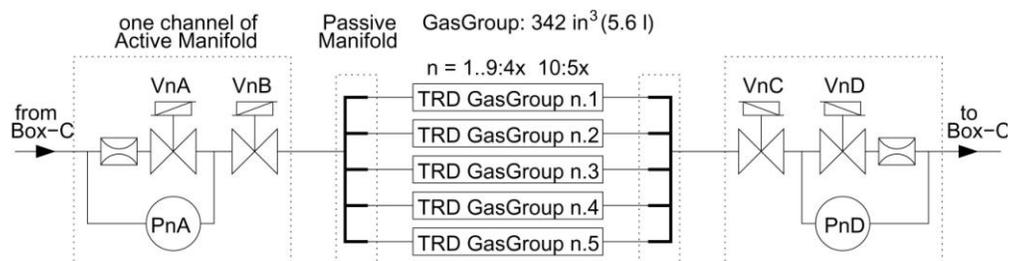


Figure 5.5.5-1 One of 10 TRD Straw Tube Segments

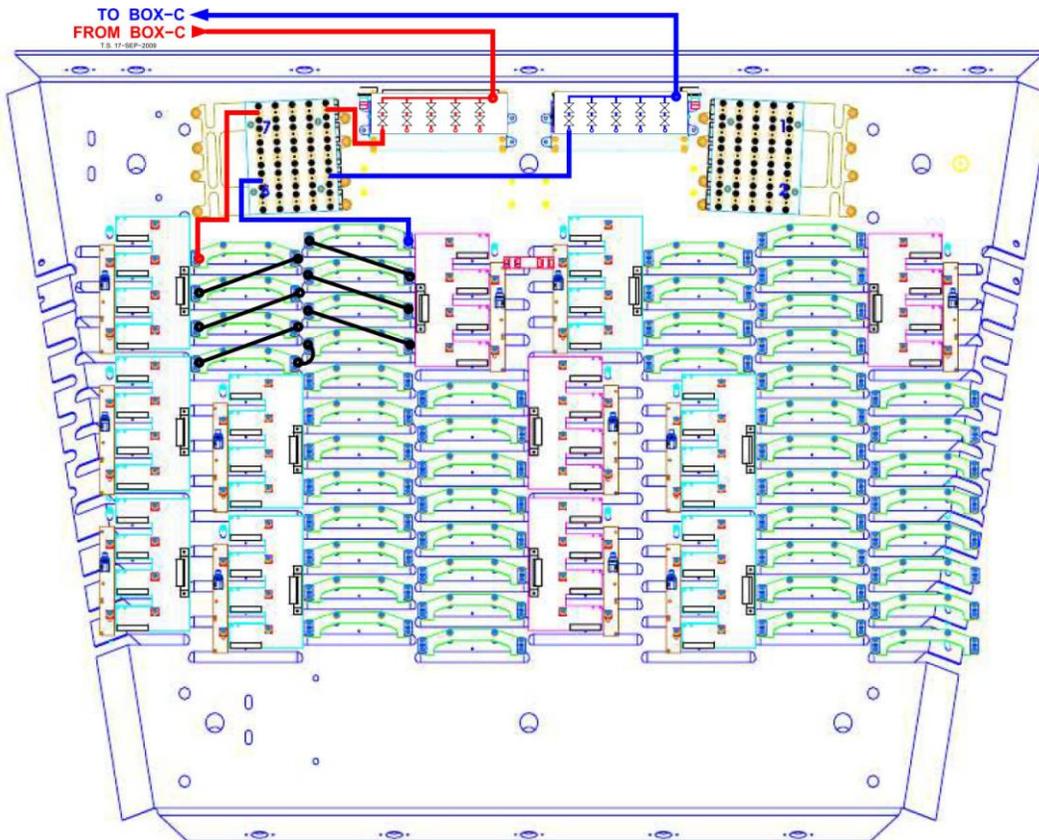


Figure 5.5.5-2 Gas Manifold Connections to TRD Segments

The isolation system is designed to protect the TRD against gas loss in order to maximize efficiency. Leakage of the Xe/CO₂ gas cannot produce a safety hazard, but can cause the gas supply to be used at a faster rate than anticipated and reduce the operational life of the TRD. The system works in two modes. In case of a sudden pressure drop in a segment, the control computer will close all four valves leading to the segment automatically to prevent further gas loss. In case of an increase in gas consumption, or as a periodic check, the computer will close two valves and monitor the differential pressure P_A and P_B . This will be used to detect slow leaks. Failure of any of the shutoff valves or pressure sensors cannot cause MDP to be exceeded.

The shutoff valve/pressure sensor assembly will be potted inside a magnetic shielding box to preclude any leak from the gas system volume. The isolation valves will be Burkert Type 6124 2/2 Way Flipper Valves. Closed, they hold 43.6 psi (3 bar) in either direction and have been leak tested to better than 1 ml/day loss, 14.5 psi (1 bar) to

vacuum through a closed valve. They can be flipped from open to closed and vice-versa by a 12V, 50 ms pulse, and otherwise consume no power. They are located near the top flange of the TRD in a region of low magnetic field. The pressure sensors are Honeywell type 24PC.

5.5.6 Monitoring and Control

The electronics that control the gas system will be located in the UG-crate. This crate will contain a Universal Slow Control Module (USCM) computer that will manage the monitoring and control tasks, as well as maintain communication with the AMS-02 Main DAQ Computer (JMDC). The USCM will be provided with interface electronics to the various gas transducers and actuators distributed throughout the gas system. The USCM and interface electronics will perform the following tasks:

1. Close or open emergency isolation valves in the manifolds.
2. Provide housekeeping data (temperature of valves, pressure vessels, etc.)
3. Store calibration constants.
4. Condition and perform analog to digital conversion for 29 pressure sensors and approximately 500 temperature sensors distributed around the TRD and gas system.
5. Control two recirculation pumps.
6. Provide logic control for approximately 56 gas valves.
7. The interface electronics will provide the power electronics to drive valves, etc.
8. Read out digital signals from the gas analyzer (spirometer).
9. Have control logic to switch the gas system to “Safe Mode” (for mission success) in case of communication failure.

The USCM, interface electronics are doubled to provide single fault tolerance for mission success. The USCM does not require or use batteries. If there is a power failure, the pumps stop, and all the Marotta valves close (they require power and special authorization to open). This ensures that the Xe and CO₂ gas tanks are sealed, and that no gas is transferred, either within Box S (e.g. to the mixing tank or other sealed volumes), or from Box S to Box C and the rest of the gas system. All mechanical safety release valves, for overpressure, remain operational. All of the flipper valves, which are used to isolate individual sectors of the gas system in case of leak, remain in whatever

state they were when power went off. This means that, on-orbit, if there is a leak in a sector which develops in the TRD when power is off, the worst that would happen is the loss of the approximately 230 liters of gas in the TRD over a period of 5 hours, which is small compared to the 10,000 liters of gas in the Xe and CO₂ tanks. Any sector previously isolated because of a leak will remain isolated. On the ground, a leak with power off would slowly contaminate the gas in the TRD with air so that it would not work well when power was switched on again, but would have no safety impact.

The TRD HV system consists of HV generation cards (UHVG). Six each are located in the two U crates to provide the HV for 82 TRD straw tube HV channels. They are monitored by the U crate interface cards. Each UHVG card drives 7 HV lines with twofold internal redundancy to provide single fault tolerance for mission success. Each line is connected via shielded HV cabling to a HV distribution board (UHVD) mounted on the octagon in the vicinity of the readout cards to distribute the HV to 4 modules (64 tubes). The schematic of the HV system is shown in Figures 5.5.6-1 and 5.5.6-2. Each unit provides +1600V (control range: 700-1750V) with current limited to <100 microamps.

TRD High Voltage

2 Redundant

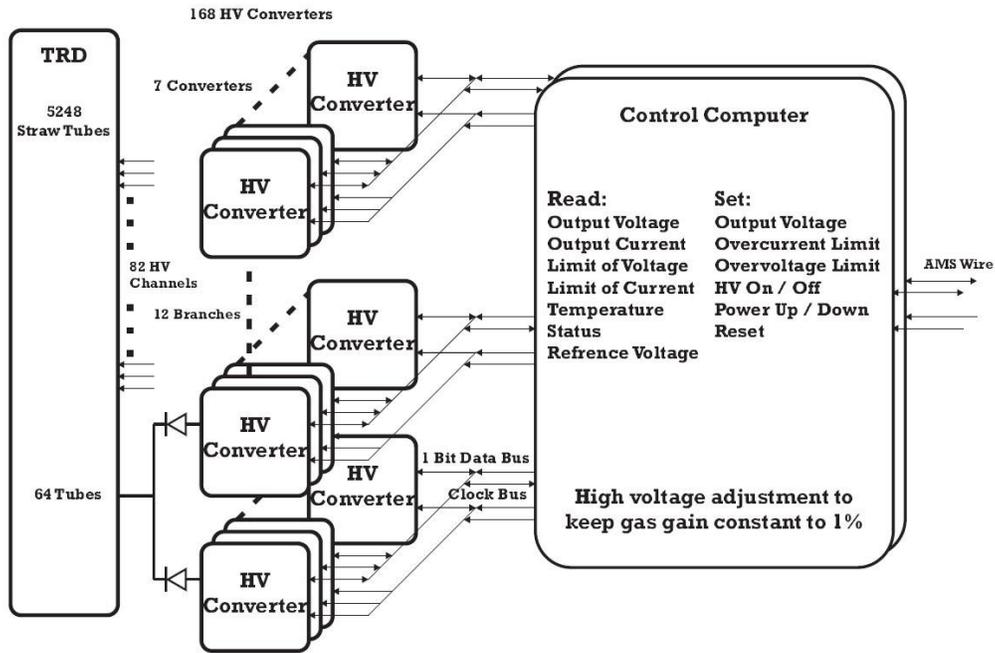


Figure 5.5.6-1 TRD High Voltage System

High Voltage Converter

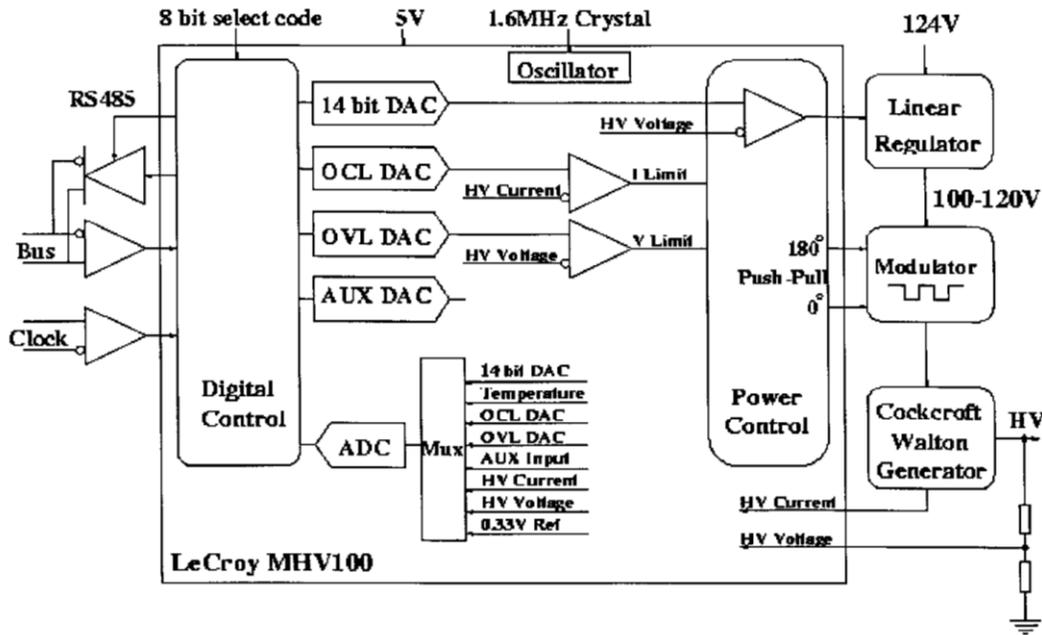


Figure 5.5.6-2 High Voltage Converter

5.6 TIME-OF-FLIGHT (TOF) SCINTILLATOR COUNTERS

The TOF serves a) as the fast trigger for the experiment when a particle crosses the bore of Permanent Magnet and Silicon Tracker, b) to measure the particles traversing the detector to a resolution sufficient to distinguish between upward and downward traveling particles and c) measure the absolute charge of the particle.

The TOF is composed of four planes of detectors, two atop the AMS tracker core, two below as shown in Figure 5.6-1. Numbered from the top down, detector assemblies 1, 2 and 4 have eight detector paddles per plane and detector assembly 3 has ten. The pairs of detector assemblies are oriented 90° to each other, shown in Figure 5.6-2. This configuration gives a 12 x 12 cm² resolution for triggering particle events over the 1.2 m² area the TOF covers. Each plane is contained inside a vented carbon fiber box.

Charged particles that pass through the scintillators generate photons that are collected at the two ends of each counter paddle, this is accomplished by special light guides directing the photons to the photomultiplier tubes (PMT). The light guides are situated at either end of the paddles for reasons of redundancy.

Each individual detector paddle is made of polyvinyl toluene (a Plexiglas-like material) that is 12 cm wide and 1 cm thick. Each detector paddle is enclosed in a cover made of carbon fiber. As shown in Figure 5.6-3, detector paddle enclosures are open at the ends and no longer requires special venting pipe as flown on AMS-01. At the ends of each panel are Lucite light guides which direct the light of scintillation to photo multipliers. These light guides are curved to orient the photomultiplier tubes within the AMS-02 magnetic field for minimum impact to photomultiplier operations. These complex curves can be seen in Figure 5.6-3 and 5.6-6.

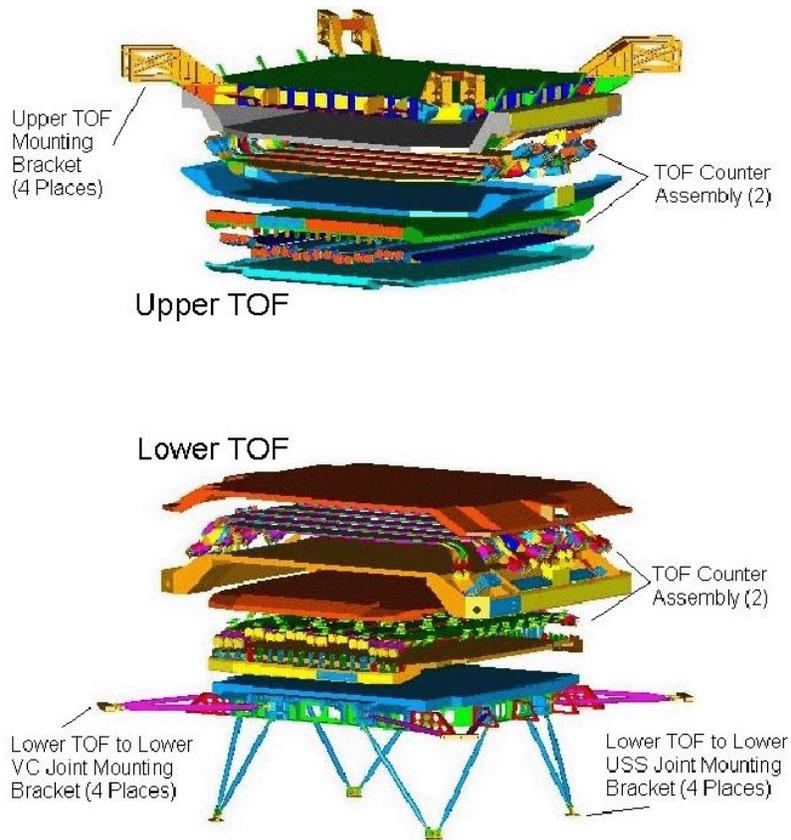


Figure 5.6-1 Time of Flight Counter Construction

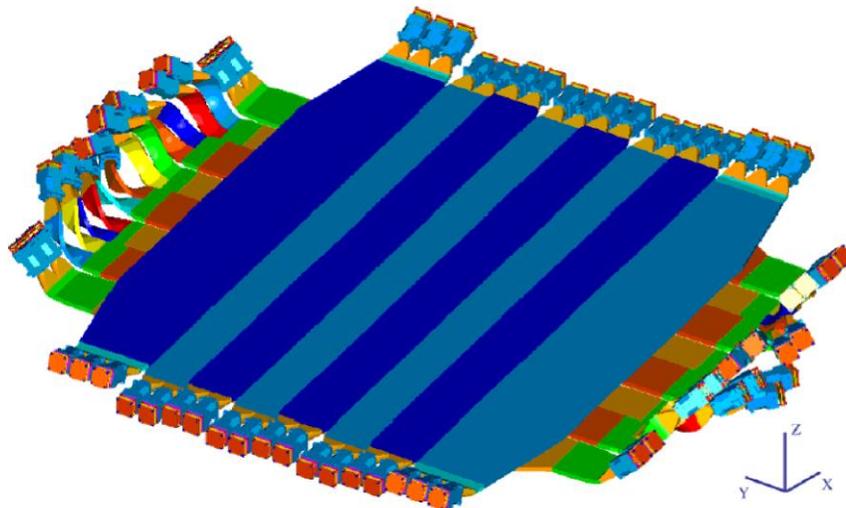


Figure 5.6-2 TOF Detector Paddles Orientation

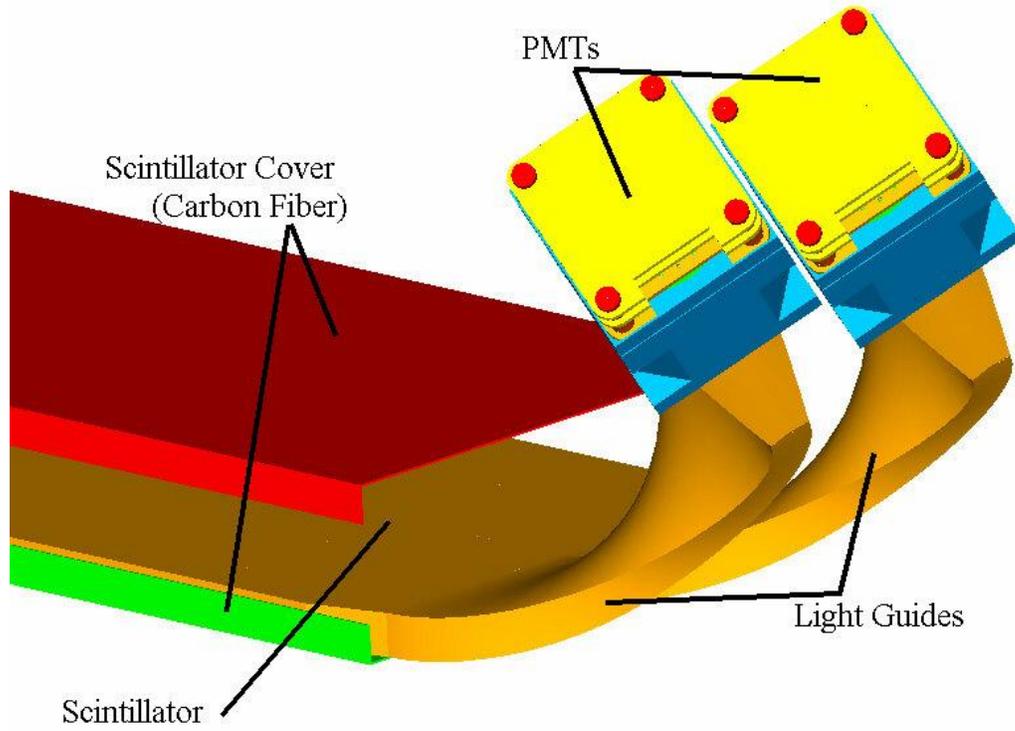


Figure 5.6-3 TOF Detector Paddle Construction

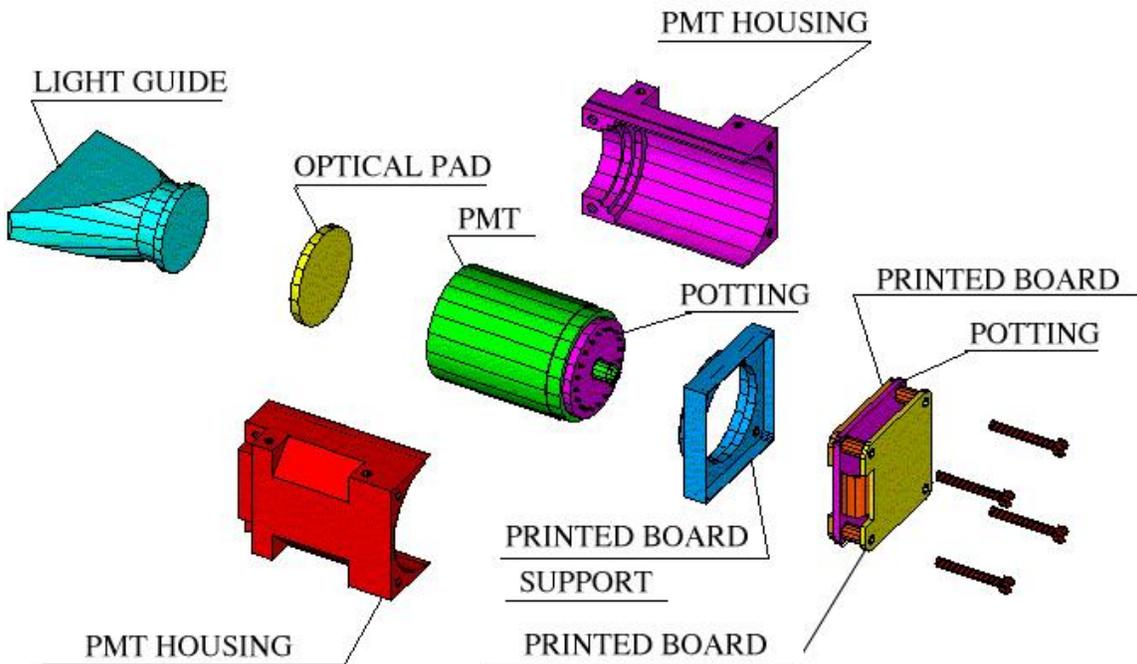


Figure 5.6-4 TOF PMT Exploded View

The TOF is instrumented with 144 Hamamatsu R5946 photomultipliers, used to detect the scintillating light. The PMT operated with a 1700-2300 Vdc voltage that is supplied by the SHV Crates. Each plane has two printed circuit boards that provide the high voltage sources for the detectors. The design of the TOF has considered the potential of discharge of high voltages at low atmospheric pressures and has implemented potting and coating of the PMT and high voltage interfaces. Access to the insulated and potted high voltage sources by an EVA crewmember is restricted as the TOF are under thermal blankets/MLI. The output from the PMTs on each end of the TOF detectors are summed to provide the necessary triggering signal that is provided to the four S Crates for data processing.

The Hamamatsu R5946 PMT is potted in place within a PMT housing, shown in Figures 5.6-4 and 5.6-5, made of black polycarbonate. The PMT is pressed into the light guides with an optical pad assuring optical transmission and providing a containment plane for the PMT tube itself.

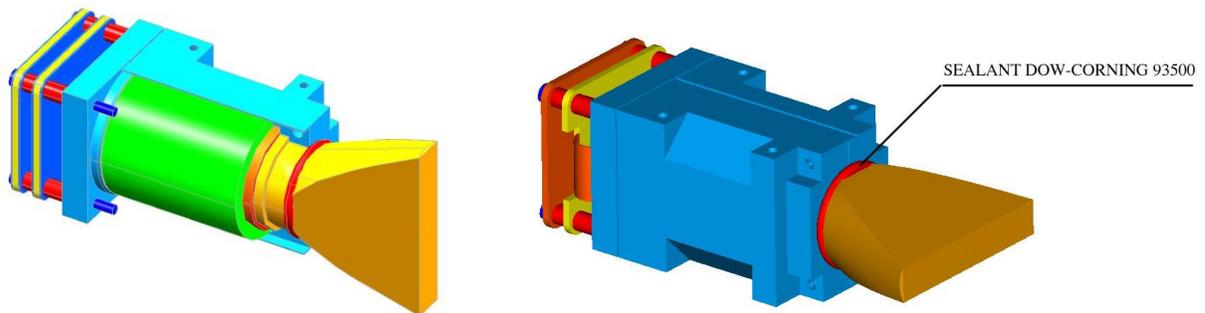


Figure 5.6-5 TOF PMT Construction

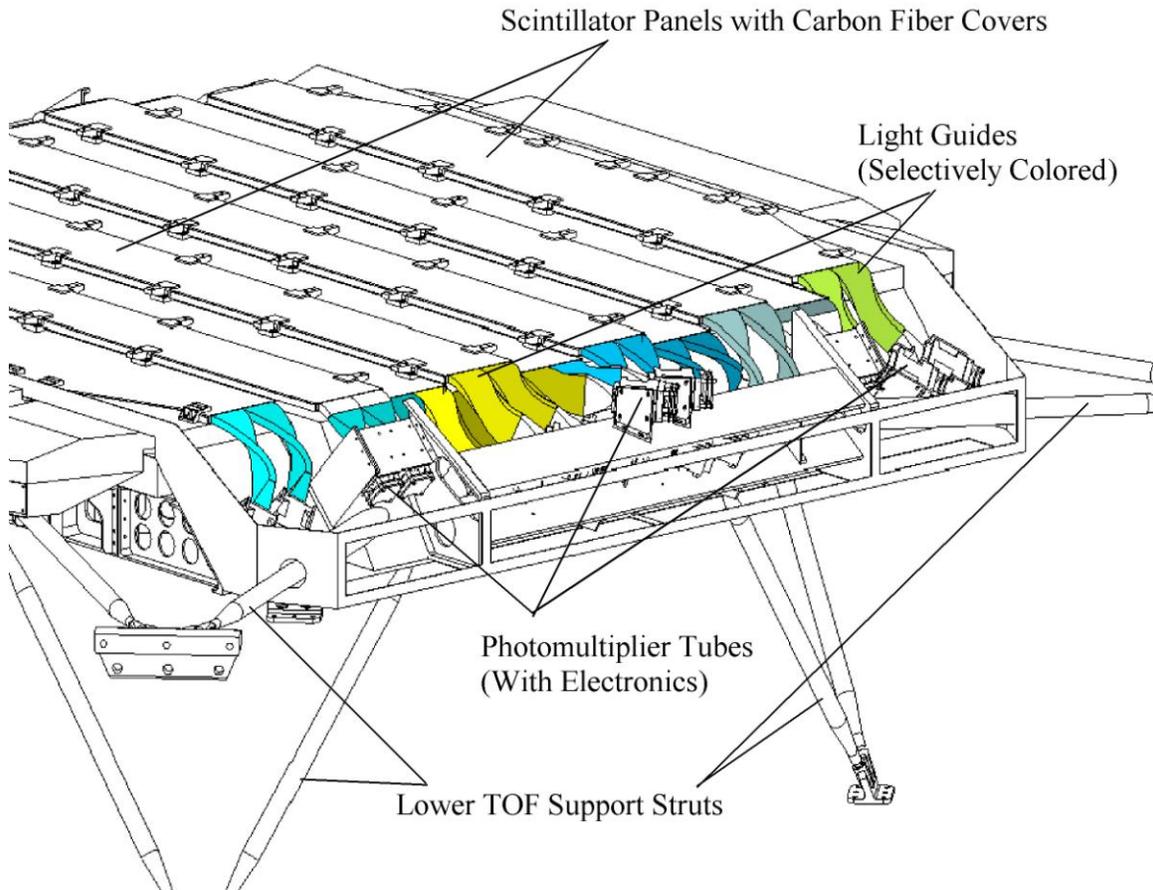


Figure 5.6-6 Mounting of TOF PMT and Detector Paddles

The upper TOF honeycomb structure attaches via brackets to the TRD corner joints which hard-mount to the USS-02 upper corner joints (Figure 5.6-7). The lower TOF honeycomb is connected to the lower USS-02 (Figure 5.6-8) via struts. The honeycomb panels are roughly square with 60.6 inches (1540 mm) sides. The thickness of the honeycomb aluminum core is 1.97 inches (50 mm) and the aluminum skin is 0.04 inch (1 mm) thick for the lower TOF. The upper TOF honeycomb core is 3.92 (100 mm) thick with the 0.04 inch (1 mm) aluminum skin.

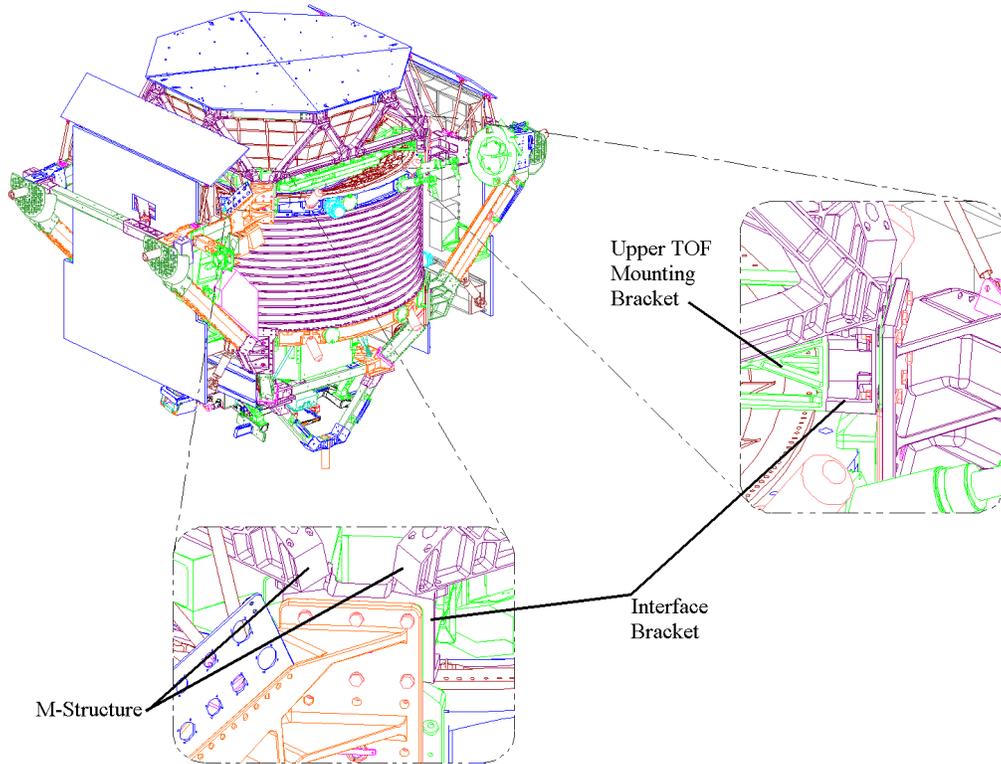


Figure 5.6-7 Structural Interfaces for the Upper TOF

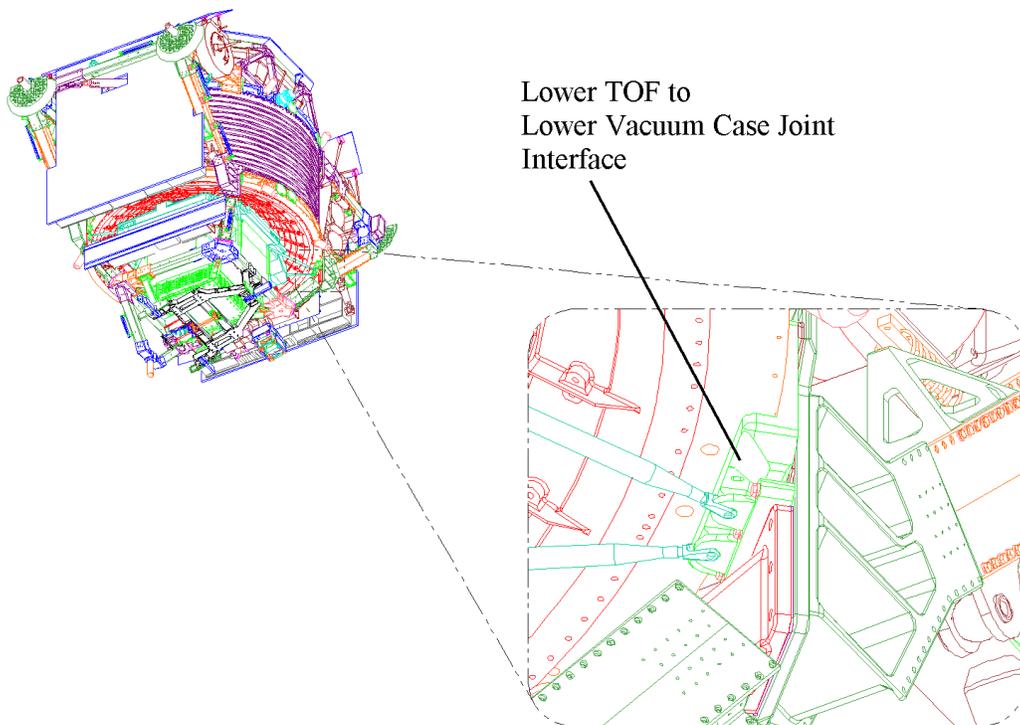


Figure 5.6-8 Structural Interfaces for the Lower TOF

5.7 STAR TRACKER

The Space Station, which is large and fairly flexible, cannot measure its own position and orientation with a high degree of accuracy and thus cannot directly tell the AMS-02 where it is exactly and where it is pointing. To optimize science from the Tracker detector carried by AMS it is important to have the capability to determine accurately the position of the AMS payload at the exact time that an event occurs. To accurately determine its position, AMS carries a Star Tracker called AMICA (for Astro Mapper for Instrument Check of Attitude). AMICA is equipped with a pair of small optical telescopes (AMICA Star Tracker Cameras or ASTCs). The ASTCs are mounted to the upper Vacuum Case Conical Flange on opposite sides of AMS to increase the probability that one has a clear view of the stars (Figure 5.7-1 and 5.7-2). The positioning of the Star Trackers while in the Shuttle Payload Bay does not place the ASTCs within nominal EVA translation paths. The location atop of the tracker places the ASTCs outside of EVA translation paths on the ISS and EVA operations that may be performed on the AMS-02 are not in proximity of the Star Trackers.

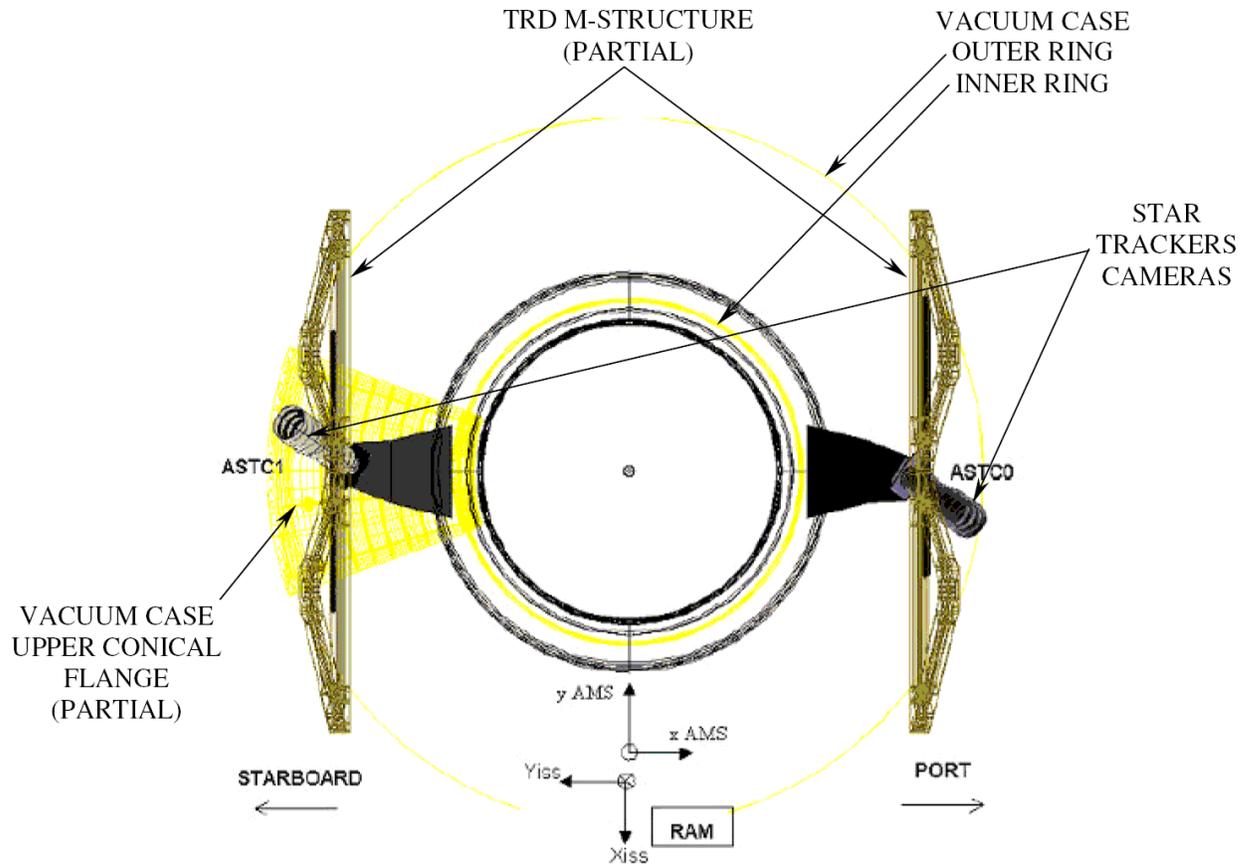


Figure 5.7-1 Star Tracker Position on the AMS-02

Each camera acquires an image of the stars with a Charged Coupling Device (CCD) detector and compares the resultant image to an on-board sky map. With this information, the attitude of AMS can be determined within a few arc-seconds (arc-sec) accuracy.

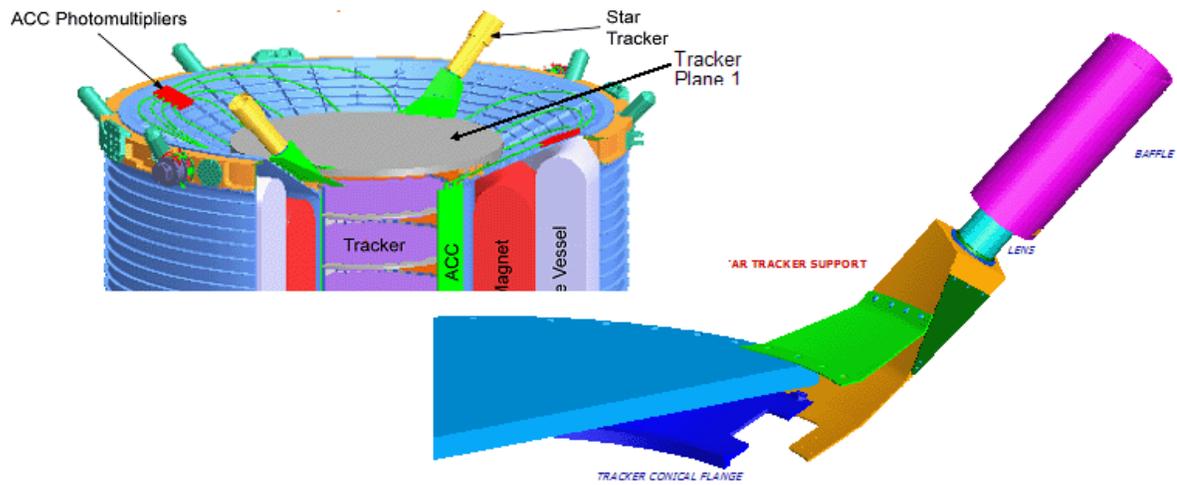


Figure 5.7-2 Star Tracker Mounting on the AMS-02

The hardware consists of an optics system [f/1.25 lens with 75 mm focal length and a 6.3° X 6.3° field of view (FoV)]; a lens cover containing a 3 mm thick blue filter and a 2 mm thick red filter; a low noise frame-transfer CCD (512 X 512 pixels); and a baffle to limit the stray light intrusion to the optics. The baffle is made of black anodized aluminum Al 6061 that is 1 mm thick, the exterior covered with silver coated Teflon. The Star Tracker optical components are shown in Figures 5.7-3 and 5.7-4. The baffle is not mechanically connected to the lens assembly and is supported independently by a bracket mounting the baffle to the M-Structure, the configuration allowing for relative motion between the baffle and the lenses without leaking light into the optical path. The interface between the baffle and the lens assembly is made light tight by a fabric MLI cover.

The interior of the baffle is being considered sharp enough to cut EVA gloves, the interior of the baffle cannot be rounded to meet the sharp edge requirements without losing the optical properties of a baffle to limit stray light. This will be controlled with an EVA keepout zone for each baffle.

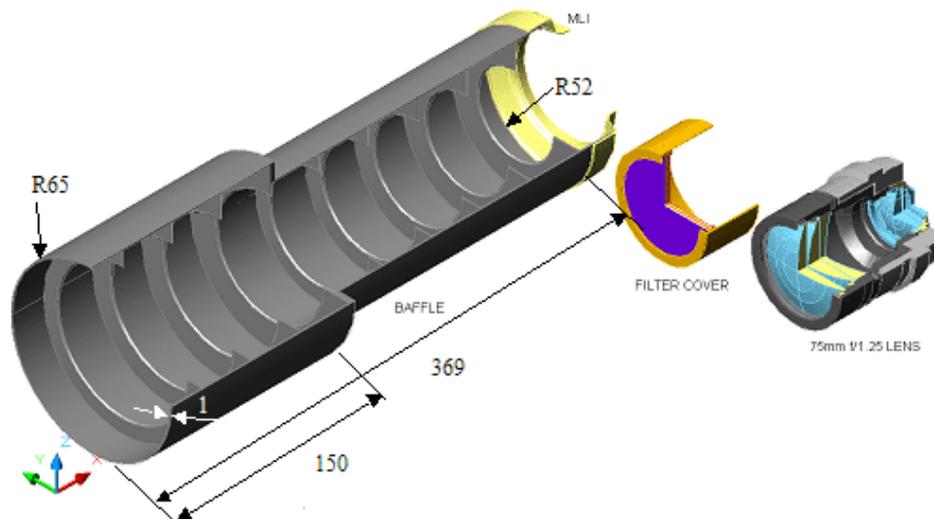


Figure 5.7-3 Star Tracker Optical Components

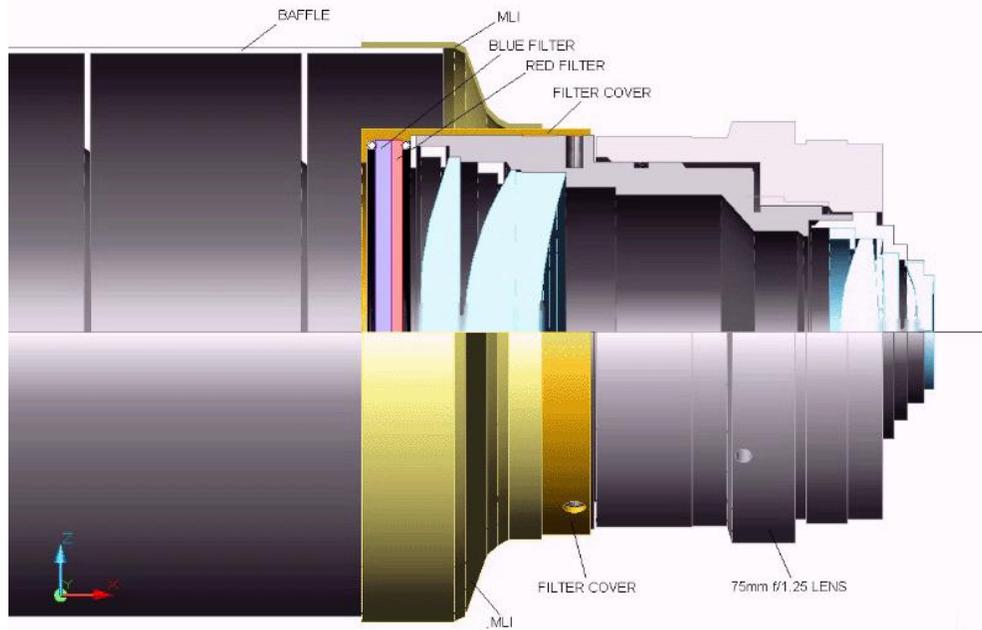


Figure 5.7-4 Star Tracker Optics

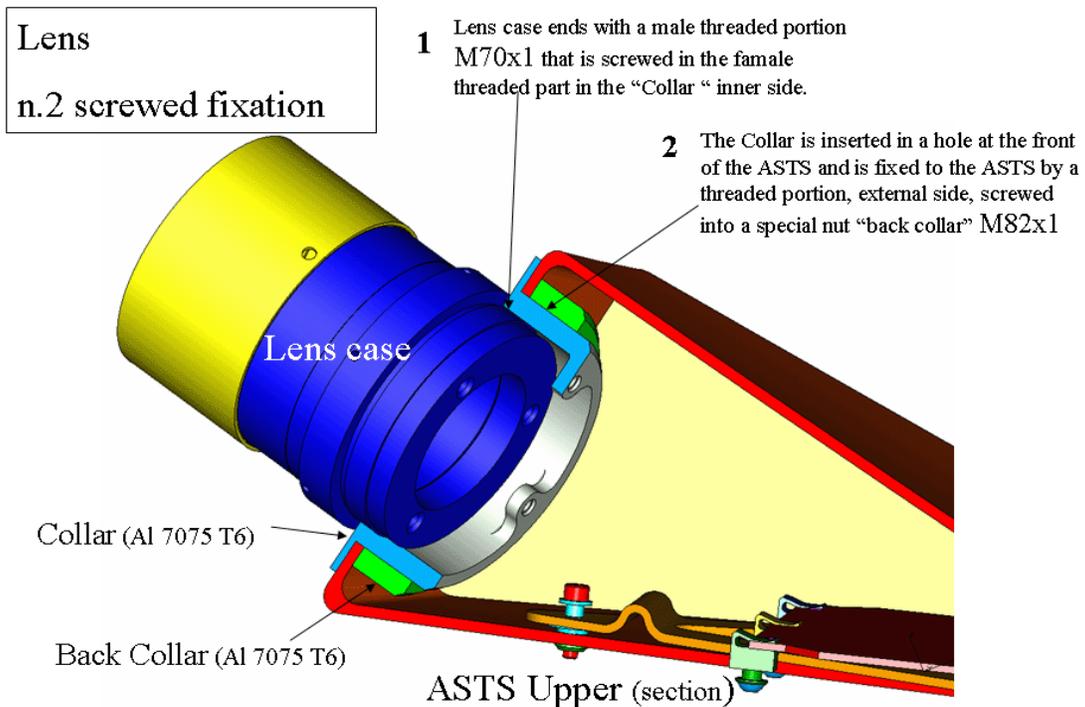


Figure 5.7-5 Star Tracker Lens Mounting

The AMICA lenses utilize standard optics mounting techniques (Figure 5.7-5) attaching to the housing body and in the construction of the lenses and filters. There is no specific

venting paths provided for in the design of the lens assemblies, however the threaded body provides ample venting paths as shown during venting tests.

The enclosed volume of the Star Tracker is vented through the fastener access holes that are used for tool access when installing the Star Tracker to the AMS-02 as shown in Figure 5.7-6.

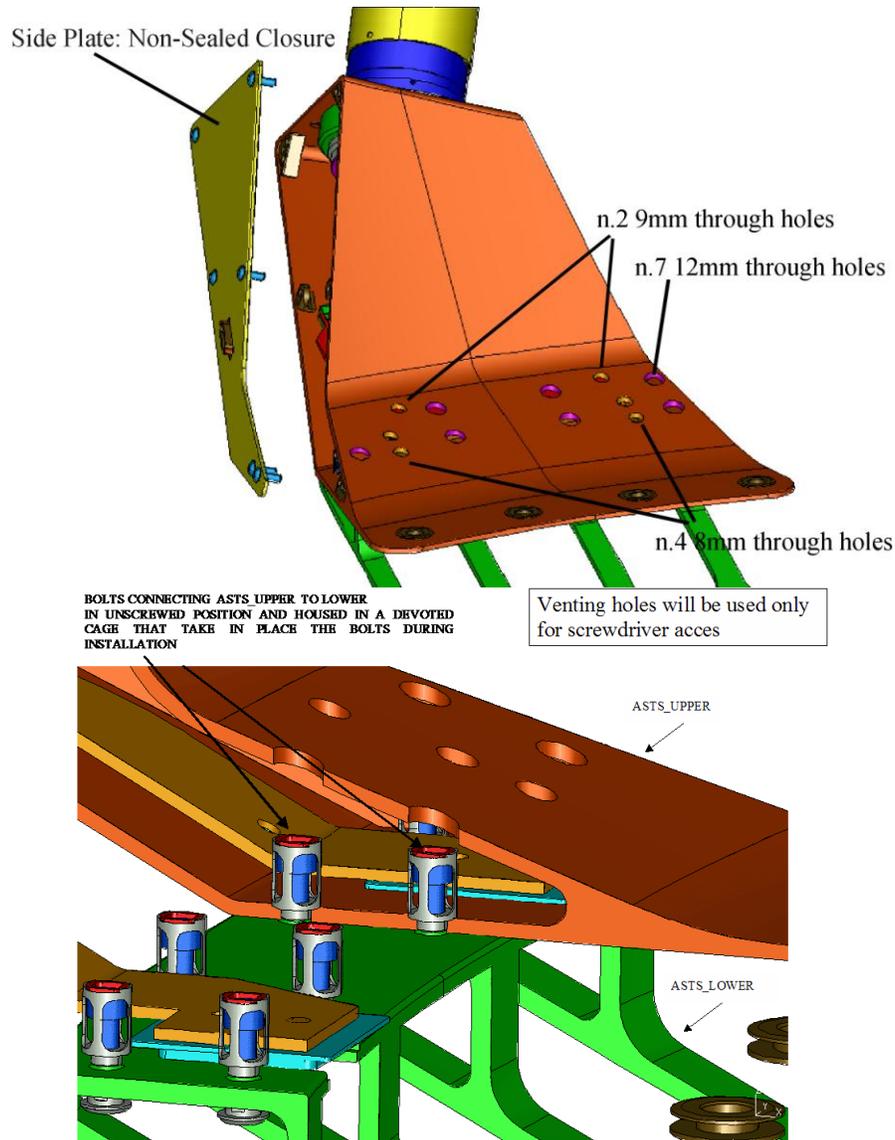


Figure 5.7-6 Star Tracker Assembly and Venting Paths

The AMICA operates on +5, ±12 Vdc and converts power internally to +35 V, +12 V, +7 V and +5 V distributed power. One small section of the circuitry operates at a maximum

of +45 V. The boards are conformally coated to reduce any potential for high voltage effects. The ASTCs are interfaced to the M-crate located on the ram side by two cables, one 8 conductor 24 AWG shielded cable to provide the SpaceWire Link for data and one four conductor 22 AWG cable for power. The thermal load from the Star Tracker CCD and electronics board inside the sensors is carried by a copper “bus” to the thermal blocks connecting to the Tracker Thermal Control System (Figure 5.7-7). The electronics unit is based on a VME bus, which contains the processor (DSP21020) and power switching boards. The CCD front end electronics boards for each ASTC are contained in the AMICA Star Tracker Supports (ASTSs) that attach the instrument to the Tracker.

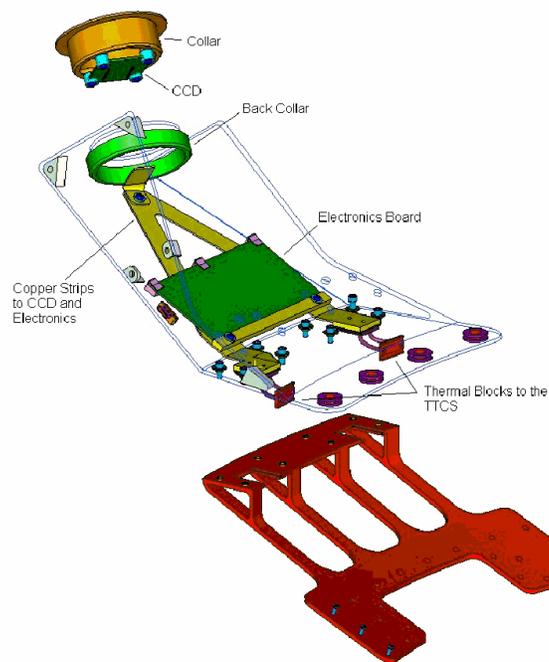


Figure 5.7-7 Star Tracker Thermal Interface and CCD Electronics

5.8 ANTI-COINCIDENCE COUNTERS (ACC)

The ACC is a single layer of scintillating panels that surround the AMS-02 Silicon Tracker inside the inner bore of the PM (Figure 5.8-1). The ACC detects and identifies particles that enters or exits the Tracker through the side or that have not cleanly traversed the Tracker. The ACC provides a means of rejecting particles that may confuse the charge determination if they leave “hits” in the Tracker close to the tracks of interest.

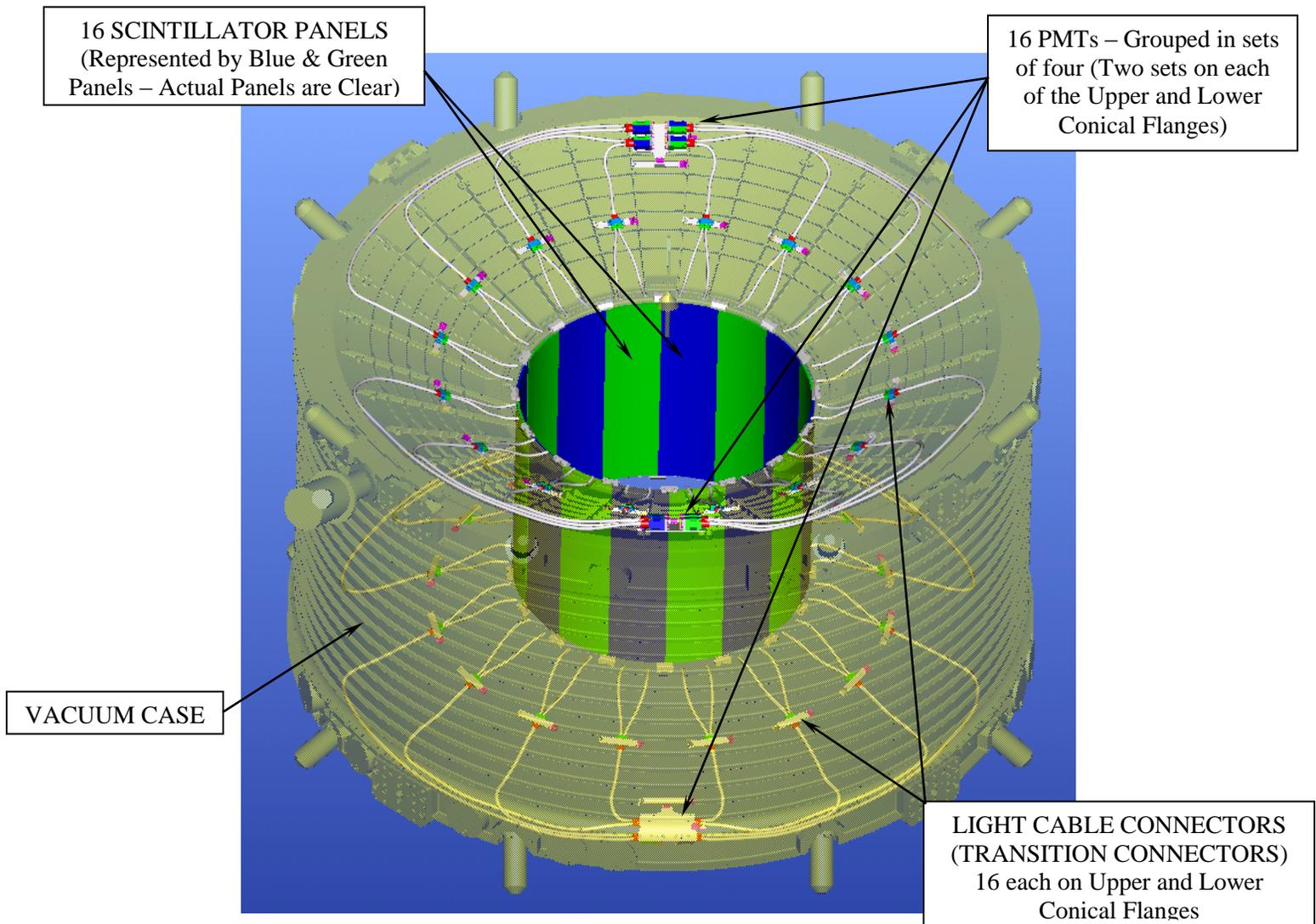


Figure 5.8-1 ACC Location Within the Inner Cylinder of the Vacuum Case

The ACC scintillating panels are fitted between the Tracker shell and the PM. The ACC is composed of sixteen interlocking panels fabricated from BICRON BC414 (Figures 5.8-

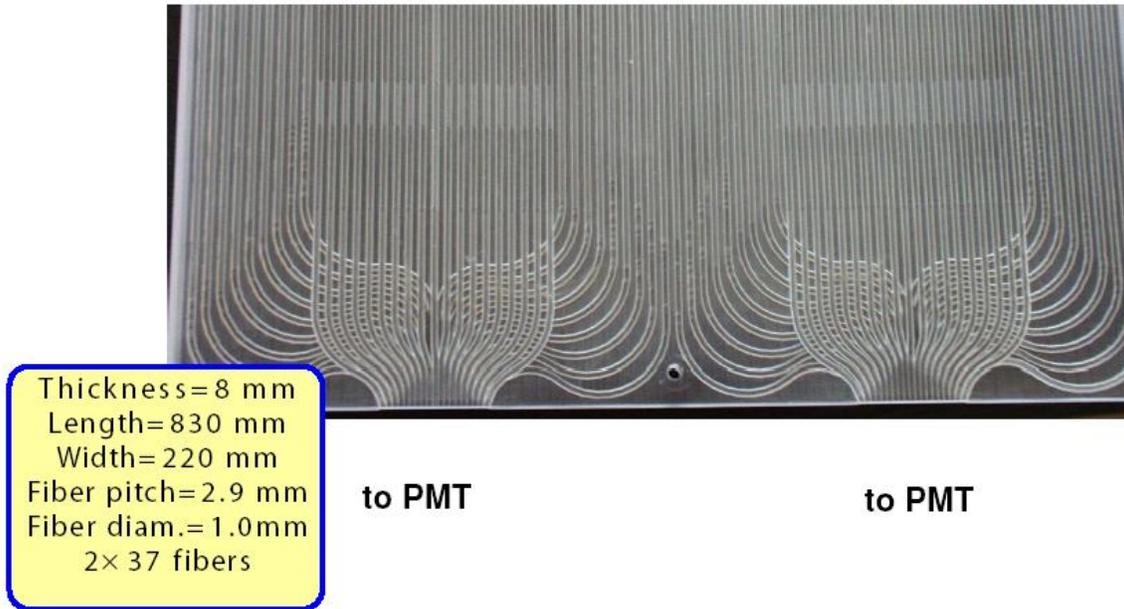
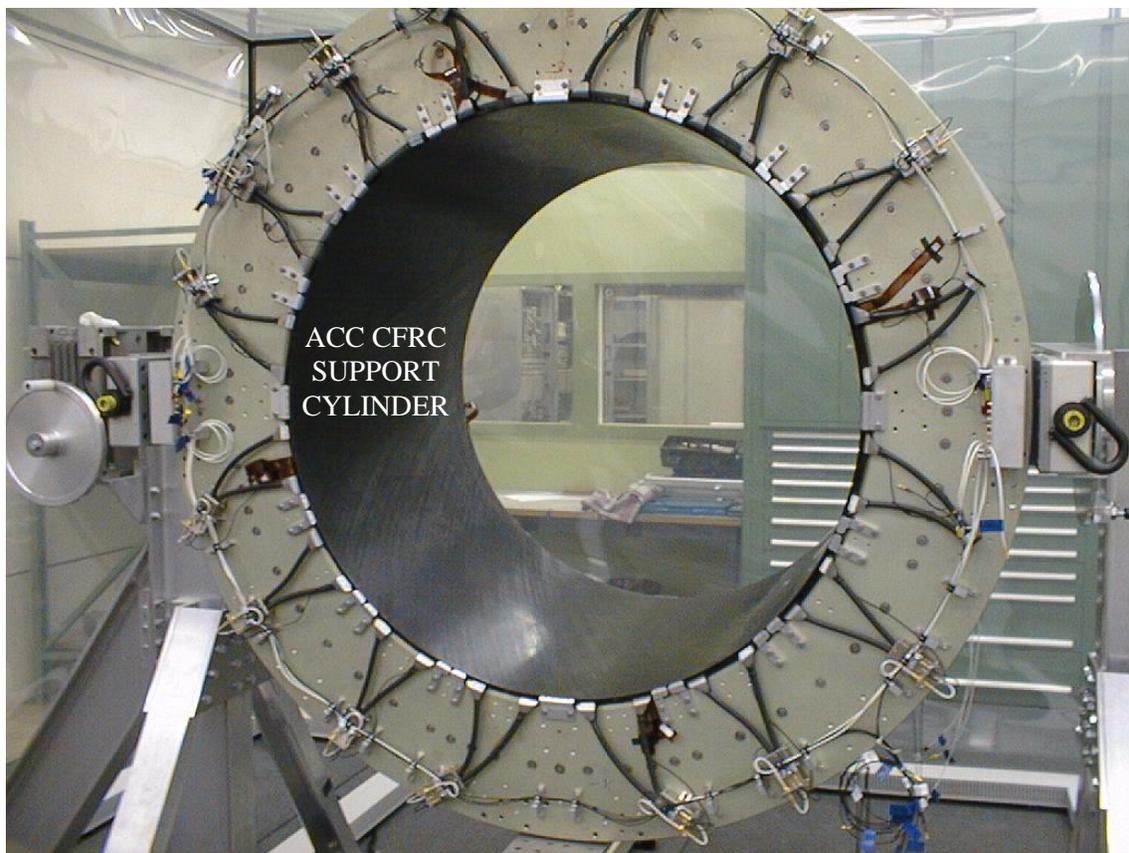


Figure 5.8-3 Finished End of an ACC Scintillator Panel



**Figure 5.8-4 ACC Carbon Fiber Reinforced Composite Support Tube
(installed for AMS-01 in the PM, fiber optic cable configuration different)**

The light of scintillation from particles passing through the panels are collected by 1 mm wavelength shifter fibers (Kuraray Y-11(200)M) that are embedded in groves milled into the panel surface. A panel has two collection arrays, each consisting of 37 fibers. The embedded fibers are collected into 2 output ports of 37 fibers each at both ends of the panel (Figures 5.8-2 and 5.8-5). For each panel there are two transition connectors (Figure 5.8-6), one each located on the upper and lower conical flanges of the Vacuum Case (Figure 5.8-7). From these transition connectors the light is routed through clear fibers up to PMTs mounted on the rim of the Vacuum Case (Figure 5.8-8).

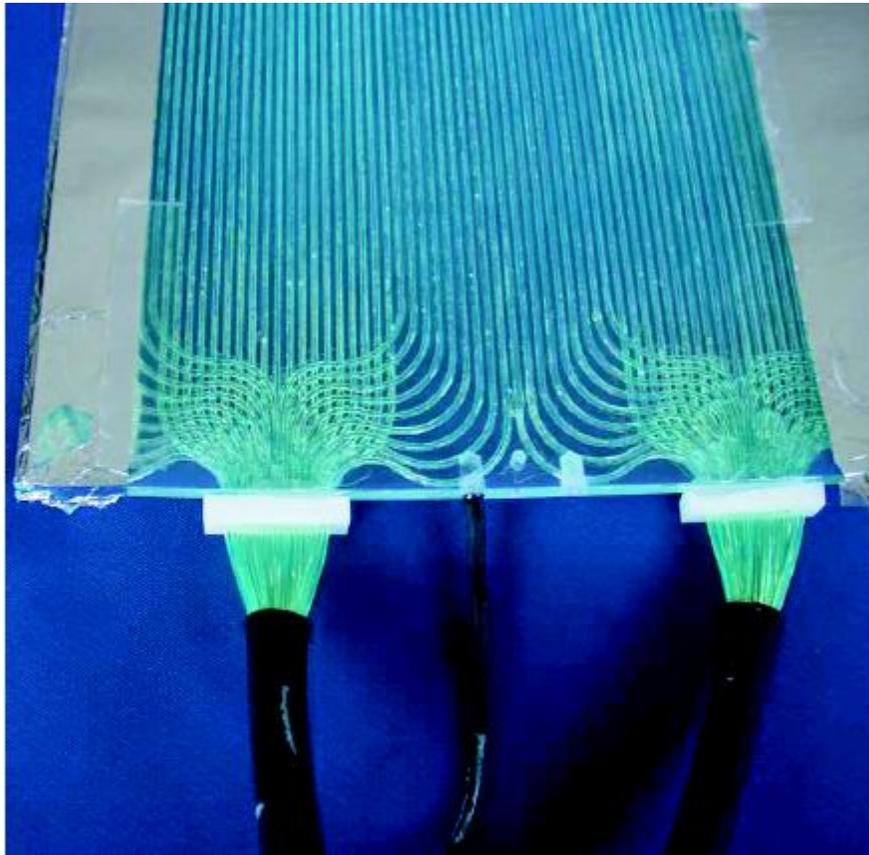


Figure 5.8-5 Fibers Collected at the End of an ACC Scintillator Panel

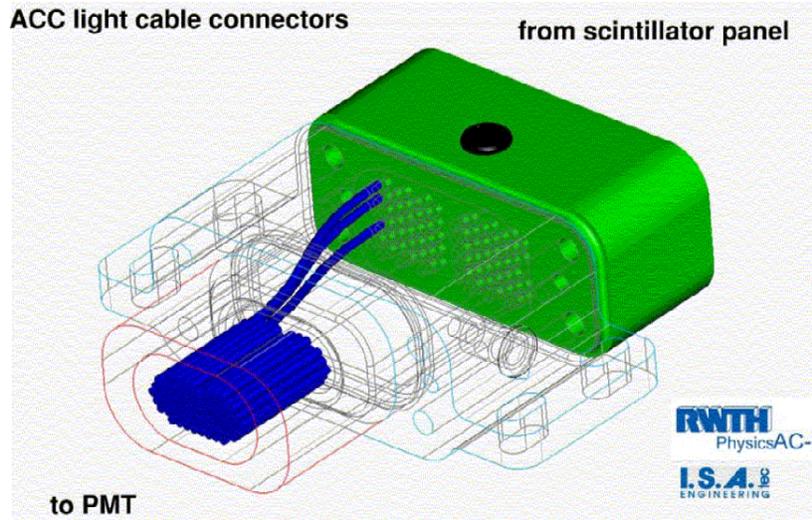


Figure 5.8-6 ACC Fiber Optic Transition Connector

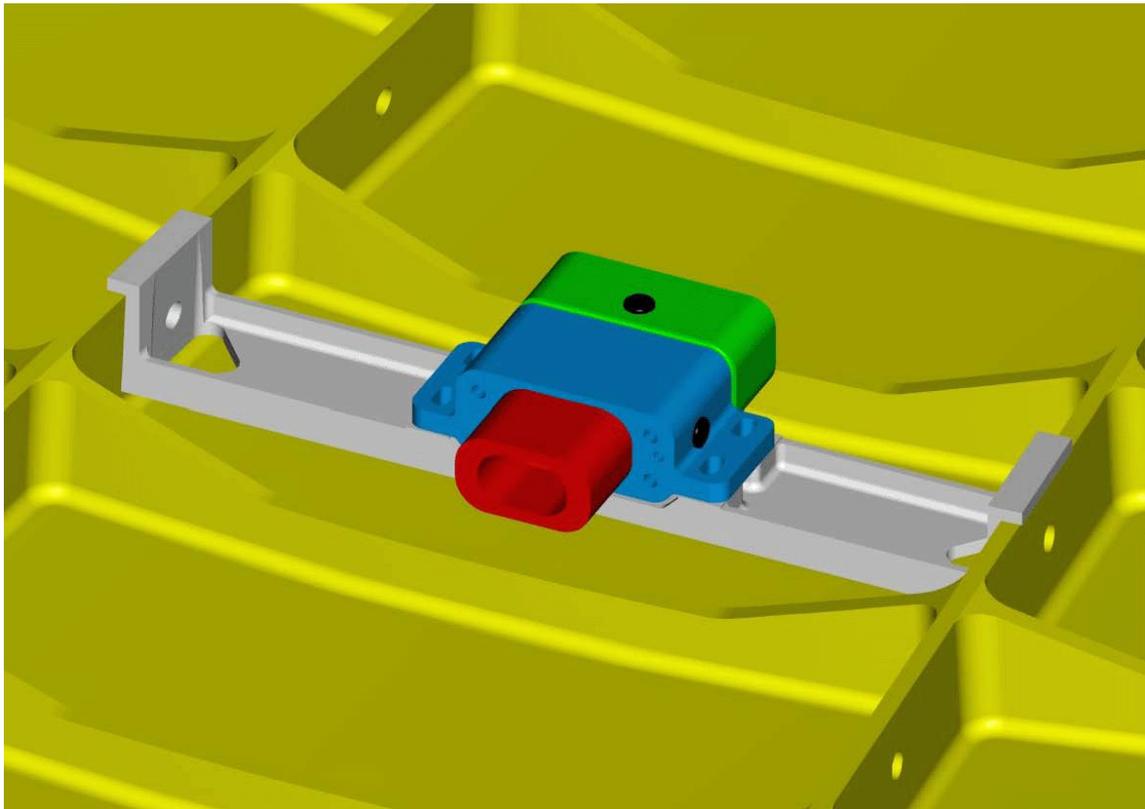


Figure 5.8-7 ACC Transition Connector Mounted to the Conical Flange

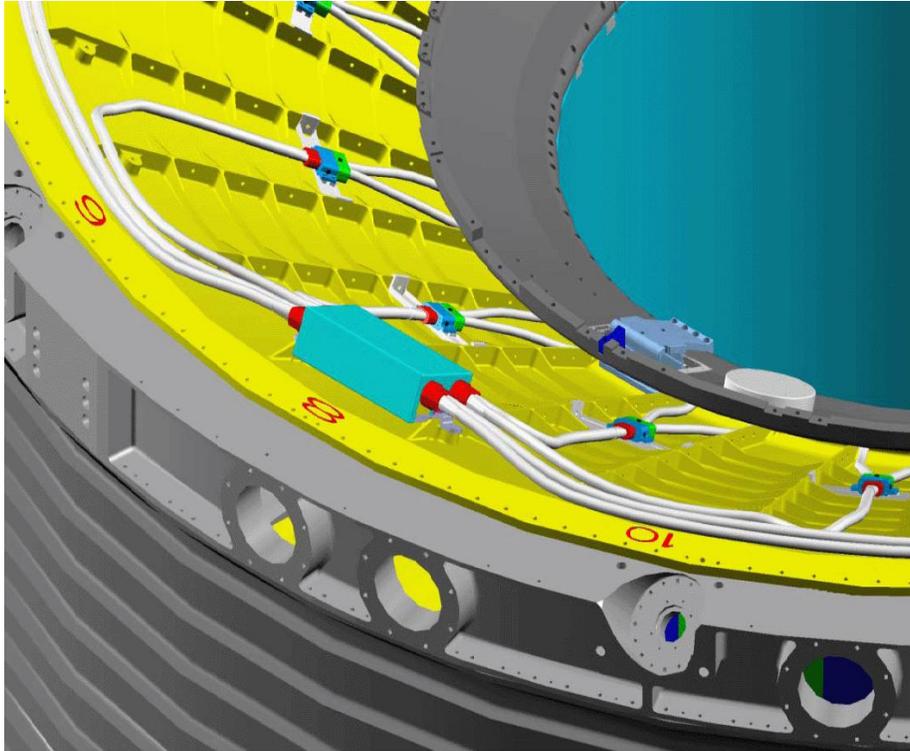


Figure 5.8-8 Routing of the ACC Fiber Optic Cables from the Scintillating Panels through the Transition Connectors to the PMTs

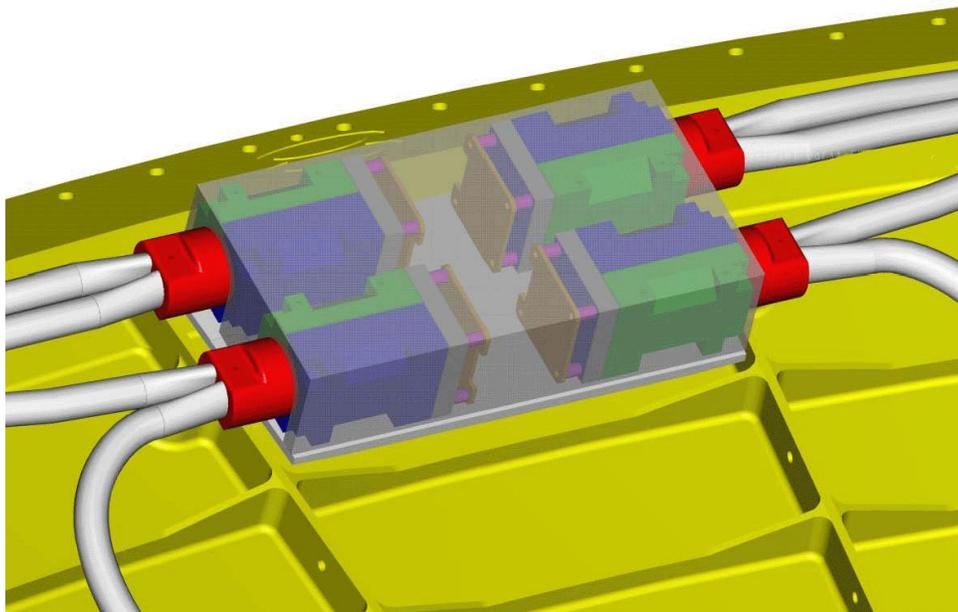


Figure 5.8-9 PMTs Mounted to the Conical Flange

The PMTs that record the light signals from the ACC panels are identical to the PMTs used in the TOF system (Hamamatsu R5946) (Figures 5.8-10 & 5.8-11). The ACC PMTs have to work in a moderate (~1.2 kG) magnetic field at locations on the top and bottom of the VC, approximately 40 cm from the racetrack coils. To minimize the impact of this, the PMTs are oriented with their axes parallel to the stray magnetic field.

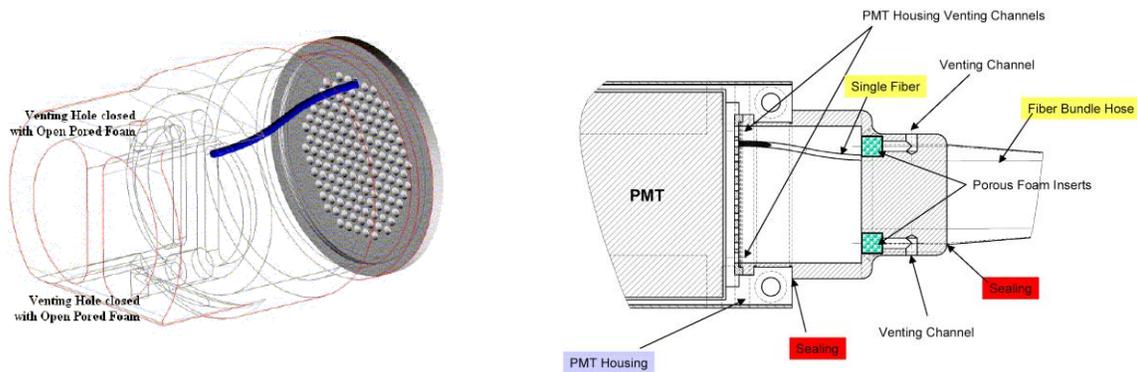


Figure 5.8-10 ACC PMT Fiber Optic Interface Construction

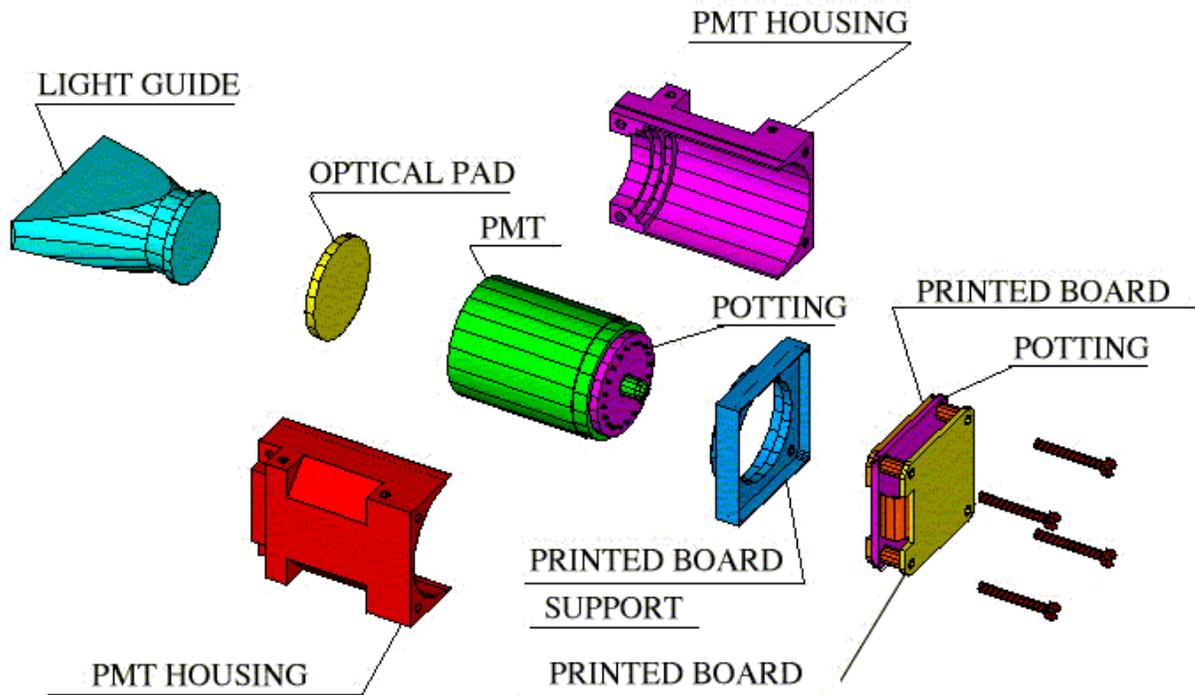


Figure 5.8-11 Basic Construction of ACC PMT

(Similar to TOF PMT Shown with Light Guide Replaced with Fiber Optic Interface)

The ACC also utilizes the same avionics architecture as the TOF to detect and interpret the passage of particles through the scintillating panels. Cables from the ACC PMTs are routed out from under the MLI covering the conical flanges to high voltage sources the S-Crate (Figure 5.8.12).

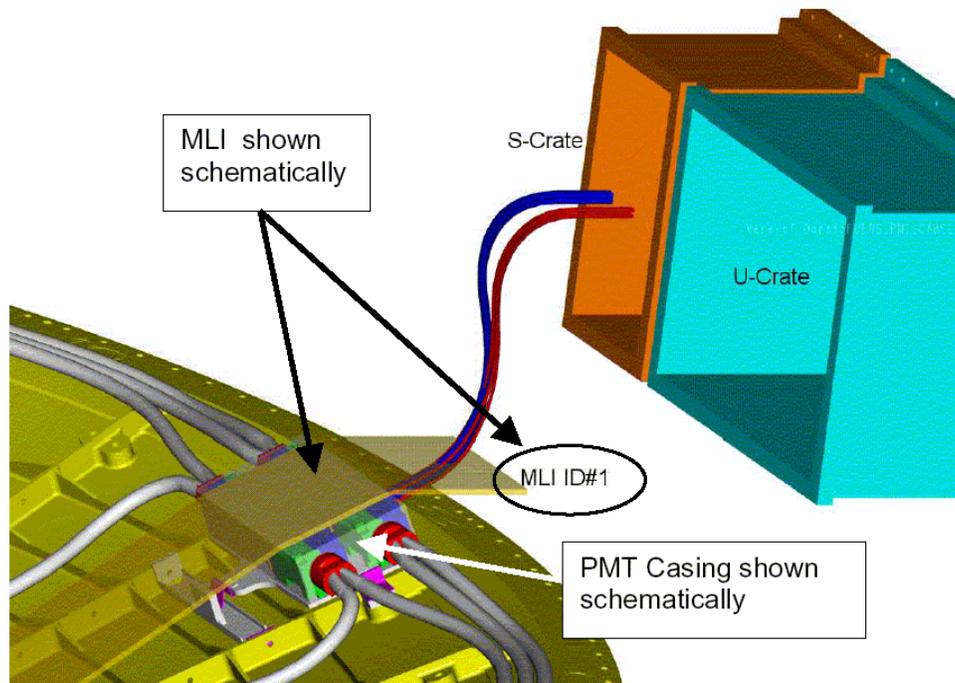


Figure 5.8-12 Wiring of the ACC PMTs to the S-Crate

5.9 SILICON TRACKER

In combination with the Permanent Magnet, the Silicon Tracker represents the centerpiece of the AMS-02 suite of detectors. The Tracker (Figure 5.9-1 and 5.9-2) consists of nine layers of silicon micro-strip detectors (ladders) on six support planes. Within the bore of the Permanent Magnet three of the double sided planes will operate and another single plane will operate at the top of the Permanent Magnet (original location). A single sided plane has been installed above the TRD and is suspended from a composite structural plane on the AMS-02 Zenith location. An additional single layer plane is positioned between the RICH and the ECAL. All nine tracker planes together comprise 192 silicon ladders corresponding to an active area of about 6 m² of silicon and 200,000 readout channels. The entire tracker electronics consume 800 W of power.

In addition, the Tracker is equipped with an infra-red (IR) laser Tracker Alignment System (TAS) that will pass IR laser beams through the central seven of the nine planes in the bore of the magnet. The TAS will periodically monitor the X- and Y-position of the tracker layers with respect to each other by passing IR laser beams through selected areas of the silicon detectors, called Alignment Holes, in each detector plane where the laser can penetrate and be measured on that detection plane by a silicon ladder. Measurement of the beam location allows for any relative distortions between the layers being reflected in the calculations of particle trajectory. Laser energy is generated in five Laser Fiber Coupler (LFCR) boxes and that light is conducted to the uppermost of the bore located planes into beam port that send the beams across the planes. With the modifications to the AMS-02 with the conversion to the PM, half of the LFCR outputs have been capped and are not used.

The remaining layers will be aligned to those monitored by the TAS by utilizing the measured trajectories of cosmic rays passing through the Tracker.

The AMS-02 Tracker is the second generation of the Tracker that flew on STS-91 (AMS-01). It utilizes the same honeycomb panels and exterior cylindrical shell (Figure 5.9-3). The flat flanges on both the top and bottom of the AMS-01 Tracker have been replaced by conical flanges on the AMS-02 detector (Figure 5.9-4) and the Tracker feet

were redesigned to interface with the VC. The Tracker mounts at eight attach locations (4 at the top, 4 at the bottom) to the VC conical flanges. Data from accelerometers flown on STS-91 was used to develop the design load factors for AMS-02.

The three inner planes are ≈ 3.6 ft (1.07 m) in diameter and the top and bottom planes are a ≈ 4.9 ft (1.43 m) in diameter. The Core Tracker is ≈ 3.9 ft (1.2 m) high and weighs ≈ 438 lbs (198.5 kg) including cables.

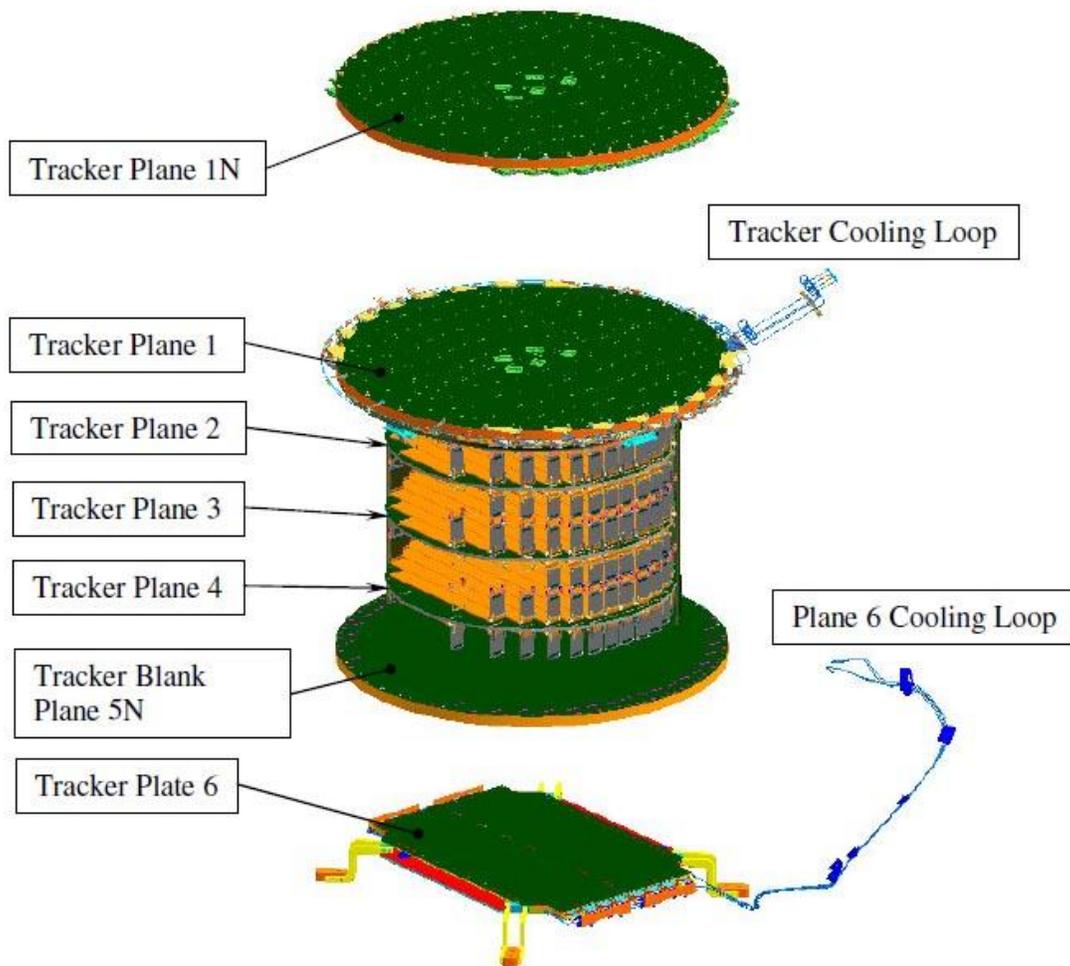


Figure 5.9-1 Layout of the AMS-02 Silicon Tracker

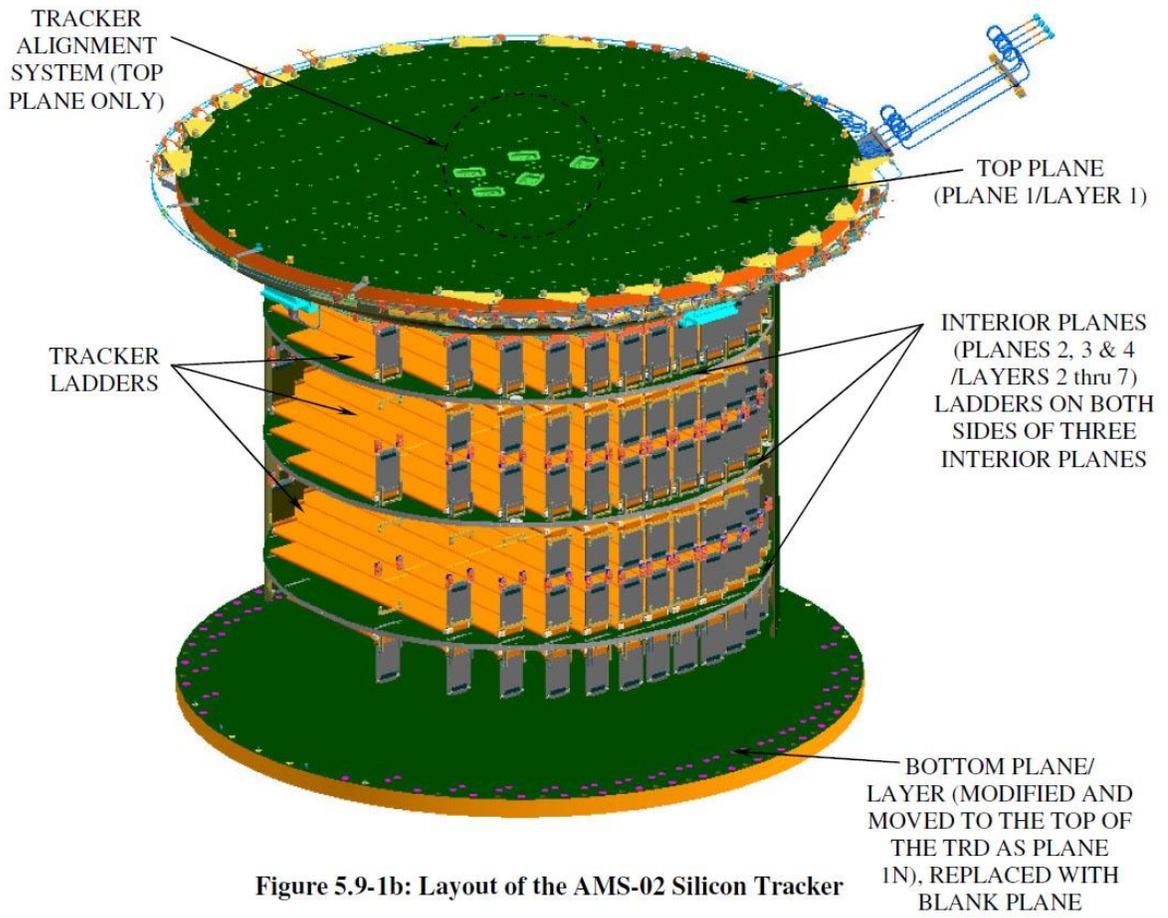


Figure 5.9-1b: Layout of the AMS-02 Silicon Tracker

Figure 5.9-2 Layout of the AMS-02 Silicon Tracker

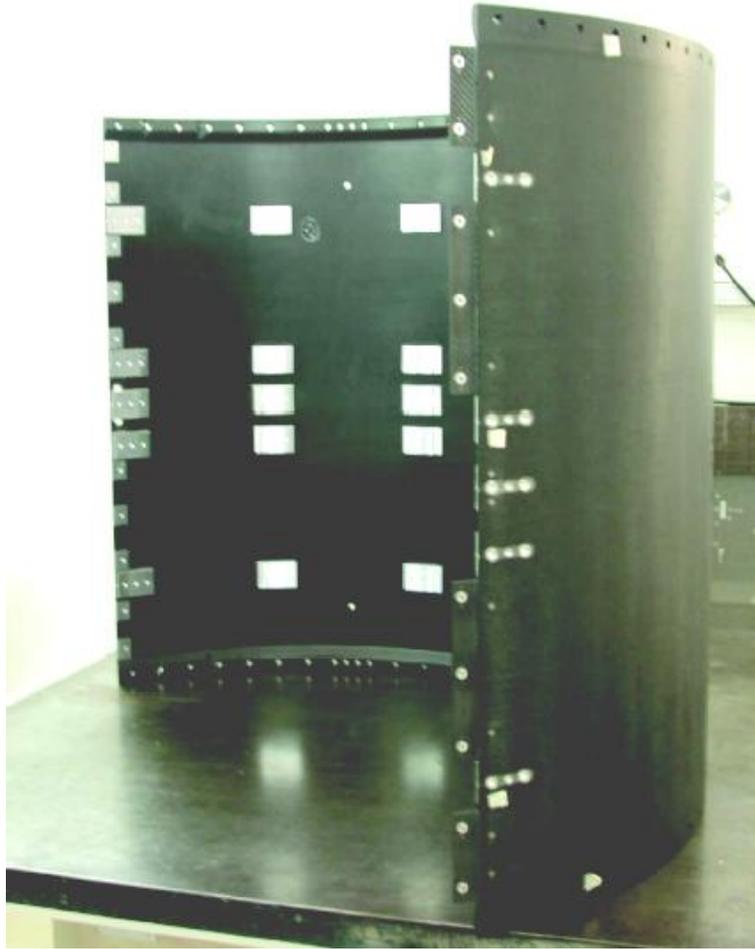


Figure 5.9-3 A Section of the Tracker Support Structure Cylindrical Shell



Figure 5.9-4 Tracker Support Structure – Upper Conical Flange

5.9.1 Silicon Sensors and Ladders

The AMS experiment silicon detector assemblies (Figure 5.9.1-1) contain silicon ladders made up of a series of 2.836 inch (72.045 mm) x 1.628 inch (41.360 mm) x 0.012 inch (0.300 mm) double-sided silicon micro-strip sensors, electrically connected by microbonds. The silicon sensors are reinforced by sandwich structures made of foam with light-weight carbon composite backing. Hybrid boards at the ends of the ladders enable the sensors to be electrically connected to the tracker electronics. The ladder assemblies vary in length from ≈ 11.47 inches (290 mm) to ≈ 22.45 inches (621 mm), and are 2.836 inches (72.045 mm) wide and $\approx .394$ inches (10 mm) thick.

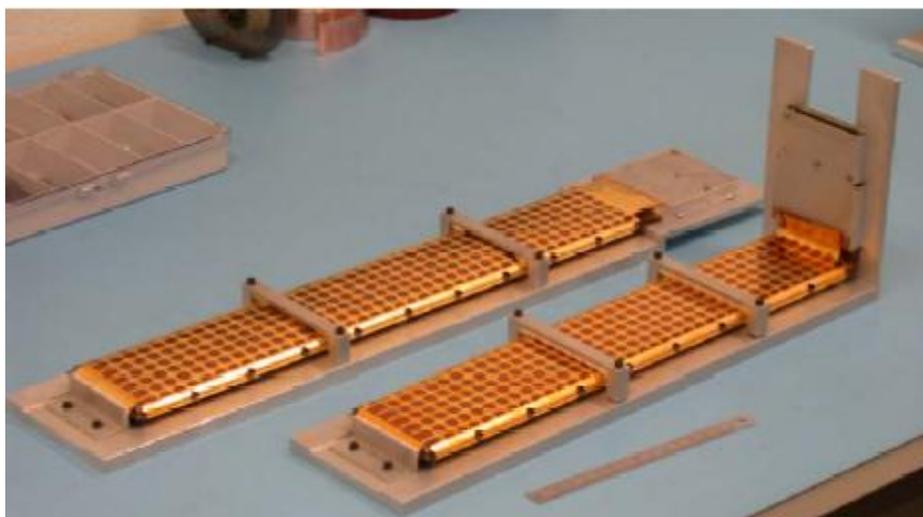


Figure 5.9.1-1 Tracker Ladders (typical) prior to mounting on a Tracker Support Plane

Figure 5.9.1-2 shows the principal elements of the silicon ladder and the main components of the readout hybrids. A 50 μm Upilex film (an ultra-high heat-resistant polyimide film) is used extensively in the ladder. Metalized Upilex film, glued directly to the silicon sensors, serves as a routing cable to bring the n-side signals to the n-side front end hybrid, which is located at the ladder end closest to the Cryomagnet wall. The flexible Upilex film and a second short Upilex film joining the p-side strips to their hybrid allow the hybrids to be placed back-to-back, perpendicular to the detection plane, thus minimizing the material in the sensitive region of the tracker. Finally, an

electromagnetic shield in the form of a doubly-metalized Upilex film surrounds each ladder.

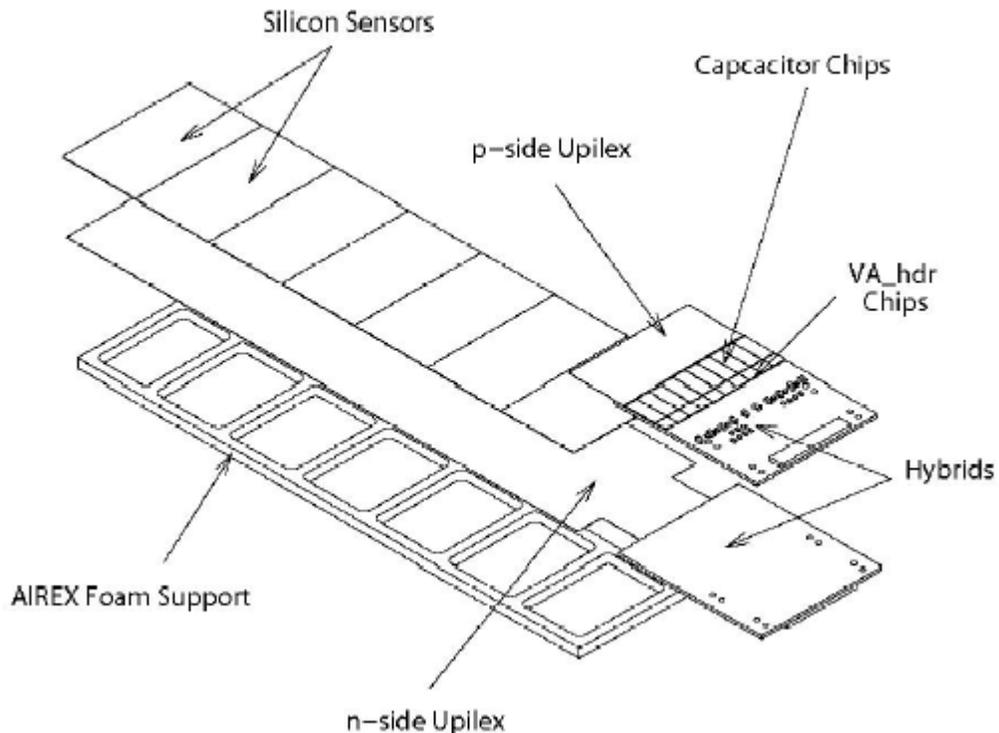


Figure 5.9.1-2 Principal Components of the Silicon Ladder

The silicon sensors of each ladder are supported by a 0.2 inch (5 mm) thick Airex foam that is glued to the K-side Upilex film. The exposed surface of the foam is covered with a 100 μm thick layer of carbon fiber. Small (5 mm³) 7075 aluminum support feet are glued to the carbon fiber surface; the exact number depends on the ladder length. The feet contain screw fixation holes which are used to attach the ladder to its tracker plane.

The silicon sensors are grouped together, for readout and biasing, in ladders of different lengths to match the cylindrical geometry of the AMS Permanent Magnet (Figures 5.9.1-3 and 5.9.1-5). The maximum combined strip length in the silicon for a single readout channel is ~24.4 in (62 cm).



Figure 5.9.1-3 Tracker Support Plane 2 with Ladders installed

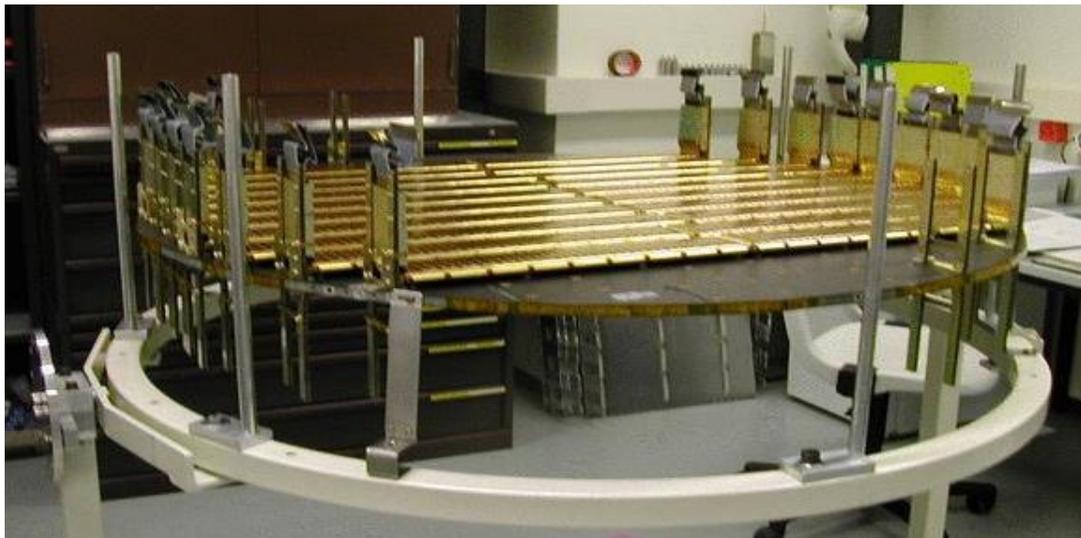


Figure 5.9.1-4 Tracker Support Plane 3 with Ladders installed

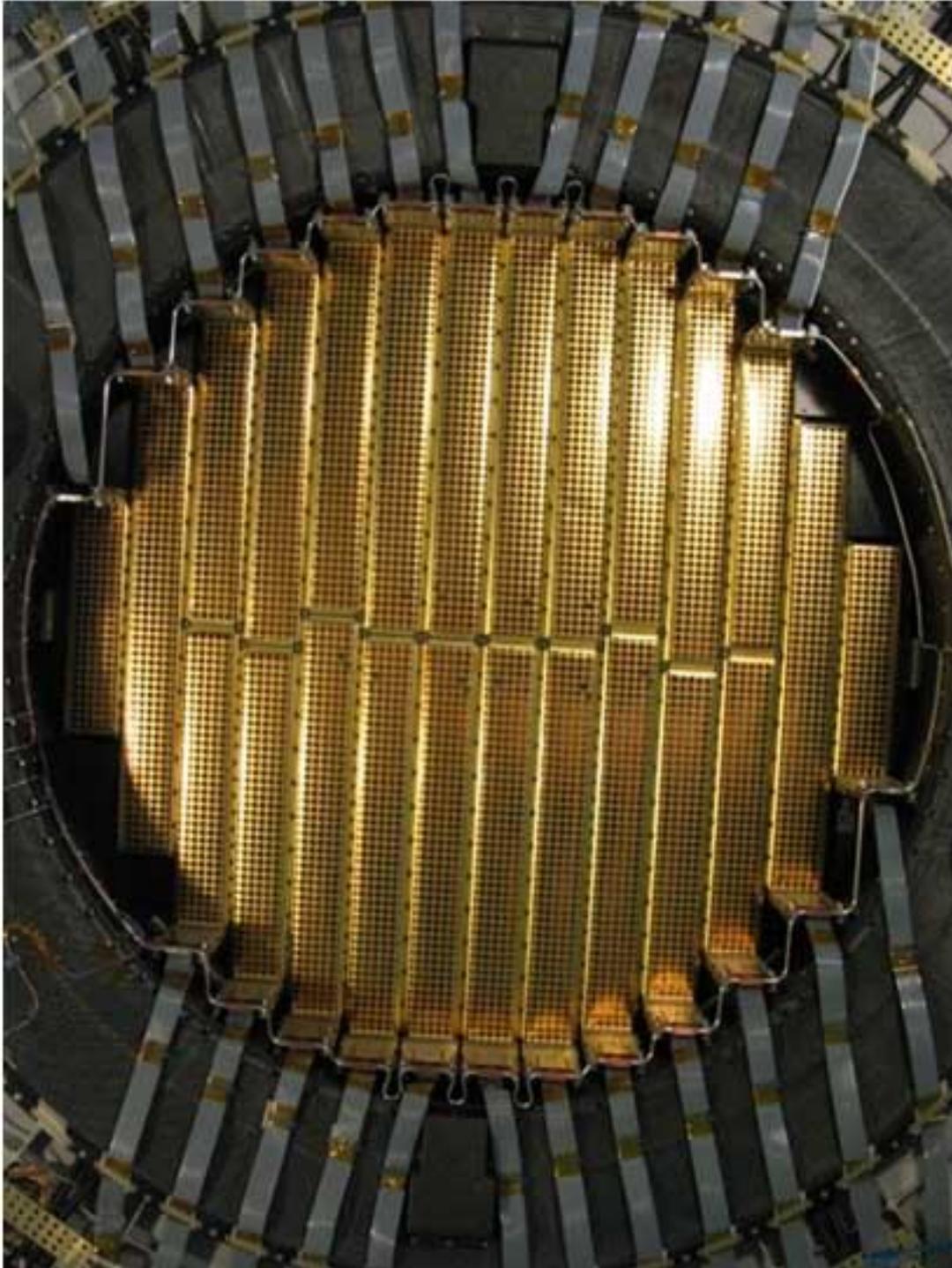


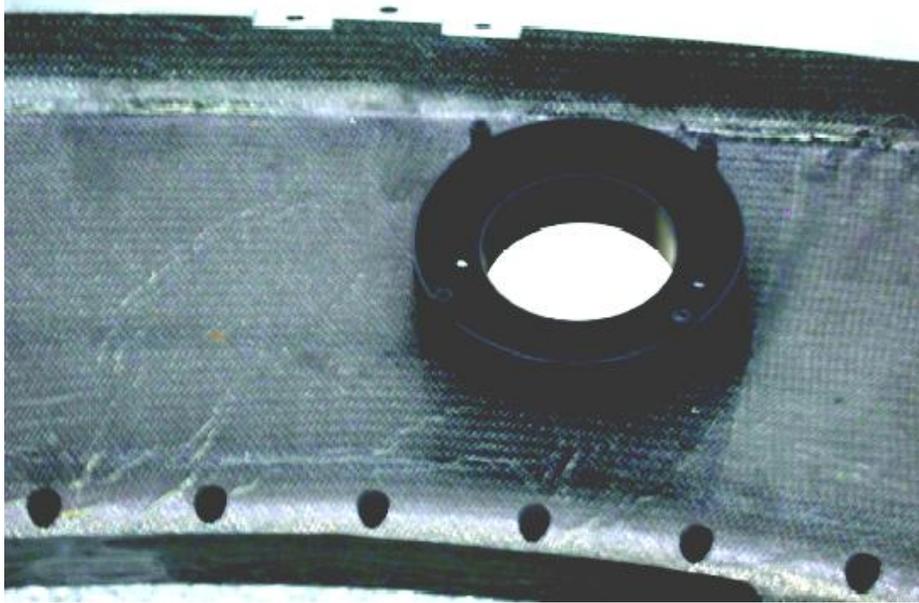
Figure 5.9.1-5: Tracker Planes Installed on Bottom of Plane 4

5.9.2 Tracker Support Structure

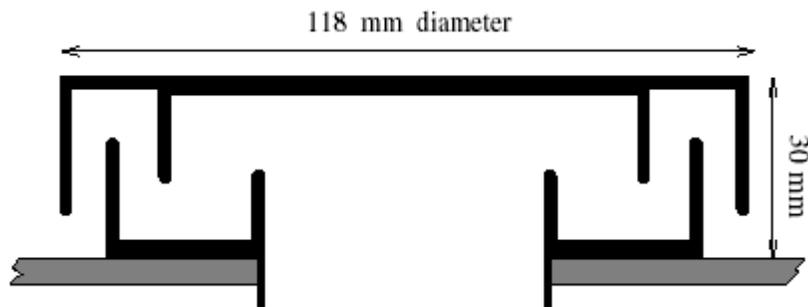
5.9.2.1 Core Tracker Structure

The Core Tracker support structure (the Tracker elements within the bore of the magnet and immediately above it) is divided into three sections: a carbon fiber cylindrical shell which supports the planes 2 to 4 located “inside” the Magnet bore, and two carbon fiber flanges which support the exterior planes 1 and the unpopulated plane 5N (Shown in Figure 5.9.2-4,) these planes being considered “outside” the Permanent Magnet bore. The Tracker planes located inside are the same as those used for AMS-01. The inside planes have a composite structure with two 220 μm thick layers of carbon fiber surrounding a 12 mm thick, low density aluminum honeycomb interior, $\rho = 16.02 \text{ kg/m}^3$. The outside planes have a composite structure with two 700 μm thick layers of carbon fiber surrounding a 40 mm thick, low density aluminum honeycomb interior, $\rho=32 \text{ kg/m}^3$. The diameter of the interior planes is 1.07 m the outside planes 1.43 m. To equalize the pressure inside the Tracker with the pressure in the payload bay during launch and landing, the Upper and Lower Conical Flanges each contain two light tight, filtered chicane vents (Figures 5.9.2-1 through 5.9.2-3) that permit air to exit or enter the enclosed Tracker volume of 40.26 ft^3 (1.14 m^3).

The Tracker Support Planes, Cylindrical Shell, and Conical Flanges are fabricated from M55J Fiber/Cyanate Ester Composite face sheet with a Hexcell Composite Honeycomb Core. The Tracker Support Feet are made from Titanium Ti6AlV4.



**Figure 5.9.2-1 Light Trap/Vent Hole – Upper Conical Flange
(with cover and filter mesh removed)**



**Figure 5.9.2-2 Chicane Light Trap/Vent Hole (Cross Section)
Filter mesh not shown**

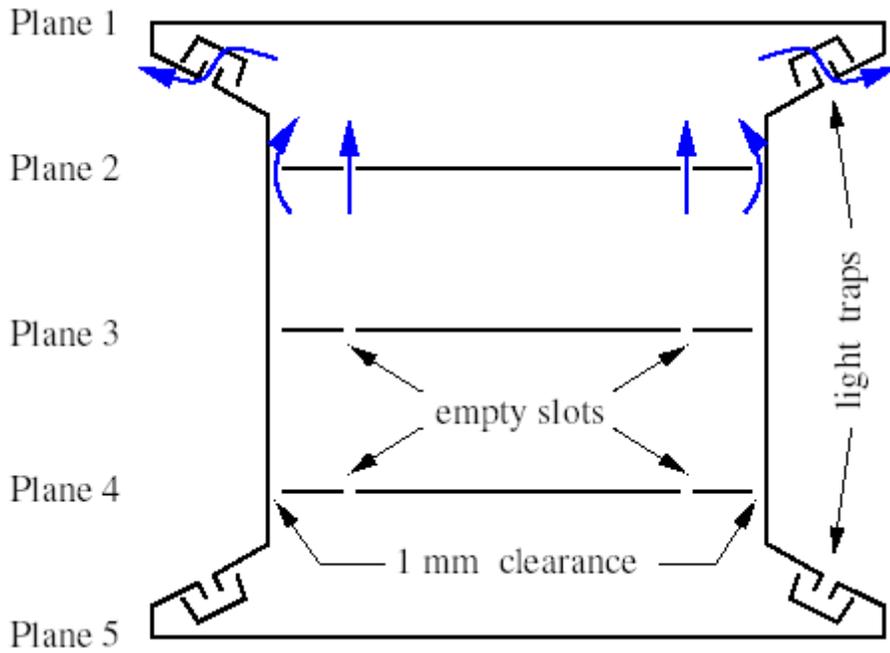


Figure 5.9.2-3 SiliconTracker Typical Vent Paths For Depressurization

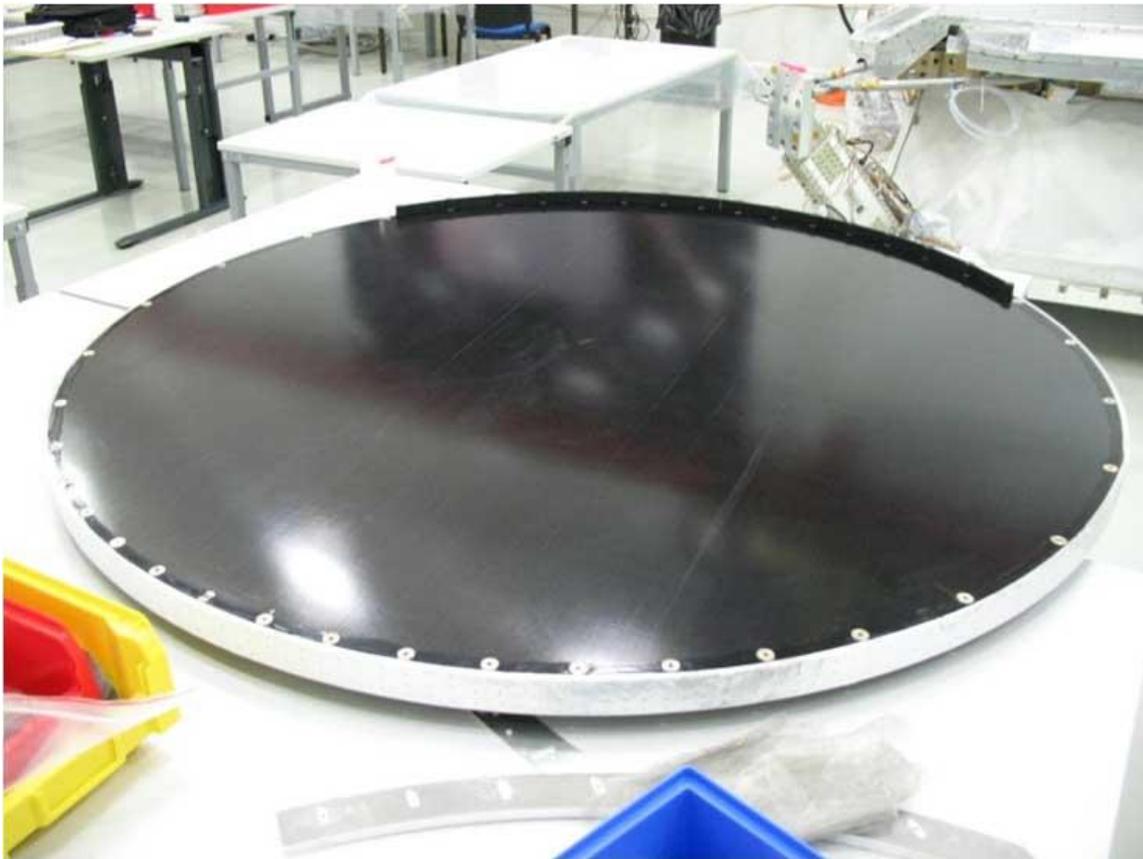


Figure 5.9.2-4 Tracker Plane 5N With Partial Installation of Light Shield

5.9.2.2 Tracker Plane 1N

Tracker Plane 1N is the original Tracker plane 5 from the Core Tracker assembly, mounted to the underside of a rigid honeycomb composite structure, referred to as plane 1NS. Plane 1NS is mounted atop the TRD where the Zenith radiator was previously located prior to removal of the Cryomagnet from the AMS-02 design. The Plane 1N support structure (1NS) utilizes the same structural interface points as the four Zenith Radiators used. Figure 5.9.2-4 shows the mounting of the 1N plane to 1NS with brackets. Plane 1N is mounted by stand-off pins to the support structure. Figure 5.9.2-5 shows the mounting of the 1N structure to the TRD.

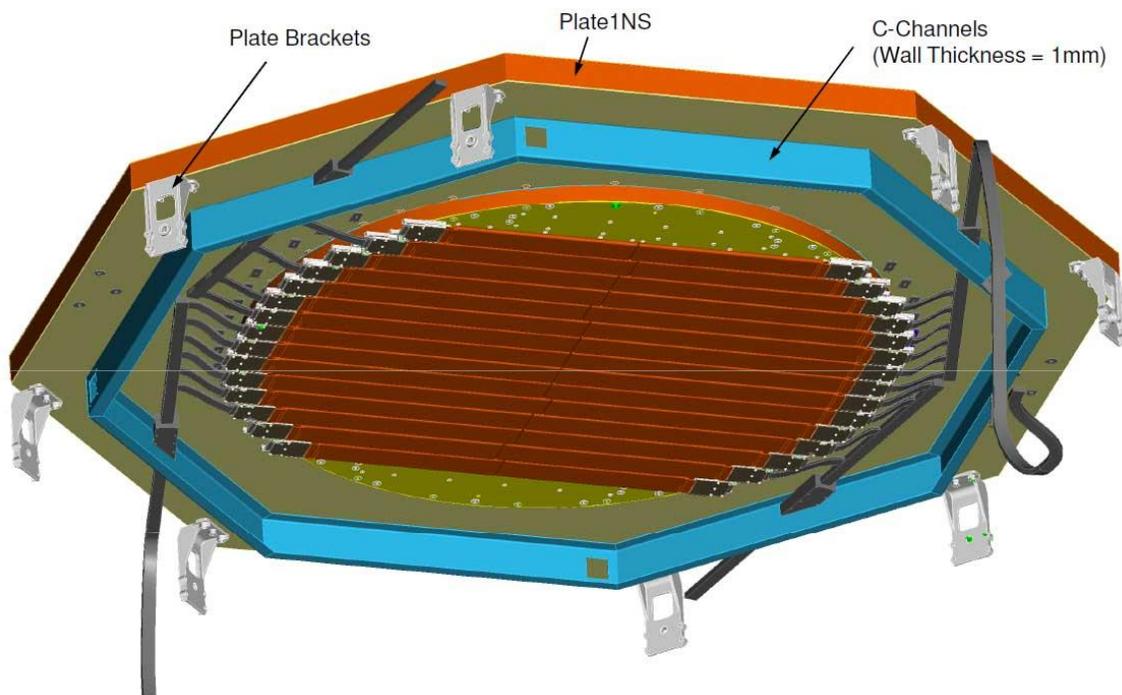


Figure 5.9.2-4 Tracker Plane 1N and Support Structure

A selected removal of outer planes has been made to populate the new Tracker Plane 6. Thermostatically controlled heaters, an A and B chain, are mounted to 1NS to warm Tracker Plane 1N as it sits on the deep space zenith surface of the AMS-02. The heater/thermostat combination is designed to warm the planes and preclude thermal runaway that could damage the composite structure that they are mounted to.

Atop 1NS, the GPS patch antenna will be mounted by way of a short bracket to position the receiver's antenna for best GPS signal reception.

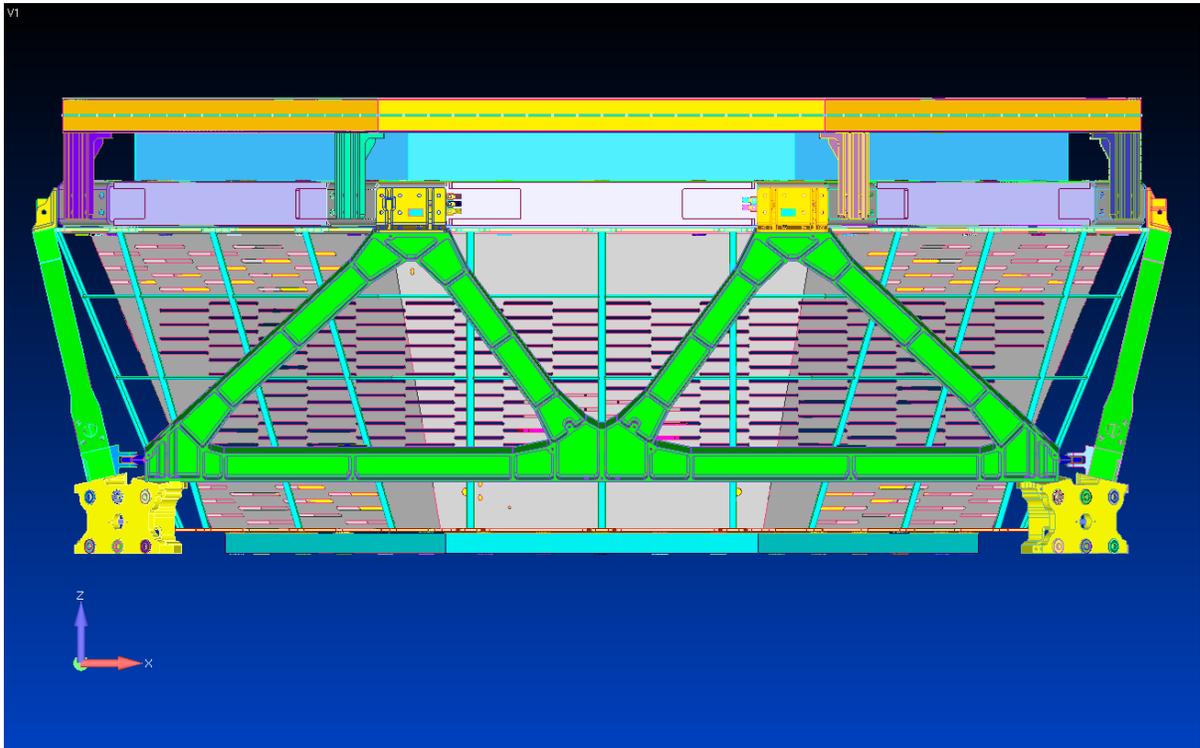


Figure 5.9.2-5 Installation of Tracker Plane 1N to TRD

The Tracker Silicon Ladders are assembled and wrapped to provide containment of the potentially fragile silicon wafers as they are in the Core Tracker assembly. A “C” channel is used around the perimeter will provide the final layer of containment, closing the distance between the support structure and the top of the TRD structure, with RTV between the “C” channel and the TRD used to finish the seal when installed. The volume will be vented through a light tight chicane that has a fine mesh to contain any fractured silicon components that may be released by the adhesive retention.

5.9.2.2.1 Tracker Plane 1N Support Structure

The Tracker Plane 1NS is fabricated from M55J fiber/cyanate ester composite face sheet with a 7 cm (1.755 in) Hexcell composite honeycomb core and serves to provide the structural support for plane 1N .

5.9.2.3 Tracker Plane 6

Tracker Plane 6 is a new plane which uses a composite face-sheet/aluminum honeycomb core structure similar to the other tracker planes. This new plane is mounted between the Ring Imaging Cerenkov Counter (RICH) and the Electromagnetic Calorimeter (ECAL), as shown in Figure 5.9.2-6. A single layer of silicon ladders is mounted on the upper face of the plate, facing the RICH. These ladders have been taken from other planes and are identical to the tracker elements on the other planes.

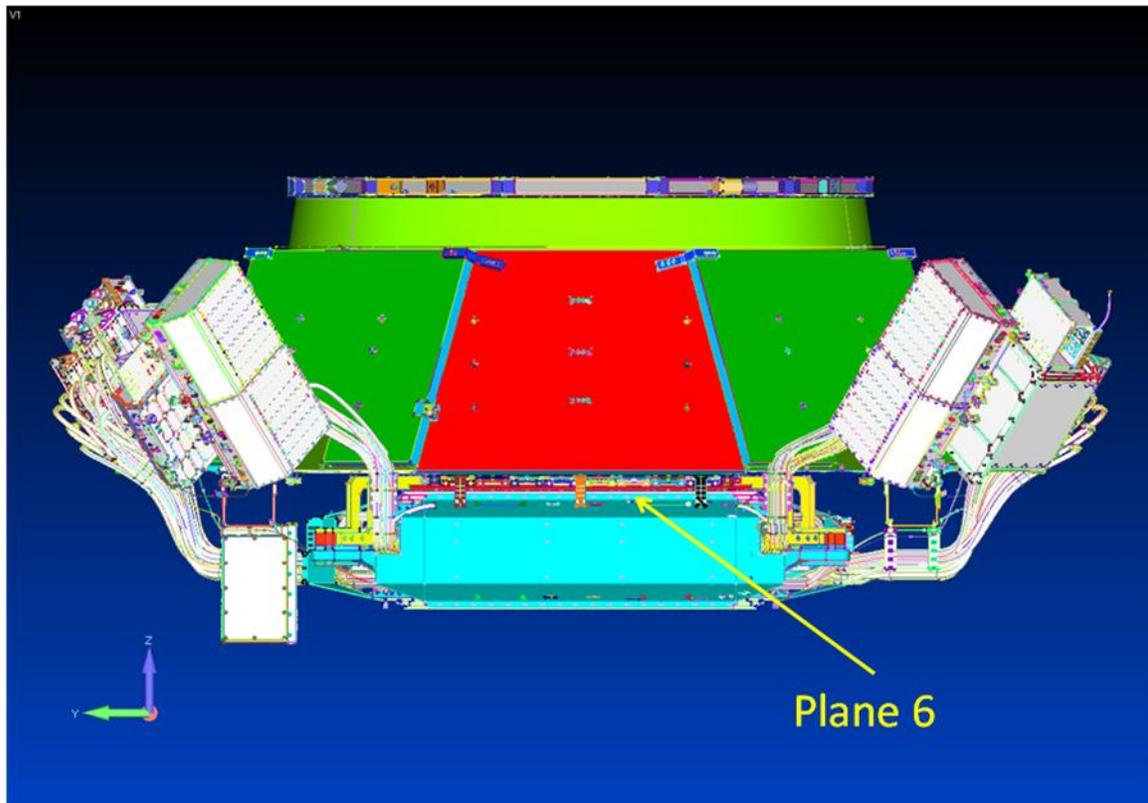


Figure 5.9.2-6: Tracker Plane 6

Plane 6 is supported by four L-shaped brackets made of Al 7075 which tie to the lower part of the USS-02 at the same mounting locations used by the ECAL. A 35mm Al 7075 spacer attached between the prongs of this bracket lowers the ECAL by the same amount, which provides enough room for both the plane and the ladders to be installed. This movement of the ECAL has been assessed and does not create a hazard during payload bay, berthing, or on-orbit operations. Both the bracket (yellow) and the spacer (orange) are shown in Figure 5.9.2-7. Figure 5.9.2-8 shows a representative component group and

Figure 5.9.2-9 shows the assembled Plane 6 prior to integration of electronics and ladder assemblies.

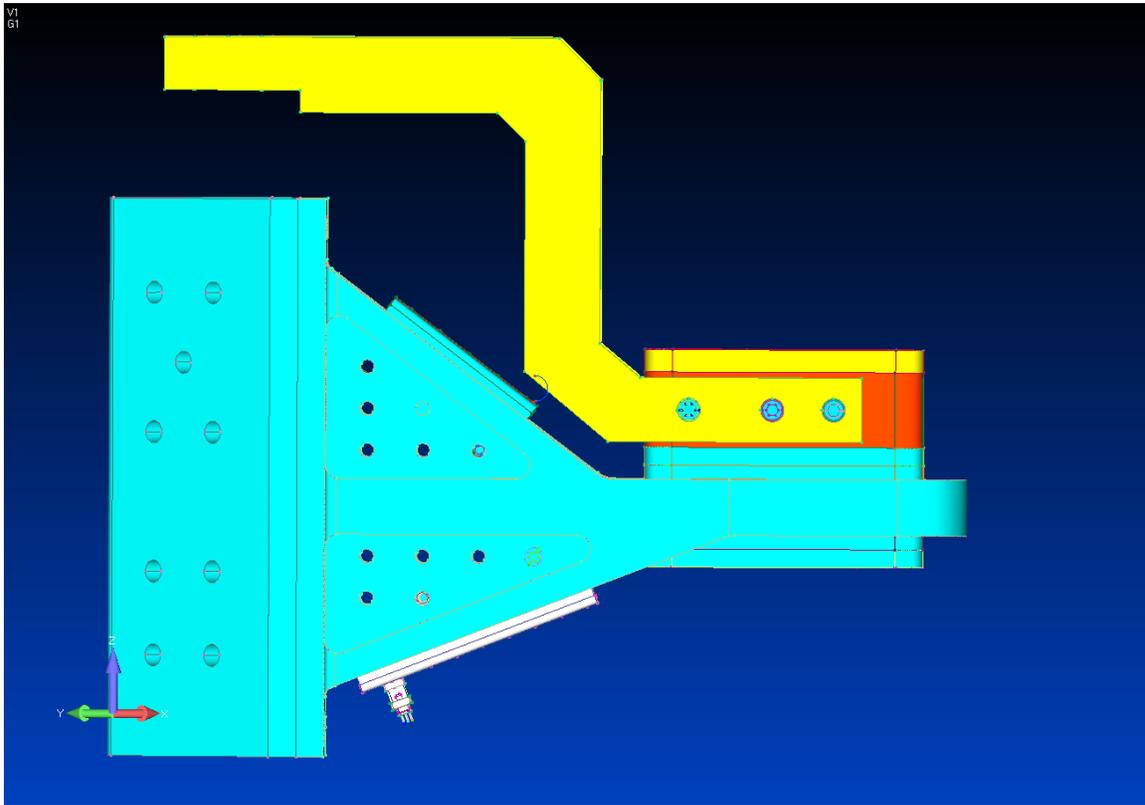


Figure 5.9.2-7 Plane 6 Support Structure



Figure 5.9.2-8: Bracket and Spacer Components after Manufacturing

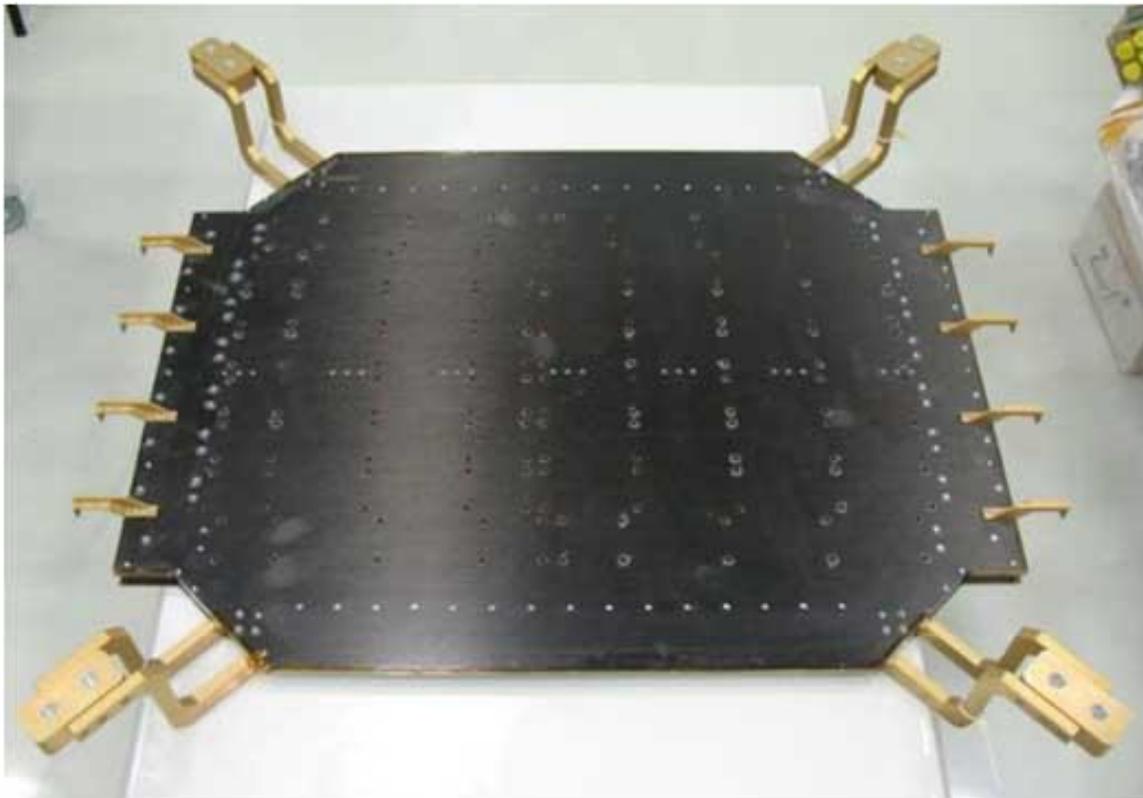


Figure 5.9.2-9: Tracker Plane 6 without Ladders

5.9.2.3.1 Tracker Plane 6 Structure

The Tracker Plane 6 Lower Plate is fabricated from M55J fiber / cyanate ester composite face sheet with a Hexcell composite honeycomb core and supports the silicon plane ladders, electronics, and the upper and lower cover which are also manufactured from M55J fiber / cyanate ester composite face sheet. See figure 5.9.2.3.1-1. These face sheets combined with C-channels lateral ribs serve to enclose the electronics. Two vent holes (chicanes) providing pressure equalization with light tightness. See figure 5.9.3-2.

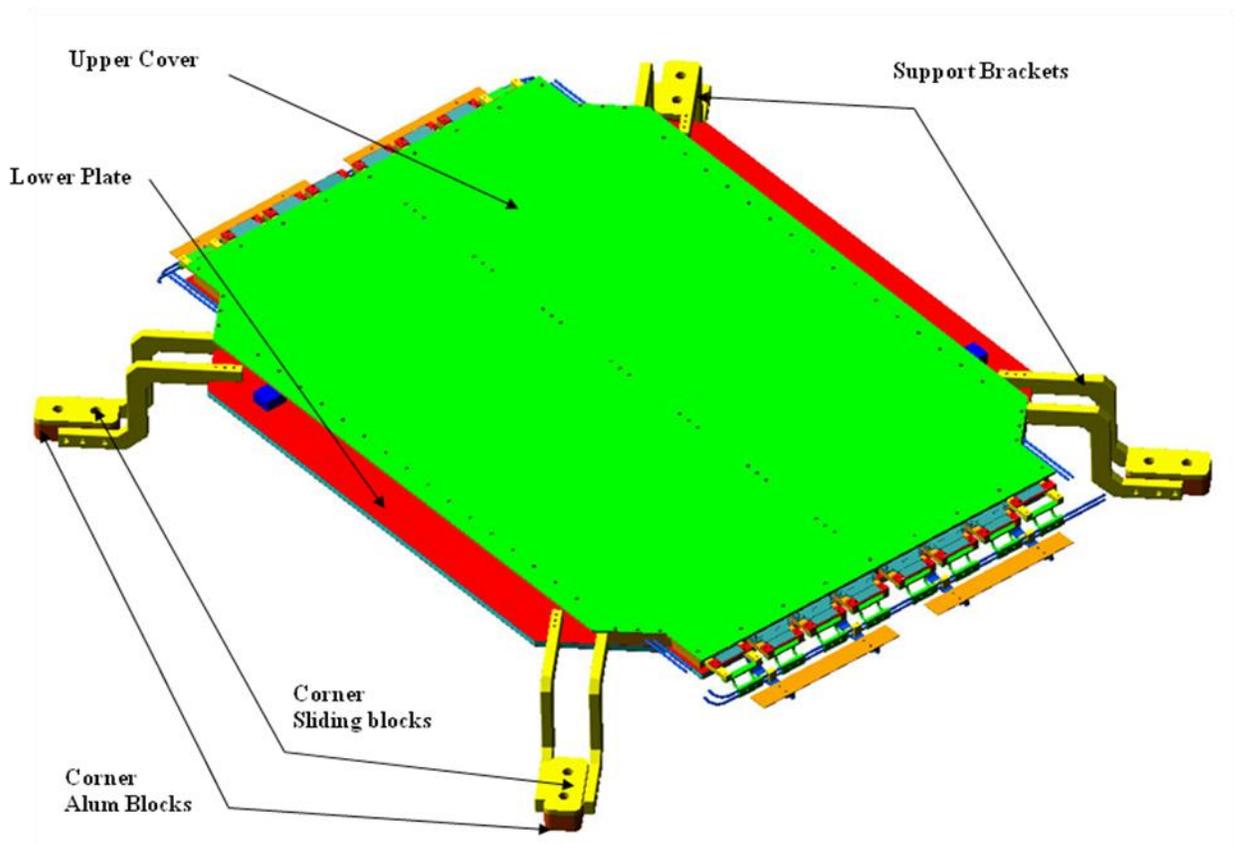


Figure 5.9.2.3.1-1 Tracker Plane 6

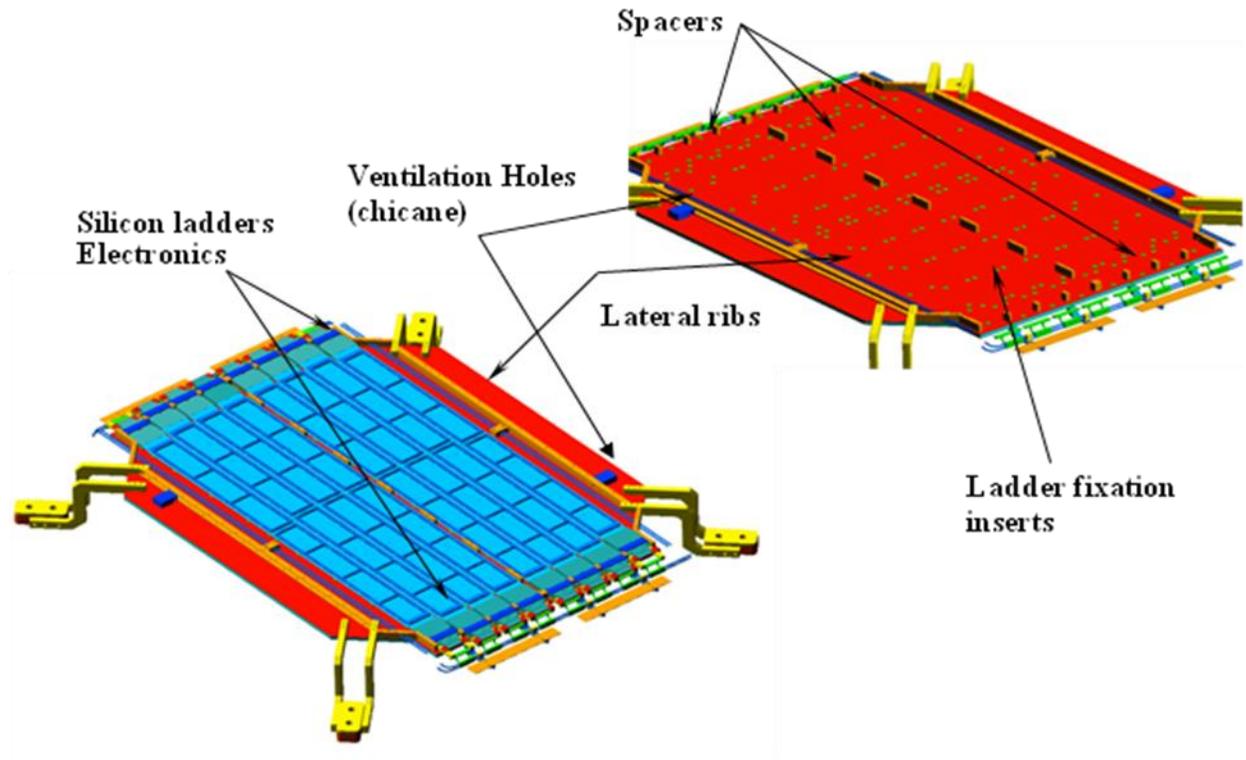


Figure 5.9.2.3.1-2 Tracker Plane 6 Internal Structure

Tracker Plane 6 is integrated into the TTCS cooling system and provides internal cooling bars for heat transfer to the cooling pipes. Pipe supports are secured to the honeycomb carbon fiber face sheet composite structure. Cabling that services the silicon ladders are secured to cable trays which are also secured to the honeycomb/carbon fiber face sheets composite structure. See figure 5.9.2.3.1-3.

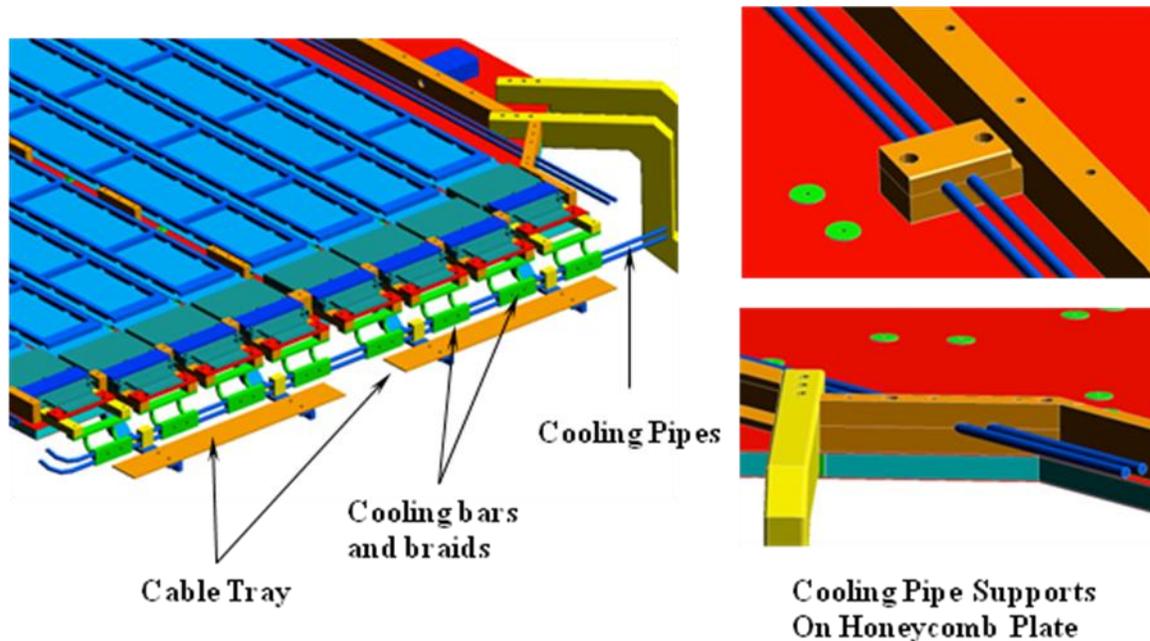


Figure 5.9.2.3.1-3 Tracker Plane 6 Internal Cooling

5.9.3 Tracker Alignment System (TAS)

The Tracker Alignment System (TAS) provides optically generated signals in 7 layers of the silicon tracker that mimic straight (infinite rigidity) tracks of particles. It has been shown with AMS-01 that these artificial straight tracks allow the tracing of changes of the tracker geometry with a position (angular) accuracy of better than $5\ \mu\text{m}$ ($2\ \mu\text{rad}$). The system uses the same silicon sensors for both particle detection and control of the alignment. It serves to generate position control data within seconds at regular time intervals (4 to 6 times per orbit), for example, while the ISS flies into the shadow of the Earth or comes back into the sunlight.

The TAS is represented in Figure 5.9.3-1. A total of 20 fiber optic carried laser beams are used in generating the alignment beams (20 beam paths and fibers have been removed with the move of Tracker plane 5 to become plane 1N.) The beams are narrow (diameter $< 0.5\ \text{mm}$) and of small divergence ($< 1\ \text{mrad}$). The TAS generates laser energy from ten independent laser diodes, each pair of the diodes are contained within one of five Laser Fiber Coupler (LFCR) boxes (Figure 5.9.3-2). This energy is generated by Eagleyard EYP-RWL-1083 infrared (1083 nm) laser diodes with a maximum power output of 80

mW. Each laser diode will emit at a 1 kHz interval with a pulse duration less than 8 μ s when operating. Each laser diode's emissions are split into four mono-mode optical fibers as an output of the LFCR, each optical fiber with approximately one quarter of the total power output. Half of these outputs are blocked at the output of the LFCR and half are transferred by fiber optics to the Tracker plane 1 LBBX. The LFCR boxes are light tight and cannot release any laser emissions with the exception of the fiber ports where laser emissions are nominal design features.

The beams enter the tracker volume through 5 pairs of Laser Beamport Boxes (LBBX) mounted on the outer face of the top outer tracker support plane (Plane 1 only) (Figures 5.9.3-3 thru 5.9.3-5). Each LBBX accepts four fibers and directs these independent laser sources through a common beam location on the Tracker (allowing for minor source location differences of the twenty independent beams because of LBBX interior reflector positioning). The tracker sensors on the alignment beams are equipped with antireflective coatings (SiO_2 and Si_3N_4) optimized for the wavelength chosen (residual reflectivity $\sim 1\%$). In addition, the readout strip metallization width was reduced to 10 μm width in the coated areas and the other implants not metalized. Together these measures have resulted in a transparency of the alignment sensors of 50% and the (now removed) 8th layer of the tracker receives about 0.8% of the intensity coming out of the LBBX. A Laser alignment will be performed coincident with data taking. The operation of the TAS consists of less than 1% of the AMS-02 operational time.

The alignment of the Tracker planes 1N and 6 are accomplished by utilizing the alignment knowledge gained from the TAS and calculating the positioning of the outer planes by utilizing cosmic ray particles as alignment sources. Positioning of the planes is calculated using an algorithm that predicts the cosmic ray's path and then adjusts the position of the planes for data reduction purposes.

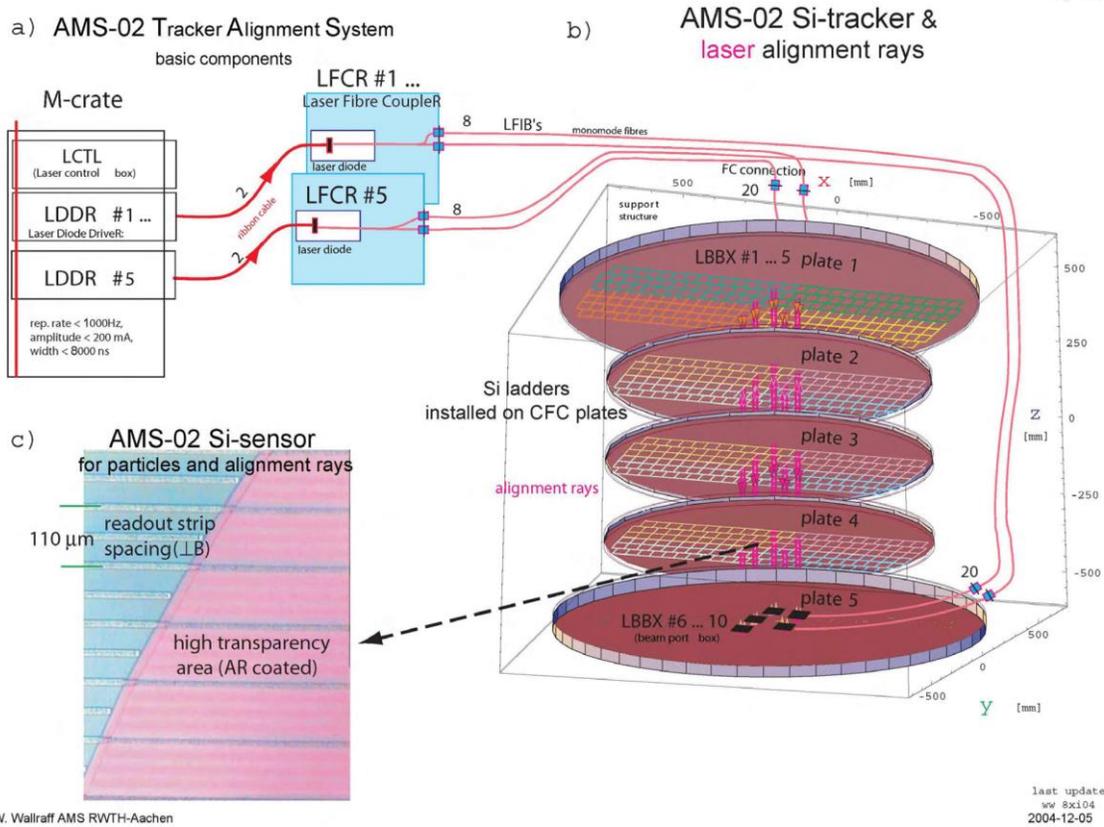
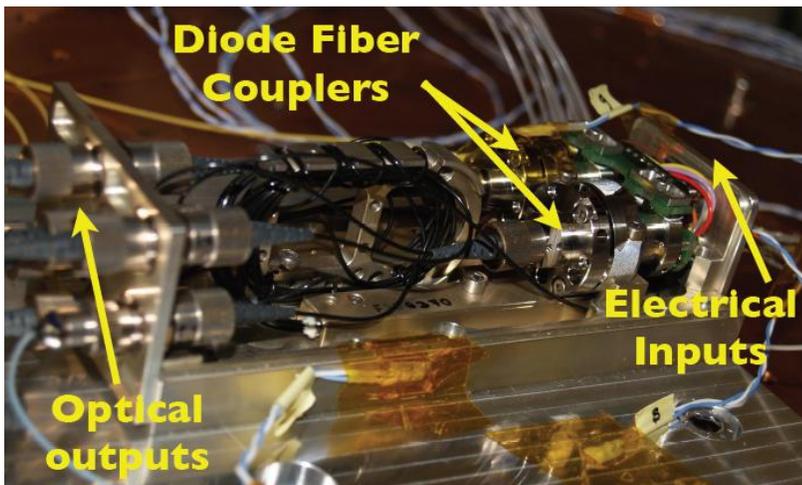


Figure 5.9.3-1 AMS-02 Silicon Tracker Laser Alignment System (TAS) Overview (Top Plane used only)



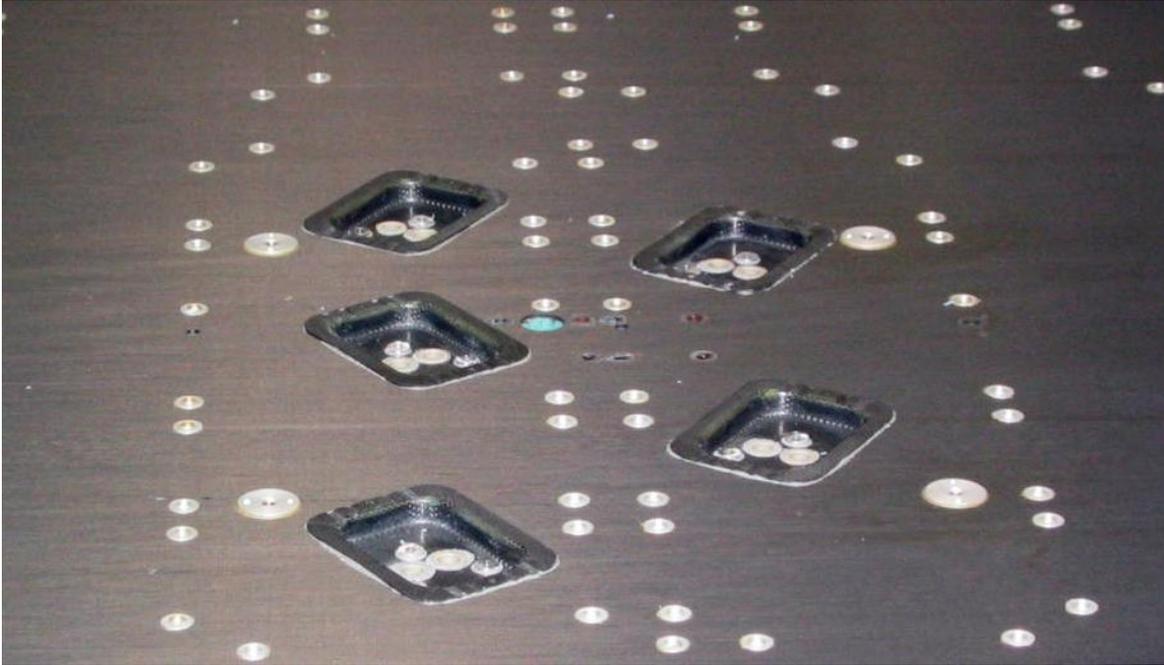


Figure 5.9.3-4 LBBX on Tracker Plane 1

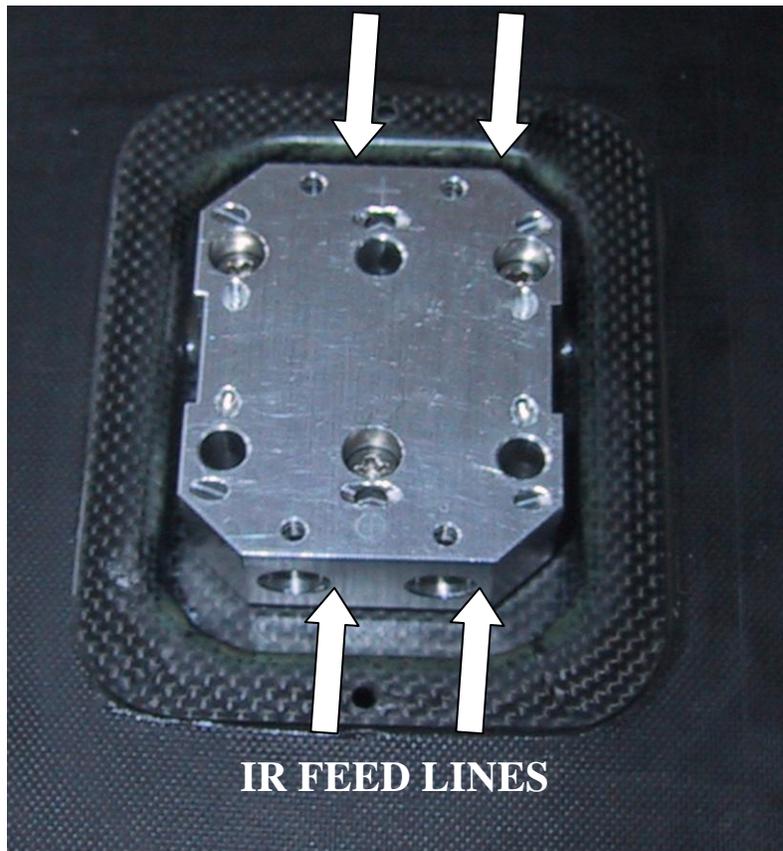


Figure 5.9.3-5 A Laser Beamport Box (LBBX) installed on Tracker Plane 1

5.9.4 Tracker Thermal Control System (TTCS)

The TTCS is one of the most complex thermal control systems used on AMS-02. The Tracker, which is completely encased inside the inner bore of the Vacuum Case, generates 144 watts which need to be rejected while minimizing heat flow to the vacuum case inner cylinder. The TTCS thermal design includes thermal bars, a pumped CO₂ cooling loop, radiators, manifolds, accumulators and numerous other components. A detailed description of the TTCS is included in Section 5.13.7 of this SDP.

5.10 RING IMAGING CERENKOV COUNTER (RICH)

The RICH subdetector is located near the bottom of the experiment stack, below the Lower TOF and above the ECAL. The RICH is used to measure the velocity of the particles that traverse the AMS-02. The RICH is able to determine the velocity of charged particles by measuring the vertex angle of the cone of Cerenkov light emitted as the particle passes through a tile of the silica aerogel or sodium fluoride that forms the “radiator”. Cerenkov radiation from the Cherenkov Effect is emitted as a charged particle passes through a transparent non-conducting material at a speed greater than the speed of light in that material. It consists of visible and ultraviolet light that can be detected and counted by means of the RICH photomultipliers (PMTs). The number of photons per particles gives a measure of the charge of the traversing particle. The use of a high efficiency reflector ring allows for greater data acquisition than direct incident of the photons on the PMTs alone, without the ring, the plane of sensitive PMTs would be much larger.

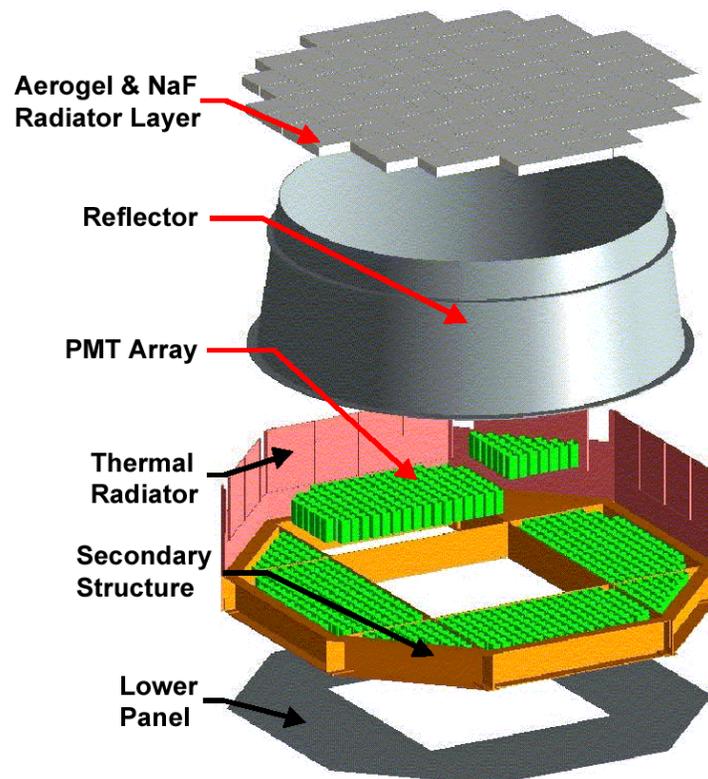


Figure 5.10-1 RICH Basic Elements

Functionally the RICH is composed of three basic elements, the top layer, the Cerenkov radiator, is composed of silica aerogel and sodium fluoride (NaF) blocks that serve as sources for the Cerenkov photons. An intermediate conical mirror and the lower PMTs are supported by a strong aluminum frame that constitute the primary structural interface. In the top layer the aerogel and NaF blocks are mounted within a carbon fiber reinforced composite (CFRC) container that provides mechanical rigidity of the elements and provides an enclosure. The aerogel and NaF blocks are between a PORON spacer and carpet and a Polymethylmethacrylate (PMMA) cover that seals with a Viton gasket to the CRFC structure. The PMMA cover allows the photons generated by the passage of the high-energy particles to be observed by the photomultipliers while containing the radiator inside the container.

Figures 5.10-2, 5.10-3 and 5.10-4 show the general construction of the assembly.

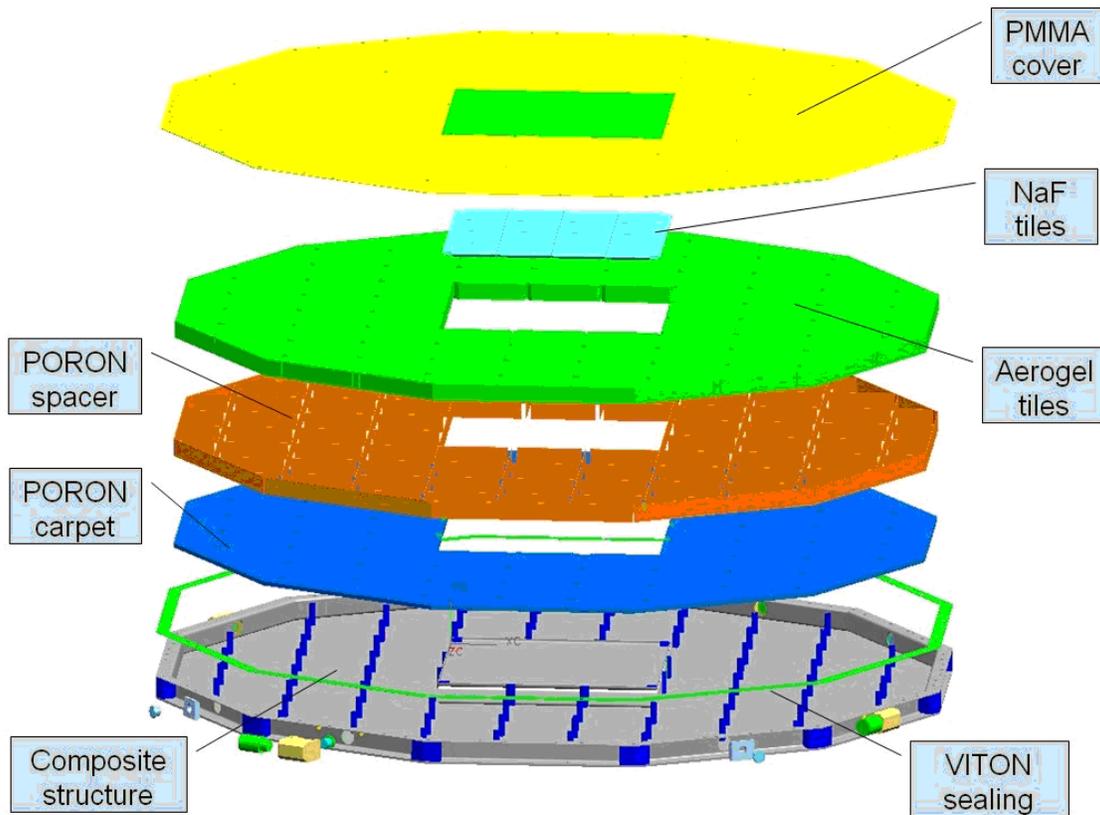


Figure 5.10-2 RICH Aerogel & NaF Container

The RICH upper assembly of aerogel and NaF blocks is vented during ascent by four vent valves and during descent pressurization is controlled by three vent valves. In order to protect this volume once constructed it will be purged through a dedicated valve port with dry nitrogen to provide a clean controlled environment within the Cerenkov Radiator. 50 μm filter screens on the valves will prevent large aerogel or NaF particles that could possibly evolve from being released or exterior contaminants becoming ingested. The locations of these valves are shown in Figures 5.10-3 and 5.10-4 and a cross section of the selected breather valve is shown in Figure 5.10-6. These valves will be Halkey Roberts C770RP 1.0 one way valves that have a cracking pressure with a 1 psi differential. The valves will be interfaced to the 50 μm filter screens through a polyetheretherketone (PEEK) interface block as shown in Figure 5.10-7. During ground handling/transportation and processing this interior volume is protected from thermal and atmospheric pressure variation introducing humidity into the interior of the Cerenkov Radiator by having a buffer volume contained within an expandable reservoir (0.5 l) made of Teflon®/Tedlar® supported within a vented enclosure and a positive flow of dry nitrogen supplied by a ground based source. This expandable reservoir is represented in Figures 5.10-5 and 5.10-8 a-c. Design of this assembly assures that there will not be more than a 1 psi differential between the interior and exterior pressure, even when a GSE supplied blanketing pressure flow of dry nitrogen is provided into the volume to keep the aerogel and NaF blocks from acquiring moisture. Reentry loads of pressure loading on the aerogel during pressurization have been conservatively established to be approximately 1/15th of aerogel compression allowable. The aerogel is considered the most sensitive element of the sandwich of materials.

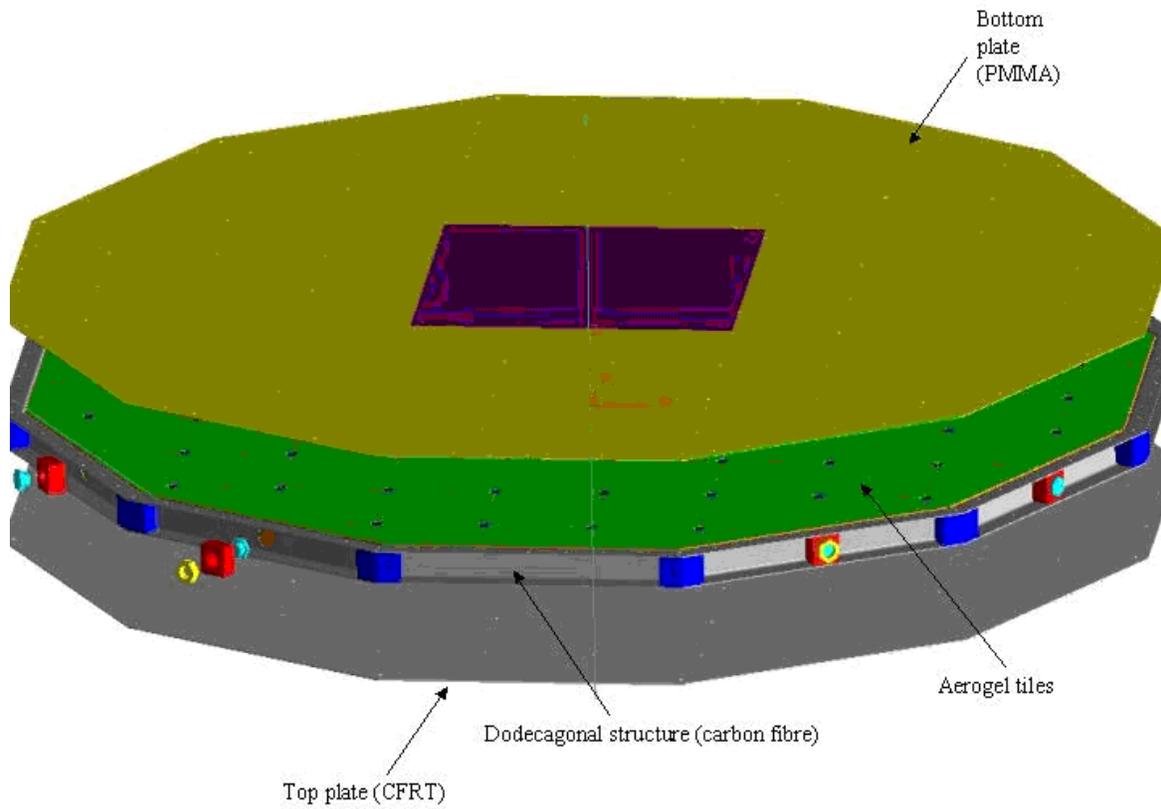


Figure 5.10-3 RICH Aerogel and NaF Assembly

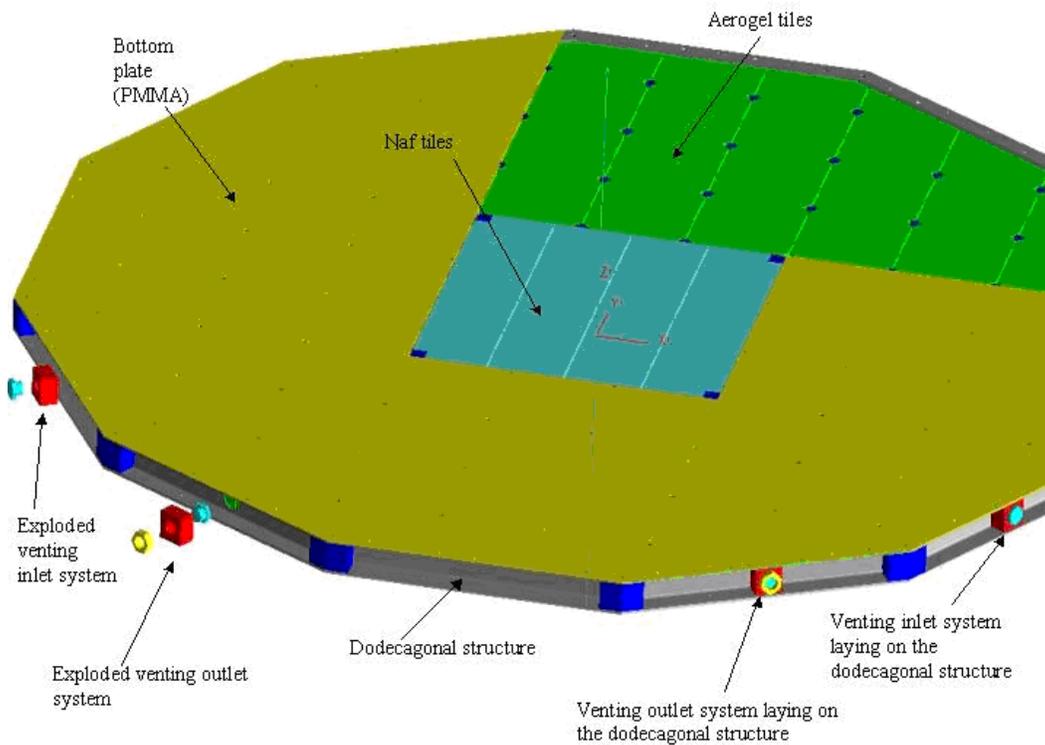


Figure 5.10-4 RICH Aerogel and NaF Assembly

(Vent interface updated in Figure 5.10-7)

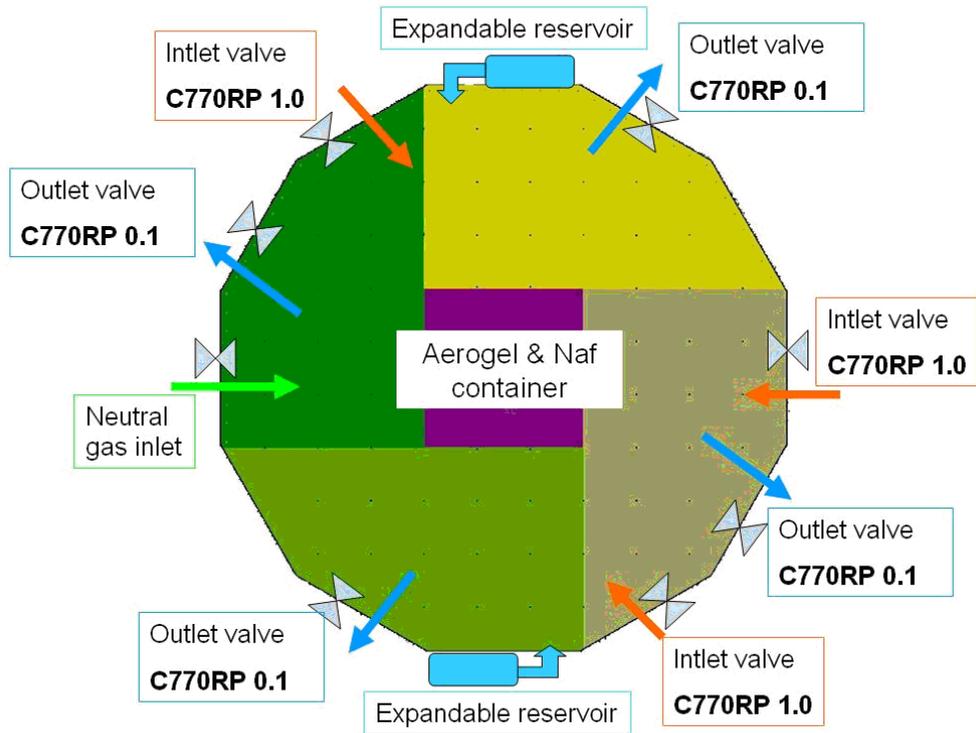


Figure 5.10-5 RICH Functional Venting, Interior Environment Control

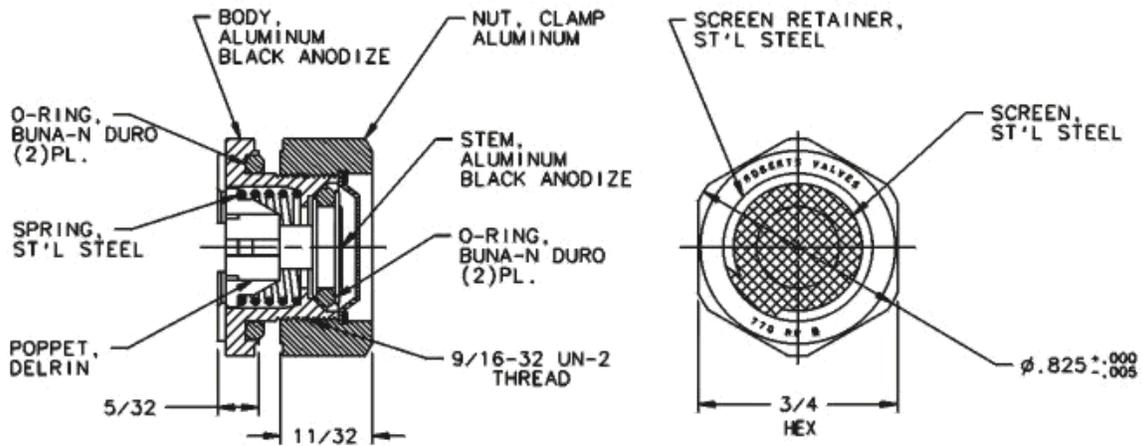


Figure 5.10-6 RICH Halkey-Roberts C770RP 1.0

(Cracking Pressure =- 1.0 psi)

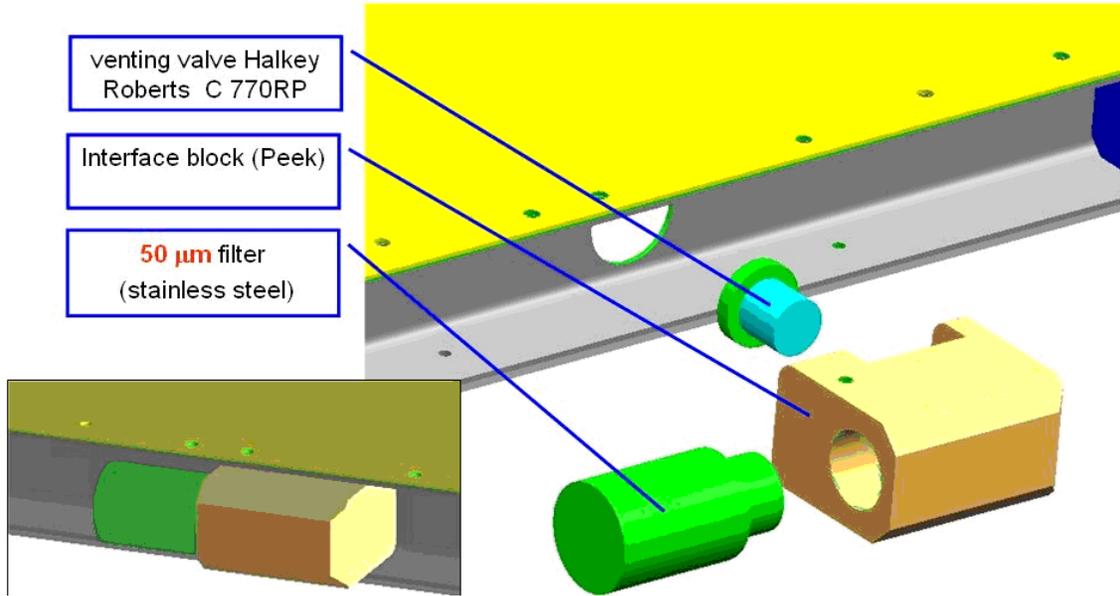


Figure 5.10-7 RICH Vent Valve and Filter Installation

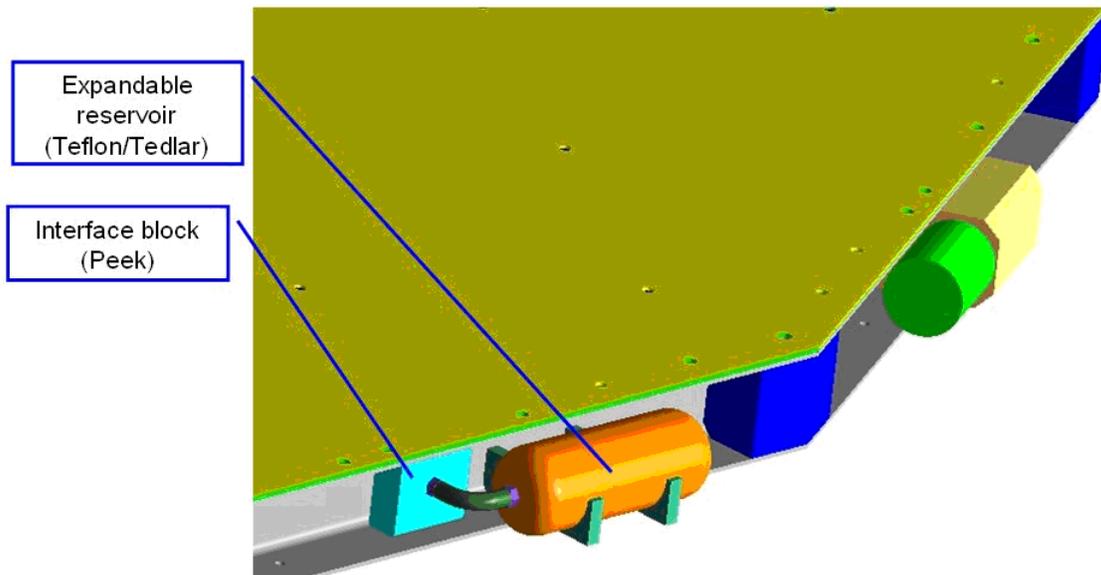


Figure 5.10-8a RICH Expandable Reservoir

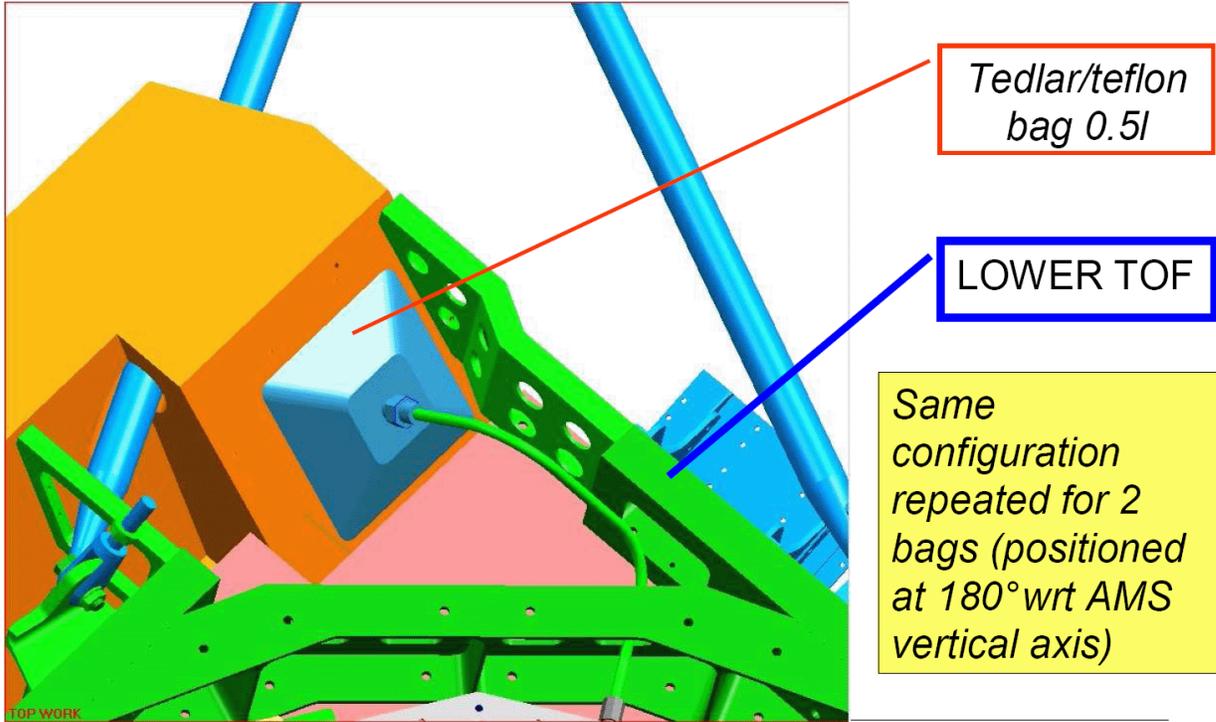


Figure 5.10-8b RICH Expandable Reservoir

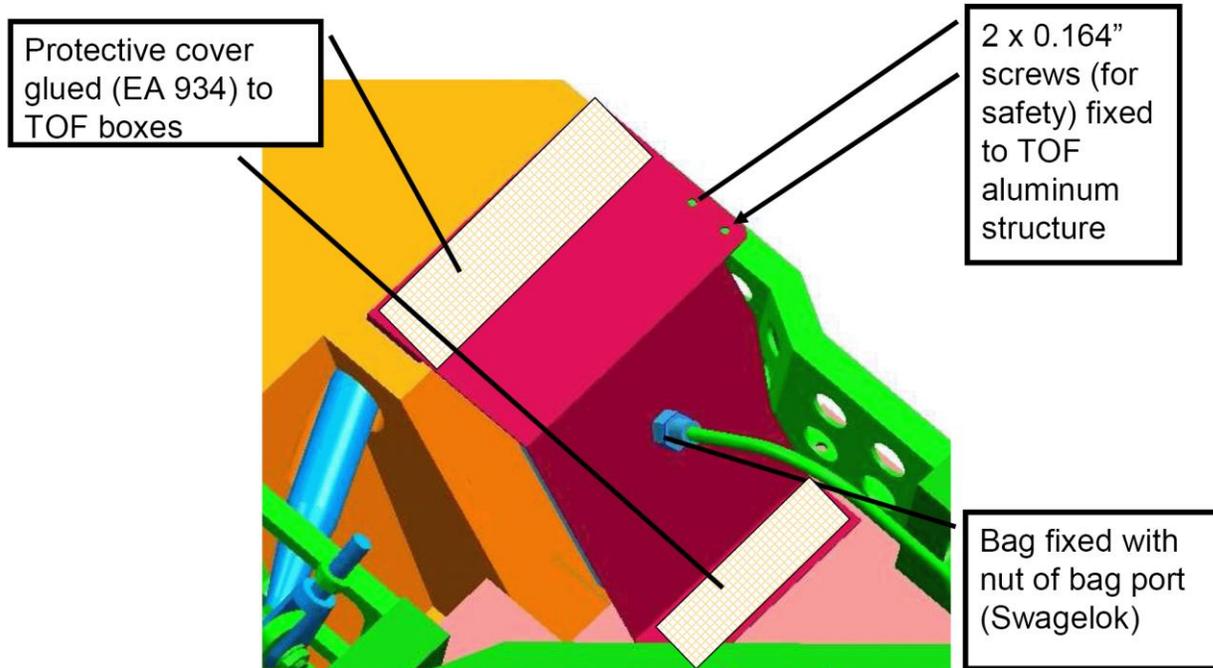


Figure 5.10-8c RICH Expandable Reservoir Cover

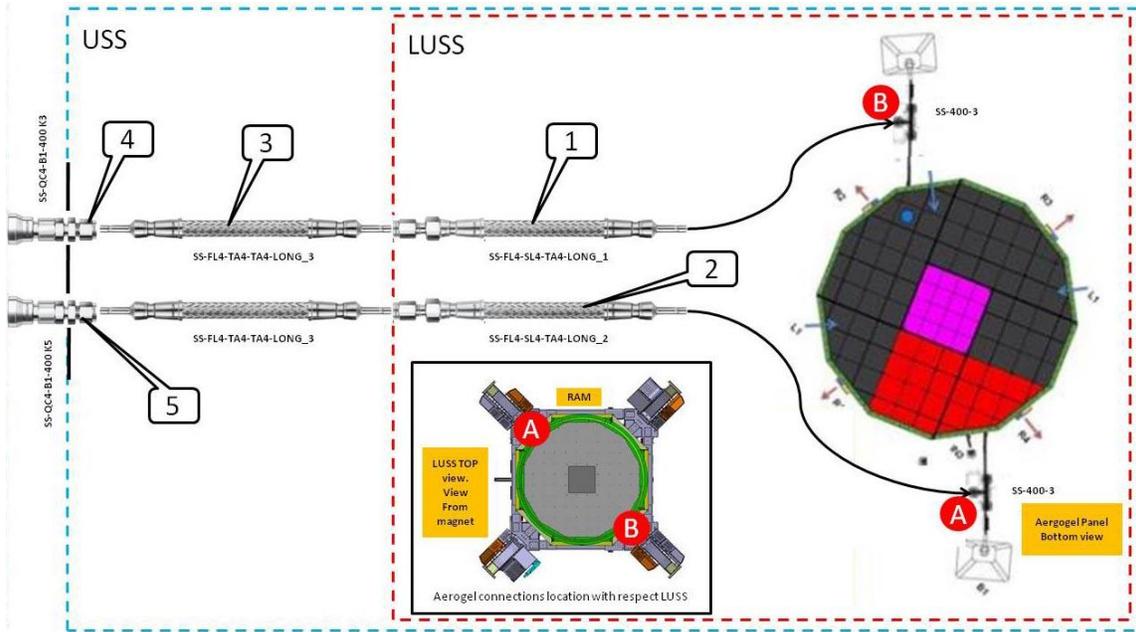


Figure 5.10-9 RICH N2 Flow System (Ground Use Only)

The second layer of the RICH is a reflector that is shaped as a truncated cone. The interior surface of this element is a highly polished composite/metal mirror. The mirror is manufactured in three pieces (Figure 5.10-10) to be very light and have a precise, highly reflective, surface. The reflector is made of carbon fiber composite material with layers of deposited aluminum and transparent quartz (to protect from oxidation). A debris shield consisting of eight carbon fiber composite/aluminum honeycomb panels surround the reflector to protect it from penetrations that would damage the mirrored surface and allow light to enter the RICH and disturb detection.

TABLE 5.10-1 RICH MIRROR COMPOSITION

Carbon Fiber/Epoxy Resin	1.5 mm
Aluminum	0.1 μm
Quartz	200 nm

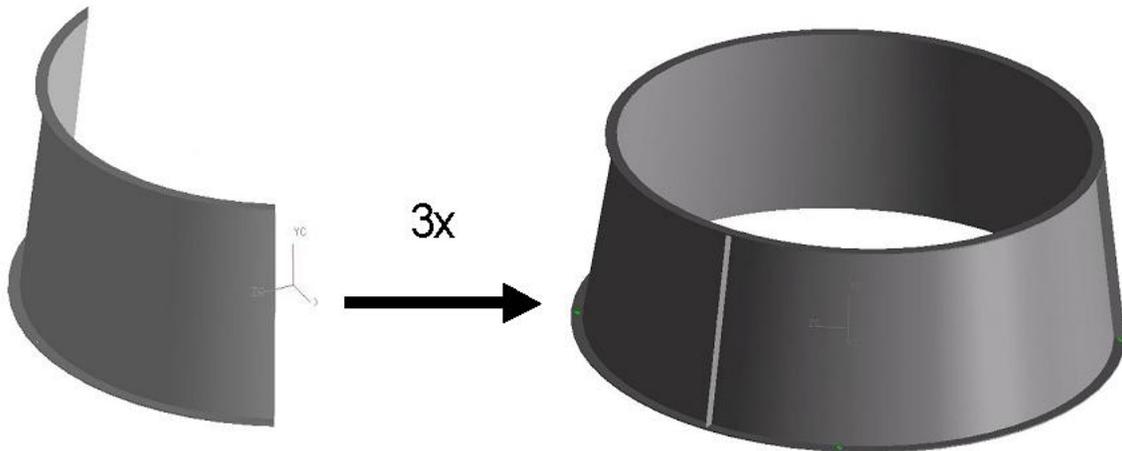


Figure 5.10-10 RICH Reflector Construction

The lower layer of the RICH is the primary structure that supports the RICH and interfaces to the Lower USS-02. Within the secondary structure of the lower assembly are the rectangular and triangular arrays of photomultiplier tubes that will detect the photons from the Cerenkov radiation. Construction of the Lower RICH support structure and PMT support grids are shown in Figure 5.10-11.

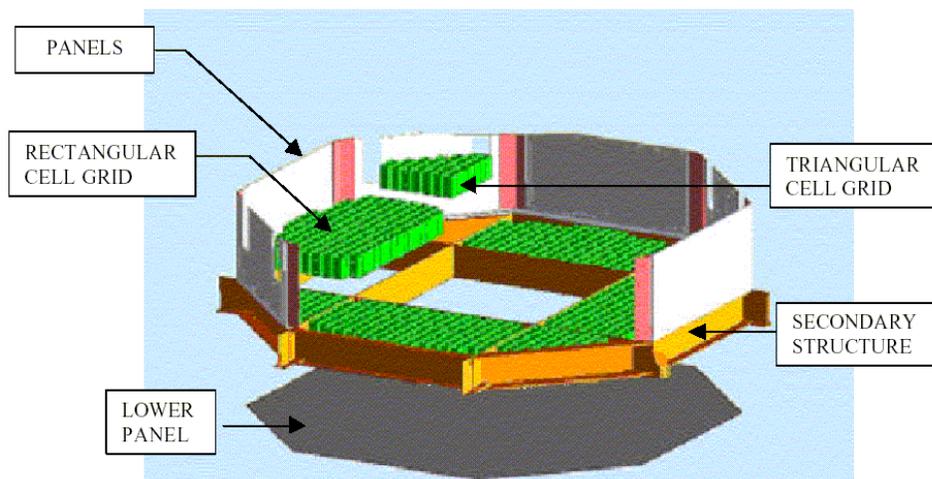


Figure 5.10-11 Lower RICH Construction

The PMTs for the RICH are constructed using Hamamatsu R7600 M16 photomultiplier tubes and a 4x4 matrix of light guides to correlate with the 4x4 photocathode grid of the photomultiplier tube. An optical pad assures the proper transmission of light into the photomultiplier tube and also seals off the glass front of the vacuum tube. The light

guides are glued into the optical pad and further retained by using Nylon cords. The assembly of an individual PMT is shown in Figure 5.10-12.

The base of the photomultiplier tube is potted and the boards of the PMT are conformally coated to protect the electronics and to limit the coronal breakdown potential for the high voltage system. This can be seen in the upper left image of Figure 5.10-13. The welded soft iron outer body provides attenuation of the magnetic fields and support interfaces for integrating into the RICH secondary structures as shown in the lower graphic of Figure 5.10-13.

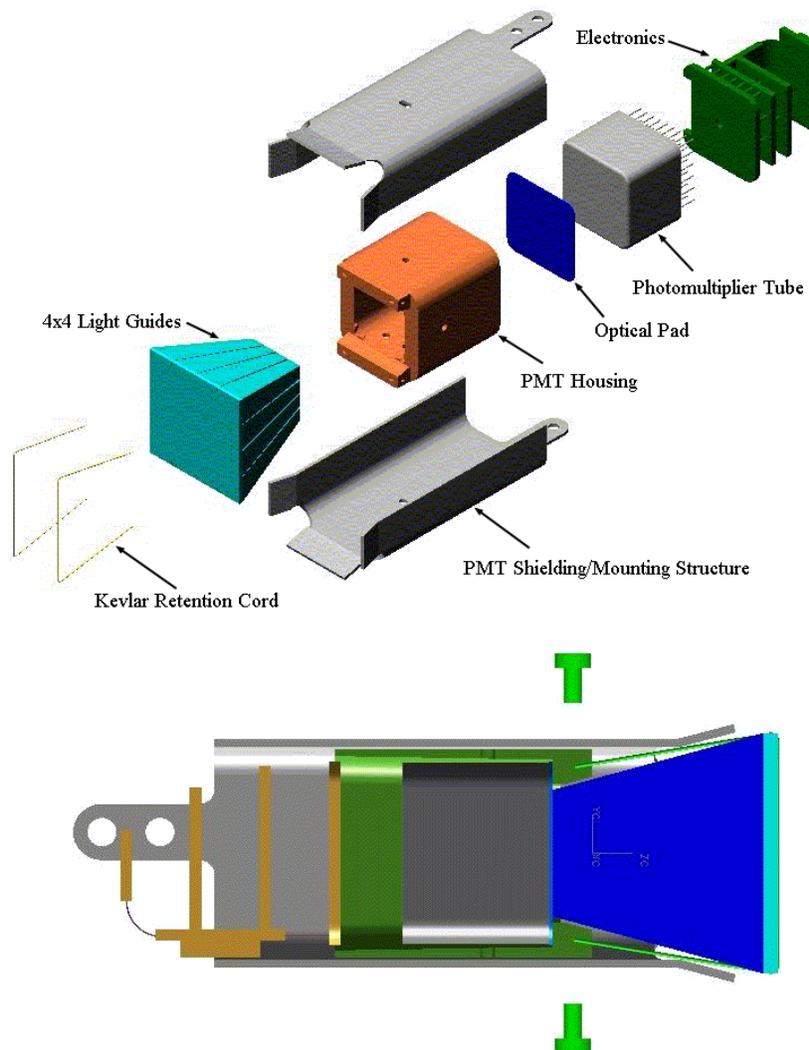


Figure 5.10-12 RICH PMT Construction
(Kevlar cord replaced with Nylon wire)

The individual PMTs are mounted to the triangular and rectangular grids shown in Figure 5.10-11. The upper right image of Figure 5.10-13 (a and b) shows the mounting technique used within the grids.

The RICH PMTs are powered by four RICH high voltage bricks attached to the Lower USS-02 structure. Each of these bricks generates voltages at 1000 VDC and supplies this voltage to the PMTs. The RICH high voltage bricks are fully potted as are the high voltage electronics on the PMTs. The cabling used to route this power is rated in excess of the voltages present and use high voltage connection techniques to eliminate possible sources for discharge, corona and electrical shock. Figure 5.10-14 shows the mounting locations for the high voltage bricks.

The signals from the PMTs are sent to the R Crate for data processing to establish the high energy particle or radiation incident characteristics.



Figure 5.10-13a RICH PMT Construction and Mounting

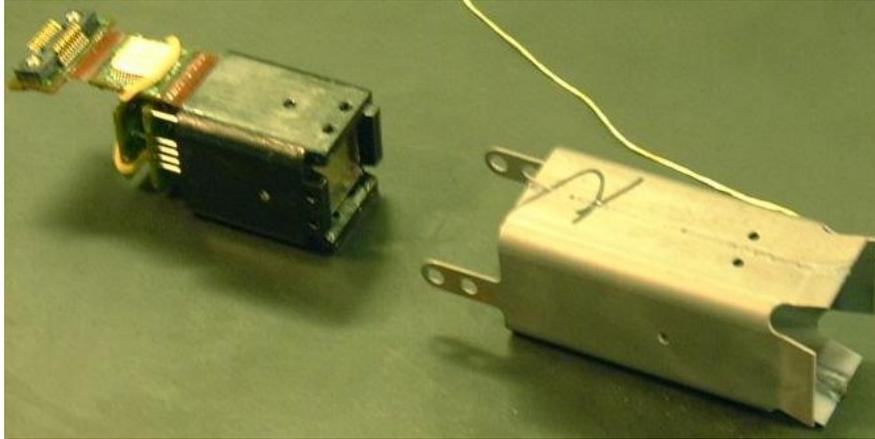


Figure 5.10-13b RICH PMT Construction and Mounting

The 406 lb (184 kg) RICH interfaces with 8 flanges on the Lower USS-02 as shown in Figure 5.10-15. Each interface uses 2 bolts per flange (16 total) secure the RICH to the Lower USS-02. Each of these flanges is riveted to the Lower USS-02 box beams with 24 structural rivets.

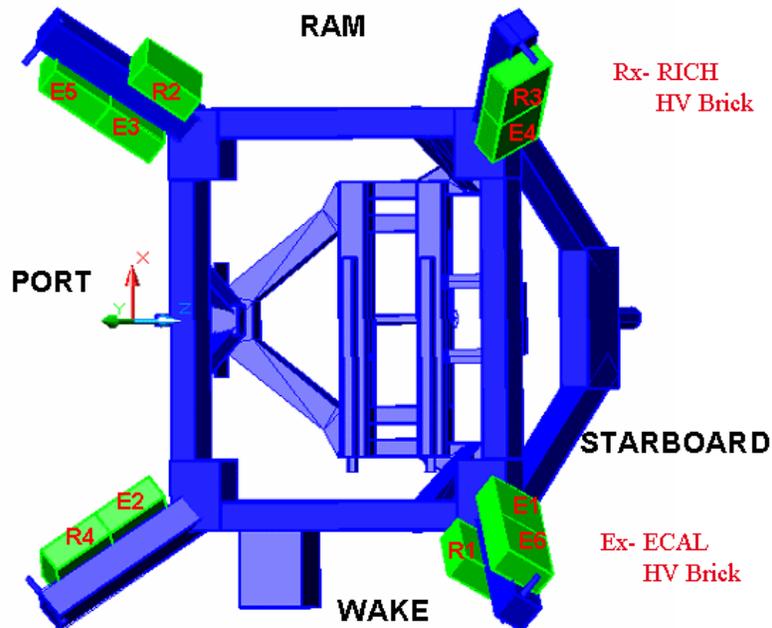


Figure 5.10-14 Lower USS-02 Mounting of RICH & ECAL HV Bricks

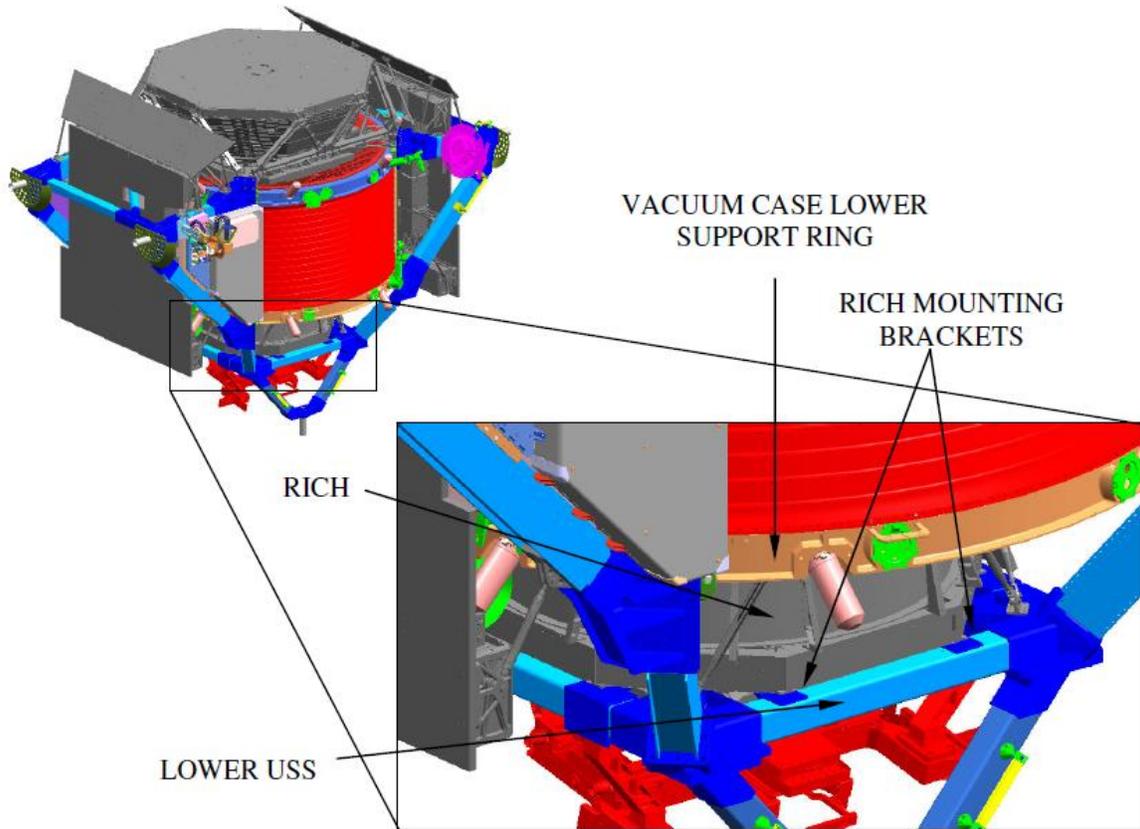


Figure 5.10-15 RICH Structural Interface

5.11 ELECTROMAGNETIC CALORIMETER (ECAL)

The Electromagnetic Calorimeter (ECAL) of the AMS-02 experiment is a fine grained lead-scintillating fiber sampling calorimeter that allows precise, 3-dimensional imaging of the longitudinal and lateral shower development, providing high ($\geq 10^6$) electron/hadron discrimination (identify particle type) in combination with the other AMS-02 detectors and good energy resolution (energy measurement). The calorimeter also provides a stand-alone photon trigger capability to AMS. The ECAL measures the energy of electrons, positrons and gamma rays up to 1 TeV.

The active sensing element of the ECAL consists of layers of lead foils and polymer scintillating fibers (Figure 5.11-1). Each lead foil layer is a lead-antimony alloy with a density of $11.2 \pm 0.5 \text{ gr/cm}^3$ with an effective thickness of 0.04 inch (1 mm). Each lead layer is grooved (rolled) on both sides (Figure 5.11-2) to accommodate the PolyHiTech Polifi 0244-100 scintillating fibers. Each fiber is 1.0 mm in diameter and is secured in the aligned grooves with BICRON BC-600 Optical glue that is applied as lead layers are assembled and pressed together. Each layer consists of 490 fibers across the 25.9 inch (658 mm) width of the layers. Lead layers are grouped together in “superlayers” (Figure 5.11-3) that are comprised of eleven layers of lead foil and ten layers of scintillating fibers. Each superlayer has all scintillating fibers oriented in the same direction, alternating the direction orthogonally of the fibers with each of the superlayers (Figure 5.11.1), 9 in total. Once assembled and pressed, each cured superlayer is milled to a uniform thickness of 0.7 inch (18.5 mm) thick. The superlayers are assembled as larger elements and sized (milled) for flight into squares with 25.9-inch (658 mm) long sides. The last (bottom) lead layer of the bottom superlayer has been replaced with a milled aluminum plate to reduce weight of the overall ECAL. Estimated savings by replacing the last plate with aluminum is approximately 2 kg.

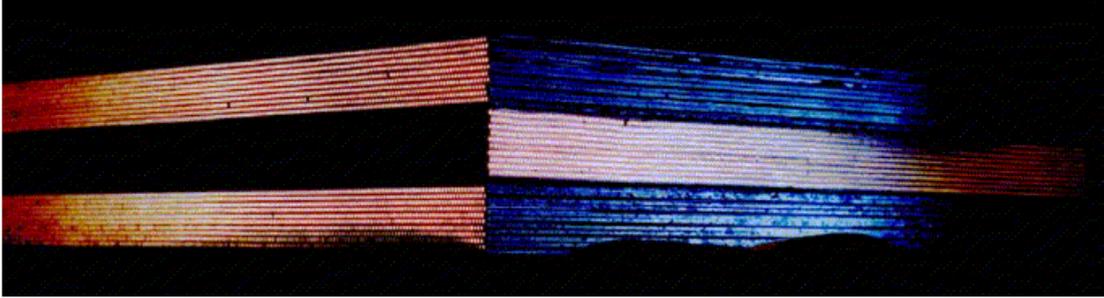


Figure 5.11-1 Three ECAL Superlayers
Alternating Layers Of Lead Foil And Scintillating Fibers And Alternating Superlayer Orientation

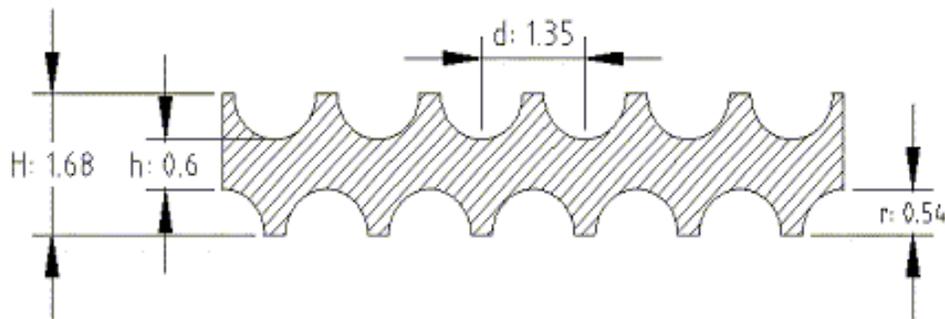


Figure 5.11-2 Individual Lead Foil Profile (Dimensions in mm)

The “pancake” of lead layers with scintillating fibers is the foundation of the ECAL sensor. Sensitive photomultiplier tubes (PMTs) are positioned around the periphery of the brick to sense photons generated by the passage of particles, secured against the edges of the brick where the Superlayer fibers terminate. A position of one of these PMT locations with its four pixels is depicted in red in figure 5.11-3. A side view of the ECAL (before the PMTs are installed) is provided in Figure 5.11.4.

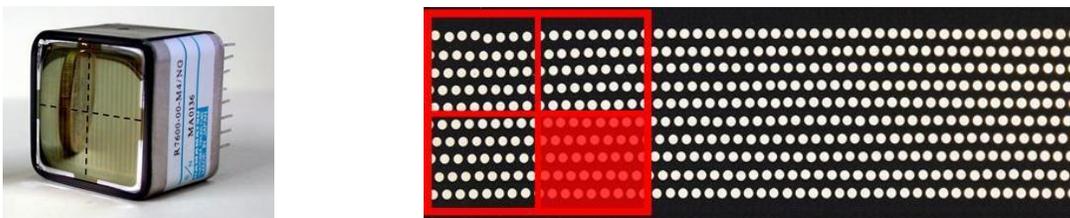
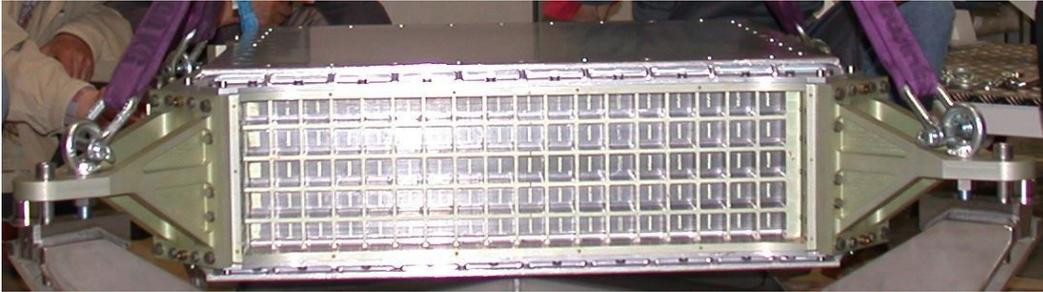


Figure 5.11-3 The 4-Anodes Photomultiplier and Superlayer Coverage



**Figure 5.11-4 ECAL Side Panel Grid
Prior to the installation of the PMTs**

The ECAL is approximately 31.5 inches (800 mm) square x 9.8 inches (250 mm) high and weighs approximately 1478 lbs (643 Kg). Approximately 75% of this weight is due to the lead foils.

The ECAL “pancake” is supported by the ECAL “box”. The box is made of 6 elements (Figure 5.11-5). The top and bottom pieces are aluminum honeycomb plates framed with aluminum. The plates are bolted to four lateral panels along the edges. The four lateral panels are made of Aluminum plates, 4 inch (10.16 cm) thick, carved with squared holes of 1.26-inch (32 mm) sides to house the light collection system. Four corner brackets, made of Aluminum plate, link the four plates together and connect the detector to the USS-02 at the bottom of the AMS-02 instrument (Figure 5.11-6). The four mounting locations include a pair of radial slotted holes so that the loads of the ECAL are transferred to the USS-02, but the loads from the USS-02 that are transferred into the ECAL are limited.

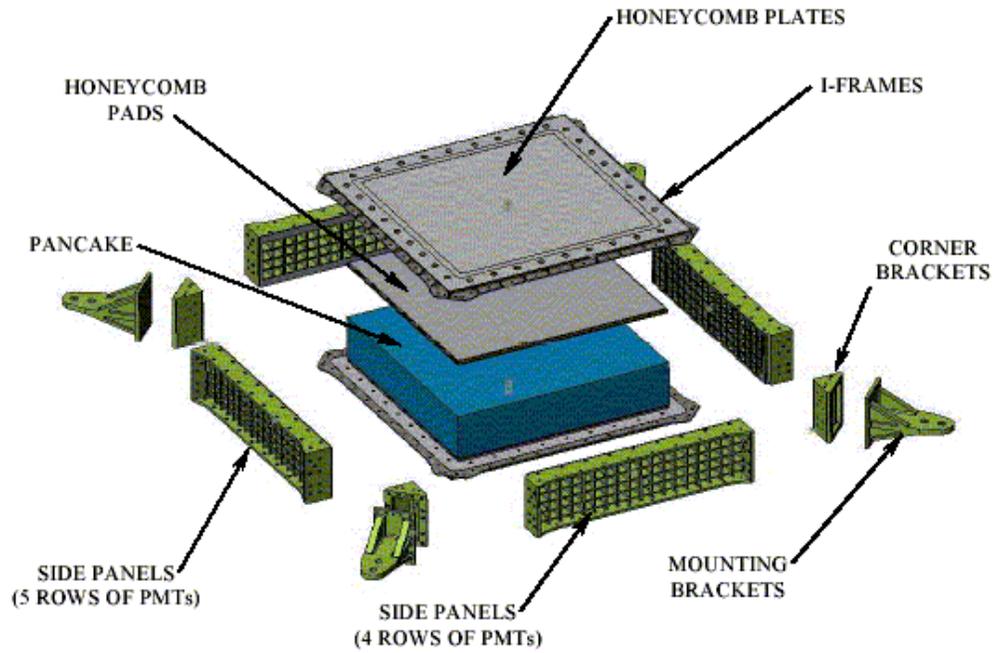


Figure 5.11-5 ECAL Construction

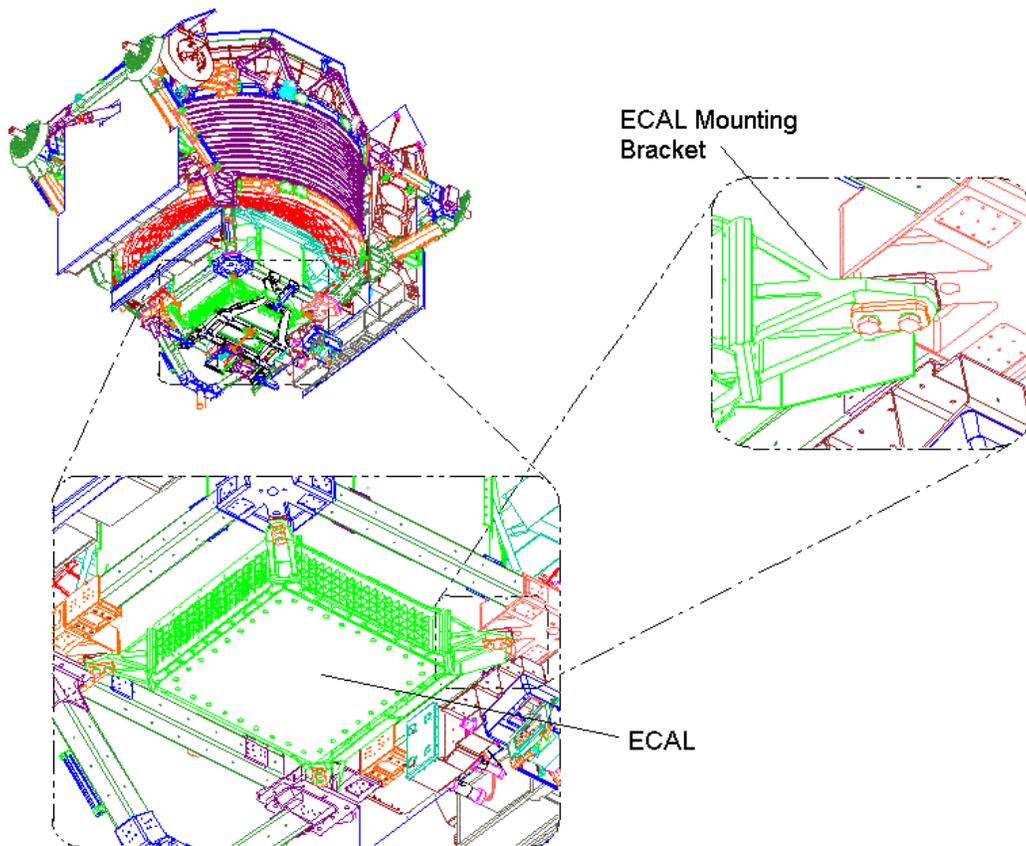


Figure 5.11-6 Location of the ECAL on the AMS-02

The light collection system is mounted about the periphery of the ECAL pancake in the four lateral panels. Two sides, serving 4 superlayers, have 72 holes while the two other faces, serving 5 superlayers, have 90 holes each (Figure 5.11-7).

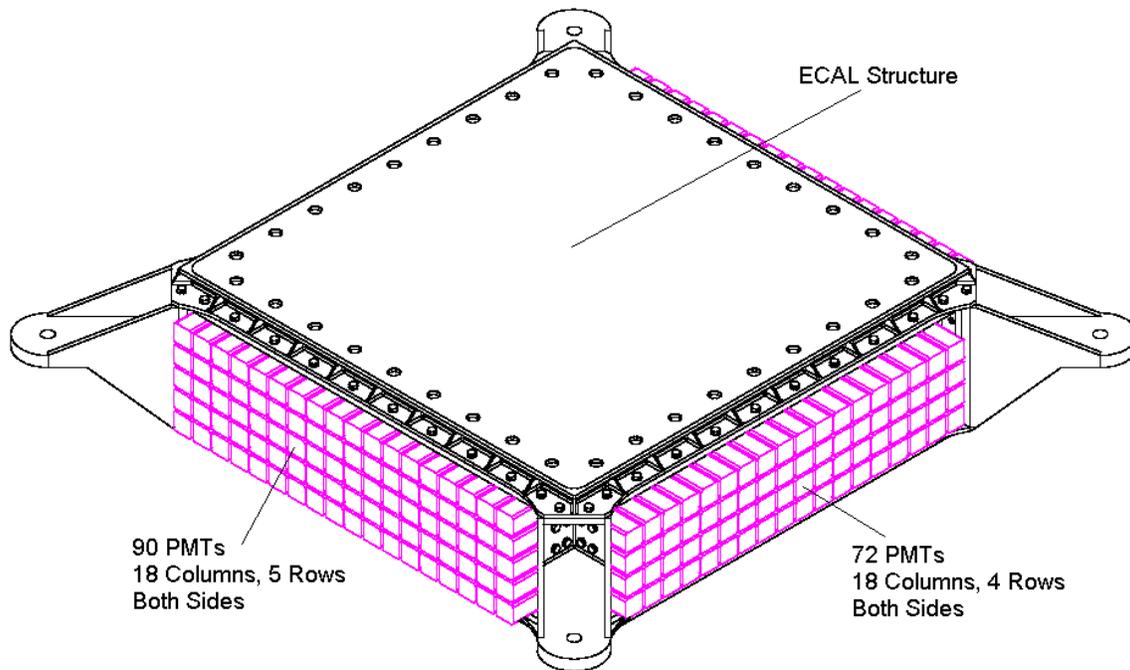


Figure 5.11.7 ECAL Assembly showing the location of the 324 PMTs

For each hole, the light collection consists of a mu-metal square tube for magnetic field shielding, light guides and photomultiplier tubes (PMTs) with driver electronics (Figure 5.11-8). An aluminum backplate is fixed on the rear side of each lateral panel to keep all the light collection systems in the correct position, securely engaged with the lead foil surface and scintillating fibers, and to prevent any displacements of the systems themselves. The glass front of the ECAL PMT is covered with a DC 93-500 Optical coupling pad and is potted in the same material, encapsulating the glass element. The ECAL Intermediate Boards (EIBs) (Figure 5.11-9) are electronic boards coated and fixed in aluminum frames directly mounted on the ECAL back panels. The EIBs provide the interface for the PMTs to get commands from the data acquisition system and to send data from driver electronics to it.

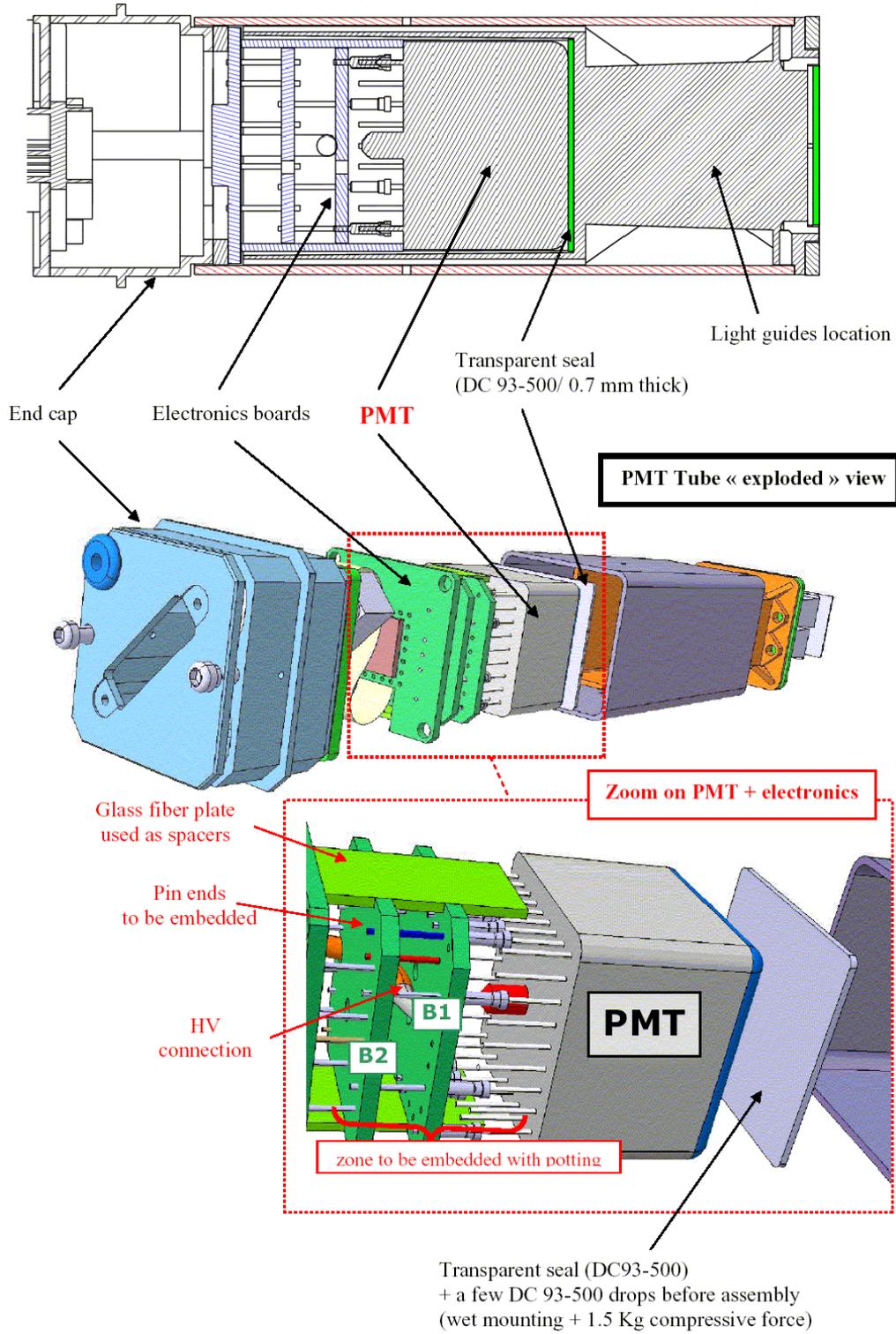


Figure 5.11-8 ECAL PMT Construction

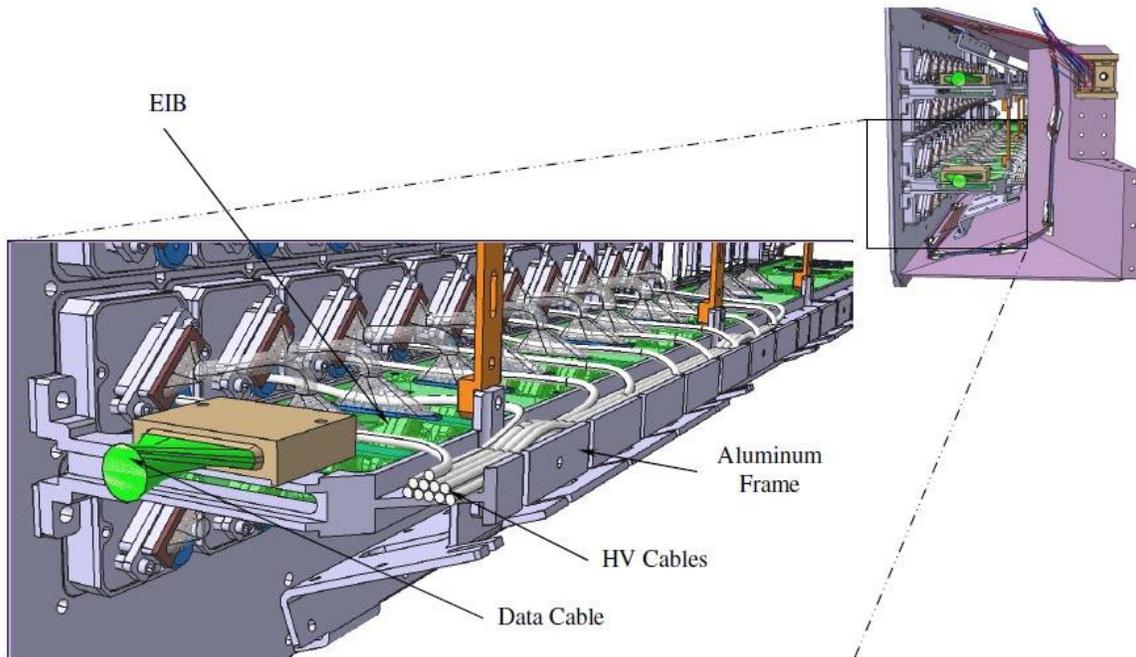
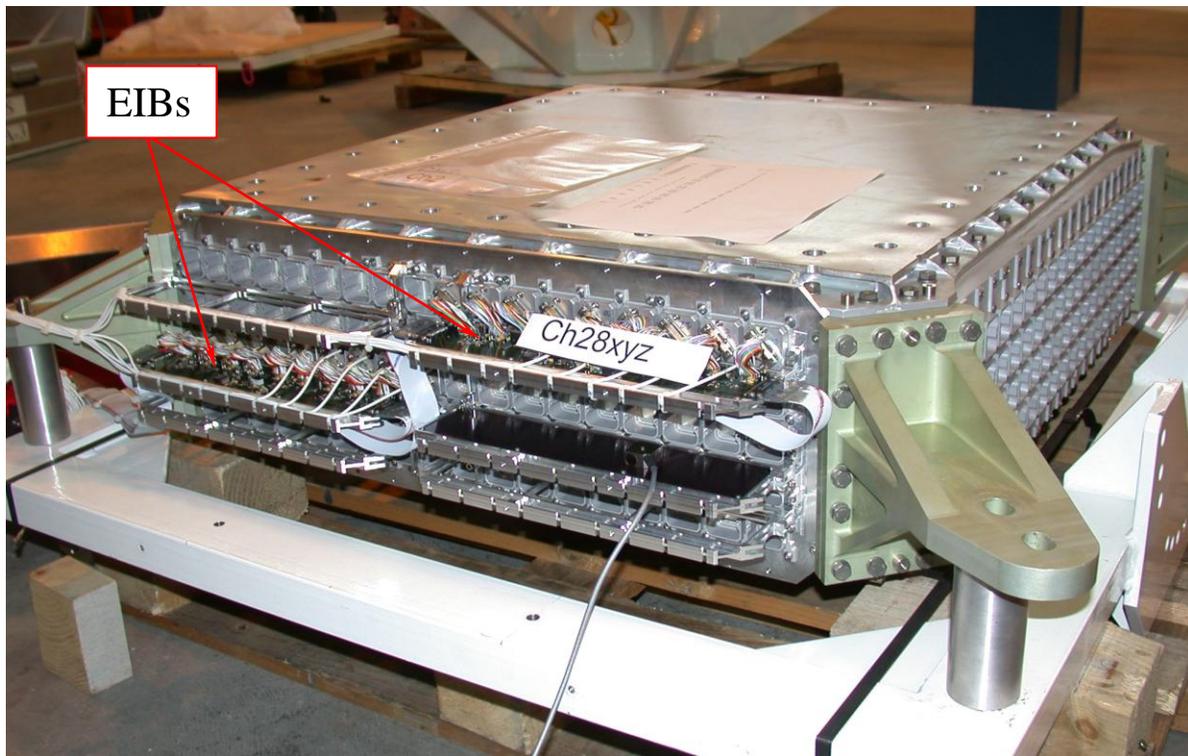


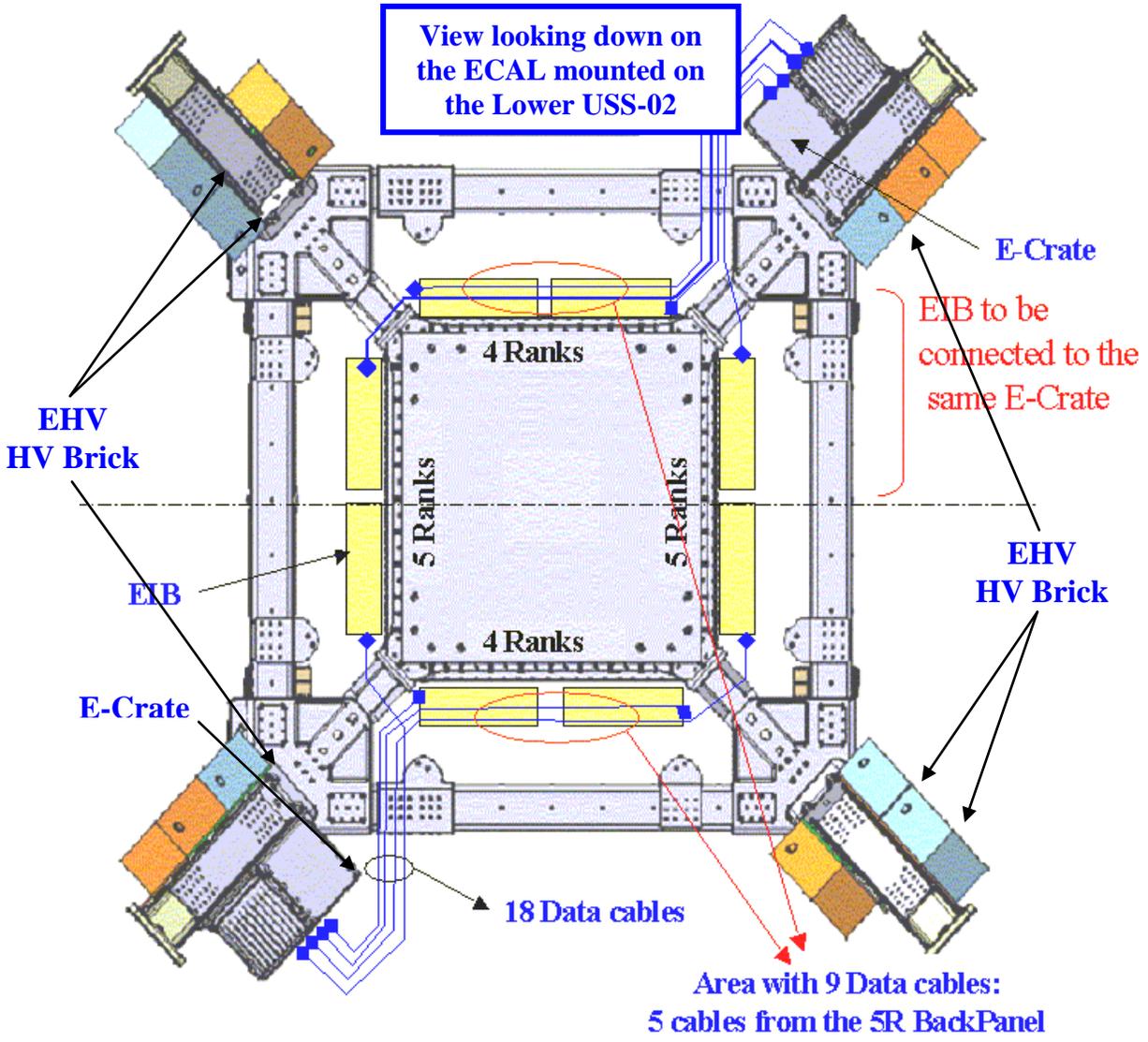
Figure 5.11-9 ECAL Backpanel Showing EIBs in Frames



**Figure 5.11-10 ECAL Engineering Model
ECAL Intermediate Boards (EIBs) mounted in their frames**

The ECAL utilizes two types of electronics boxes, the E-Crate and ECAL High Voltage (EHV) boxes, which are mounted to the lower USS-02 structure (Figure 5.11-11). The two E-Crates provide data acquisition and triggering functions and the four EHV boxes contain high voltage (HV) bricks (Figure 5.11-14) – each with 55 HV channels per brick – supply the high voltages for PMT operations. The HV bricks are fully potted. Two EHV boxes mounted on diagonally opposite legs of the lower USS-02 accommodate two HV bricks each, while the EHV boxes mounted on the two other legs accommodate one brick each. Three bricks are packaged per each of the four EHV boxes. The ECAL utilizes high voltages up to 800 VDC to operate the PMTs. Figure 5.11-15 provides a graphical representation of the HV design.

The cabling for HV, data and triggering are routed about the lower USS-02 using cable guides (Figures 5.11-11 through 5.11-13), the HV being routed separately from the data and trigger cabling. Figures 5.11-10 and 5.11-11 show the routing for data and trigger cabling. Cable runs are carefully designed to keep the critical timing of recorded events synchronized.



**Figure 5.11-11 Routing of ECAL Data Cables
Location of E-Crates and EHV High Voltage Bricks**

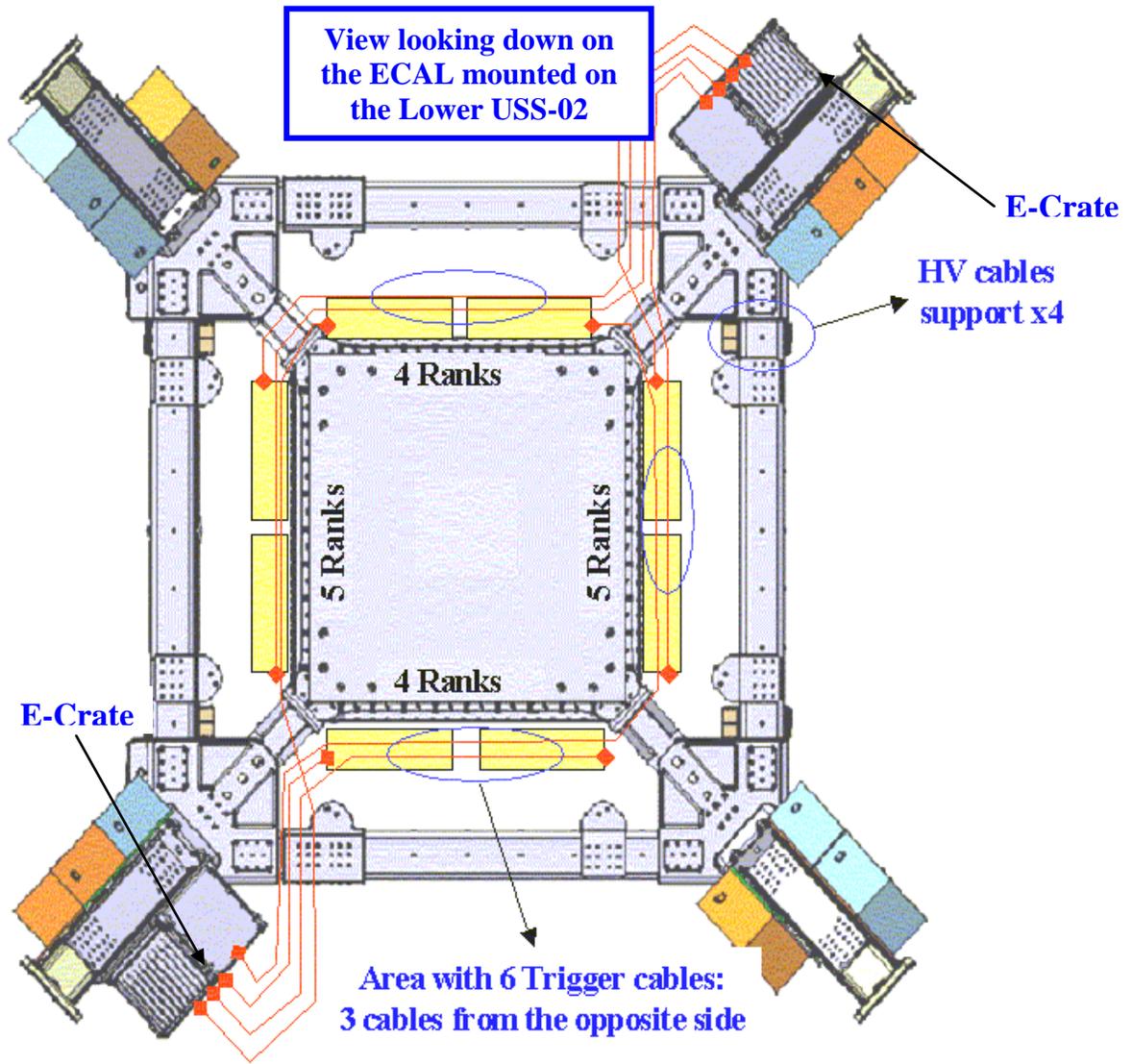


Figure 5.11-12 Routing of ECAL Trigger Cables

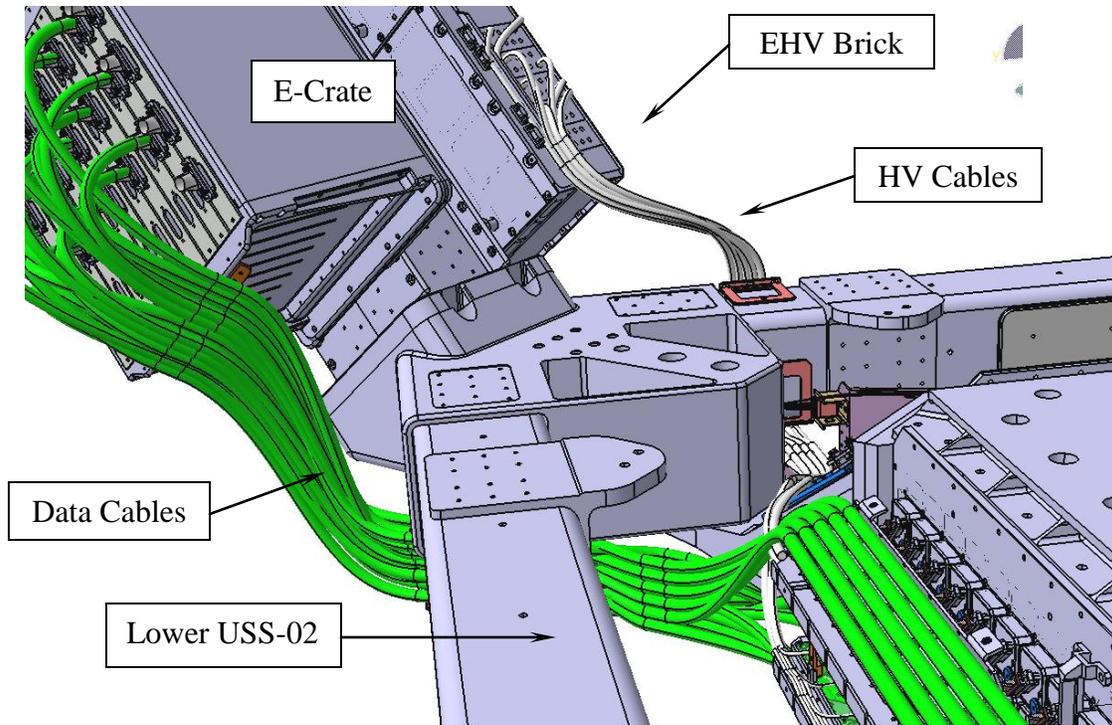


Figure 5.11-13 HV & Data Cable Routing from the ECAL to the HV Bricks and E-Crate



Figure 5.11-14 ECAL HV Brick

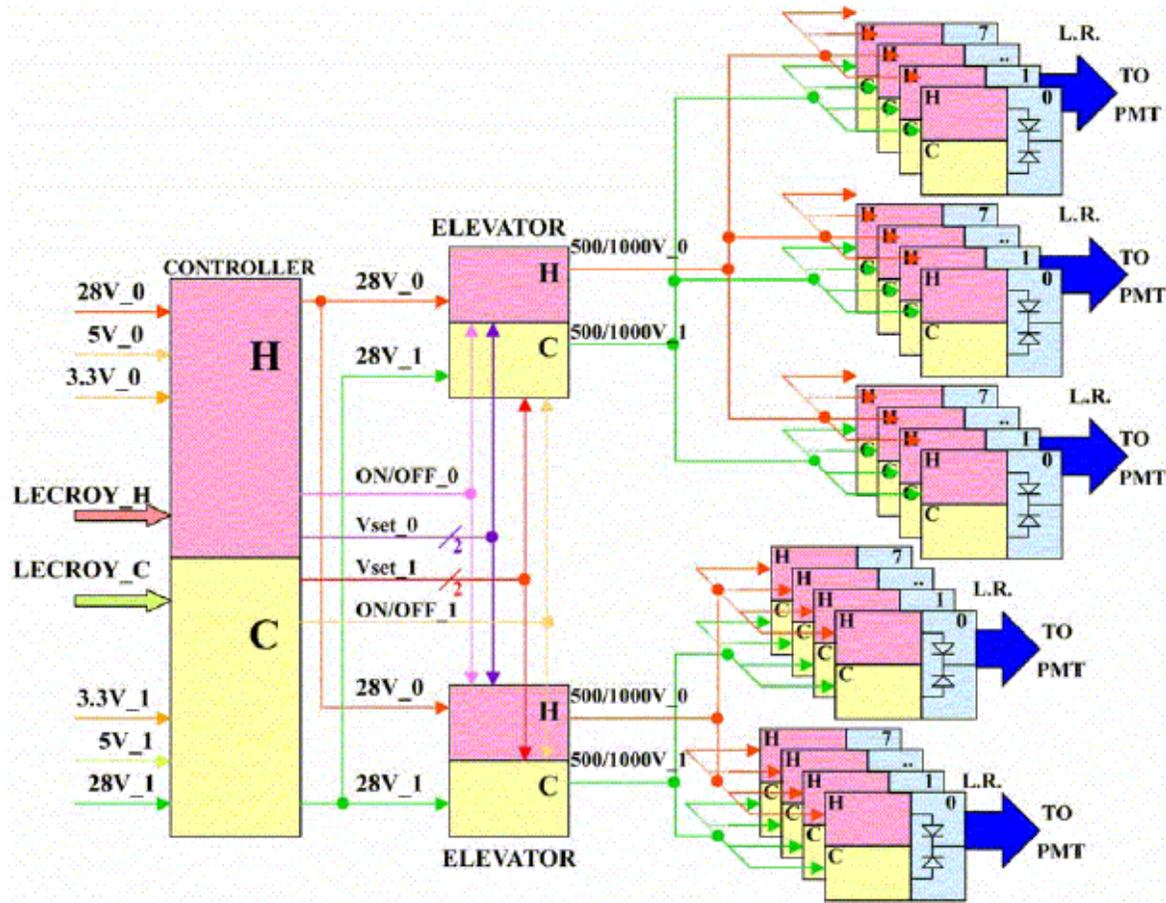


Figure 5.11-15 ECAL High Voltage Design

With the addition of Plane 6 for the Tracker installed above the ECAL, the ECAL had to be lowered by 35 mm by the addition of spacer blocks to provide room for the new plane's installation. This change caused an envelope violation with the ISS CAS Site as shown in Figure 5.11-16. The blocks themselves are the orange items in Figure 5.11-17,

Design with the ECAL
Lowered 35mm (1.37 inch)

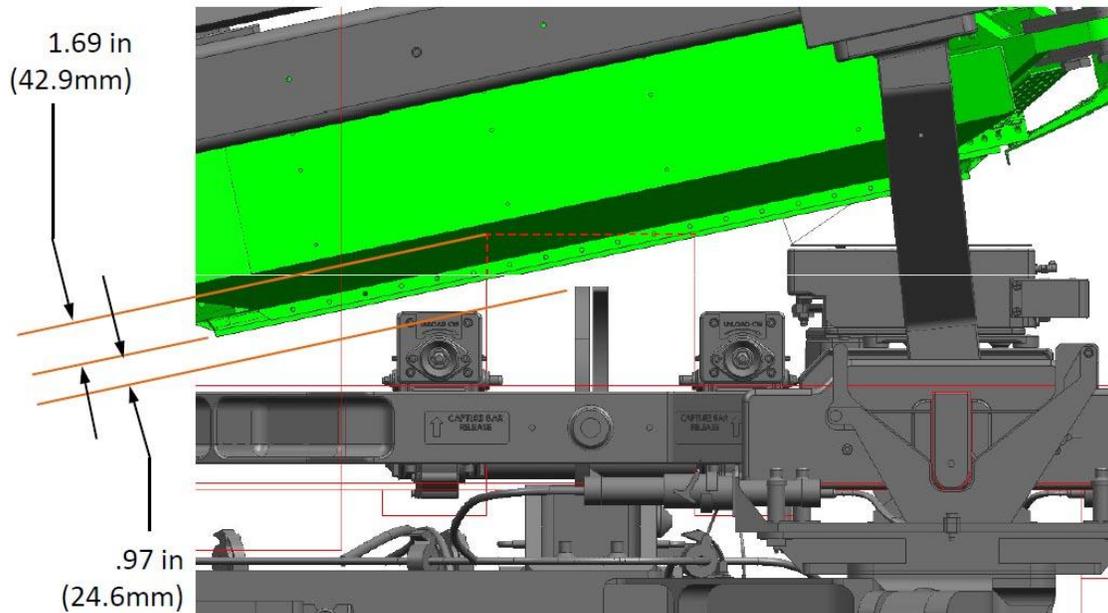


Figure 5.11-16 Altered Envelope of the ECAL and CAS Site Claw Envelope

This violation of the claw's envelope has been assessed and the closest approach occurs during the claws open and will not create a problem when compared to the Claw's motion as opposed to the conservative ICD defined envelope. An ICD waiver has been processed on this condition.

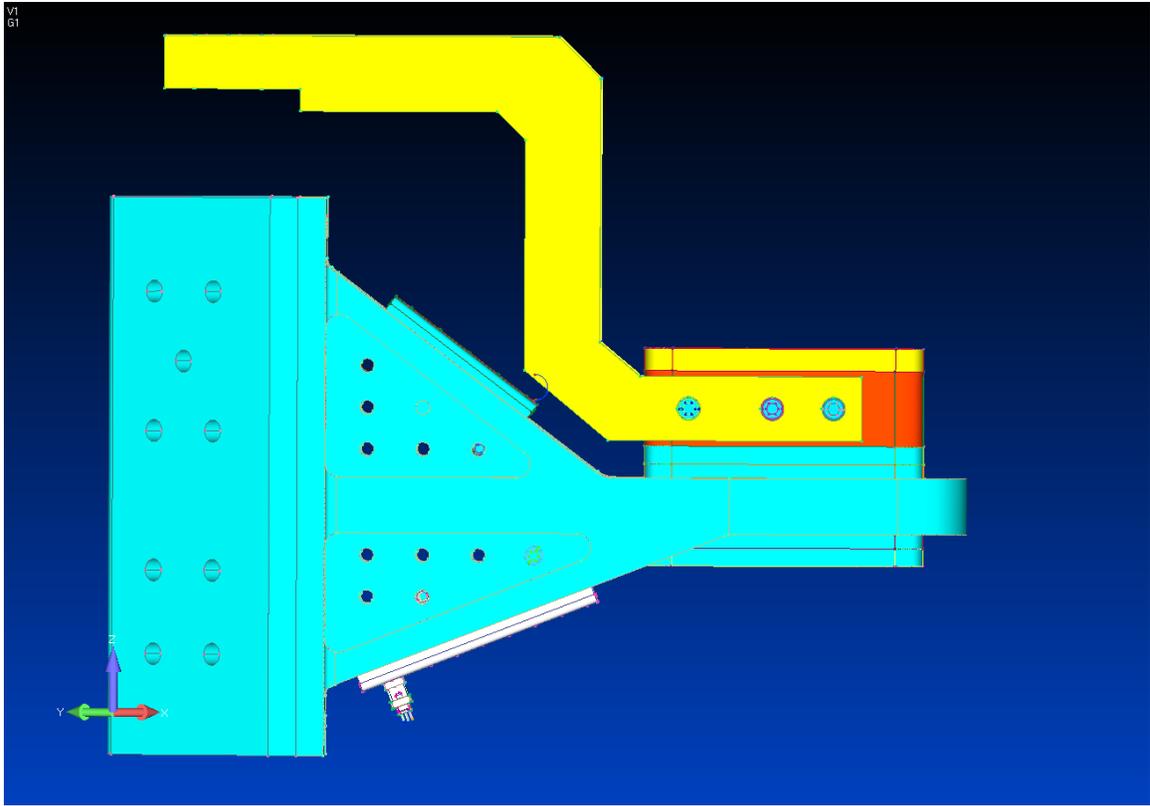


Figure 5.11-17 New ECAL Interface

5.12 AMS ELECTRONICS

The AMS avionics primary functions are front end data collection for the scientific instruments, data and command communication interface between the various portions of the payload, as well as between the payload and the STS and ISS; and power distribution throughout the payload. The details provided in this section are broken down into the following subsections:

- AMS-02 Electronics Systems Architecture Description
- Power Interfaces
- Power Distribution System (PDS)
- High Voltage Sources
- Grounding/Bonding Scheme for the AMS-02 Experiment
- AMS-02 Integration Cabling De-Rating
- AMS-02 Data Systems and Interfaces

5.12.1 AMS-02 Electronics Systems Architecture Description

AMS-02 contains numerous electronics boxes, some termed “Crates,” that supply the necessary readout/monitor/control electronics and power distribution for each detector (Figures 5.12.1-1 through 5.12.1-4). The box nomenclature is generically x-Crate or xPD, where “x” is a letter designating the detector function, and “Crate” refers to the readout/monitor/control electronics box and “PD” refers to the Power Distribution box for that specific detector. Similarly xHV bricks provide high voltage for some detectors. Values of “x” are designated as follows:

- E ECAL
- J Main Data Computers (MDC) and Command & Data Handling interfaces
- JT Trigger and central data acquisition
- M Monitoring
- R RICH
- S Time of Flight (TOF) Counters and Anti-Coincidence Counters (ACC)
- T Tracker

- TT Tracker Thermal
- U Transition Radiation Detector (TRD)
- UG TRD Gas

Additionally, electronics are mounted in the Power Distribution System (PDS). A small amount of electronics are also mounted directly on the detectors themselves, and are described in the detector section.

The interface boxes PDS and J-Crate provide the isolation and protection functions necessary to protect the STS and ISS vehicles from damage. Therefore, detailed internal box design for each of the detector crates will not be supplied; however, those which contain High Voltage sources will be identified, and the controls explained in Section 5.12.7.

One of the most critical safety functions to be performed for ISS protection is the isolation and protection of the Power Distribution System from the ISS, as described in Section 5.12.3. In most cases the PDS provides the isolation and circuit protection required to prevent feedback to the ISS; however some Heater Circuits receive 120Vdc pass-through power from the PDS. Explanation of their isolation and protection schemes is also included.

Finally, a brief description of the AMS-02 data systems and their interfaces can be found in Section 5.12.9. The AMS-02 data systems and their functions have been reviewed and been deemed mission success only. As such, the description of the AMS-02 data systems is top-level, and for reference only.

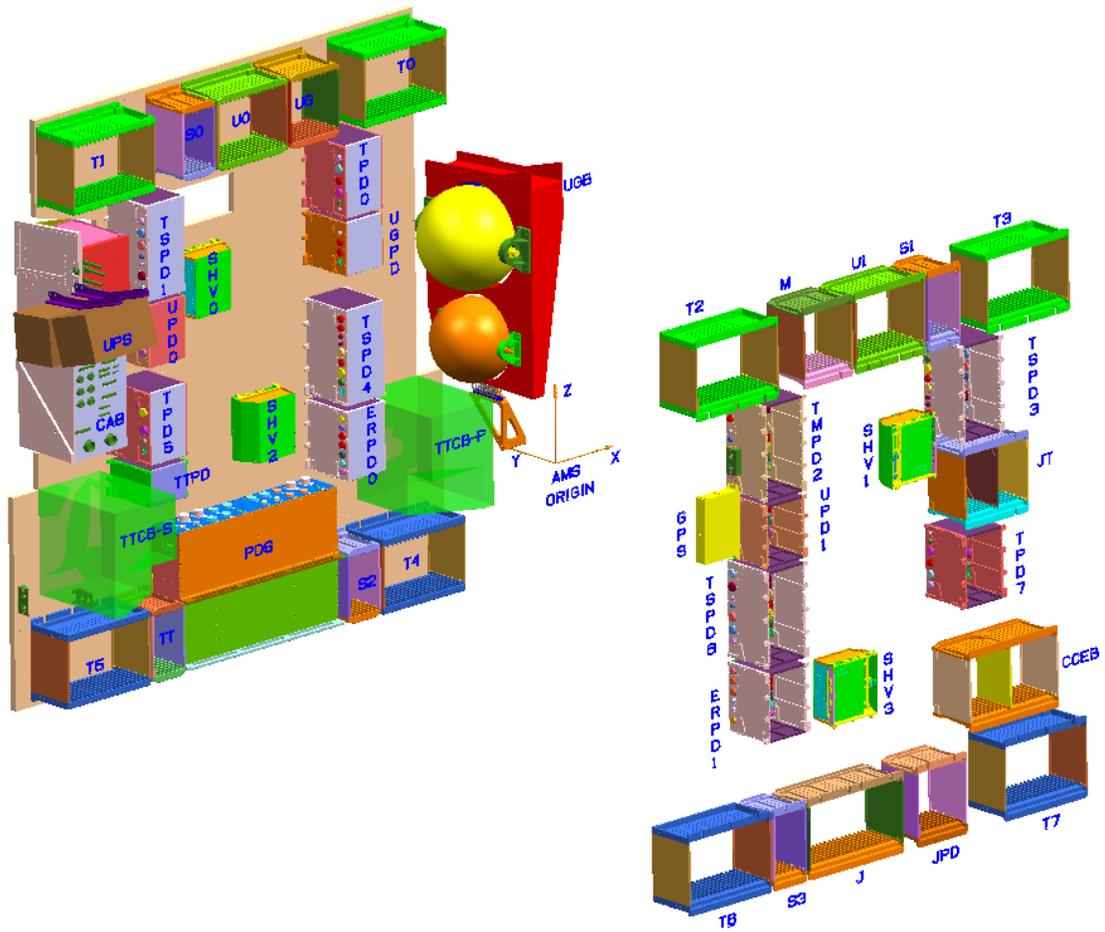


Figure 5.12.1-1 Electronics Crate Locations (UPS & CAB Removed)

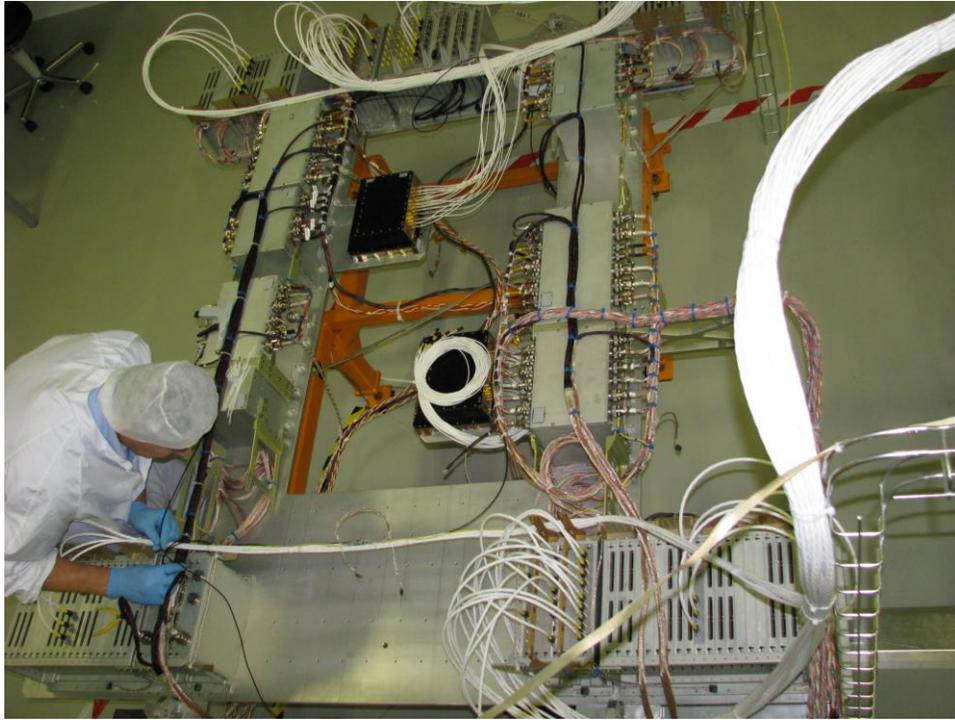


Figure 5.12.1-3 Electronics Crates on Wake Radiator Prior to Installation

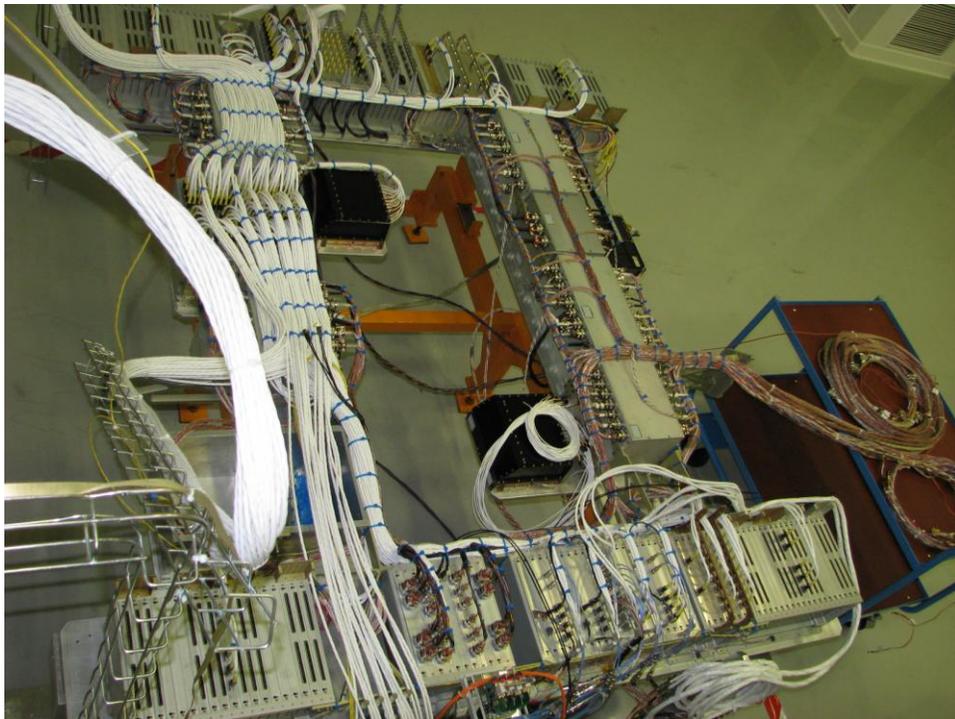


Figure 5.12.1-4 Electronics Crates on Ram Radiator Prior to Installation

5.12.2 Power Interfaces

The AMS-02 Power Distribution System (PDS) serves as the primary front-end for the power distribution to the subsystems and experiment detector electronics. It performs power conversion and distribution functions described in Section 5.12.3. The power isolation within the PDS, also described in Section 5.12.3, is designed to meet the 1 Mega Ohm Isolation requirement defined in SSP-57003.

Wire sizing has been selected in compliance with the requirements defined in NSTS 1700.7b, “Safety Policy and Requirements for Payloads Using the Space Transportation System”, NSTS 1700.7b ISS Addendum, “Safety Policy and Requirements for Payloads Using the International Space Station”, and NASA Technical Memorandum TM 102179, “Selection of Wires and Circuit Protection Devices for NSTS Orbiter Vehicle Payload Electrical Circuits”.

Power for the AMS-02 Payload is supplied from several sources dependent upon mission phase, as described in the following sections. For reference see Figure 5.12.2-1 and Figures 5.12.7-1 through 5.12.7-4.

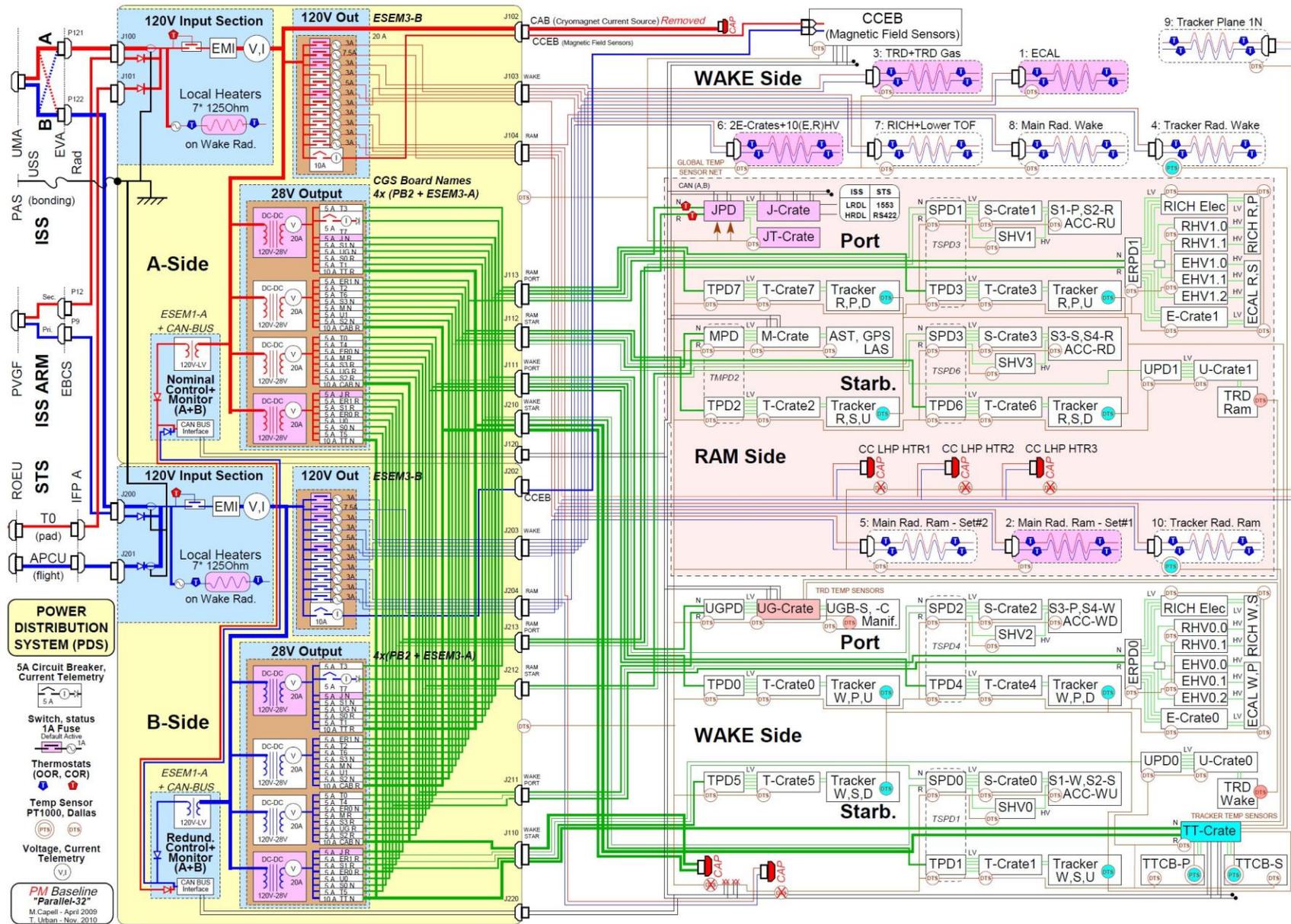


Figure 5.12.2-1 Payload Power Interfaces

5.12.2.1 Power Interface for Ground Operations in the STS

During ground operations, 120Vdc power is supplied via the T0 Umbilical, through the Remotely Operated Electrical Umbilical (ROEU) to the PDS to power experiment electronics. The GSE T0 power supply is a 3 kW Type B power supply per SSP 30482, Volume I, Rev. C.

Following payload installation 400 W of DC power is required for monitoring functions. Monitoring at this time is supplied by both the 1553 Bus and RS422 serial communications, each routed through the T-0 umbilical interface.

5.12.2.2 Ascent Power Interface on the STS

During Ascent, the AMS-02 does not require power to the payload. All payload power is planned to be off during ascent.

5.12.2.3 Power Interface for On-Orbit Operations on the STS

While in the Shuttle payload bay, on-orbit 120Vdc power for the AMS-02 comes from two ISS provided Assembly Power Converter Units (APCUs) through the ROEU to the PDS. Up to a maximum of 2.2 kW can be drawn during Shuttle based operations to power experiment electronics. Since the cooling system for the AMS-02 consists of radiators (that will be mostly pointing at the PLB walls), cooling on the STS will be limited. A continuous power of approximately 400W is expected, with excursions up to 2 kW as environmental conditions allow.

The ROEU PDA is mounted on a boom that positions it such that it can interface the Orbiter side of the ROEU while the AMS-02 is mounted in the payload bay. The extension of the PDA on this boom extends out of the attached payload physical envelope for the AMS-02 ISS PAS location, as defined in SSP-57003 (It does not intrude into the adjacent envelope directly.) This exceedence has been accepted by the ISS Program. The power supply characteristics for the ROEU provided power are shown in Table 5.12.2.3-1.

TABLE 5.12.2.3-1 STS ROEU POWER SUPPLY CHARACTERISTICS

INPUT BUS	Internal BUS connection	PIN	Max Power [KW]	Current Rating	Lowest Current Limitation Level	Minimum Trip Decision Time	TYPE	CONNECTOR I/F	PDS connector
T0	A	4 x AWG12	1.8	14.7 A (1)	22 A (1)	100 msec (1)	--	IFPA P8	J101
APCU	B	3 x AWG8	1.8 3.6 (2)	14.7 A 29.4A (2)	22 A	100 msec	--	IFPA P1	J201

- (1) These value are for reference only. The power supply will be a ground power provided by the KSC with performances similar to the APCU.
- (2) (2) If two APCU in parallel are used

5.12.2.4 Power Interface for Extra Vehicular Robotics (EVR) Activities

Just prior to transfer activities, the AMS-02 is powered down, the APCUs are deactivated, and the ROEU is disconnected from the PDA attached to the AMS-02. The AMS-02 is grappled by the SRMS via a FRGF attached to the payload. The FRGF has no power interface capabilities.

The SRMS maneuvers the AMS-02 for an Arm-to-Arm transfer to the SSRMS) The SSRMS grapples the payload via a PVGF located on the opposing side of the AMS-02 from the FRGF. The PVGF provides pass-through ISS power from the SSRMS to the Electronic Berthing Camera System (EBCS) mounted on the AMS Passive Payload Attach System (PAS). The EBCS uses this 30 W of power to operate avionics that provide a video signal, which is returned to the crew compartment via the PVGF and SSRMS. The EBCS is used to align the payload and determine closure range during payload berthing operations. Additionally, the EBCS can pass through power from the PVGF to the AMS-02 payload. AMS-02 contains thermostatically controlled heaters that may utilize some or all of this power to maintain the payload temperature within design limits. The amount of power required is dependent on environmental conditions during transfer and the length of time the payload spends on the SSRMS.

The nominal power supply characteristics, provided in *SSP 42004, Mobile Servicing System (MSS) to User (Generic) Interface Control Document Part I*, for the PVGF provided power are shown in Table 5.12.2.4-1. Due to SSRMS payload bus wire sizing, and worse case thermal analysis for these wires, the SSRMS payload bus operating current has been limited to 16.7 Amps. Detailed design analysis by the developer of the PDS, Carlo Gavazzi Space (CGS), shows that for all SSRMS based operations, and over the entire range of possible input voltages, the AMS-02 payload will comply with this current limit. The upstream Remote Power Control

Module (RPCM) that supplies SSRMS payload power bus is a Type II RPCM, which limits the power at 25 Amps. It is therefore required to further protect the SSRMS payload power bus wiring, which cannot handle 25 Amps, This is performed by the circuit protection devices of the default-on (shaded pink) circuits of the PDS as shown in Figure 5.12.3-1 AMS-02 Power Distribution System

In Figure 5.12.2.4-1, the SSRMS payload back-up bus and PDS A-side are shown for completeness. The SSRMS payload prime bus and PDS B-side (not shown) are identical. Finally, 30 W has been added as the power consumed by the EBCS avionics.

TABLE 5.12.2.4-1 ISS PVGF TO USER ELECTRICAL INTERFACE PARAMETERS

Circuit Name	INTERFACE V _{range} (volts) 3	Operating Current (amps)	Overcurrent Protection
PVGF1	107.5 to 126	0 to 16.7	1, 2
PVGF2	107.5 to 126	0 to 16.7	1, 2

NOTES:

- 1 Protection is equivalent with SSP 30263:002, Type II RPCM Standard ICD
- 2 Protection is equivalent with SSP30263:002, Type VI RPCM Standard ICD.
- 3 Minimum voltage includes 1 volt drop across the PVGF harness.

5.12.2.5 Power Interface for ISS Operations

All power and data services for the AMS-02 payload are provided through an Umbilical Mechanism Assembly (UMA) mounted to the Payload Attach Site. ISS provides two 120 Vdc power feeds, each controlled by Type II RPCM (25A). AMS-02 is capable of operating from either or both buses. In the event of a loss of the ISS power input bus that feeds Bus A (or B), an EVA operation can be performed to switch EVA connectors for Bus A and Bus B. if a coincidence of bus failure and power supply failure occur. This operation is performed on the EVA Connector Panel (schematically shown in Figure 5.12.7-4, and depicted physically in Figure 5.12.2.5-1). It should be noted that Bus A and Bus B have independent PDS output sections to preclude cross linking. The power supply characteristics for the UMA provided power are shown in Table 5.12.2.5-1.

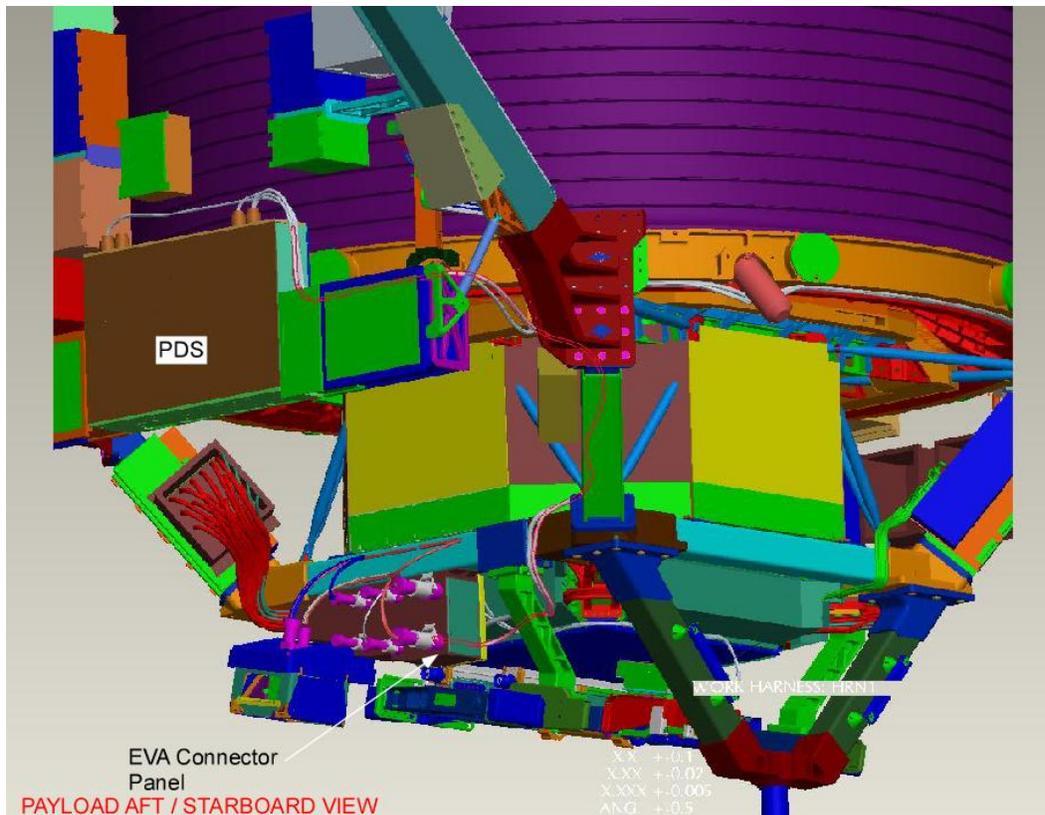


Figure 5.12.2.5-1 EVA Connector Panel

TABLE 5.12.2.5-1 ISS UMA POWER SUPPLY CHARACTERISTICS

INPUT BUS	Max Power [KW]	PIN	Current Rating	Lowest Current Limitation Level	Minimum Trip Decision Time	TYPE	CONNECTOR I/F	PDS connector
A	3	3 x AWG8	25 A	27.5 A	31 ms	RPCM II	EVA PANEL P121	J100
B	3	3 x AWG8	25 A	27.5 A	31 ms	RPCM II	EVA PANEL P122	J200

5.12.3 Power Distribution System (PDS)

The PDS, the yellow shaded box in Figure 5.12.2-1, also shown schematically in excerpt in Figure 5.12.3-1, consists of four distinct sections: 120 Vdc Input; 120 Vdc Output; 28 Vdc Output; and Low Voltage Control and Monitor. The PDS physical location is shown in Figure 5.12.2.5-1. The bus to bus isolation of the 120Vdc outputs is provided by the end-subsystem, by either DC-to-DC or AC converters, or relays. The isolation for all other outputs is provided

internally to the PDS by DC-to-DC converters. The PDS has two independent “channels” side A and side B (Figure 5.12.3-2), which have four identical subsections.

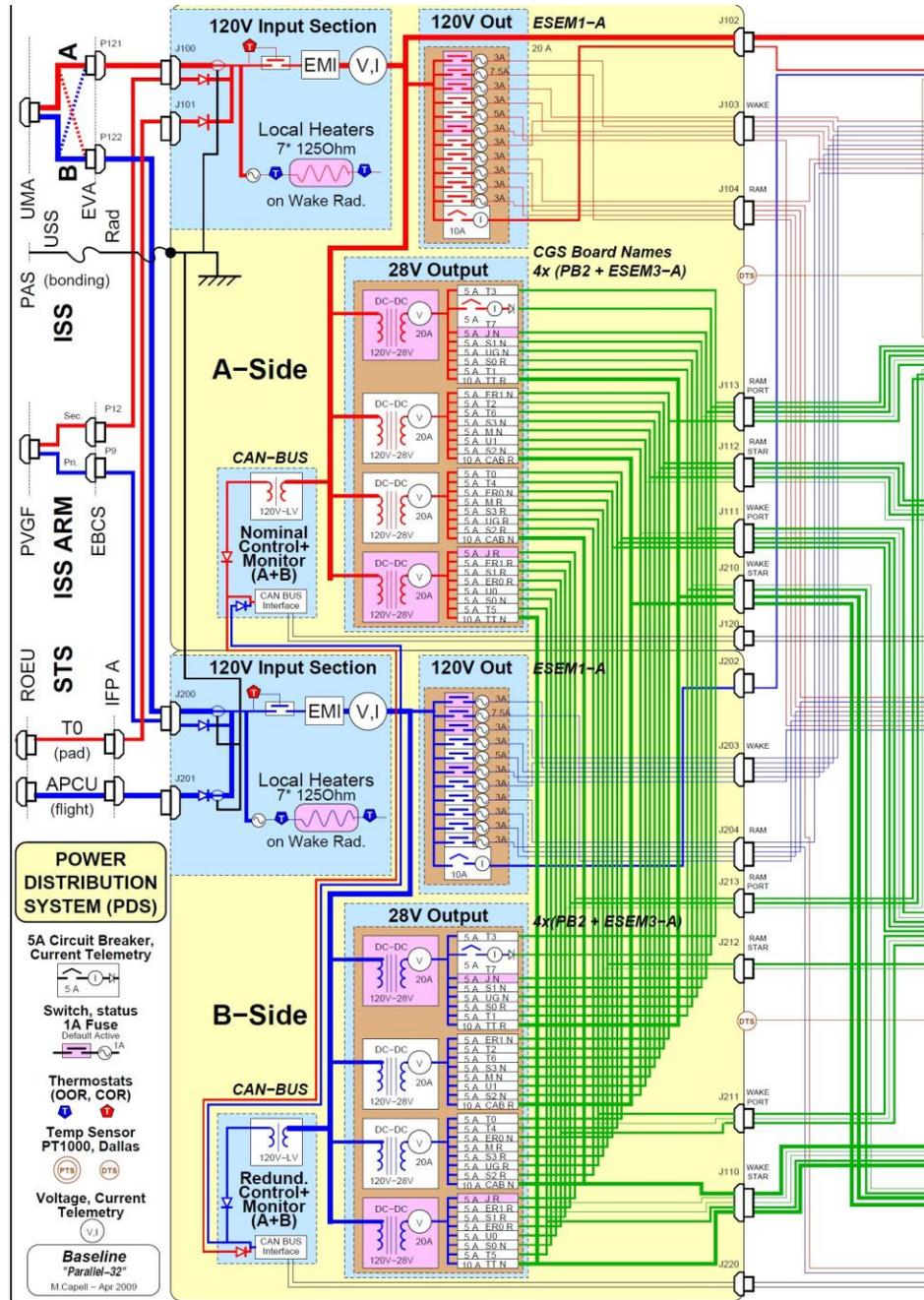


Figure 5.12.3-1 AMS-02 Power Distribution System
(Excerpt from Figure 5.12.2-1)

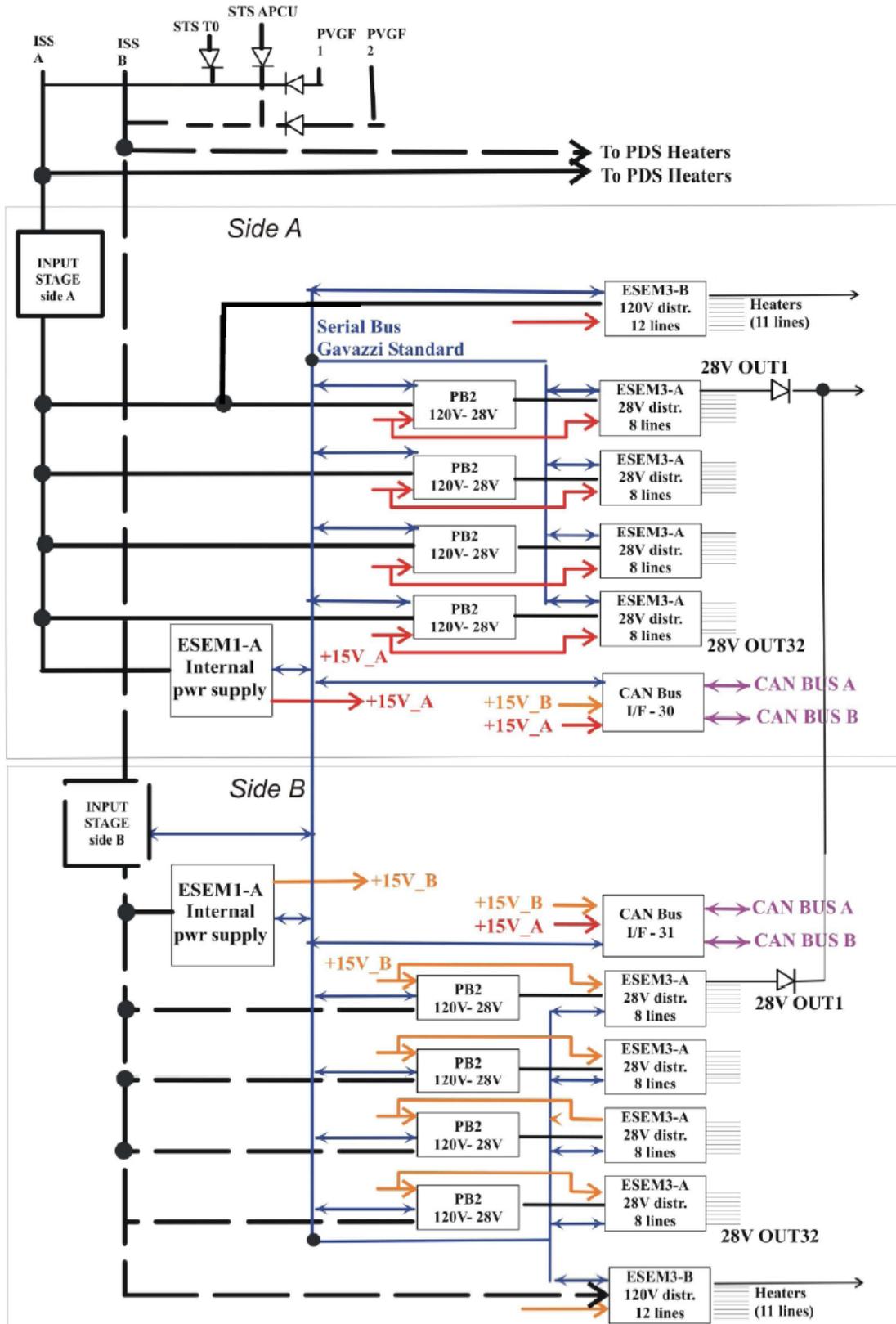


Figure 5.12.3-2 AMS-02 Power Distribution System, Sides A and B

The interfaces for the individual sections shown in Figure 5.12.3-2 are detailed in Table 5.12.3-1.

TABLE 5.12.3-1 PDS SECTION INTERFACE DETAILS

PDS SIGNAL & POWER INTERFACES		
INPUT SECTION		
ISS	Power I/F input	<ul style="list-style-type: none"> • 120V Feeder A • 120V Feeder B
STS	Power I/F input	<ul style="list-style-type: none"> • 120V Feeder APCU • 120V Feeder T0
BCS (PVGf)	Power I/F input	<ul style="list-style-type: none"> • 120V Feeder PVGF 1 • 120V Feeder PVGF 2
EMI FILTER		<ul style="list-style-type: none"> • EMI I/F
INPUT TELEMETRY		
INPUT TELEMETRY	Signal I/F	(Via internal serial I/F to the CAN BUS module) <ul style="list-style-type: none"> • INPUT CURRENT • INPUT VOLTAGE
INTERNAL POWER SUPPLY SECTION		
ESEM 1-A	Power I/F	15V Internal Power Supply
	Signal I/F	(Via internal serial I/F to the CAN BUS module) <ul style="list-style-type: none"> • ON/OFF DC/DC CONVERTER • DIGITAL Board Status Monitoring <ul style="list-style-type: none"> • OK/NOK • OVERTEMP • DC/DC 1 OVERCURRENT • DC/DC 2 OVERCURRENT • DC/DC 1 MAIN ON/OFF • DC/DC 2 MAIN ON/OFF • MAIN POWER ON • DIGITAL TEST OUT • ANALOGUE Board Monitoring <ul style="list-style-type: none"> • TEMPERATURE • ANALOG REFERENCE VOLTAGE • MAIN POWER VOLTAGE
120V OUTPUT SECTION		
DIRECT OUTPUT	Power I/F	
ESEM 3-B	Power I/F	<ul style="list-style-type: none"> • OUT 1 for AMS heaters • OUT 2 for AMS heaters • OUT 3 for AMS heaters • OUT 4 for AMS heaters • OUT 5 for AMS heaters • OUT 6 for AMS heaters • OUT 7 for AMS heaters • OUT 8 for AMS heaters • OUT 9 for AMS heaters • OUT 10 for AMS heaters • OUT 11 for AMS heaters

TABLE 5.12.3-1 PDS SECTION INTERFACE DETAILS (CONTINUED)

PDS SIGNAL & POWER INTERFACES		
	Signal I/F	(Via internal serial I/F to the CAN BUS module) <ul style="list-style-type: none"> • ON/OFF OUTLET Command • DIGITAL Board Status Monitoring <ul style="list-style-type: none"> • OK/NOK • OVERTEMP • OUTLET STATUS (ON/OFF) • ANALOGUE Board Monitoring <ul style="list-style-type: none"> • TEMPERATURE • ANALOG REFERENCE VOLTAGE
120V TO 28V CONVERSION SECTION		
PB2	Power I/F	<ul style="list-style-type: none"> • 28V OUTPUT to the ESEM 3-A distribution board
	Signal I/F	(Via internal serial I/F to the CAN BUS module) <ul style="list-style-type: none"> • ON/OFF DC/DC CONVERTER Command • DIGITAL Board Status Monitoring <ul style="list-style-type: none"> • OK/NOK • OVERTEMP • DC/DC CONVERTER STATUS (ON/OFF) • INPUT OVERCURRENT • OUTPUT OVERVOLTAGE • ANALOGUE Board Monitoring <ul style="list-style-type: none"> • TEMPERATURE • 28V OUTPUT VOLTAGE • ANALOG REFERENCE VOLTAGE
ESEM 3-A	Power I/F	<ul style="list-style-type: none"> • 8 x 28V output lines <ul style="list-style-type: none"> • out 1 to 7 @ 5A each • out 8 @ 10A
	Signal I/F	(Via internal serial I/F to the CAN BUS module) <ul style="list-style-type: none"> • ON/OFF OUTLET Command • DIGITAL Board Status Monitoring <ul style="list-style-type: none"> • OK/NOK • OVERTEMP • OUTLET STATUS (ON/OFF) • OUTLET TRIP STATUS • ANALOGUE Board Monitoring <ul style="list-style-type: none"> • TEMPERATURE • OUTLETS CURRENT • ANALOG REFERENCE VOLTAGE
DIGITAL I/F SECTION		
CAN BUS I/F	Signal I/F	<ul style="list-style-type: none"> • CAN BUS I/F • PDS INTERNAL BUS I/F • DIGITAL Command to the boards • ANALOGUE ACQUISITIONS of the boards telemetry • DIGITAL ACQUISITIONS of the boards status

The design of the PDS is such that the power conversion and distribution is performed by four different printed circuit board types. These types, and quantities per sides A and B, along with current protection details, are described in Table 5.12.3-2.

TABLE 5.12.3-2 PDS PRINTED CIRCUIT BOARD & CURRENT PROTECTION DETAILS

Board Type	Quantity	Function	Outputs	Current Protection	Notes
ESEM3-A	4 per side	Distribution of the 28V secondary voltage, provided by the PB2 modules, to AMS-02 Payloads	8	MOSFET Current limiter, trips @ 130% nominal current between 5 and 6 msec. <ul style="list-style-type: none"> Channels 1 - 7: 5 Amp Channel 8: 10 AMP 	Eight output channels individually: <ul style="list-style-type: none"> Equipped with MOSFETs for ON/OFF switching Provided with status and current measurement circuitry
ESEM3-B	1 per side	Distribution of the 120V provided by the power input BUS to supply AMS-02 heaters	12	<ul style="list-style-type: none"> Channels 1 - 11: Fuses, derated (see Table 5.8.3-3) Channel 12: Not Used 	Twelve outlets that are independently: <ul style="list-style-type: none"> Equipped with MOSFETs for ON/OFF switching Protected by fuse in series with MOSFET Provided with status monitor circuitry <ul style="list-style-type: none"> 1.4A (>50% derating) 3.2A (>50% derating) 2.3A (>50% derating)
PB2	4 per side	120Vdc to 28Vdc converter module.	1	Redundant DC-DC converters with current limiting and breaking element comprised of two power MOSFETs (2N7225) connected in parallel	Current intervention threshold is fixed at $9A \pm 0.4A$ (the timing of the protections is lower than 1ms to guarantee for trip coordination with upstream characteristics). If the current rises above this threshold, the MOSFETs are switched off bringing the gate voltage to zero.
ESEM1-A	1 per side	Provides for the generation of the internal power line (15V/5A) required for PDS operation.	1 @ 15VDC 1 @ 5VDC	Redundant DC-DC converters with current limiting - current breaking element comprised of one power MOSFET (2N6798) trips @ 200% nominal current.	Each DC/DC converter includes an in-rush current limiter and an over current circuitry with, <ul style="list-style-type: none"> a PWM controller, a power cell based on half bridge topology, input under voltage detection circuit, input EMI filter

The fuses for the ESEM3-B printed circuit board 120 VDC outputs are detailed in Table 5.12.3-3.

TABLE 5.12.3-3 PDS 120 VDC FUSE DETAILS

DESCRIPTION	PROC.SPEC	SUPPLIER	P/N-ID.CODE	EM Notes
Fuse 3A FM12 style fuse (subminiature, high performance)	MIL-PRF-23419	AEM - USA	P600L-135-3	3A fuse Network code: 251003
Fuse 7.5A FM12 style fuse (subminiature, high performance)	MIL-PRF-23419	AEM - USA	P600L-135-7.5	7A fuse Network code: 251007
Fuse 5A FM12 style fuse (subminiature, high performance)	MIL-PRF-23419	AEM - USA	P600L-135-5	5A fuse Network code: 251005

The PDS has associated heaters, which serve to raise the PDS temperature to its minimum operation limit when power is applied to the AMS, as shown in Figure 5.12.3-3.

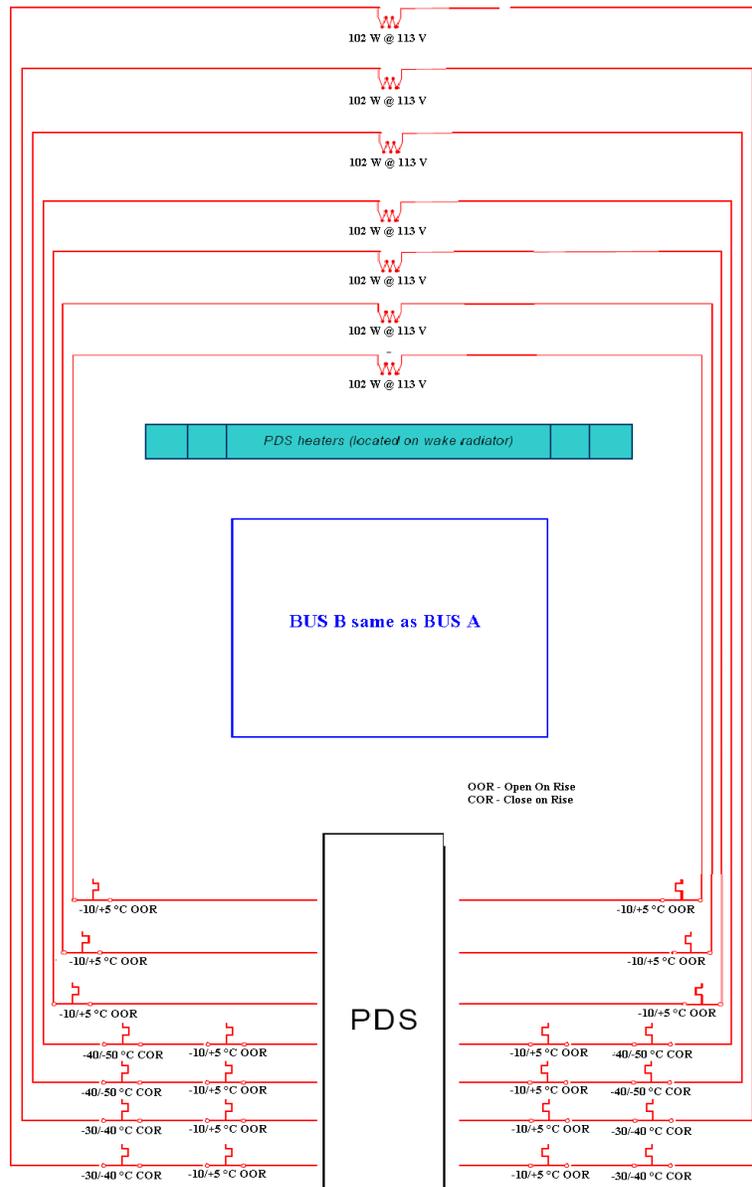


Figure 5.12.3-3 PDS Internal Heaters

The PDS is located on the Main Wake Crate Rack very close to the Passive Umbilical Mechanism Assembly (Figure 5.12.3-4).

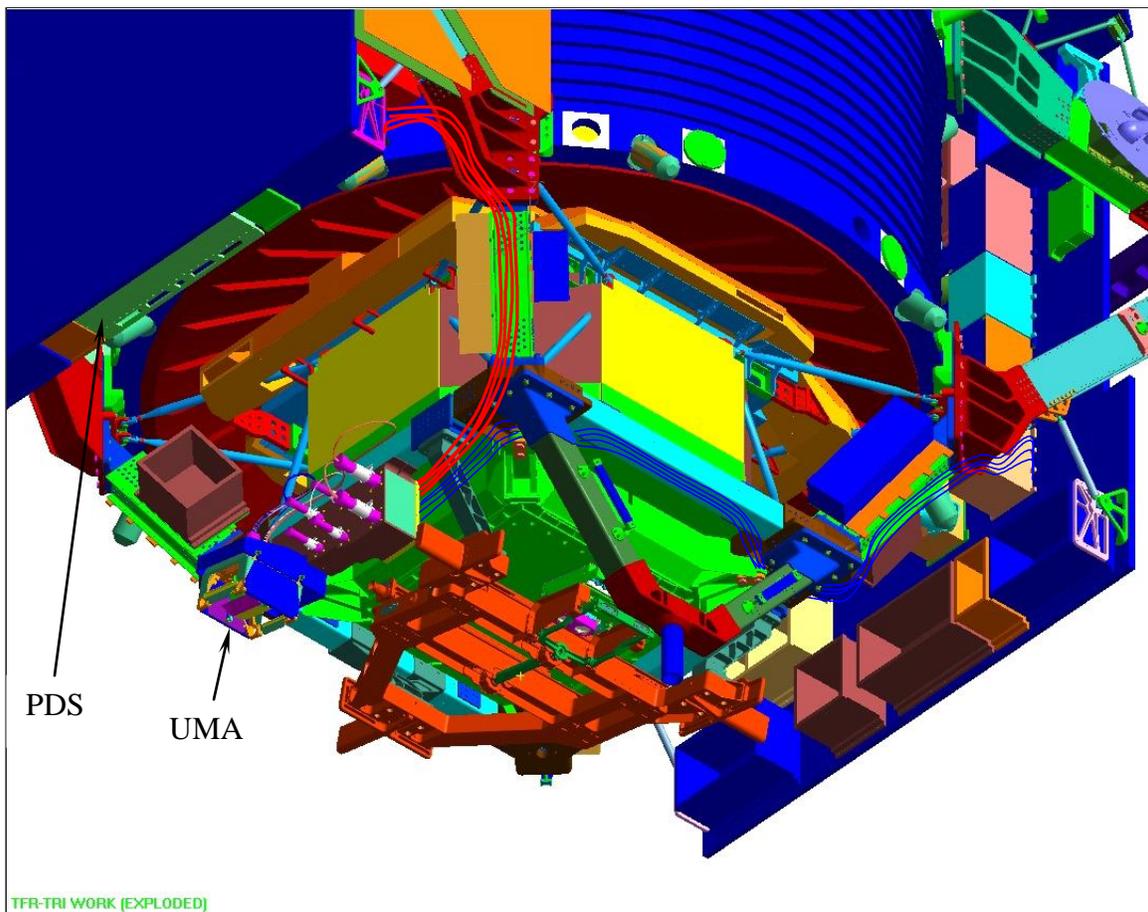


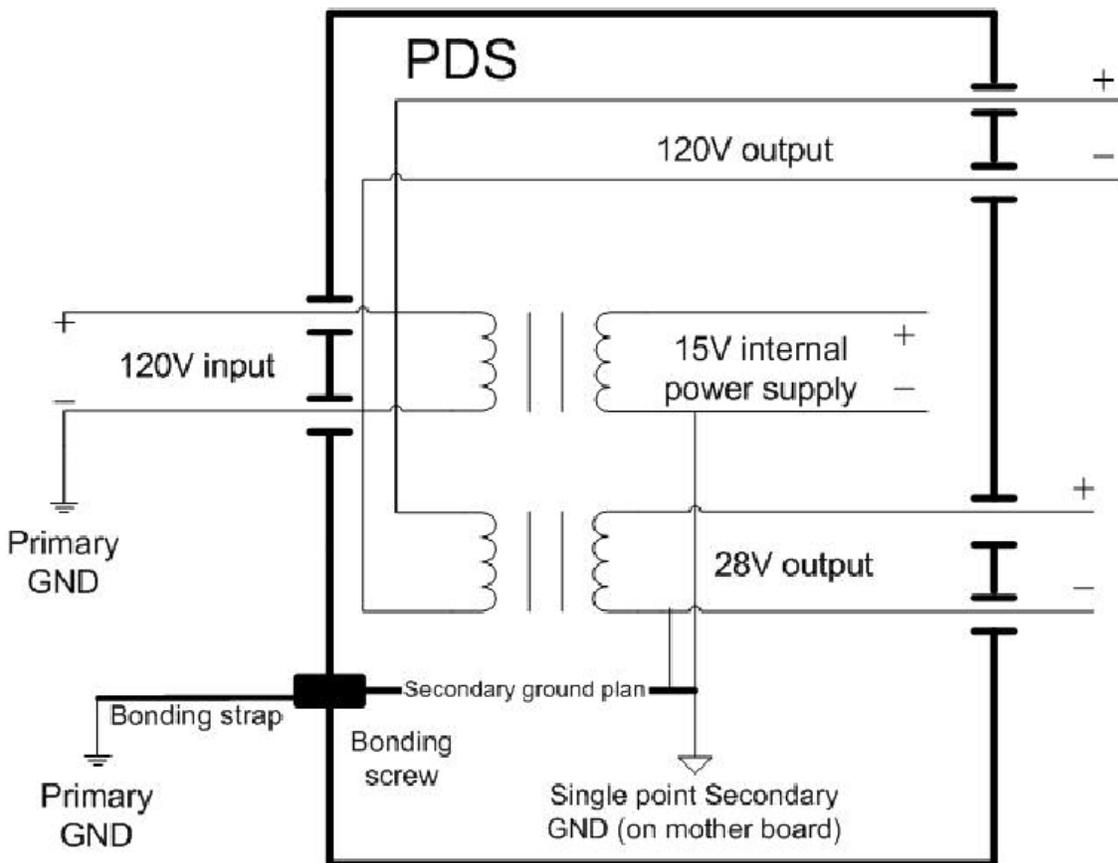
Figure 5.12.3-4 Location of the PDS and UMA on AMS-02

The PDS shall comply with the bonding requirements as defined in SSP 57003 Attached Payload Interface Requirements Document, Revision B, paragraph 3.2.2.4.2 between:

- Different parts of the equipment chassis
- Connector receptacles and equipment chassis/connector brackets
- Equipment chassis and bond strap
- Bond strap and structure

The method proposed for the PDS bonding to the AMS structure is Bond Strap using one (1) attachment point on the structure. The attachment point location is on the rear wall. All PDS metallic components and surface shall be bonded in order to preclude accumulations of static charge inside the PDS Box.

The bonding diagram for the PDS, representative of Side A or Side B, only, is shown in Figure 5.12.3-5.



**Figure 5.12.3-5 Bonding Diagram of the PDS,
representative of Side A or Side B, only**

The PDS avionics, with respect to the overall grounding system, shall be based on the following concepts as per SSP 30240 Space Station Grounding Requirements, Revision C:

- The primary electrical power shall be isolated from PDS chassis by a minimum of $1M\Omega$
- Implementation of a galvanic isolation between the primary power bus and all the secondary internal or distributed powers
- All the secondary power references are connected together and to the PDS structure in a single point represented by a bonding stud located on one PDS wall
- The secondary power references shall be isolated from the PDS chassis by a minimum of $1M\Omega$ when the single point bonding is not connected.

All the parts of the box housing the PDS electronic are electrically connected together in order to offer a low impedance path. The PDS box is equipped with a bonding stud. A copper bus bar shall be placed inside the PDS in order to collect the single point bonding from the Power Boards. The copper bus bar shall be isolated from the PDS wall. The copper bus bar shall be connected internally to the PDS bonding stud by means of ring terminals and the PDS Bonding Stud shall be connected to the AMS structure by means of a bond strap. The bonding stud will be connected to the AMS support structure in such a manner:

- To conduct electrical faults current without creating thermal or electrical hazard
- To minimize differences in potential between all equipment

The mechanical box will operate as a shield against the internally generated emissions and the externally generated emissions.

The functions of the four subsections of the PDS are described in detail in the following sections.

5.12.3.1 PDS 120 Vdc Input Section

The 120Vdc Input Section is designed to receive power from three sources, and dependent on mission phase these three source powers are supplied from either T0 or APCUs via the ROEU, the PVGF or the ISS UMA power sources. The inputs use diode protection or connector protective covers to prevent crew or ground personnel from potential exposure to “hot-pins”.

As described earlier, during ground operations, this power may be supplied via the T0 umbilical (for normal operations); and the APCUs for end-to-end type testing with power supplied through the ROEU. During Shuttle flight operations, power is supplied solely via the APCU interface. The ROEU PDA does not provide a “protective cover” to prevent incidental contact with hot pins or sockets after disconnection from the active half. Therefore, diode protection is provided for the ROEU power feeds to prevent power feeds from the SSRMS and the ISS UMA from being present on the ROEU PDA.

For transfer operations on the SSRMS, power may be supplied by either feed via the PVGF interfaces. Standard ISS Operations Procedures dictate only one or the other feed from the SSRMS will be active at any time. While the EBCS will use this power to operate camera avionics, AMS-02 will use the feed-through power from the EBCS to operate thermostatically

controlled heaters while the payload is on the SSRMS. Ideally, this operation will be relatively short (entire transfer should take less than 4 hours); and AMS-02 will be thermally conditioned prior to transfer, so no heater power should be required. The PVGF does not provide a protective cover to prevent incidental contact with hot pins or sockets when not connected to the SSRMS. Therefore, diode protection is provided for the PGVF power feeds to prevent power from other sources being present on the PVGF connector. The UMA passive half does include a protective cover to prevent incidental contact with “hot-pins” and therefore precludes the need for additional diode protection.

Once mated to the ISS (following deactivation of PVGF power and activation of ISS power via the UMA), the AMS-02 will be capable of operation from either or both ISS Buses.

Internally to the PDS, these power source feeds are combined into the two internal PDS buses and EMI Filters are used for compatibility with ISS Complex Impedance and EMC requirements. Voltage and Current measurements are provided within this “input section” to determine overall power consumption.

PDS “box-level” thermostatically controlled heaters are provided to ensure the PDS maintains operational thermal limits. There is a lockout feature that prevents operation of the PDS if it is not within operational thermal specifications when power is applied. Only these heaters operate until the PDS operational lower limit is reached, after which the distribution circuitry is activated. The heaters have two thermostats in series (one in the return leg of the heaters as demonstrated in Figure 5.12.3-3). All heaters and thermostats are redundant to accommodate either the A or B power feed. Following activation, internal electronics power consumption is expected to be sufficient to maintain thermal limits without requiring additional heating.

Note: A “Global Temperature Sensor Network” is used: to monitor box temperatures across the entire experiment, ensure that each box is activated only after operating temperatures are achieved; and to determine when the Solid State Power Controllers (SSPCs) can be opened to disable the heaters.

5.12.3.2 PDS 120 Vdc Output Section

For each 120 Vdc output, isolation is provided by the end-subsystem, by either DC-to-DC converters or relays. 120 Vdc feed-through power from the PDS includes outputs to the 8 zone heaters.

Bus isolation of the heater outputs from the PDS is provided by the operation of two independent heater circuits (one for each power feed). Thus, ISS Power Bus A feeds the “A” heaters and ISS Power Bus B feeds the “B” heaters independently. All of the heater power is delivered “on demand” to the thermostatically controlled heaters. Application of power to both buses can result in both heater sets operating or the SSPCs (commanded by the USCM) can be used to deactivate either or both heater circuits. Zone heaters outputs from the PDS are current limited to between 3A and 7.5A by the SSPCs.

5.12.3.3 PDS 28 Vdc Output Section

The 28 Vdc Output Section provides isolation from the 120 VDC input for all 28 Vdc outputs via DC-to-DC Converters. This output section provides the bulk of the power to operate the Detector and Command and Data Handling Avionics. As a general rule, power from these outputs is routed to an xPD (subsystem Power Distribution Box) for powering of the x-Crate electronics and the detectors.

The 28 Vdc Output Section receives power from either of the internally generated 28 Vdc Buses, and 5 Amp SSPCs are used for power management and circuit protection. Therefore each output can be controlled to operate from either bus. The outputs of the SSPC from each bus are connected exclusively via diodes to their respective load. Voltage and current measurements are provided from the DC-to-DC converters and current measurements are provided at each SSPC for downlink.

5.12.3.4 PDS Control and Monitor Section

The Control and Monitor Section provides isolation for the low-voltage power system via DC-to-DC Converters (voltage and current measurements provided for downlink). This section is used primarily for autonomous control and monitoring of the PDS to ensure activation only after the minimum operating temperature is achieved, and ground control and monitoring of the all PDS

outputs for power management. Communications with this section are maintained via a Controller Area Network (CAN) Bus Interface used for low-rate data and command interfaces. All PDS telemetry is passed through this section to the Main Data Computers for downlink.

5.12.4 (Deleted)

5.12.5 (Deleted)

5.12.6 High Voltage Sources

Table 5.12.6-1 lists the high voltage sources on the AMS-02 along with maximum current and wire/cabling implemented for that application.

TABLE 5.12.6-1 AMS-02 HIGH VOLTAGE OR CURRENT SOURCES

High Voltages (and Currents) in AMS-02.						
Item	Subsystem	Source	Load	Voltage	Current	AWG
14	ECAL	EHV0-0	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
15	ECAL	EHV0-1	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
16	ECAL	EHV0-2	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
17	ECAL	EHV1-0	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
18	ECAL	EHV1-1	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
19	ECAL	EHV1-2	55 ECAL PMTs	<1000VDC	<250uA	Coax-26
20	Interface	ISS	AMS-PDS	120VDC	<25A	8
21	Interface	ISS/PVGF	AMS-PDS	120VDC	<15A	12
22	Interface	ISS/T0	AMS-PDS	120VDC	<25A	12
23	Interface	STS/APCU	AMS-PDS	120VDC	<25A	8
24	Power	PDS	CCS in CAB (removed)	120VDC	<20A	12
25	Power	PDS	CCEB	120VDC	<7.5A	12
26	RICH	RHV0-0	40 RICH PMTs	<1000VDC	<80uA	Coax-26
27	RICH	RHV0-1	40 RICH PMTs	<1000VDC	<80uA	Coax-26

Wire: AWG 00=M22759/41-02-5D, AWG 12 – 24=M22759/44-*, HV 24= Reynolds 178-8066, Coax 36=Reynolds 167-2896

TABLE 5.12.6-1 AMS-02 HIGH VOLTAGE OR CURRENT SOURCES (CONTINUED)

High Voltages (and Currents) in AMS-02.						
Item	Subsystem	Source	Load	Voltage	Current	AWG
28	RICH	RHV1-0	40 RICH PMTs	<1000VDC	<80uA	Coax-26
29	RICH	RHV1-1	40 RICH PMTs	<1000VDC	<80uA	Coax-26
30	S:TOF+ACC	SHV0	34 TOF+4 ACC PMTs	<2500VDC	<50uA	Coax-26
31	S:TOF+ACC	SHV1	34 TOF+4 ACC PMTs	<2500VDC	<50uA	Coax-26
32	S:TOF+ACC	SHV2	38 TOF+4 ACC PMTs	<2500VDC	<50uA	Coax-26
33	S:TOF+ACC	SHV3	38 TOF+4 ACC PMTs	<2500VDC	<50uA	Coax-26
34	Thermal	PDS	ECAL Heaters	120VDC	<3A	20
35	Thermal	PDS	Ram Heaters	120VDC	<7.5A	20
36	Thermal	PDS	TRD Heaters	120VDC	<3A	20
37	Thermal	PDS	Tracker Wake Heaters	120VDC	<3A	20
38	Thermal	PDS	Wake Heaters	120VDC	<5A	20
39	Thermal	PDS	LUSS Boxes	120VDC	<3A	20
40	Thermal	PDS	RICH Heaters	120VDC	<3A	20
41	Thermal	PDS	LTOF Heaters	120VDC	<3A	20
43	Thermal	PDS	Tracker Ram Heaters	120VDC	<3A	20
45	Tracker	TPD0	2 TBS in T0-Crate	<120VDC	<10mA	22
46	Tracker	TPD1 in TSPD1	2 TBS in T1-Crate	<120VDC	<10mA	22
47	Tracker	TPD2 in TMPD2	2 TBS in T2-Crate	<120VDC	<10mA	22
48	Tracker	TPD3 in TSPD3	2 TBS in T3-Crate	<120VDC	<10mA	22
49	Tracker	TPD4 in TSPD4	2 TBS in T4-Crate	<120VDC	<10mA	22
50	Tracker	TPD5	2 TBS in T5-Crate	<120VDC	<10mA	22
51	Tracker	TPD6 in TSPD6	2 TBS in T6-Crate	<120VDC	<10mA	22
52	Tracker	TPD7	2 TBS in T7-Crate	<120VDC	<10mA	22
53	Tracker	2 TBS in T0-Crate	24 Tracker Ladders	<80VDC	<10mA	26
54	Tracker	2 TBS in T1-Crate	24 Tracker Ladders	<80VDC	<10mA	26
55	Tracker	2 TBS in T2-Crate	24 Tracker Ladders	<80VDC	<10mA	26
56	Tracker	2 TBS in T3-Crate	24 Tracker Ladders	<80VDC	<10mA	26
57	Tracker	2 TBS in T4-Crate	24 Tracker Ladders	<80VDC	<10mA	26
58	Tracker	2 TBS in T5-Crate	24 Tracker Ladders	<80VDC	<10mA	26
59	Tracker	2 TBS in T6-Crate	24 Tracker Ladders	<80VDC	<10mA	26
60	Tracker	2 TBS in T7-Crate	24 Tracker Ladders	<80VDC	<10mA	26
61	TRD	UPD0	6 UHVG in U0-Crate	<120VDC	<35mA	22
62	TRD	UPD1	6 UHVG in U1-Crate	<120VDC	<35mA	22
63	TRD	6 UHVG in U0-Crate	2624 TRD Straw Tubes	<1800VDC	<100uA	Coax-26
64	TRD	6 UHVG in U1-Crate	2624 TRD Straw Tubes	<1800VDC	<100uA	Coax-26
65	TRD-Gas	UGPD	UHVG in UG-Crate	<120VDC	<35mA	22

ISS, STS Voltages after EMI filter

Wire: AWG 00=M22759/41-02-5D, AWG 12 – 24=M22759/44-*, HV 24= Reynolds 178-8066, Coax 36=Reynolds 167-2896

5.12.7 Grounding/Bonding Scheme for the AMS Experiment

The AMS-02 payload shall comply with the bonding requirements as defined in *SSP 57003 Attached Payload Interface Requirements Document, Revision B*. The AMS-02 payload, with respect to the overall grounding system, shall comply with *SSP 30240 Space Station Grounding Requirements, Revision C*.

The AMS-02 payload structure is mechanically grounded, depending on mission phase, as follows:

- A. STS – via the payload mounting trunnions
- B. SSRMS – via the SSRMS / PVGF interface
- C. ISS CAS site – via the PAS guide vane pins

The overall AMS-02 payload interface schematic is represented in Figures 5.12.7-1. The AMS-02 payload grounding scheme and interfaces are shown specifically for the various mission phases in Figures 5.12.7-2 through 5.12.7-5

Integration Cable Schematic
 AMS-02 / T. Urban 21/04/10
 PM Rev. 1

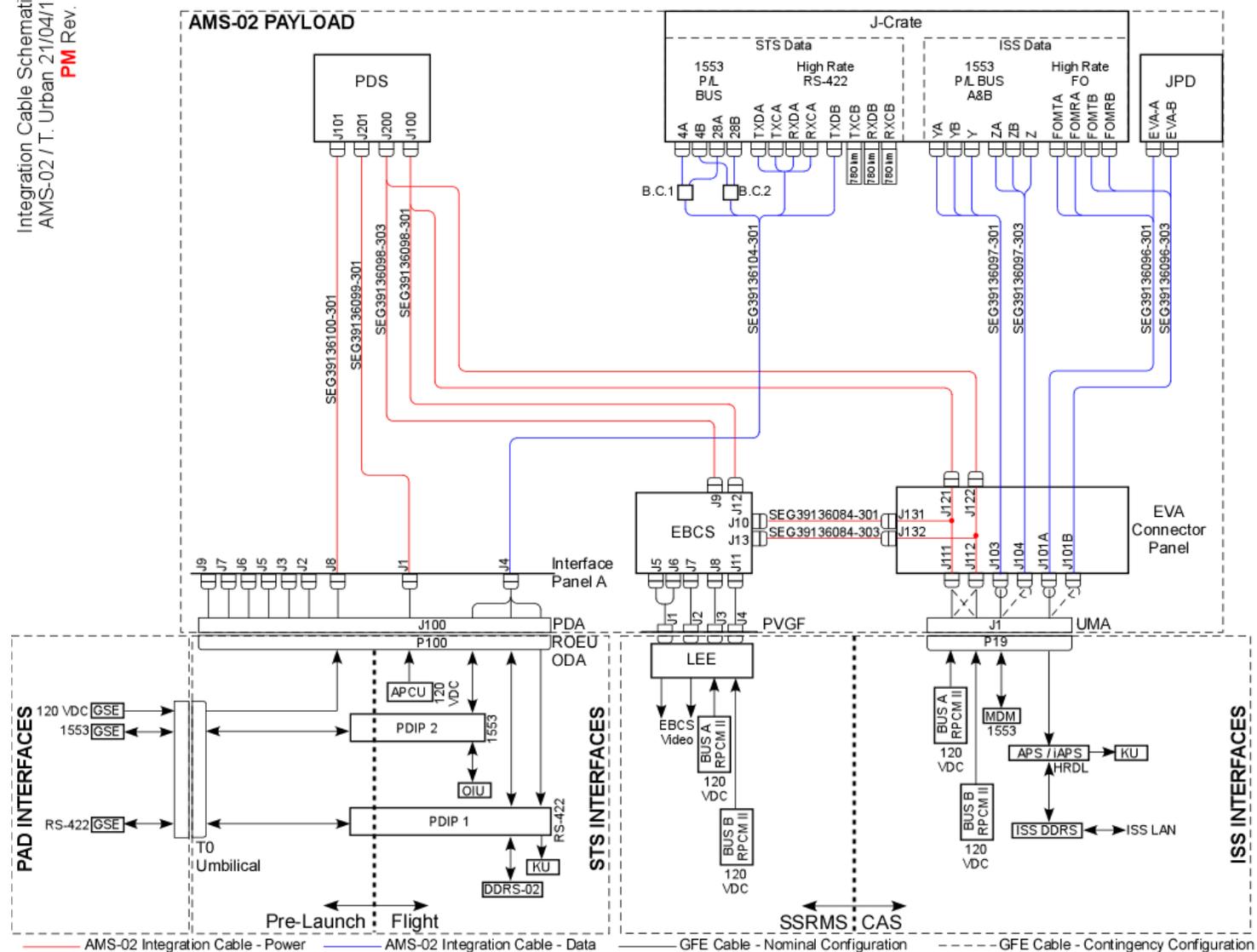
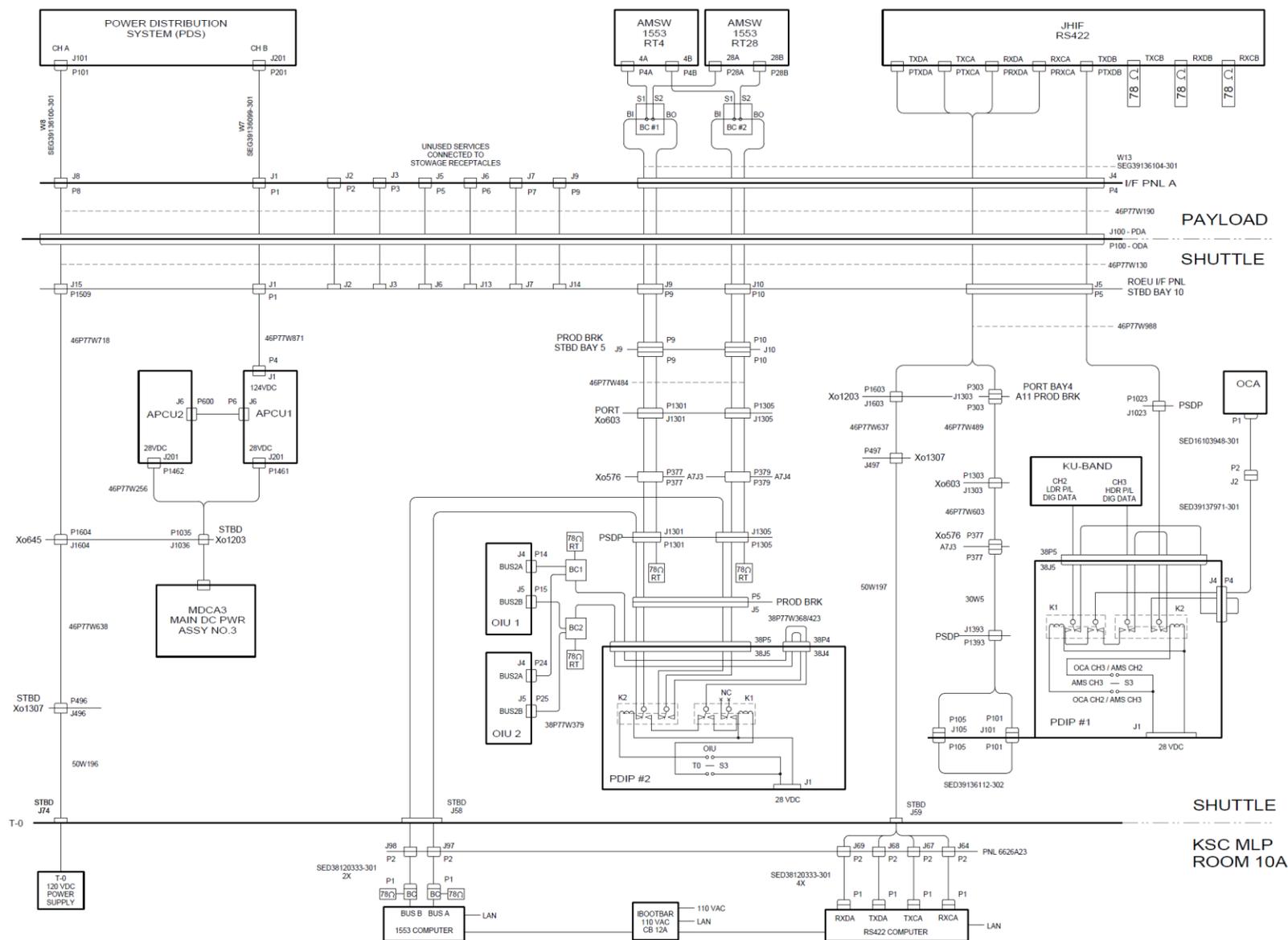


Figure 5.12.7-1 AMS-02 Top Level Interface Diagram.



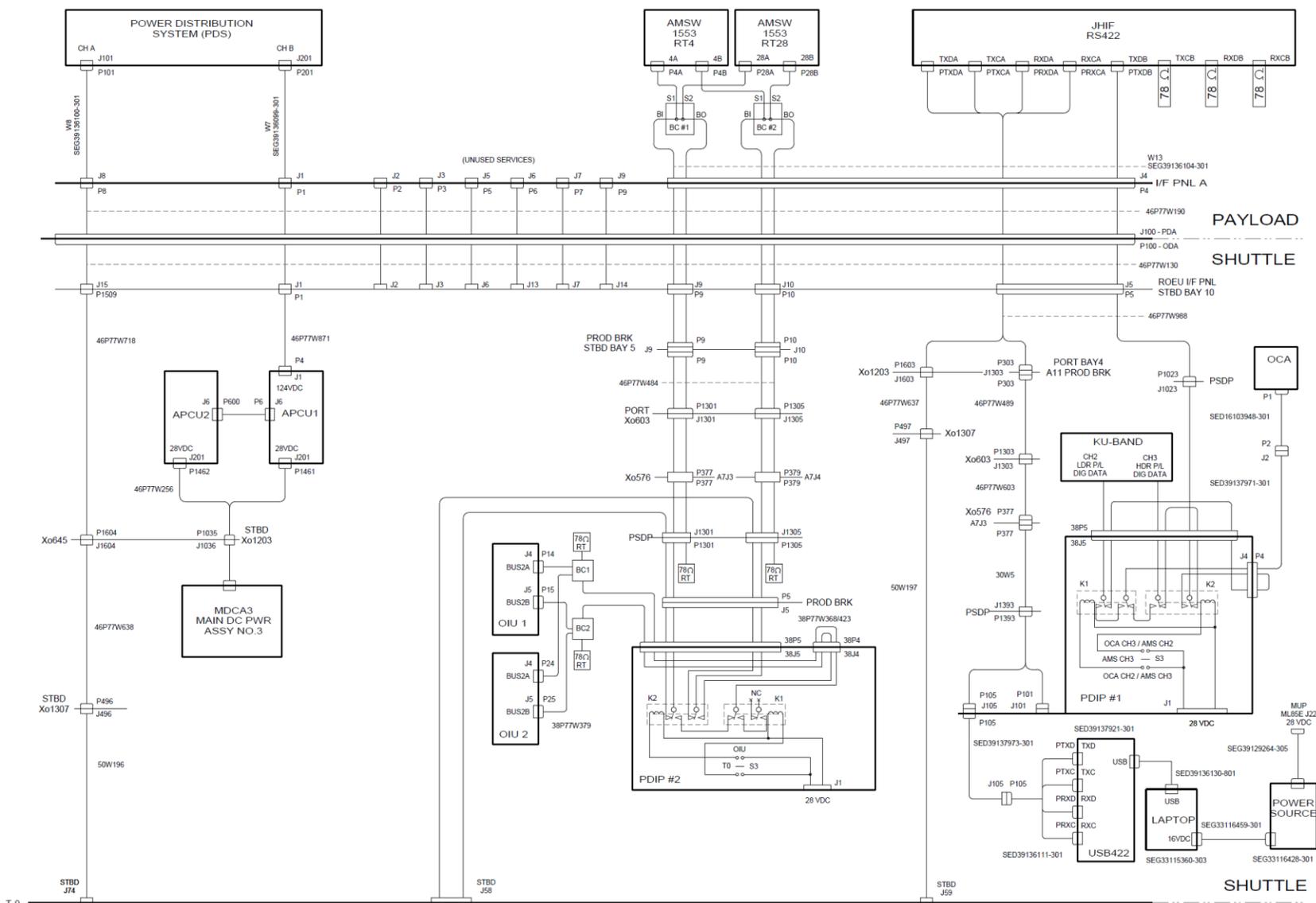


Figure 5.12.7-3 AMS-02 STS Interface Diagram

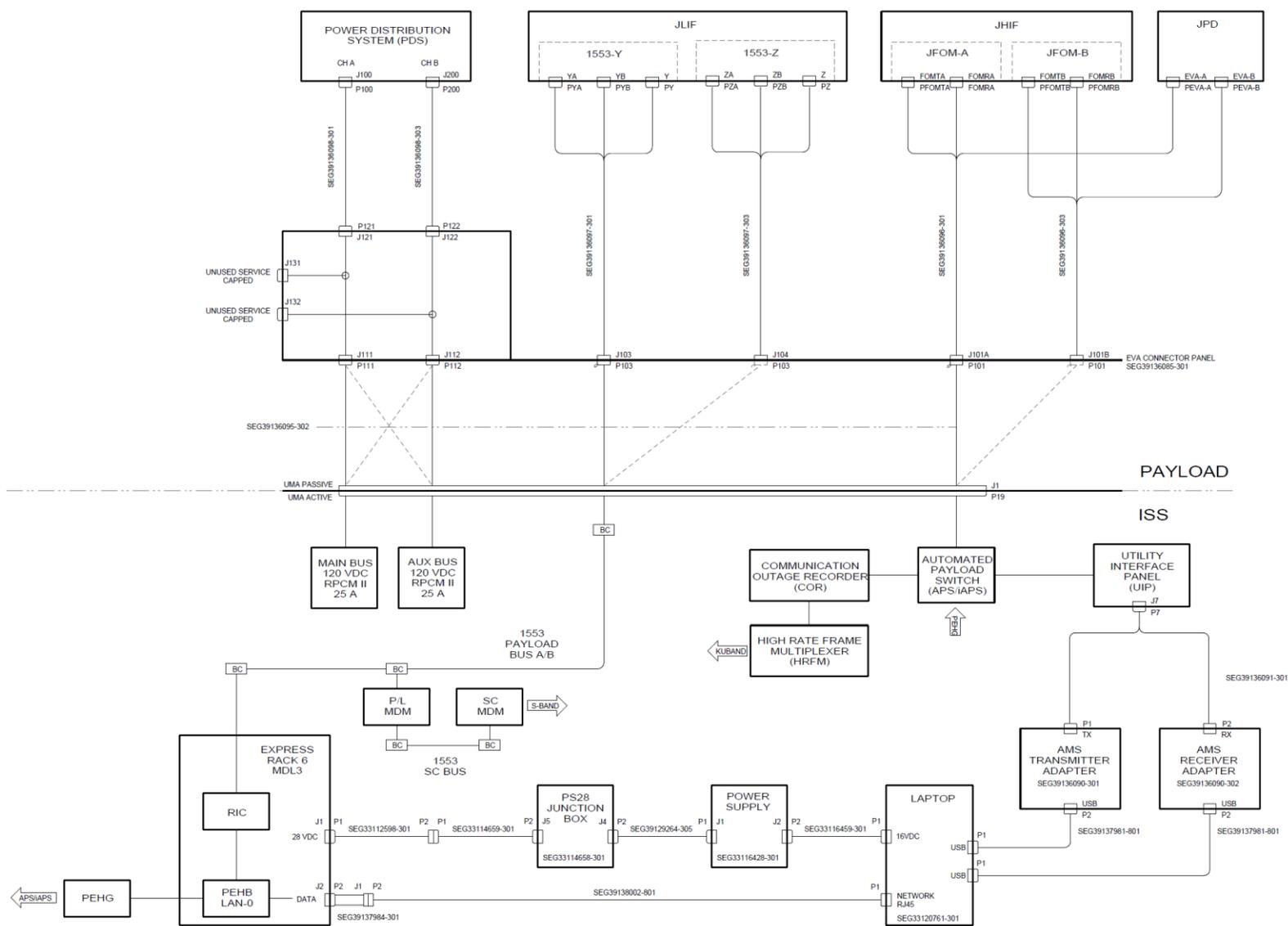


Figure 5.12.7-5 AMS-02 ISS PAS UMA Interface Diagram

The ISS supplies three 8 AWG wires for each of two power buses at the UMA interface. One wire is intended for power, one for return, and the third is a fault ground. The power and return lines are run from a Type II RPCM with an over-current set-point of 25 A. The Fault Ground wires are attached to the truss system as a ground and do not run through the RPCM. The RPCM maintains two fault ground paths:

- A. Via a connecting wire from Station Structure through its input connector
- B. Conductive path from chassis to structure.

The AMS will take these wires as input thru two separate connectors each into the Power Distribution System (PDS), which has three output sections:

- A. 120VDC output
- B. 28VDC output
- C. Low Voltage (Control and Monitor) output.

The Fault Ground wires are tied to chassis within the PDS and provide the common ground for the entire USS. A short to chassis in the PDS would result in tripping the RPCM and current will be returned to ISS via the Fault Ground to ISS structure. A likely result of a bent pin in the UMA for either the Power or Return lines would be an open-circuit (high voltage/no current) with this implementation. A short circuit between power and return or ground in the UMA would trip the RPCM.

As far as downstream avionics boxes are concerned, extensive effort has been taken to isolate them from the ISS power supply and to current limit the output from the “front-end”. This current limiting and isolation is located within the PDS. So, the amount of current that could flow from a short in a downstream avionics box is very limited and will trip a breaker in milliseconds.

All avionics boxes on the AMS are electrically tied to structure as this provides the common ground. This grounding is effected either through direct bonding across the mechanical attach points via alodined faying surface of the footprint, or by bonding straps that are attached to alodined faying surfaces. All mechanical grounds will be measure post-integration to verify compliance with bonding and grounding requirements.

A type II RPCM is the first level protection for the ISS from the AMS. At 115 ± 5 percent of max current rating (i.e. 27.5 – 30Amps), the Type II RPCM initiates a current limiting mode at 0.2 milliseconds, and trips between 31 and 38 milliseconds.

Additionally, the PDS will have a Fault Ground wire. The primary purpose of the Fault Ground wire is to protect the ISS and payload against a fault that would dump the full 25A from ISS to payload. The PDS is the front end interface to the ISS Power feed. Protection against this fault is provided by tying these wires to chassis. In the event of a short to chassis, the Fault Ground wire is the lowest resistance return to the power source.

Again, the PDS serves as the front-end for the AMS experiment and it further isolates its outputs from the ISS power supply and provides much lower current limiting with DC to DC converters (current limiting and voltage step-down) and circuit breakers. For all of the lower voltage outputs (28VDC or less) these outputs are limited to 5A except for the TT-Crates, for which the redundant feeds are limited to 10A.

The measurements taken on the sample riveted joint interface (with 10 less rivets than the actual joints will have), led to a resistance measurement of less than 0.02 milliohms. From NSTS 37330, an STS specification, it states that a maximum resistance of .074 milliohms can be used to carry 1000A.

5.12.8 AMS-02 Integration Cabling De-Rating

The AMS-02 integration cabling de-rating information is provided in Table 5.12.8-1.

TABLE 5.12.8-1 AMS-02 INTEGRATION CABLING DE-RATING INFORMATION

Assembly Part Number	Component Part Number	Component Description	Specification / Supplier	EMC	V (max) Rating (VDC)	V (max) Applied (VDC)	V Ratio	V (derating) Required	I (max) Rating (Amp)	I (max) Applied (Amp)	I Ratio	I (Derating) Required	Notes
SEG39136099-301	MS3456L24-11SW	Plug, Cable Mount, P201	MIL-C-5015	EO	200	124	0.62	1	-	-	-	-	Box mount connector J201 designated by AMS Collaboration
	ME414-0234-7246	Receptacle, Flange Mount, J1	ME414-0234		200	124	0.62	1	-	-	-	-	Cable mounted connector P1 on cable assy P/N 46P77W190 supplied by program office
	M22759/12-8-9	Wire, 8 AWG, PTFE, Nickel Coated CU	MIL-W-22759/12		600	120	0.20	-	40.86	29.03	0.71	1	Two (2) APCU parallel config, 3600 W @ 124 VDC
SEG39136100-301	MS3456L24-11SW	Plug, Cable Mount, P101	MIL-C-5015	EO	200	120	0.60	1	-	-	-	-	Box mount connector J101 designated by AMS Collaboration
	NB0E18-8SNT3	Receptacle, Flange Mount, J8	40M39569		200	120	0.60	1	-	-	-	-	Cable mounted connector P8 on cable assy P/N 46P77W190 supplied by program office
	M27500-12RE2U00	Cable, 2 Cond, 12 AWG, Nickel Coated CU	MIL-DTL-27500		600	120	0.20	-	24.11	16.67	0.69	1	AMS-02 requires 2 kW for calibration and contingency
SEG39136101-301	NB6GE16-26SNT3	Plug, Cable Mount, P1	40M39569	HO	200	28	0.14	1	-	-	-	-	Cable mounted connector P9 on cable assy P/N 46P77W190 supplied by program office
	NB0E16-26SNT3	Receptacle, Flange Mount, J9	40M39569		200	28	0.14	1	-	-	-	-	Cable mounted connector P9 on cable assy P/N 46P77W190 supplied by program office
	M27500-20RE2N06	Cable, 2 Cond, 20 AWG, TSP, Nickel Coated CU	MIL-DTL-27500		600	28	0.05	-	6.27	3.5	0.56	1	Vacuum Pump p/n MVP020-3DC, Max current 3.5 A, 24 VDC
SEG39136102-301	NB6GE10-6SNT3	Plug, Cable Mount, P2	40M39569	HO	200	28	0.14	1	-	-	-	-	Cable mounted connector P7 on cable assy P/N 46P77W190 supplied by program office
	NB0E22-55SNT3	Receptacle, Flange Mount, J7	40M39569		200	28	0.14	1	-	-	-	-	Cable mounted connector P7 on cable assy P/N 46P77W190 supplied by program office
	M27500-20RE2N06	Cable, 2 Cond, 20 AWG, TSP, Nickel Coated CU	MIL-DTL-27500		600	28	0.05	-	6.27	5	0.80	1	Source: Standard Switch Panel circuit breaker rated at 5 A
SEG39136103-301	NLS6GT8-35SNT3	Plug, Cable Mount, P3	40M38277	ML	200	5	0.03	1	-	-	-	-	Cable mounted connector P5 on cable assy P/N 46P77W190 supplied by program office
	NLS0T14-35SNT3	Receptacle, Flange Mount, J5	40M38277		200	5	0.03	1	-	-	-	-	Cable mounted connector P5 on cable assy P/N 46P77W190 supplied by program office
	M27500-22RE4N06	Cable, 4 Cond, 22 AWG, Nickel Coated CU	MIL-DTL-27500		600	5	0.01	-	4.02	0.02	0.005	1	Source: MDM Low Level Discrete Output (DOL)
SEG39136104-301	5-0051-2-218	Plug, Cable Mount, 450 Series, Twinax, P4A	Trompeter	RF	900	30	0.03	1	-	-	-	-	Box mount connectors 4A, 4B, 28A, 28B, TXDA, TXCA, RXDA, RXCA, and TXDB designated by AMS Collaboration
	5-0051-2-218	Plug, Cable Mount, 450 Series, Twinax, P4B	Trompeter		900	30	0.03	1	-	-	-	-	Trompeter Voltage Rating @ sea level
	5-0051-2-218	Plug, Cable Mount, 450 Series, Twinax, P28A	Trompeter		900	30	0.03	1	-	-	-	-	1553 Application
	5-0051-2-218	Plug, Cable Mount, 450 Series, Twinax, P28B	Trompeter		900	30	0.03	1	-	-	-	-	
	5-0051-2-201	Plug, Cable Mount, 450 Series, Twinax, PTXDA	Trompeter		900	5	0.01	1	-	-	-	-	
	5-0051-2-201	Plug, Cable Mount, 450 Series, Twinax, PTXCA	Trompeter		900	5	0.01	1	-	-	-	-	
	5-0051-2-201	Plug, Cable Mount, 450 Series, Twinax, PRXDA	Trompeter		900	5	0.01	1	-	-	-	-	
	5-0051-2-201	Plug, Cable Mount, 450 Series, Twinax, PRXCA	Trompeter		900	5	0.01	1	-	-	-	-	
	5-0051-2-201	Plug, Cable Mount, 450 Series, Twinax, PTXDB	Trompeter		900	5	0.01	1	-	-	-	-	
	NLS0T16-35SNT3	Receptacle, Flange Mount, J4	40M38277		200	30	0.15	1	-	-	-	-	
	NDBC-TFE-22-2SJ-75	NASA Data Bus Cable, 2 Cond, TSP, 22 AWG, TFE, 75 Ohms	SSQ21655		600	30	0.05	-	4.34	0.25	0.06	1	

TABLE 5.12.8-1 AMS-02 INTEGRATION CABLING DE-RATING INFORMATION (CONTINUED)

Assembly Part Number	Component Number	Part	Component Description	Specification / Supplier	EMC	V (max) Rating (VDC)	V (max) Applied (VDC)	V Ratio	V (derating) Required	I (max) Rating (Amp)	I (max) Applied (Amp)	I Ratio	I (Derating) Required	Notes
SED39136111-301	NLS6GT12-35P		Plug, Cable Mount, P105	40M38277	RF	200	5	0.03	1	-	-	-	-	
	DAMA-15S		Plug, Cable Mount, P201	MIL-DTL-24308		1250	5	0.004	1	-	-	-	-	
	M22759/12-22-9		Wire, 22 AWG, Nickel Coated CU	MIL-W-22759/12		600	5	0.01	-	3.21	0.25	0.08	1	
SED39136115-801	76000294		DATAFIRE SYNC/570i X.21	DIGI International	RF	300	5	0.02	-	4	0.25	0.06	-	COTS Cable RS422 Application
SEG39136098-301	MS3456L24-11S		Plug, Cable Mount, P100	MIL-C-5015	EO	200	124	0.62	1	-	-	-	-	
	ME414-0235-7247		Plug, Cable Mount, P121	ME414-0235		200	124	0.62	1	-	-	-	-	
	M22759/12-8-9		Wire, 8 AWG, PTFE, Nickel Coated CU	MIL-W-22759/12		600	124	0.21	-	40.86	25	0.61	1	
SEG39136120-301	MS3456L24-11S		Plug, Connector Mount, P200	MIL-C-5015	EO	200	124	0.62	1	-	-	-	-	
	ME414-0235-7247		Plug, Connector Mount, P122	ME414-0235		200	124	0.62	1	-	-	-	-	
	M22759/12-8-9		Wire, 8 AWG, PTFE, Nickel Coated CU	MIL-W-22759/12		600	124	0.21	-	40.86	25	0.61	1	
SEG39136097-301	5-0051-2-218		Plug, Cable Mount, PYA	Trompeter	RF	900	30	0.03	1	-	-	-	-	
	5-0051-2-218		Plug, Cable Mount, PYB	Trompeter		900	30	0.03	1	-	-	-	-	
	MWDM2L-21P-6J7-130		Plug, Cable Mount, PY	MIL-DTL-83513		600	5	0.01	1	-	-	-	-	
	NZGL00T1515N35SA		Receptacle, Wall Mount, NZGL Series, J103	SSQ21635		200	5	0.03	1	-	-	-	-	
	NDBC-TFE-22-2SJ-75		Cable, 2 Cond, 22 AWG, TFE, 75 Ohms	SSQ21655		600	30	0.05	-	4.34	0.2	0.05	1	
	M22759/33-26		Wire, 26 AWG, Silver Plated CU	MIL-W-22759/33		600	5	0.01	-	0.71	0.2	0.28	1	
SEG39136097-303	5-0051-2-218		Plug, Cable Mount, PZA	Trompeter	RF	900	30	0.03	1	-	-	-	-	Only used as contingency for 1553 interface
	5-0051-2-218		Plug, Cable Mount, PZB	Trompeter		900	30	0.03	1	-	-	-	-	
	MWDM2L-21P-6J7-130		Plug, Cable Mount, PZ	MIL-DTL-83513		600	5	0.01	1	-	-	-	-	
	NZGL00T1515N35SA		Receptacle, Wall Mount, NZGL Series, J104	SSQ21635		200	5	0.03	1	-	-	-	-	
	NDBC-TFE-22-2SJ-75		Cable, 2 Cond, 22 AWG, TFE, 75 Ohms	SSQ21655		600	30	0.05	-	4.34	0.2	0.05	1	
	M22759/33-26		Wire, 26 AWG	MIL-W-22759/33		600	5	0.01	-	0.71	0.2	0.28	1	
SEG39136096-301	FODT-PA1720BS		Plug, Cable Mount, PFOMTA	ITT CANNON	FO	-	-	-	-	-	-	-	-	Fiber Optic
	FODT-PA1720BS		Plug, Cable Mount, PFOMRA	ITT CANNON		-	-	-	-	-	-	-	-	
	MS27473E16F8P		Plug, Cable Mount, PEVA-A	MIL-C-38999		200	5	0.03	1	-	-	-	-	
	NZGL00T1717N13SN		Receptacle, Wall Mount, NZGL Series, J101A	SSQ21635		200	5	0.03	1	-	-	-	-	
	NFOC-2FFF-1GRP-1		NASA Fiber Optic Cable	SSQ21634		-	-	-	-	-	-	-	-	
	M27500-16RE2N06		Cable, 2 Cond, 16 AWG, TSP, Nickel Coated CU	MIL-DTL-27500		600	5	0.01	-	12.54	0.5	0.04	1	
SEG39136096-303	FODT-PA1720BS		Plug, Cable Mount, PFOMTB	ITT CANNON	FO	-	-	-	-	-	-	-	-	Only used as contingency for fiber optic interface
	FODT-PA1720BS		Plug, Cable Mount, PFOMRB	ITT CANNON		-	-	-	-	-	-	-	-	
	MS27473E16F8P		Plug, Cable Mount, PEVA-B	MIL-C-38999		200	5	0.03	1	-	-	-	-	
	NZGL00T1717N13SN		Receptacle, Wall Mount, NZGL Series, J101B	SSQ21635		200	5	0.03	1	-	-	-	-	
	NFOC-2FFF-1GRP-1		NASA Fiber Optic Cable	SSQ21634		-	-	-	-	-	-	-	-	
	M27500-16RE2N06		Cable, 2 Cond, 16 AWG, TSP, Nickel Coated CU	MIL-DTL-27500		600	5	0.01	-	12.54	0.5	0.04	1	

TABLE 5.12.8-1 AMS-02 INTEGRATION CABLING DE-RATING INFORMATION (CONTINUED)

Assembly Part Number	Component Part Number	Component Description	Specification / Supplier	EMC	V (max) Rating (VDC)	V (max) Applied (VDC)	V Ratio	V (derating) Required	I (max) Rating (Amp)	I (max) Applied (Amp)	I Ratio	I (Derating) Required	Notes
SEG391360095-303	NZGL06G2525LN7SN	Plug, Cable Mount, NZGL Series, P111	SSQ21635		200	120	0.60	1	-	-	-	-	UMA Connector J1 and pigtail supplied by program
	NZGL06G2525LN7SN	Plug, Cable Mount, NZGL Series, P112	SSQ21635		200	120	0.60	1	-	-	-	-	
	NZGL06G1515N35PA-1	Plug, Cable Mount, NZGL Series, P103	SSQ21635		200	5	0.03	1	-	-	-	-	
	NZGL06G1717N13PN	Plug, Cable Mount, NZGL Series, P101	SSQ21635		200	5	0.03	1	-	-	-	-	
SEG39136084-301	SCBM3W3F0000G	Plug, Cable Mount, P10	Positronic Industries		300	120	0.40	1	-	-	-	-	Connector P10 supplied by External Berthing Cue System (EBCS)
	NB6GE18-8PNT2	Plug, Cable Mount, P131	40M39569		200	120	0.60	1	-	-	-	-	
	M22759/12-12-9	Wire, 12 AWG, PTFE, Nickel Coated CU	MIL-W-22759/12		600	120	0.20	-	23.21	0.42	0.02	1	
SEG39136084-303	SCBM3W3F0000G	Plug, Cable Mount, P13	Positronic Industries		300	120	0.40	1	-	-	-	-	Connector P13 supplied by External Berthing Cue System (EBCS)
	NB6GE18-8PNT2	Plug, Cable Mount, P132	40M39569		200	120	0.60	1	-	-	-	-	
	M22759/12-12-9	Wire, 12 AWG, PTFE, Nickel Coated CU	MIL-W-22759/12		600	120	0.20	-	23.21	0.42	0.02	1	
SEG39136093-301	SCBM5W5F0000G	Plug, Cable Mount, P11	Positronic Industries		300	120	0.40	1	-	-	-	-	PVGF and pigtail supplied by program
	SCBM5W5F0000G	Plug, Cable Mount, P8	Positronic Industries		300	120	0.40	1	-	-	-	-	Connectors P11, P8, P7, P6, P5, P4, and P3 supplied by EBCS
	225609-4	Plug, Cable Mount, P7	AMP Inc		750	2	0.003	1	-	-	-	-	
	225609-4	Plug, Cable Mount, P6	AMP Inc		750	2	0.003	1	-	-	-	-	
	225609-4	Plug, Cable Mount, P5	AMP Inc		750	2	0.003	1	-	-	-	-	
	NB6E10-6SNT2	Plug, Cable Mount, P24	40M39569		200	120	0.60	1	-	-	-	-	
	NB6E18-8SNT2	Plug, Cable Mount, P23	40M39569		200	120	0.60	1	-	-	-	-	
	NB6E18-8SNT2	Plug, Cable Mount, P22	40M39569		200	120	0.60	1	-	-	-	-	
	BJ379-45	Plug, Cable Mount, P21	Trompeter		900	30	0.03	1	-	-	-	-	
	BJ379-45	Plug, Cable Mount, P20	Trompeter		900	30	0.03	1	-	-	-	-	
	BJ379-45	Plug, Cable Mount, P19	Trompeter		900	30	0.03	1	-	-	-	-	
	142-0303-401	Plug, Cable Mount, P4	Johnson Components		65	2	0.03	1	-	-	-	-	
	142-0303-401	Plug, Cable Mount, P3	Johnson Components		65	2	0.03	1	-	-	-	-	
Miscellaneous Items													
SDD39136117-001	650BS001M22	J2 Stowage Connector	MIL-C-5015		200	28	0.14	1	-	-	-	-	
	650BS001M22	J3 Stowage Connector	MIL-C-5015		200	28	0.14	1	-	-	-	-	
	NLSOT14-35SA	J6 Stowage Connector	40M38277		200	28	0.14	1	-	-	-	-	
SDG39136119-001	MS3115-10L	J24 Stowage Connector	MIL-C-26482		200	120	0.60	1	-	-	-	-	
	MS3115-18L	J23 Stowage Connector	MIL-C-26482		200	120	0.60	1	-	-	-	-	
	MS3115-18L	J22 Stowage Connector	MIL-C-26482		200	120	0.60	1	-	-	-	-	
	TNT1-1-78	J21 78 Ohm Terminator	Trompeter		900	30	0.03	1	-	-	-	-	
	TNT1-1-78	J20 78 Ohm Terminator	Trompeter		900	30	0.03	1	-	-	-	-	
	TNT1-1-78	J19 78 Ohm Terminator	Trompeter		900	30	0.03	1	-	-	-	-	
	142-0801-861	J4 50 Ohm Terminator	Johnson Components		250	2	0.01	1	-	-	-	-	
	142-0801-861	J3 50 Ohm Terminator	Johnson Components		250	2	0.01	1	-	-	-	-	
RS422 Terminators	TNG451P-1-78	TXCB 78 Ohm Terminator	Trompeter		900	5	0.01	1	-	-	-	-	
	TNG451P-1-78	RXDB 78 Ohm Terminator	Trompeter		900	5	0.01	1	-	-	-	-	
	TNG451P-1-78	RXCB 78 Ohm Terminator	Trompeter		900	5	0.01	1	-	-	-	-	

5.12.9 AMS-02 Data Systems and Interfaces

The AMS-02 payload uses a series of computers to process commands and data. The AMS-02 computers and their functions have been reviewed and deemed pertinent to mission success only. Since the AMS-02 experiment computer avionics systems are mission success oriented, and not safety critical, the description of these AMS-02 command and data systems is top-level, and provided for informational reference only.

The top level-computer, to which command and data services are interfaced on both the STS and the ISS, is called the Main Data Computer (JMDC), located in the J-Crate. Figure 5.12.9-1 provides an overview of the AMS avionics elements. Figure 5.12.9-2 depicts the NASA provided interfaces on the ISS and STS, as they are routed to the AMS-02 experiment top-level avionics.

For the JMDC, as well as all other electronics, AMS-02 has taken the high performance technologies used in particle physics and implemented them for use in low Earth orbit. A unified approach has been made to meet the requirements imposed by the different AMS-02 subdetectors, by NASA and most importantly, by the physics goals. Particular effort has been made to ensure that the data acquisition and trigger electronics will meet the performance requirements on orbit during the 11 years of operation. Meeting the challenges of implementing high performance, space qualified electronics has been a key activity of the entire AMS-02 collaboration.

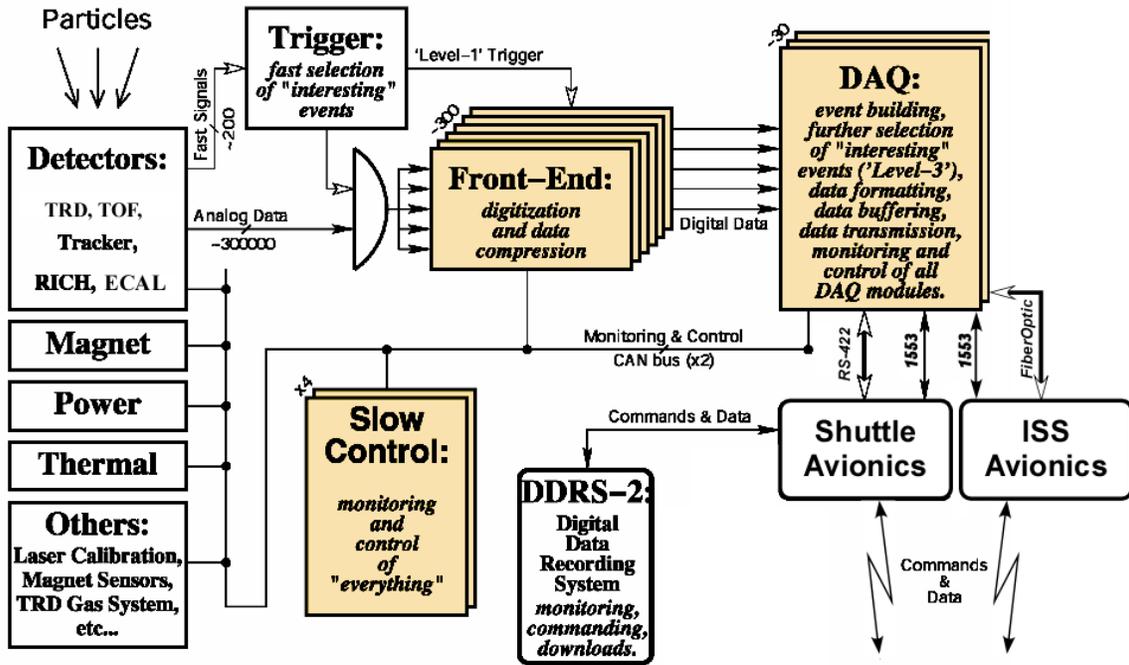


Figure 5.12.9-1 AMS-02 Electronics Elements

5.12.9.1 Data Interface for Ground Operations in the STS

During ground operations, control and data systems monitor capability will be provided by GSE located in the Mobile Launch Platform, connected via the T0 Umbilical, and through the Remotely Operated Electrical Umbilical (ROEU) to the experiment electronics. The command and data monitor capabilities are via both low-rate 1553 Bus and high-rate data system RS422 protocol serial dual communications.

As shown in Figure 5.12.9.1-1 below, low rate data (1553) is routed through T0 umbilical from the Shuttle Payload Data Interface Panel #2 (PDIP2) with the “AMS-02 1553” switch in the “T0” position, and a program provided jumper installed on PDIP2 front panel “J4” connector. High rate data (RS422) is routed through T0 umbilical from Shuttle PDIP1 via a payload provided cable installed between the PDIP2 front panel “J103” and “J105” connectors.

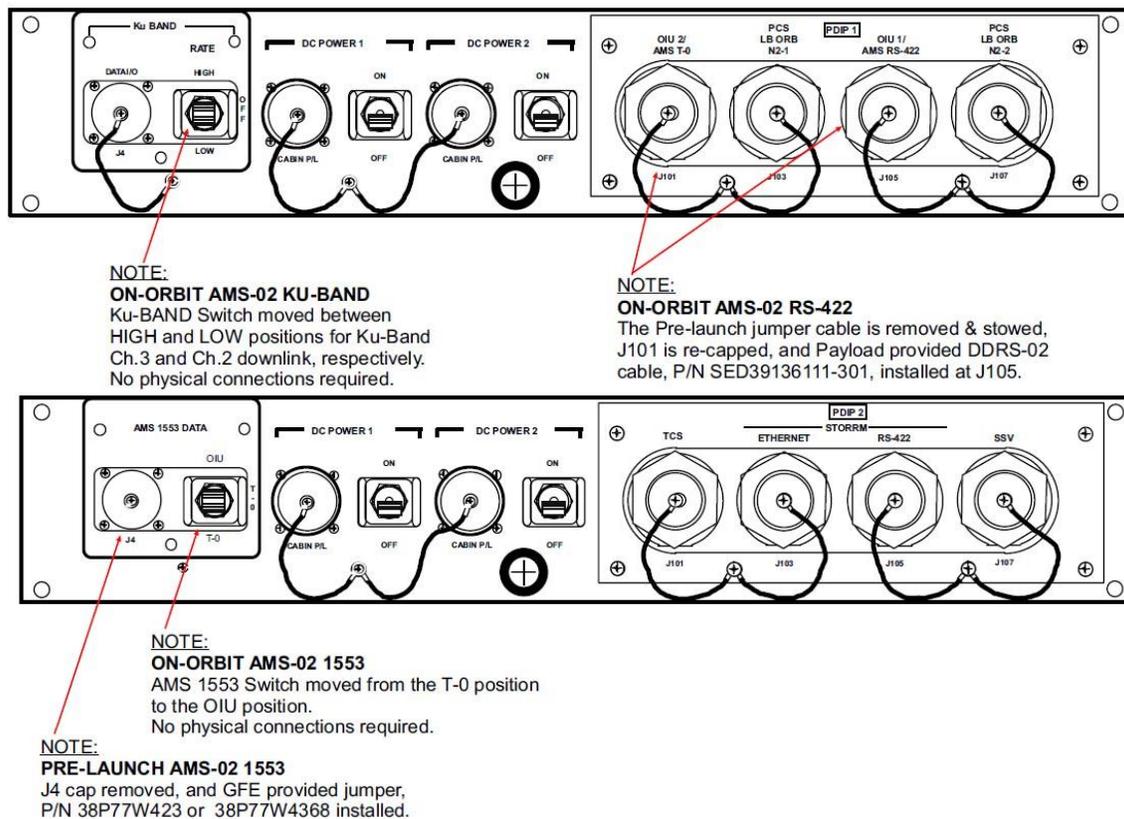


Figure 5.12.9.1-1 Payload Data Interface Panel #1 and #2 (PDIP1 and PDIP2) Layout

5.12.9.2 Ascent Data Interface on the STS

During Ascent the AMS-02 is powered off and has no required data interfaces.

5.12.9.3 Data Interface for On-Orbit Operations on the STS

Once on-orbit, and while in the Shuttle payload bay, command and monitoring capability is supplied via both 1553 Bus and RS422 serial communications each routed through the ROEU to the experiment electronics.

Following Post-Insertion activities, payload activation activities are expected to begin at approximately MET 00/02:30. At this time, a mid-deck locker stowed, STS provided, AMS Laptop (PGSC) computer will be un-stowed, set-up, and activated on the Orbiter Aft Flight Deck (AFD). Setup includes the removal of the payload provided cable between front panel “J103” and “J105” connectors on PDIP1, on the AFD, and attachment of a new payload provided cable to the PDIP1 “J105” (Figure 5.12.9.1-1) to interface with the PGSC, as shown in Figure 5.12.9.3-1 . The new cable will include a built-in multiplexer to interface the RS-422 signals into a USB on the PGSC for recording. This PGSC in conjunction with the payload cable is referred to as the AMS-02 Digital Data Recording System (DDRS-02); and will be used to record all high rate data generated by AMS-02 during checkout activities. Concurrent to these activities, or prior to them, the Orbiter Interface Unit (OIU) should be powered up and checked out in preparation for communication with the AMS-02 payload via PDIP2, with “AMS-02 1553” switch in “OIU” position (Figure 5.12.9.1-1).

During avionics checkout, RS-422 data is recorded on the hard-drive of the PGSC continuously, and AMS-02 RS-422 data from another feed-thru on the Payload Data Interface Panel #1 (PDIP1) assembly, with the “Ku-Band” switch in the “HIGH” or “LOW” position (Figure 5.12.9.1-1), will be down-linked via the STS Ku-Band Ku Channel 3 or Channel 2, respectively, as coverage and scheduling permit.

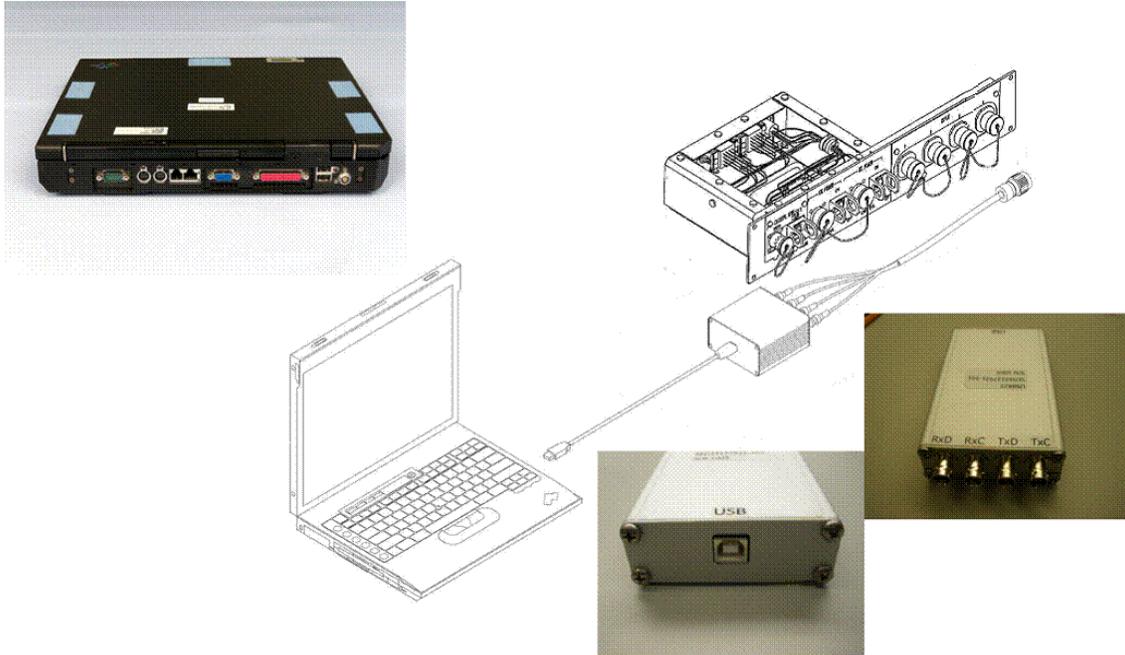


Figure 5.12.9.3-1 DDRS-02, AMS Laptop (PGSC) to PDIP2 Interface

5.12.9.4 Data Interface for Extra Vehicular Robotics (EVR) Activities

Just prior to transfer activities, the AMS-02 is powered down and the ROEU is disconnected from the PDA attached to the AMS-02. The AMS-02 is grappled by the SRMS via a FRGF attached to the payload. The FRGF has no data interface capabilities.

The SRMS maneuvers the AMS-02 for an Arm-to-Arm transfer to the SSRMS. The SSRMS grapples the payload via a PVGF located on the opposing side of the AMS-02 from the FRGF. The PVGF provides video signal interface for use by the EBCS camera during berthing operations. Additionally, the PVGF has 1553 Bus interface capability; however, this is not being utilized by the AMS-02 payload. During this mission phase, the AMS-02 payload requires only 120 VDC power via the PVGF for thermostatically controlled keep-alive heater power.

5.12.9.5 Data Interface for ISS Operations

All data services for the AMS-02 payload are provided through an Umbilical Mechanism Assembly (UMA) mounted to the Payload Attach Site. The interface consists of a low data rate link (LRDL) and a high data rate link (HRDL).

5.12.9.5.1 ISS Low Rate Data Link (LRDL) Interface

The LRDL used on ISS, like the STS LRDL, is based on the MIL STD 1553B dual serial bus. This is split to each of the four JMDCs in the J-Crate, one of which is selected to actively manage the link. As the point of splitting is a possible single point failure, AMS has two such splitters which can be selected by an astronaut swapping a cable on the EVA Connector Panel located at the bottom of the experiment, as shown in Figure 5.12.9.5.1-1, during a contingency EVA. This contingency capability is available for data transmission recovery on ISS only.

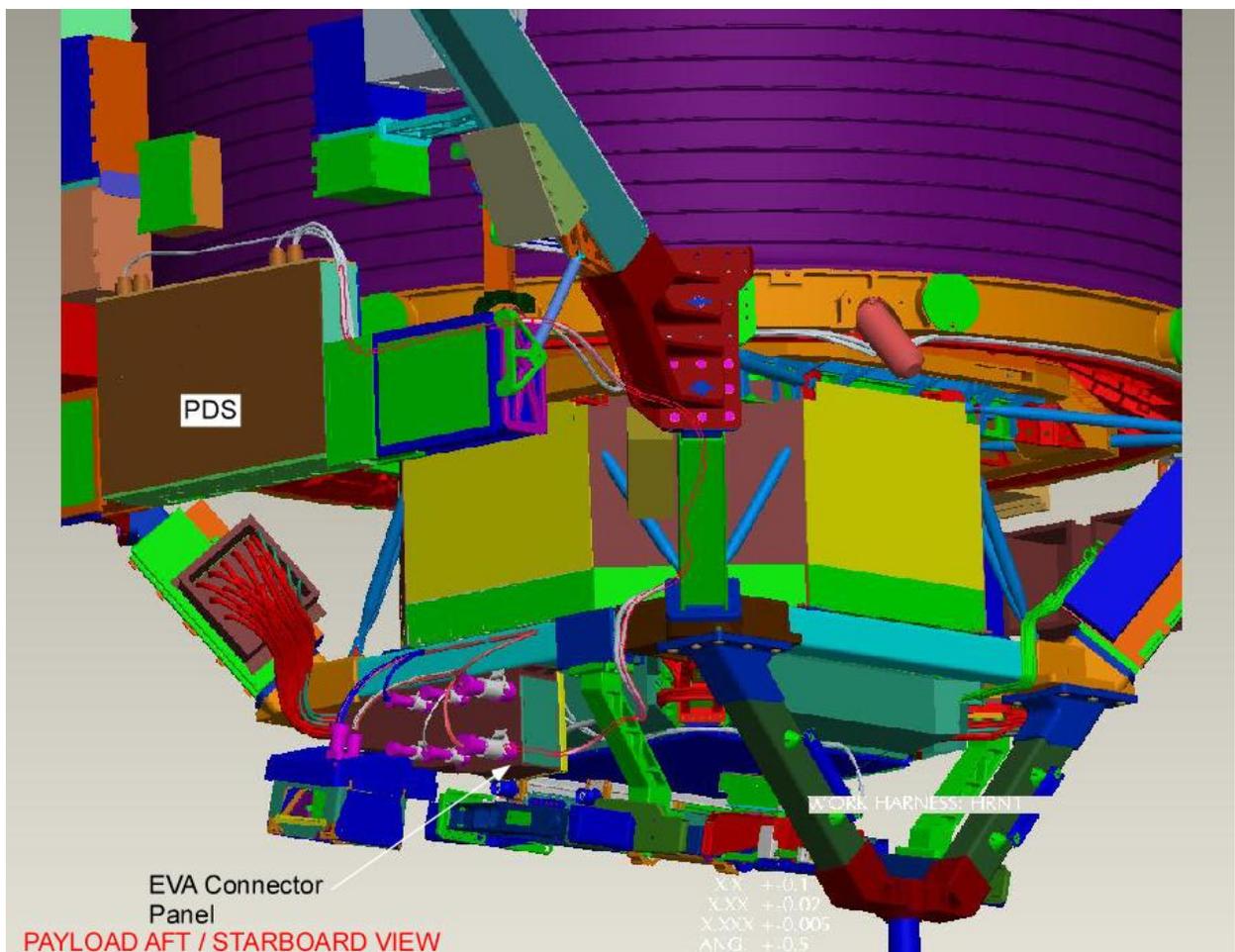


Figure 5.12.9.5.1-1 EVA Panel Location

The active JMDC receives commands and redistributes them within AMS, either to other software within that JMDC, to another JMDC or to the controllers of other electronics

subsystems. The intra-experiment command and data monitoring communications are accomplished via either AMSWire protocol (similar to SpaceWire) or CAN Bus. The controllers in turn set switches and digital to analog converters (DACs) to control various experimental parameters, such as voltages. They also monitor numerous temperatures, voltages and currents and report these values when requested to the active JMDC, where they are appropriately formatted and sent on to the LRDL.

The LRDL telemetry data is then processed through the ISS avionics and down-linked, where it is routed to the AMS Payload Operation and Control Center (POCC). The NASA avionics involved include : the S-band (intended for contingency transmission of Critical Health Data), the ACBSP S-band receiver, the Command and Control Multiplexer/Demultiplexer (C&C MDM), the Payload Multiplexer/ Demultiplexer (P/L MDM), the Automated Payload Switch (APS), the High Rate Communications Outage Recorder (HCOR), the High Rate Frame Multiplexer & High Rate Modem (HRFM/HRM), the Ku-band system connecting the ISS via the Tracking and Data Relay Satellite (TDRS) through the White Sands Ground Complex (WSGC) to the Marshall Space Flight Center (MSFC) and the Johnson Space Center (JSC). Within the US Lab on the ISS, the astronaut crew has access to this data via the ISS Digital Data Recording System (DDRS-02). In total AMS is allocated about 20 KBits/sec of data bandwidth on the LRDL, with an expected duty cycle of up to 70%. Ten highly summarized bytes per second of critical health data are being proposed to be transmitted via the S-Band system as a contingency with near to 100% duty cycle. Along the way the ISS crew and NASA ground controllers can monitor this data and, should the need arise, have the facility to issue a few key commands, for example to put the experiment into a standby state. In nominal conditions, all commands originate in the POCC and follow the inverse path, the maximum command rate being about 1 Kbit/second.

As commanding and telemetry are critical to the operation of the experiment and as the NASA provisions for payloads are not fault tolerant, substantial effort has been made to implement a parallel set of the LRDL data paths over the HRDL for both monitoring and commanding of AMS-02.

5.12.9.5.2 ISS High Rate Data Link (HRDL) Interface

The HRDL is the main data conduit out of AMS-02. It is based on a NASA specific implementation of fiber optic communications. The link can move data on the ISS at speeds up to 90 MBit/sec, and the radio down link supports up to 43 Mbit/sec, again with an at best duty cycle of 70%. Of this AMS has been allocated an orbit average of 6 Mbit/sec. The nominal AMS-02 data downlink rate has been established via the MSFC Payload Operations Integration Center (POIC) organization to be 27 Mbit/sec to account for shared ISS Ku-band downlink resources and its availability. Within AMS-02, the data is collected by the data acquisition (DAQ) system to a buffer within the JMDCs. As with the LRDL, each of the four JMDC is connected to the HRDL and a cable swap during EVA avoids a possible single point of failure. On the HRDL the data flows over the paths shown in Figure 5.12.9.5.2-1. A key element in this path is. On the ground the data is routed to the AMS-02 POCC and Science Operation Center.

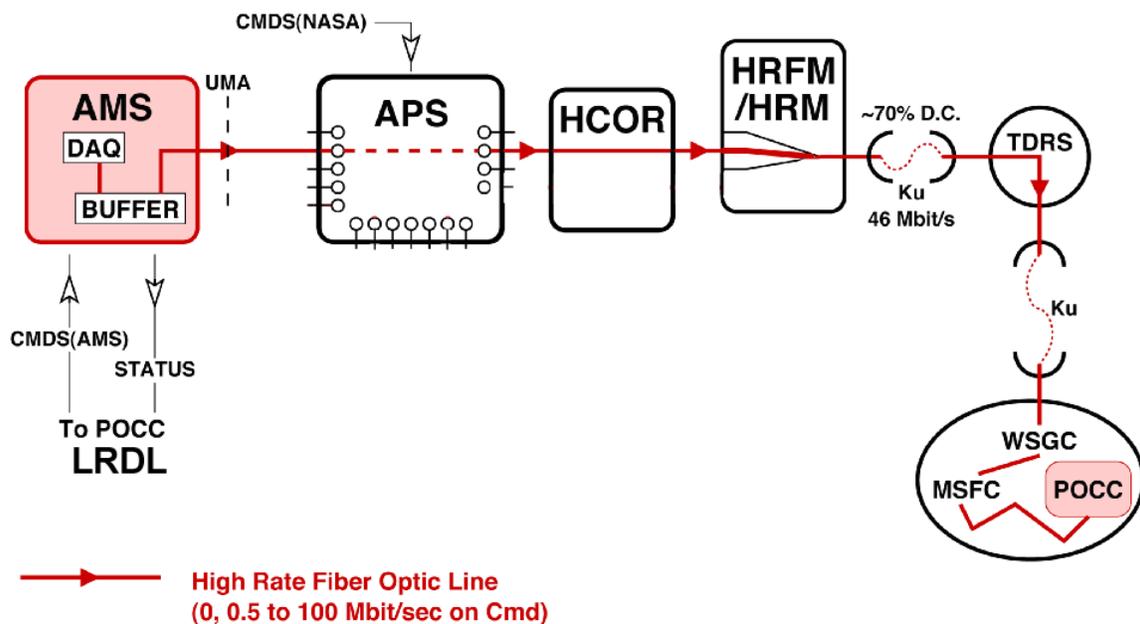


Figure 5.12.9.5.2-1 AMS-02 Science data flow over the of HRDL

5.12.9.5.3 ISS Digital Data Recording System (DDRS-02) (Not Addressed in this Safety Data Package, Flying Independently)

The ISS Digital Data Recording System-02 (DDRS02) is based on a NASA provided T61p ISS laptop, dedicated for AMS use. It will:

- Provide back-up recording (24/7) on-board the ISS for AMS-02 payload data
- Provide play-back capability to downlink lost or corrupted AMS-02 payload data
- Protect for ISS data systems, as well as AMS-02 payload, outages
- Allow for contingency crew monitor of AMS-02 payload status and contingency crew commanding of AMS-02 payload systems

The ISS DDRS-02 interfaces consist of a HRDL (fiber-optic) bi-directional connection at UIP, an ISSLAN “back-door” connection, and 28VDC input power at ExPRESS Rack.

The ISS DDRS-02 resident ISS DDRS software is loaded on T61p prime hard-drive. Back-up AMS-02 payload data will be stored on an AMS-02 project certified / provided 500G SATA hard-drive in Ultra-Bay Adaptor in the T61p ISS laptop. Crew hard-disk change-out minimized by over-writing data on the AMS disk once it is verified on the ground (only used to prolong hard disk life).

The ISS DDRS-02 interfaces and functionality are shown in the schematic Figure 5.12.9.5.3-1, and a CAD representation of the ISS DDRS-02 installation is shown in Figure 5.12.9.5.3-2. The ISS DDRS-02 HRDL to USB adaptors are shown in Figure 5.12.9.5.3-3.

The DDRS-02 will be flown independently from the AMS-02 and is NOT COVERED in this safety data package and hazard reports, a separate package will be prepared and process for its safety within the crew habitable volume. The potential impact of the ISS DDRS-02 as a commanding source as been considered with the ground based commanding in this SDP.

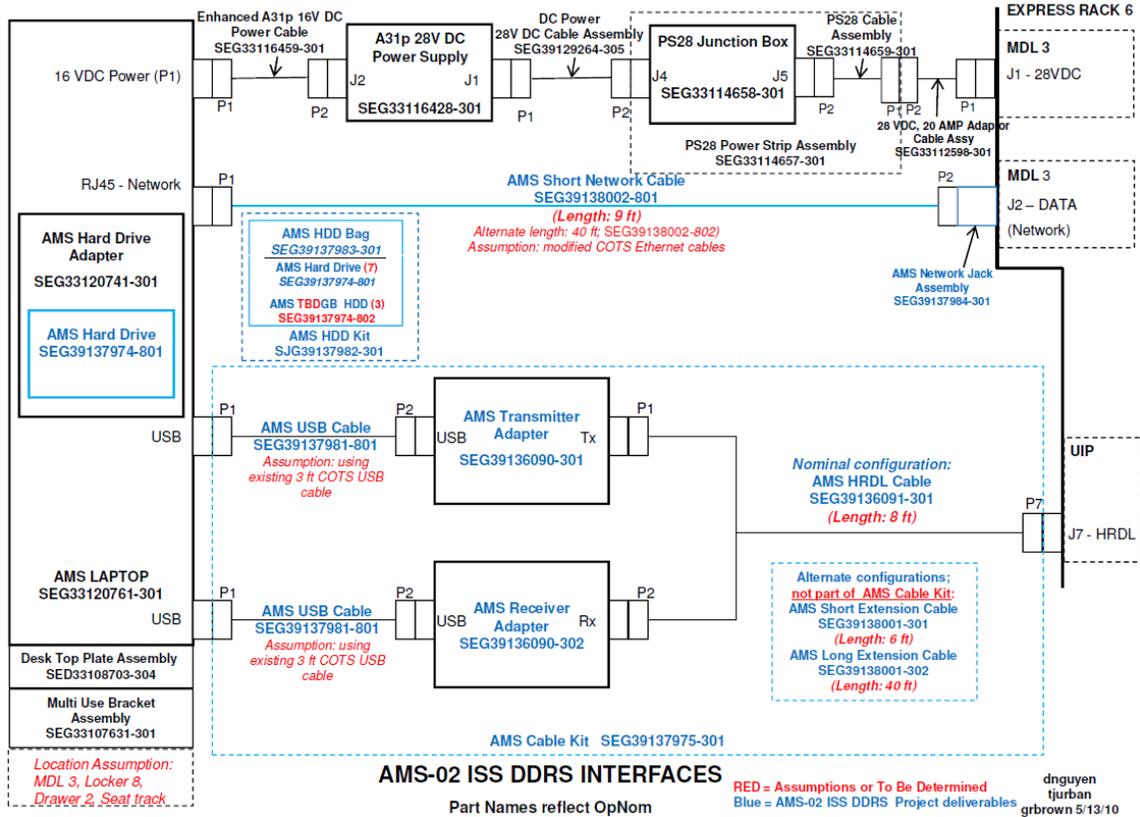


Figure 5.12.9.5.3-1 ISS DDRS-02 Schematic

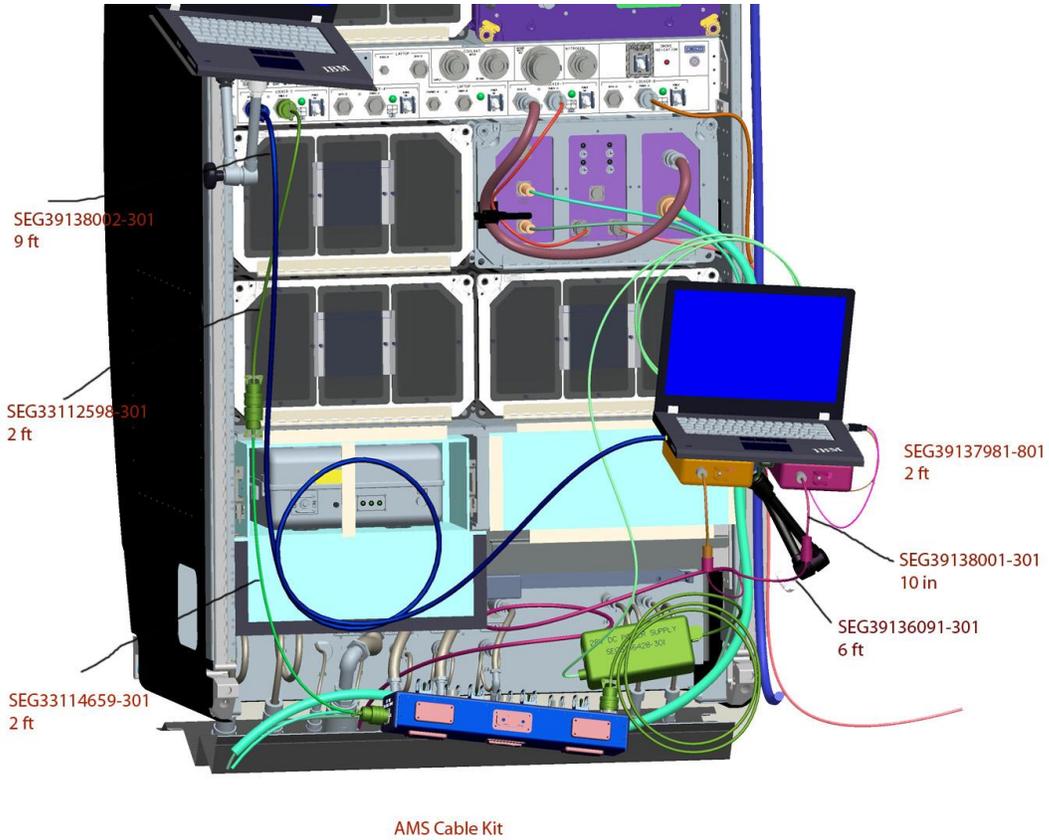


Figure 5.12.9.5.3-2 ISS DDRS-02 Installation



Figure 5.12.9.5.3-3 ISS DDRS-02 HRDL to USB Adaptors

5.13 THERMAL CONTROL SYSTEM (TCS)

The AMS-02 Thermal Control System (TCS) is being developed and designed by the AMS experiment team. During nominal operations on ISS, AMS-02 draws up to 2600 watts of power. This power must be dissipated as heat, while maintaining all components within their temperature limits. The payload also must be able to survive STS environments, handoff between STS and ISS, periods with no power (both during transfer and while berthed on ISS) and peak power excursions. Passive thermal design options are utilized as much as possible, but more complex thermal control hardware is required for some sub-detector components to assure mission success. TCS specific hardware includes radiators, heaters, thermal blankets, heat pipes, optical coatings and a dedicated CO₂ pumped loop system for Tracker cooling. AMS-02 is designed such that passive thermal control is all that is required to sustain the payload safely through extended periods of power loss without hazard.

5.13.1 Radiators

Most of the heat generated by AMS-02 is rejected to space via dedicated radiators (Figure 5.13.1-1). Ram and Wake Main radiators dissipate heat from numerous electronics crates. Ram and Wake Tracker radiators reject the heat generated inside the Tracker. A small Zenith Radiator is used to reject heat generated by Tracker Plane 1N.

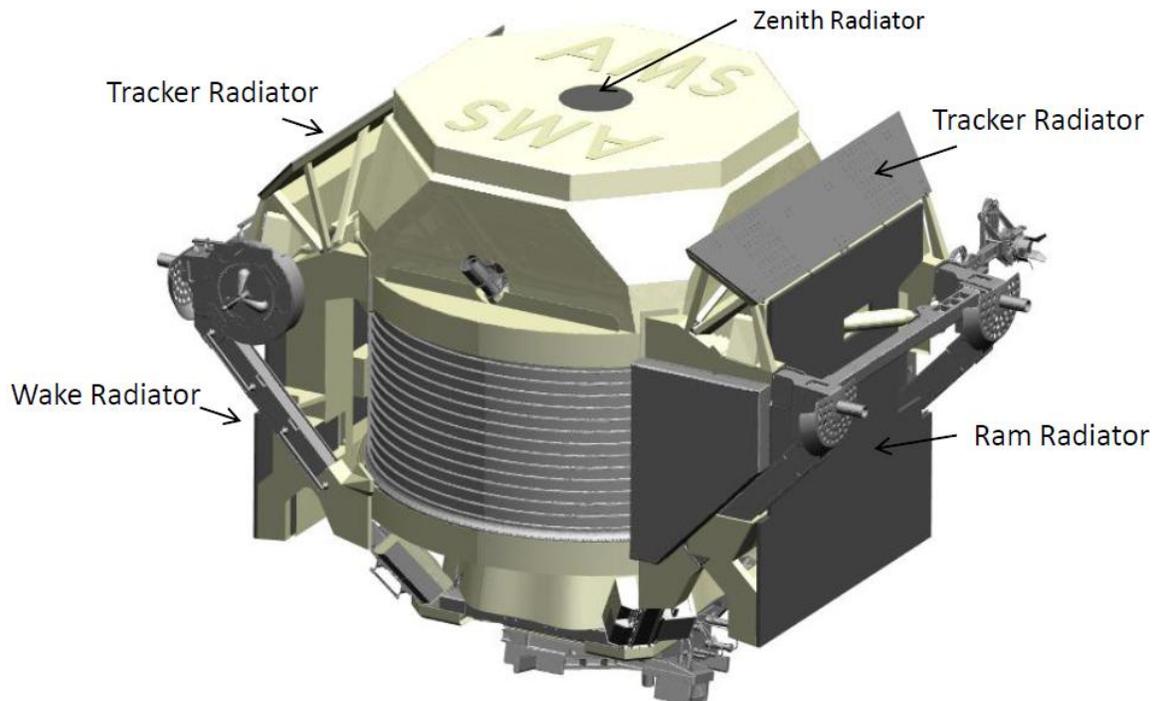


Figure 5.13.1-1 AMS-02 Radiators

5.13.1.1 MAIN (Electronics Crate) Radiators

The Ram and Wake Main Radiators are designed to both dissipate heat from the electronics crates and provide their structural support. The crates, which are optimized to transfer heat to the radiator, are bolted directly to the honeycomb panel using inserts. A silicone based thermal interface filler, Chothem 1671, is used to minimize the thermal resistance across this interface. During nominal operations the Ram radiator dissipates 525 watts over its 4.24 m² surface area, while the Wake dissipates up to 812 watts over its 3.99 m² area. Heaters mounted on these radiators are used to bring electronics above their minimum turn-on temperature after periods without power. The outer surfaces of the radiator face sheets are painted with SG121FD white paint to optimize heat rejection. Portions of the crates and inner radiator surfaces are covered with MLI blankets to minimize heat rejection back to the vacuum case and to adjacent ISS payloads.

These radiators consist of a 25mm thick ROHACELL® 51WF core with 0.5mm thick 2024 T81 aluminum face sheets and imbedded heat pipes. A cross section is shown in

Figure 5.13.1.1-1. Heat pipe layout are shown in Figures 5.13.1.1-2 a and b. The heat pipes are standard axial groove, made of aluminum 6063-T5 and filled with high purity ammonia. Each Main Radiator mounts to the USS-02 at six locations. Two brackets at the top fix the radiator to the Upper Trunnion Bridge Beams; two mid-brackets fix the middle portion of the radiator to the Lower Trunnion Bridge Beams and two pin-ended struts span the distance from the lower row of crates on the radiator to the Lower Vacuum Case Joint (Figure 5.13.1.1-3).

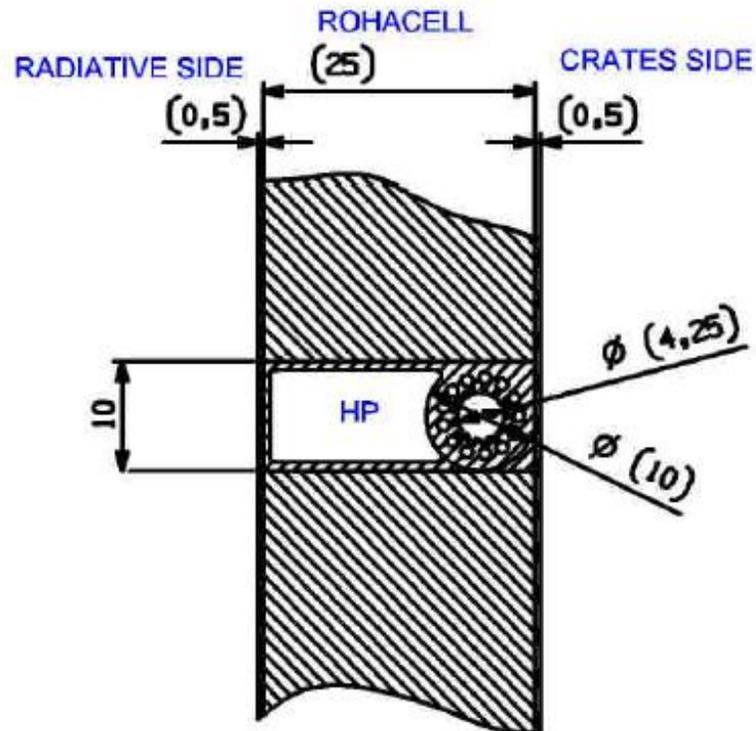
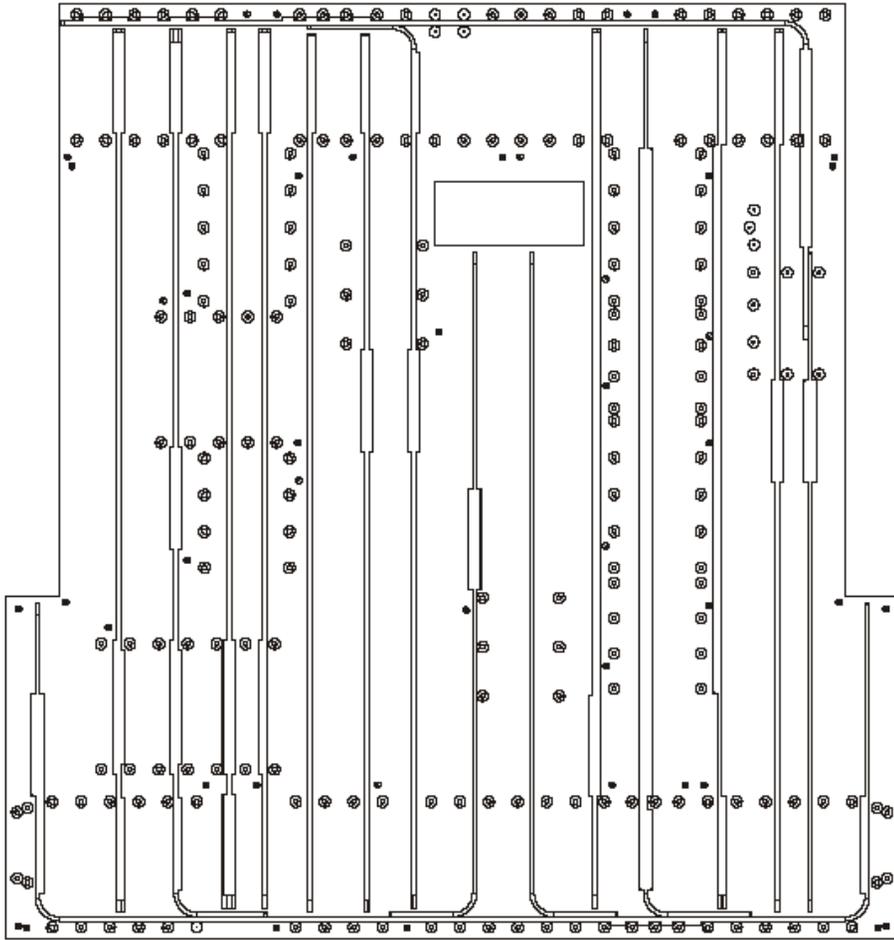
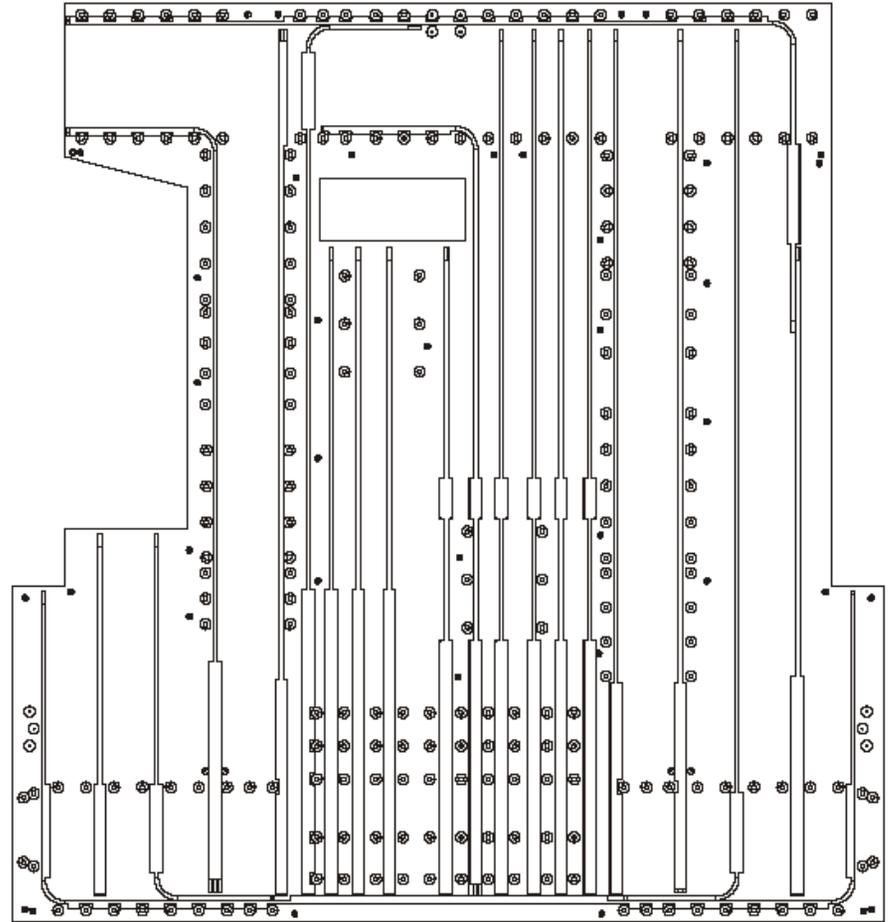


Figure 5.13.1.1-1 Main Radiator Cross Section



a) Ram Main Radiator Heat Pipes



b) Wake Main Radiator Heat Pipes

Figure 5.13.1.1-2 Ram and Wake Main radiator Heat Pipe Layout

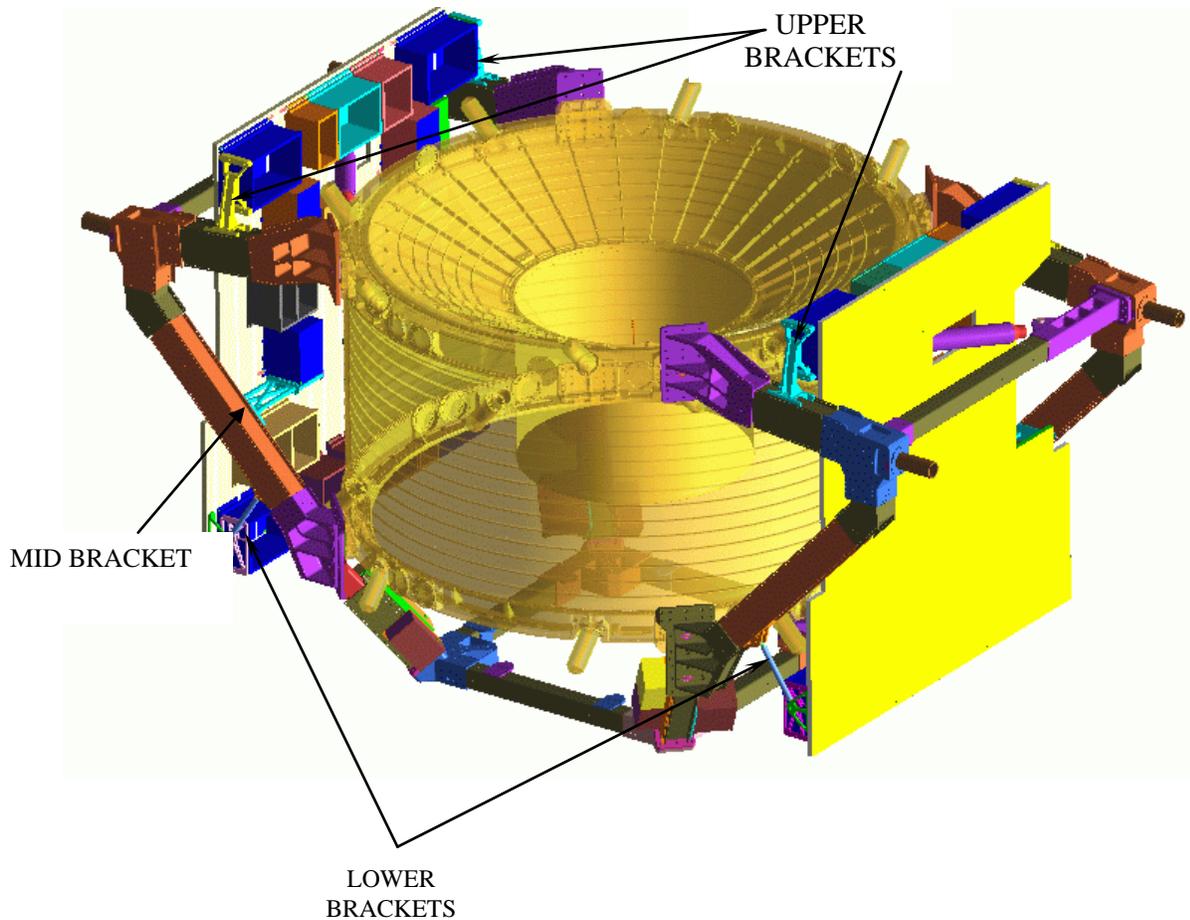


Figure 5.13.1.1-3 Main Radiator Attachment to USS-02

5.13.1.2 Tracker Radiators

The Ram and Wake Tracker radiators are designed to reject the heat transported by the Tracker Thermal Control System (TTCS), a two-phase CO₂ loop running from inside the Tracker (~144 watts) to condensers mounted on the Radiators (Figures 5.13.1.2-1 and 5.13.1.2-2). This CO₂ cooling loop is discussed in more detail in Section 5.13.6. Tracker radiators use Aluminum 2024 T81 face sheets with a ROHACELL® 51WF core and imbedded aluminum/ammonia heat-pipes (Figure 5.13.1.2-3). The tracker radiators are trapezoidal, with a lower width of 2126.8 mm, an upper width of 2600 mm, and a height of 518.6 mm. 7 heat pipes are embedded in each Tracker Radiator (Figure 5.13.1.2-4). CO₂ loop condensers mount directly to the heat pipes by bolting through the radiator (Figure 5.13.1.2-5). Each radiator is mounted using 8 pin-ended struts; 1 attached to each of the Upper Trunnion Bridge Beams and 3 attached to each of the Upper Vacuum Case joint (Figure 5.13.1.2-2). There is also a bracket attaching each Tracker Radiator to the adjoining Main Radiator. The outer surfaces of the Tracker

Radiators are painted with SG121FD white paint. The back sides will be covered with MLI blankets.

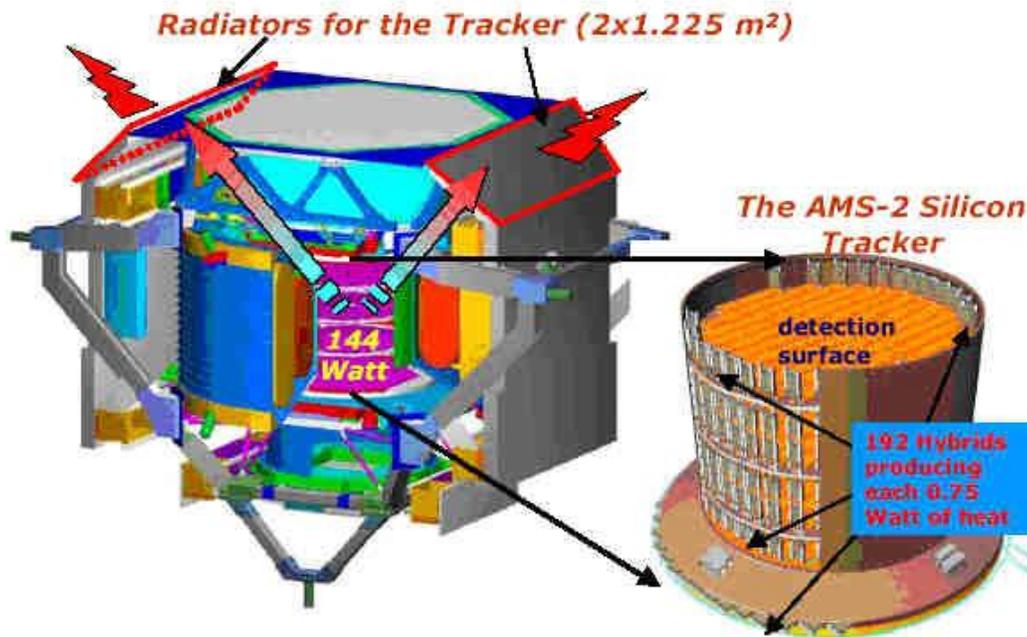


Figure 5.13.1.2-1 Tracker Cooling

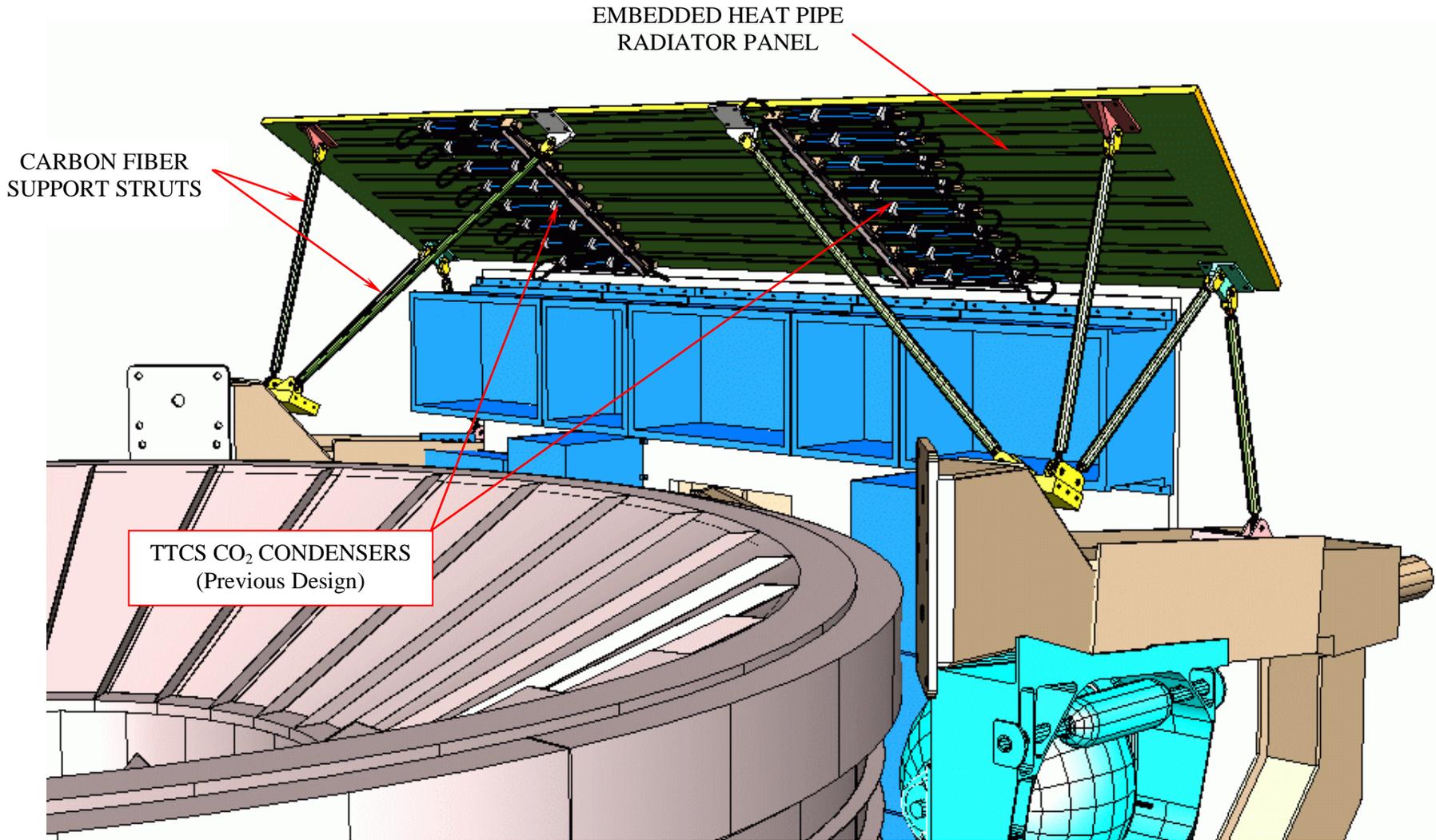


Figure 5.13.1.2-2 Tracker Radiator with TTCS Condensers Mounted

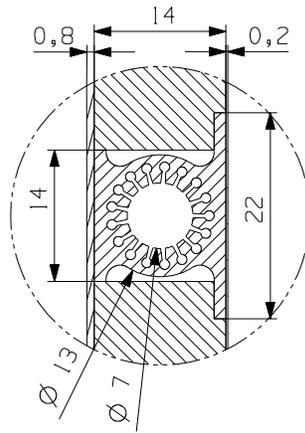


Figure 5.13.1.2-3 Tracker Radiator Cross Section

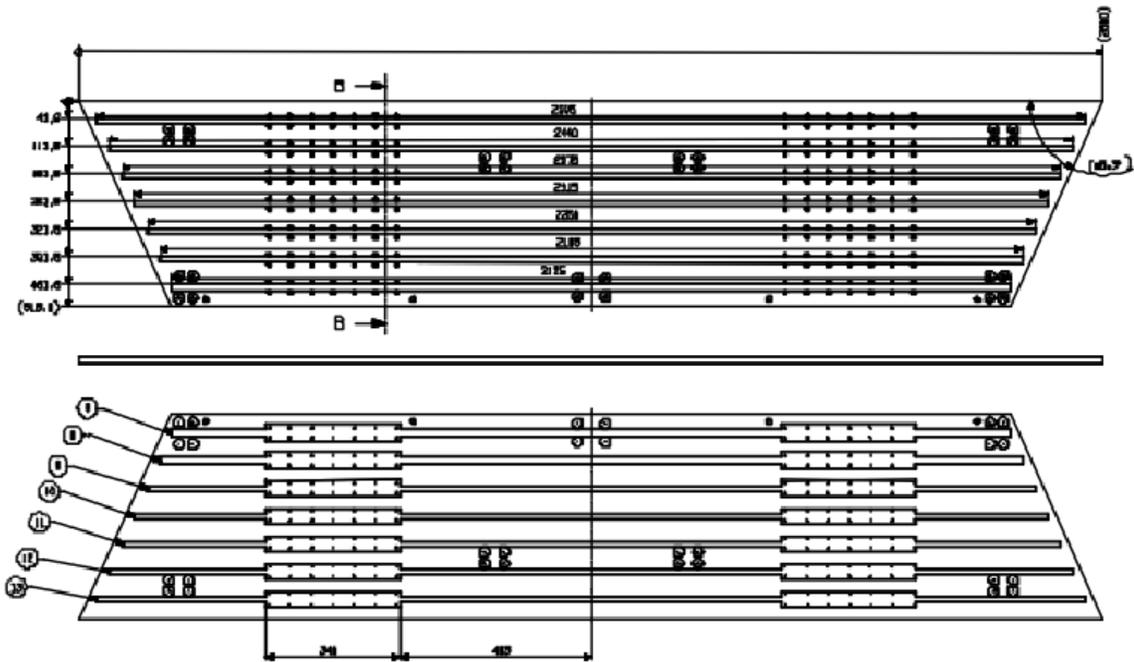


Figure 5.13.1.2-4 Tracker Radiator HP Layout

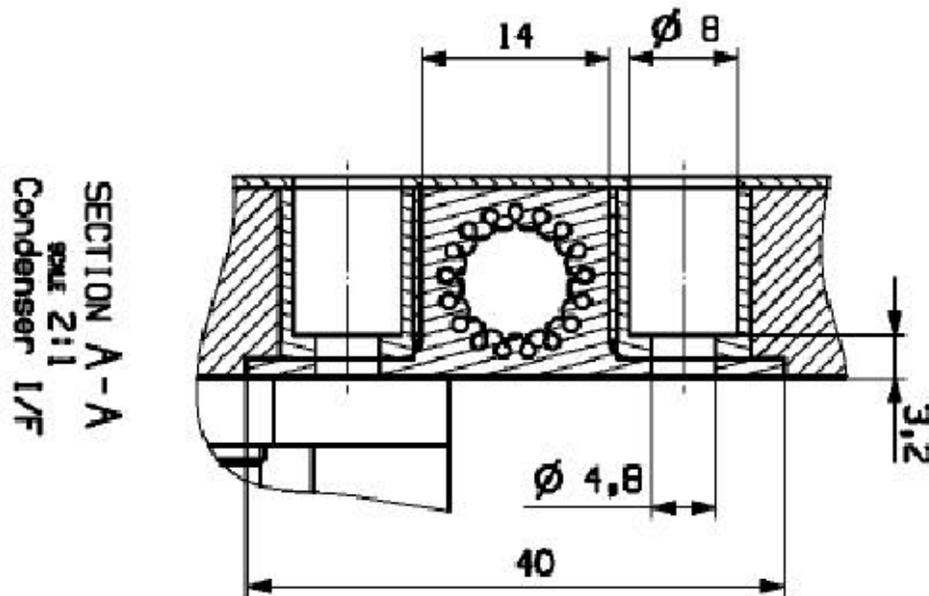


Figure 5.13.1.2-5 TTCS Condenser Mounting

5.13.2 Multi-Layer Insulation (MLI) Blankets

AMS-02 will have numerous MLI blankets on various components and sub-detectors. Concepts for a few of the larger blankets are shown in Figure 5.13.2-1. Typical construction will include Beta cloth as the outermost surface, 5 to 20 layer of aluminized Mylar separated by Dacron scrim, and either Beta cloth, reinforced aluminized Mylar, or reinforced aluminized Kapton as an inner surface. All MLI blankets used on AMS-02 will meet or exceed the NASA requirements for grounding and venting. These specifications are called out in JSC 65095, Multi-Layer Insulation for the Alpha Magnetic Spectrometer Requirements Document

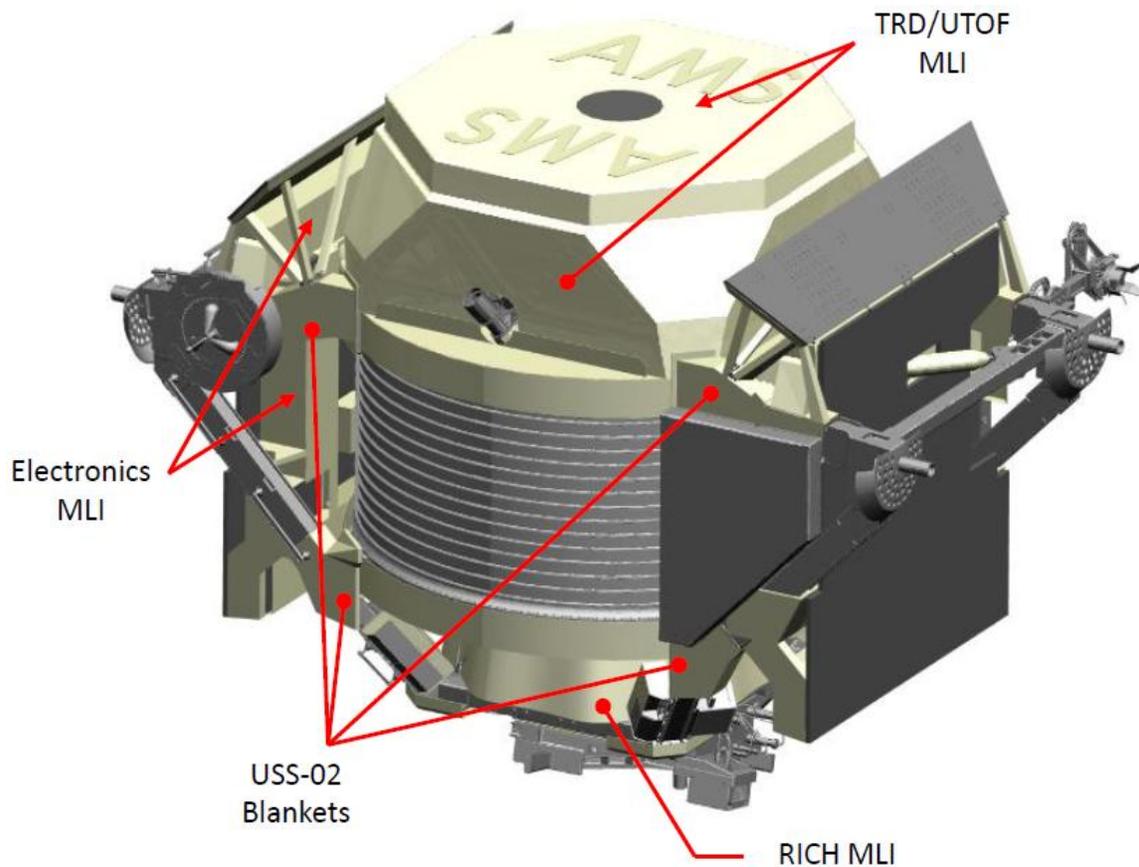


Figure 5.13.2-1 AMS-02 MLI Blankets

5.13.3 Heaters

Most heaters on AMS-02 will be used to assure that electronics are sufficiently warm before they are turned on. These heaters are mounted on the Main Radiators at locations where the embedded heat pipes can conduct heat to the crates. When AMS-02 first receives power, thermostatically controlled heaters warm up the Power Distribution System (PDS) crate to its minimum switch-on temperature. After the PDS is turned on, it then enables other heaters to warm up other electronics. When switch-on temperatures are achieved, heaters are disabled (by the PDS) prior to turning on electronics. The PDS provides 11 distinct 120V heater circuits which may be disabled or enabled as needed. A more detailed discussion of this system and the start-up procedure is found in Section 6.0

Additional heaters that will be activated during normal operation include those for the RICH, ECAL, Lower TOF, TRD, TRD Gas System, Tracker Thermal Control System,

and High Voltage Bricks. Heaters on the TTCS CO₂ lines will be used to thaw frozen CO₂ in the event of a loss of power while in a cold environment (see Section 5.13.7.3).

Analysis will be performed to evaluate the effects of “run away” heaters. Heaters were sized based on the minimum expected voltage, but failure analysis has been performed at the maximum voltage. Appendix B provides details for all heaters used on AMS-02.

5.13.4 Heat Pipes

Passive thermal control of AMS-02 includes the use of various axial groove heat pipes. While AMS-02 heat pipes vary in terms of length and cross section, all are constructed of aluminum and filled with high-purity ammonia. The amount of ammonia in each pipe is so small that freezing poses no concern.

As discussed in Section 5.13.1, heat pipes are embedded in both the Tracker and Main Radiators to help distribute heat. Besides radiators, heat pipes are also used in the TTCS control box (Section 5.13.7) and to minimize temperature gradients across one of the USS-02 joints (Section 5.13.8).

5.13.5 Optics

Thermal optical properties of external AMS-02 surfaces play a critical role in the thermal control of the payload. Typically surface optical properties are selected to bias temperatures cold where needed. This is achieved by selecting coatings which have a low ratio of solar absorptivity (α) over Infra-Red (IR) emissivity (ϵ)

Much of AMS-02 is covered with MLI blankets, which use a Teflon coated, glass-fiber cloth (e.g. Beta cloth) as the outer surface. The Main Radiators and Tracker Radiators are painted with SG121FD white paint, a very stable, low α / ϵ coating similar to what is used on the ISS radiators. The small zenith radiator and various other small electronics are covered with a silver-Teflon film (typically 5 or 10 mil FEP over vapor deposited silver over vapor deposited Inconel with 966 acrylic adhesive). This film has the lowest ratio of α / ϵ , but since it is highly specular, its use is limited to surfaces where it is absolutely needed. All exposed aluminum surfaces are anodized for corrosion protection.

Except for a few exceptions (handrails, grapple fixtures) this is a clear anodize which keeps temperatures reasonably cool. Table 5.13.5-1 lists optical coatings and properties for all significant exposed surfaces (bolt heads, rivets, cable ties, etc. are not considered thermally significant).

TABLE 5.13.5-1 AMS-02 SURFACE OPTICAL PROPERTIES

Surface Optical Property	Beginning of Life (BOL)		End of Life (EOL)	
	Absorptivity (α)	Emissivity (ϵ)	Absorptivity (α)	Emissivity (ϵ)
Beta Cloth	0.22	0.9	0.47	0.86
White paint (SG 121)	0.18	0.94	0.27	0.88
aluminized polyimide	0.14	0.05	0.14	0.05
Silver Teflon 5mil	0.08	0.78	0.13	0.75
Silver Teflon 10mil	0.09	0.89	0.15	0.85
Mixed properties (on Magnet)	0.16	0.80	0.32	0.77
anodized aluminum (clear anodize)	0.35	0.84	0.77	0.81
RICH Mirror	0.03	0.82	0.10	0.75
black anodized	0.88	0.82	0.88	0.78
gold anodized AL	0.59	0.84	0.68	0.84

5.13.6 (Deleted)

5.13.7 Tracker Thermal Control System (TTCS)

The TTCS is the most complex thermal control systems used on AMS-02 (Figure 5.13.7-1). The inner Core Tracker, completely encased inside the inner bore of the Vacuum Case, generates 112.5 Watts which need to be rejected while minimizing heat flow to the vacuum case inner cylinder. The bottom outer tracker plane (Plane 6), located between the ECAL and the RICH detectors, generates another 12 Watts which also need to be rejected by the TTCS, totaling 124.5 Watts that the TTCS must reject. The TTCS thermal design includes thermal bars, a pumped CO₂ cooling loop, radiators, manifolds, accumulators and numerous other components.

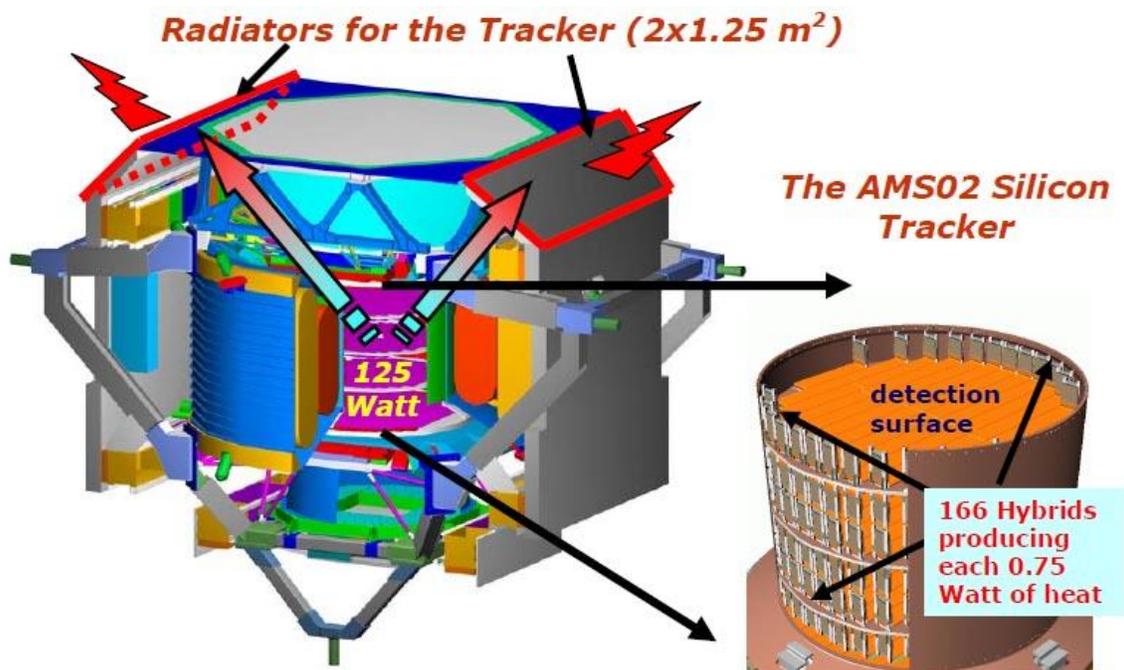


Figure 5.13.7-1 TTCS System

5.13.7.1 TTCS Evaporator

Each of the 166 hybrid electronic boards or Hybrids, located on the periphery of 8 Tracker planes, generates 0.75 watts (Figure 5.13.7.1-1). There are 6 inner rings of Hybrids inside the Vacuum Case Inner Cylinder, 1 top ring located on the upper conical

flange of the VC and a bottom ring located between the ECAL and the RICH(Figure 5.13.7.1-2). The inner ring Hybrids are attached to thermal bars, frames made of Thermal Pyrolytic Graphite (TPG) encased in aluminum 6061 (Figure 5.13.7.1-3). Between inner planes, the Thermal Bars are thermally connected to each other via flexible connectors made of copper. Thermal Bridges, also made of copper, connect the end thermal bars to the inner evaporator ring tubes (Figure 5.13.7.1-4). Hybrids on the two Outer Planes connect to the outer ring evaporator tubes via copper braids (Figure 5.13.7.1-5). There is an Inner and Outer ring evaporator on both the upper and lower Tracker flange (Figure 5.13.7.1-6). For redundancy, all evaporators include two separate tubes connected to independent cooling loops.

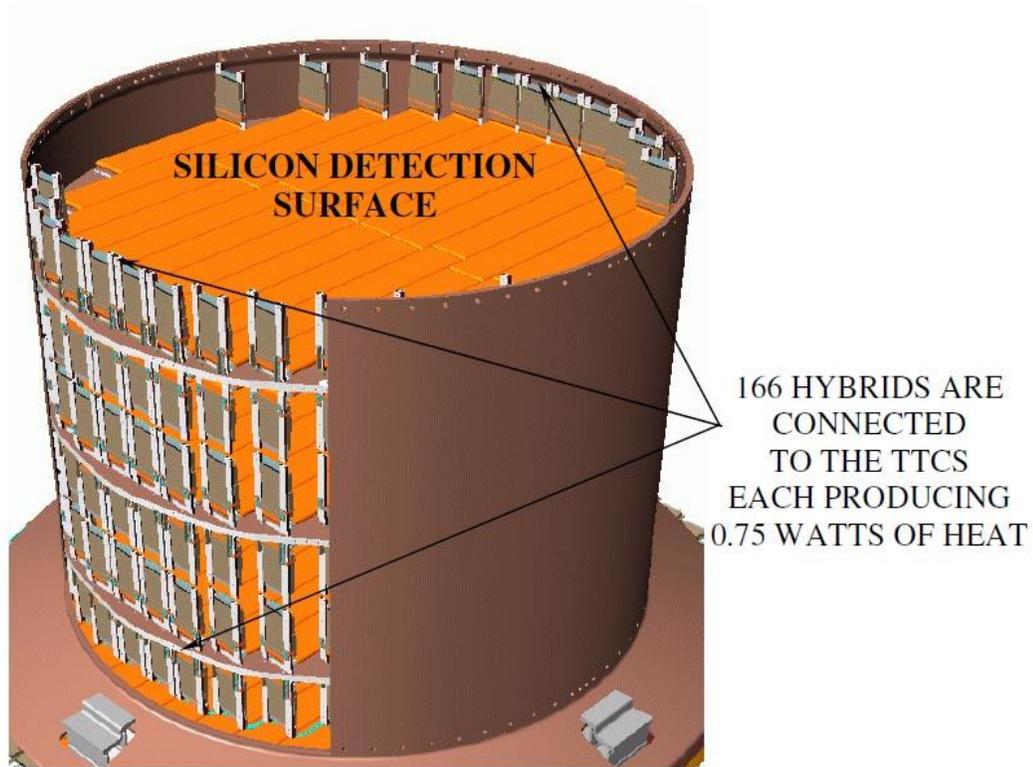


Figure 5.13.7.1-1 Tracker Hybrids

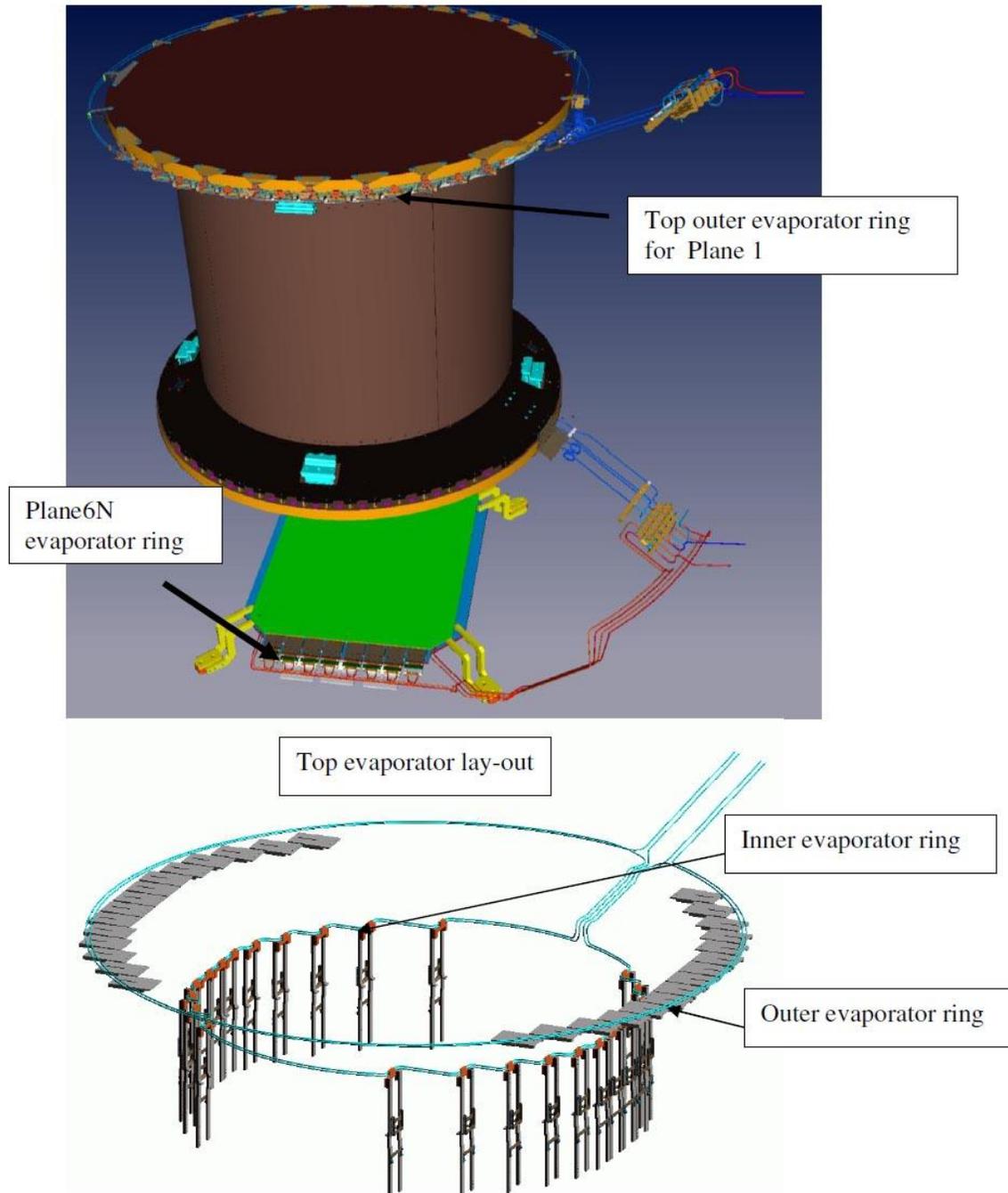


Figure 5.13.7.1-2 TTCS Evaporator (Bottom plane moved to 1N position, TTCS moved to 6N position)

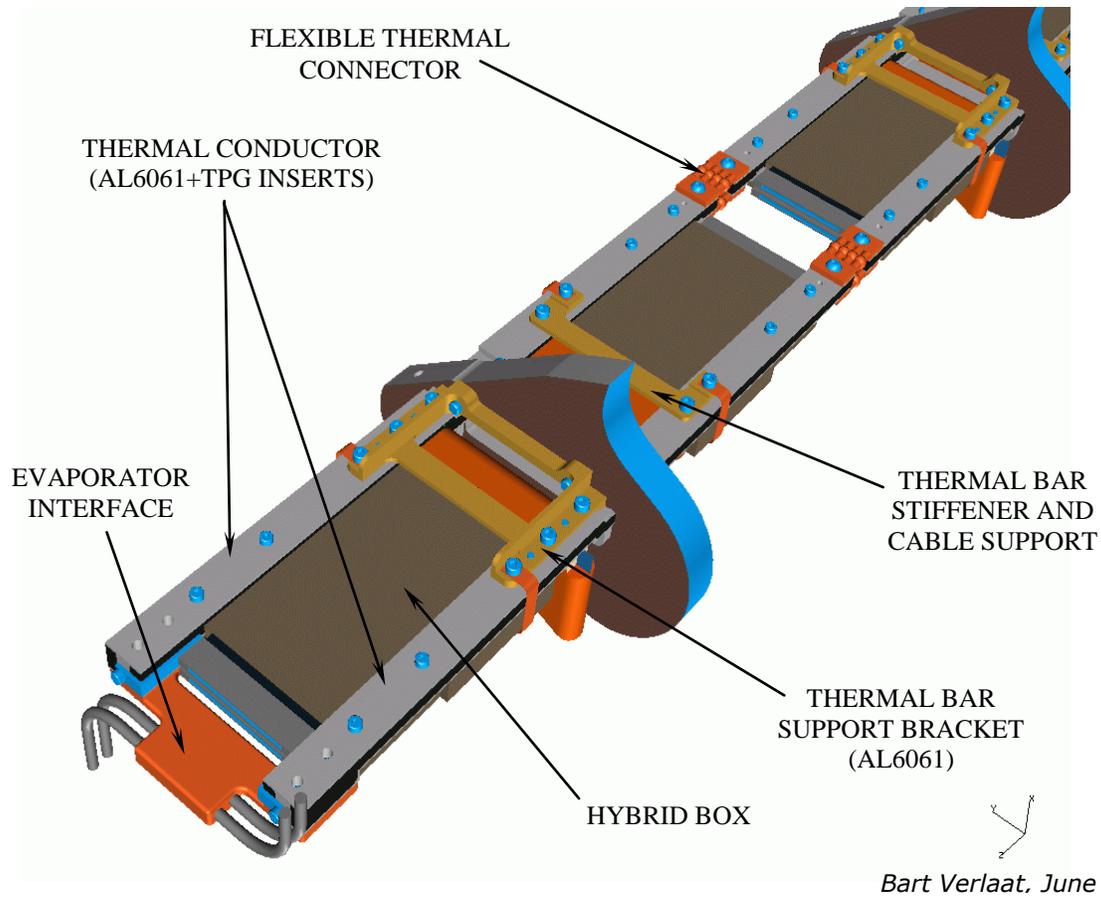


Figure 5.13.7.1-3 Internal Thermal Bar design for AMS-02

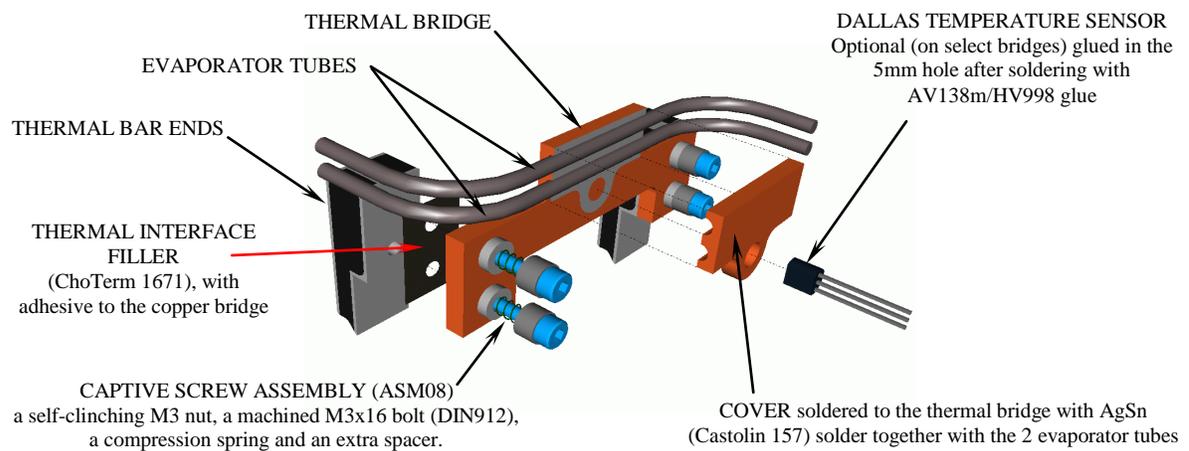


Figure 5.13.7.1-4 Connection between End of Thermal Bars and Inner Evaporator

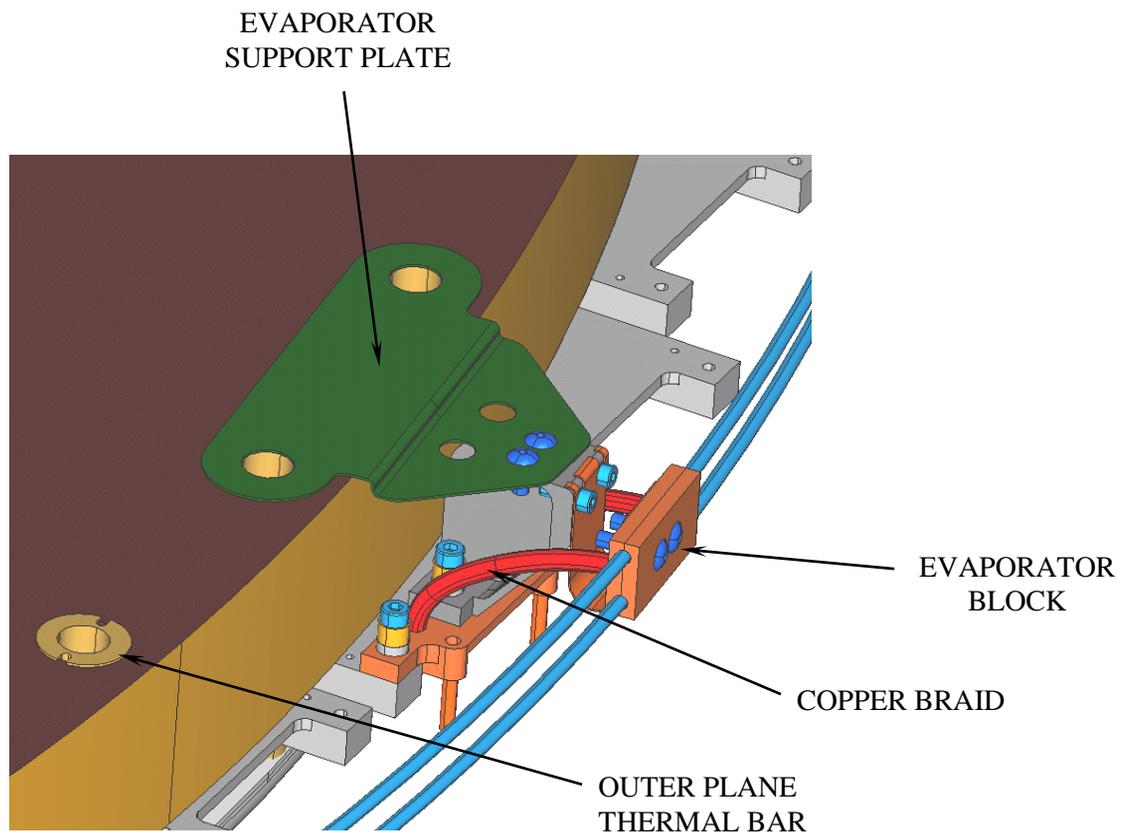


Figure 5.13.7.1-5 Connection between Outer Plane Thermal Bars and Evaporator

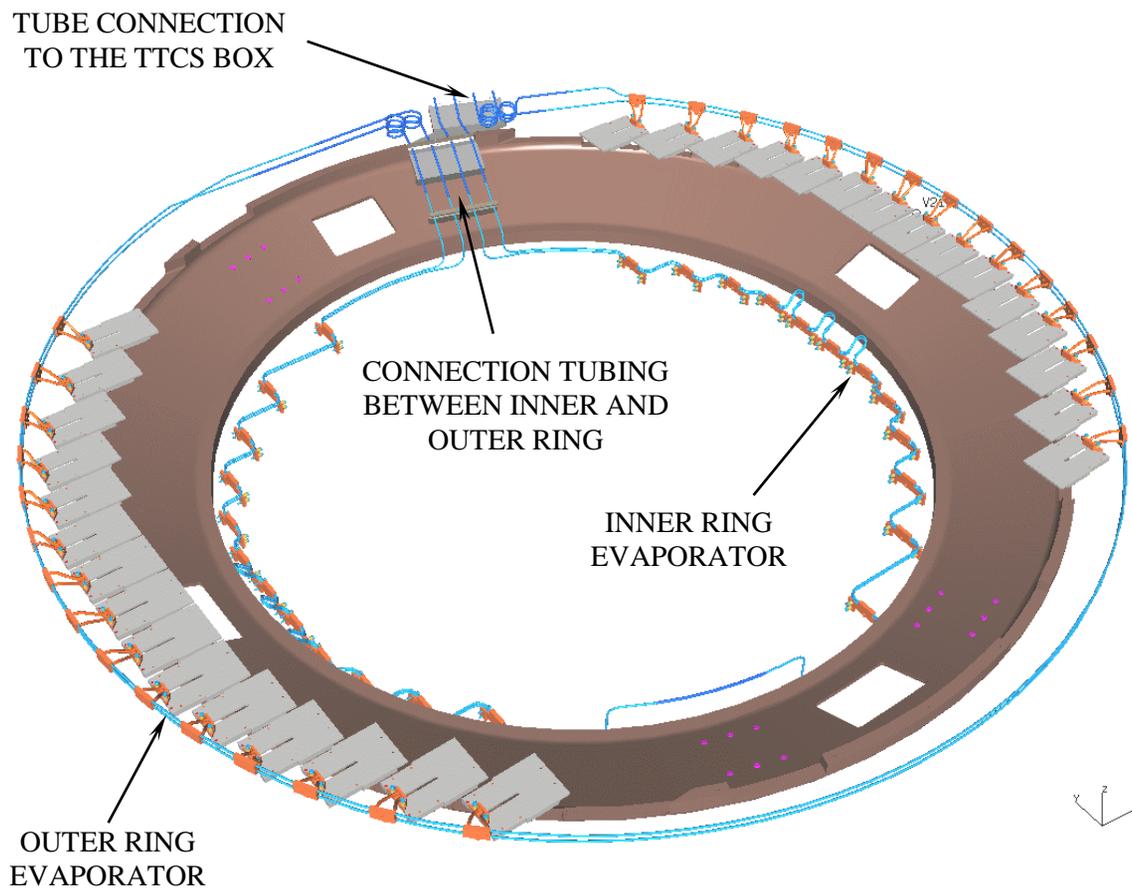


Figure 5.13.7.1-6 TTCS Evaporators

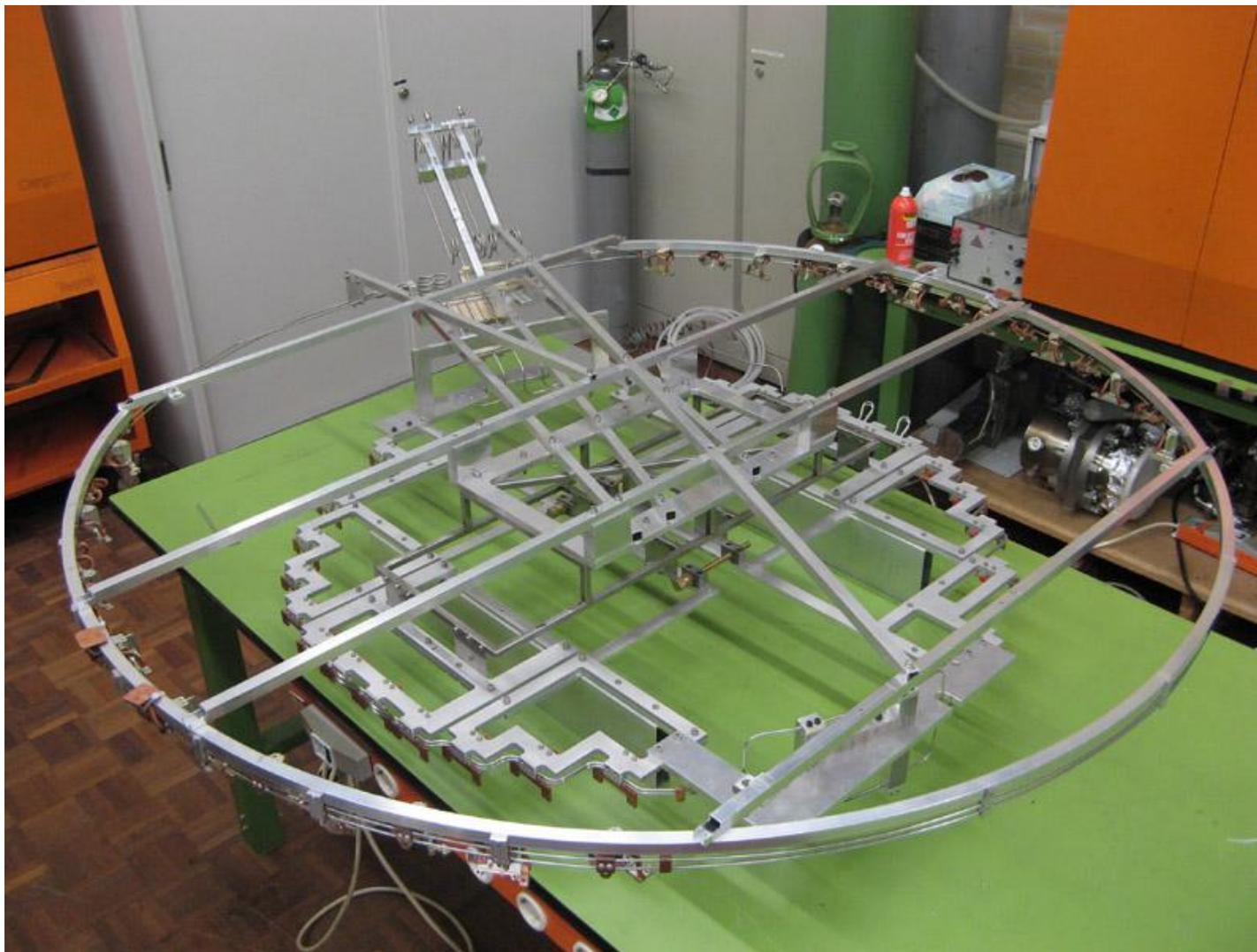


Figure 5.13.7.1-7 Photo of Upper TTCS Evaporator

5.13.7.2 TTCS CO₂ Cooling Loop

The TTCS cooling loop uses carbon dioxide to pick up heat from the evaporator rings inside the Tracker. The CO₂ transports heat to condensers connected to radiators on both ram and wake sides of AMS. Fluid is transported back to the evaporator by means of a mechanical pump. Condensers and radiators are design to assure that the CO₂ is sufficiently cooled so that only liquid will enter the pump.

Two-phase cooling is desired throughout the evaporator in order to maintain the Tracker as isothermal as possible. This is achieved by using an electric heater to pre-heat the fluid to the saturation temperature before it enters the evaporator. To minimize required heater power, a heat exchanger connects the evaporator inlet and outlet near the electric pre-heater. Figures 5.13.7.2-1 and 5.13.7.2-2 show schematics of the Primary and Secondary TTCS Cooling Loops (Figure 5.13.7.2-3 is the legend for the two preceding diagrams).

For each loop, the pump, accumulator, heat exchanger, start-up heater, pre-heater and valves are located in the Tracker Thermal Control Box (TTCB) as shown in Figure 5.13.7.2-4. The Primary TTCB is mounted on the +X +Y Lower Trunnion Bridge Beam while the Secondary is mounted to the -X +Y Lower Trunnion Bridge Beam. The boxes are thermally isolated from the beams and covered with an MLI blanket, except for the Wake facing surface which is used as a radiator. TTCS tube routing is shown in Figure 5.13.7.2-5.

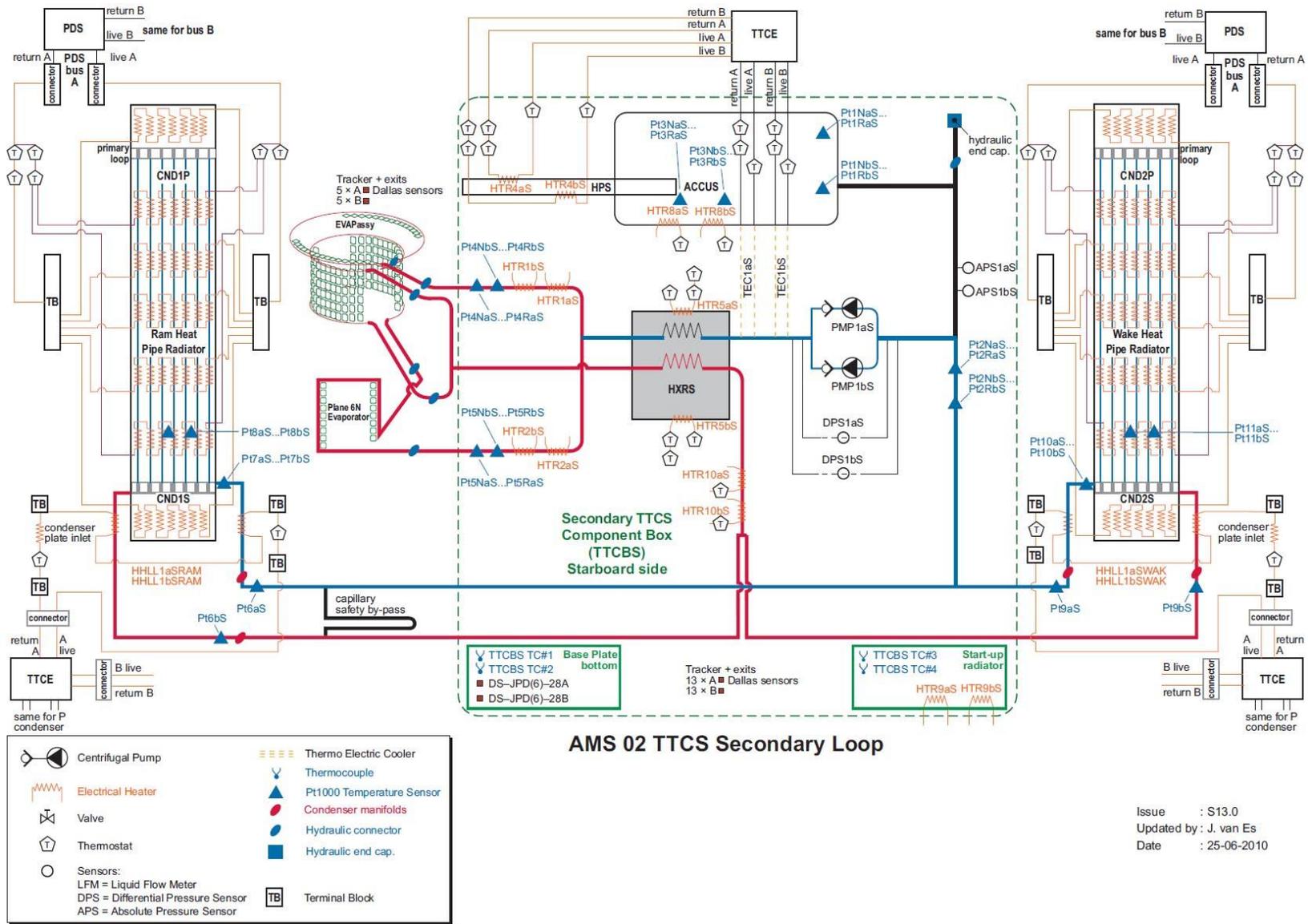


Figure 5.13.7.2-2 AMS-02 Tracker Thermal Control System Secondary Loop

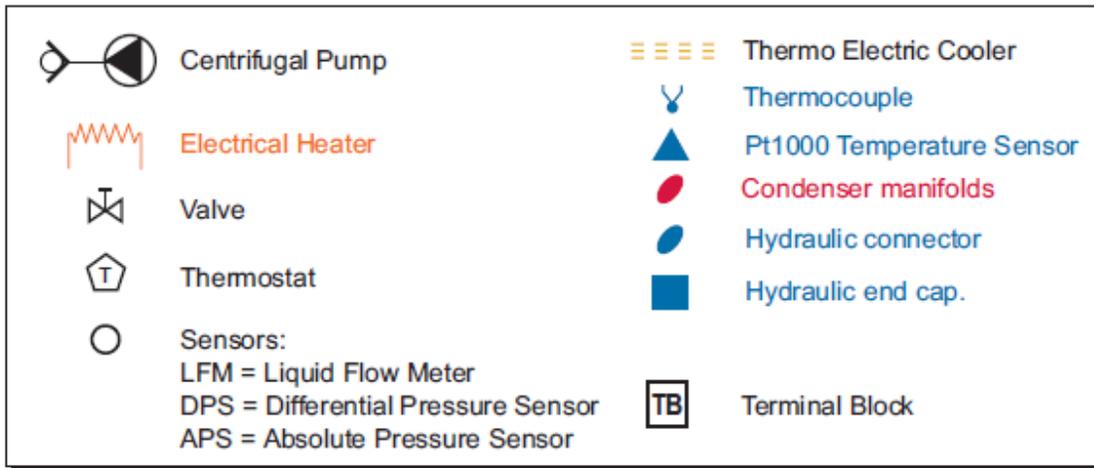


Figure 5.13.7.2-3 AMS-02 Tracker Thermal Control System Diagrams Legend

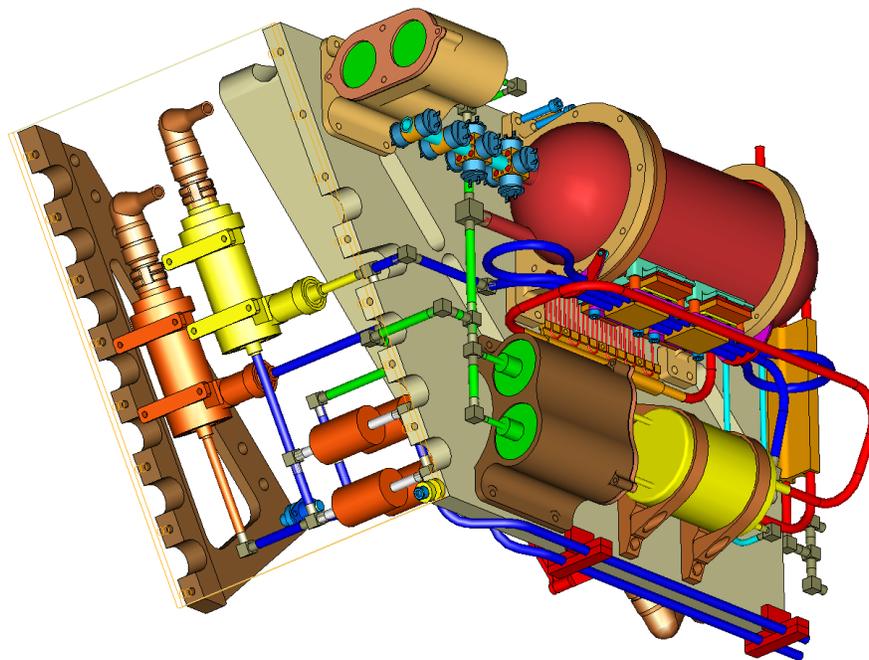


Figure 5.13.7.2-4 Primary TTCB

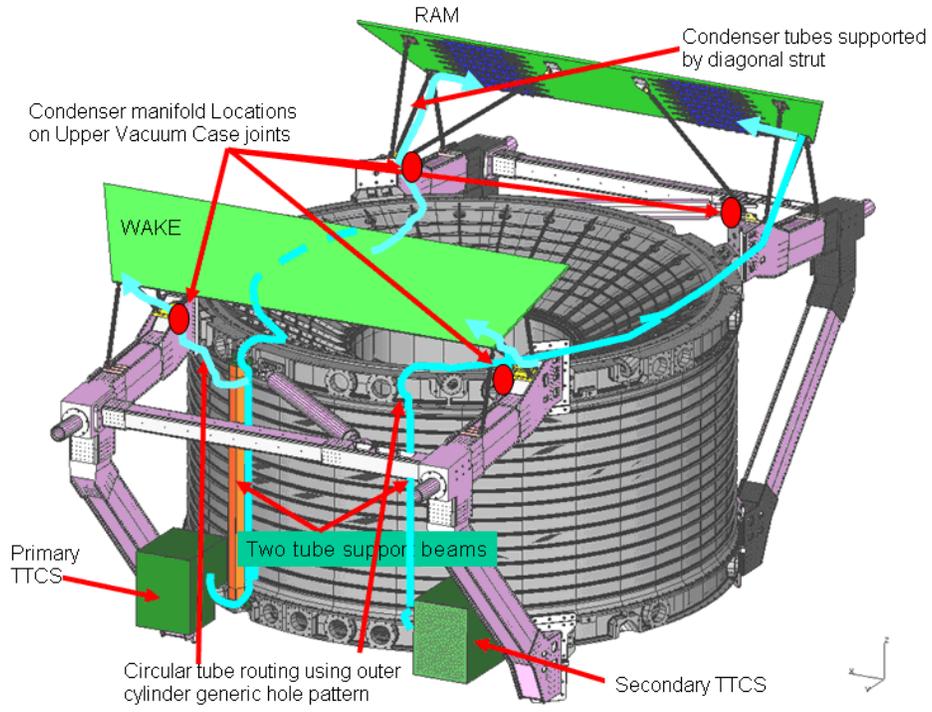


Figure 5.13.7.2-5 TTCS Condenser Connection Routing

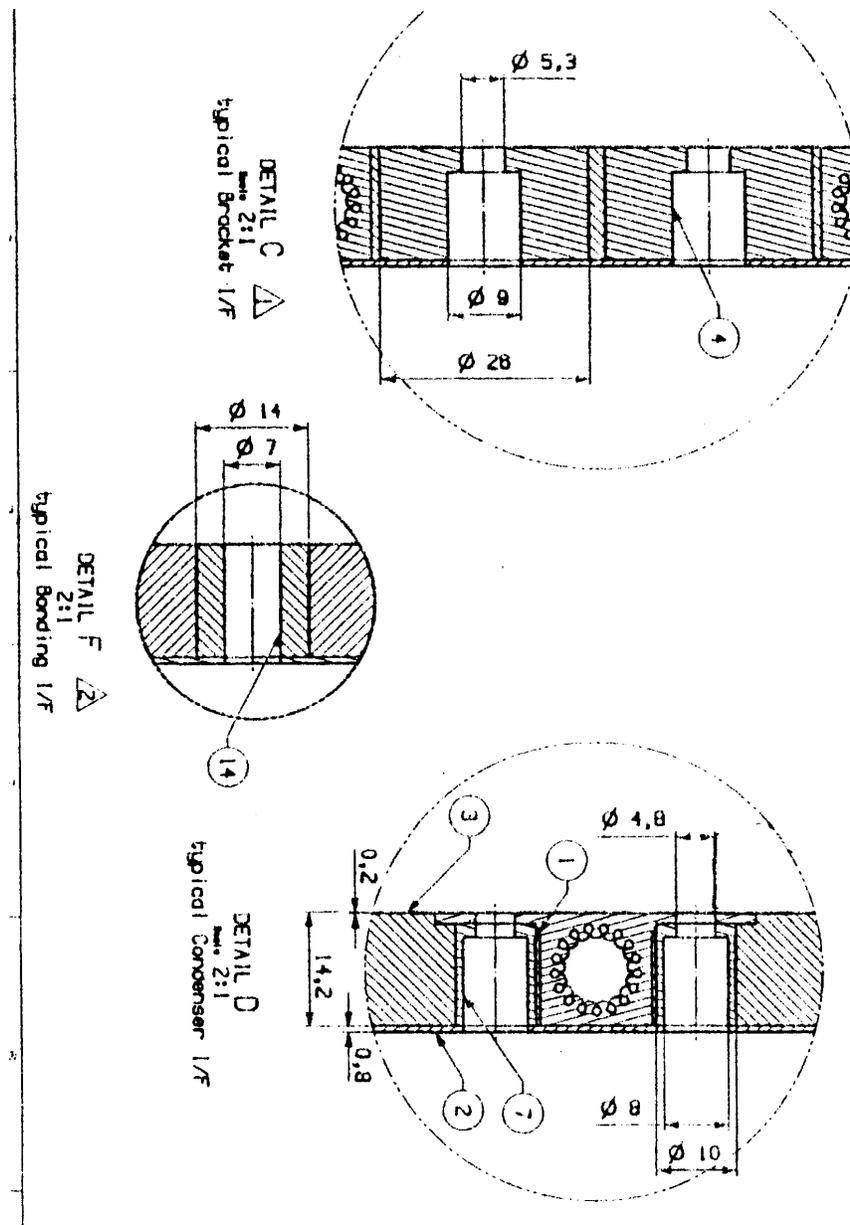


Figure 5.13.7.2.1-2 TTCS Condenser Mounting to Radiator

Each condenser is constructed with 7 parallel lines of capillary tubing made of Inconel 718, glued to an aluminum plate (Figure 5.13.7.2.1-3 through -6) and covered with another aluminum top plate. These two plates, with the embedded capillary tubing are glued together and bolted to the Tracker Radiator (At the location of the previous design represented in Figure 5.13.7.2.1-1 individual condenser locations (with seven, not eight heat pipes).

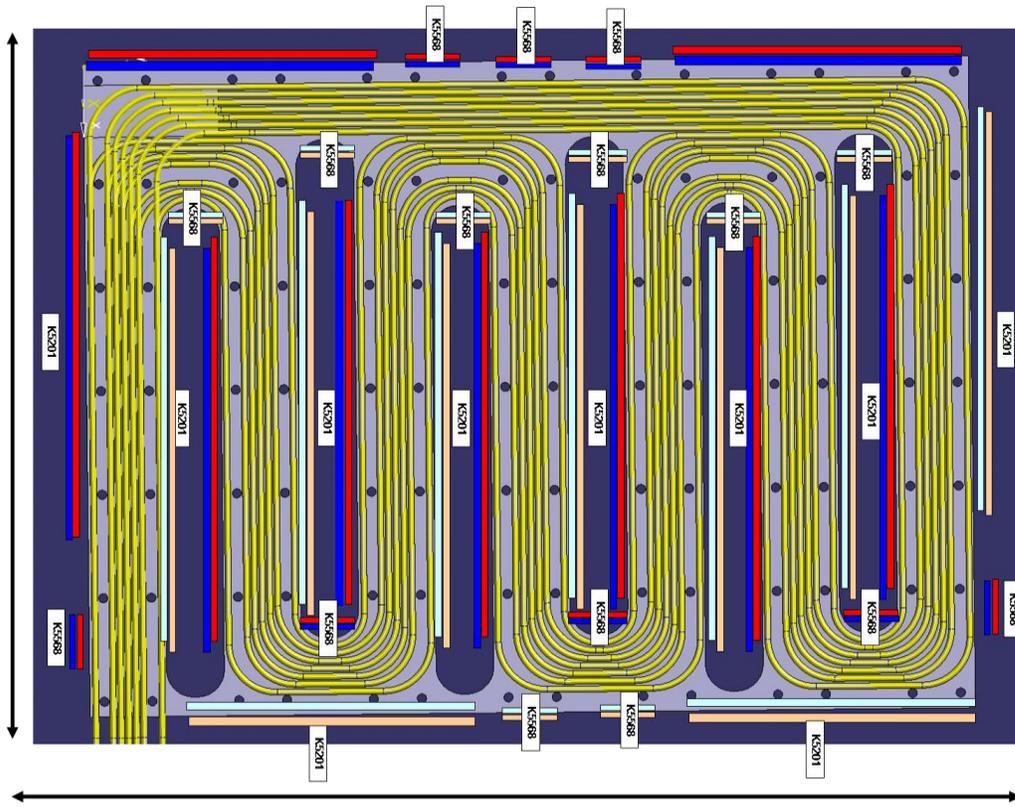


Figure 5.13.7.2.1-3 TTCS Condenser

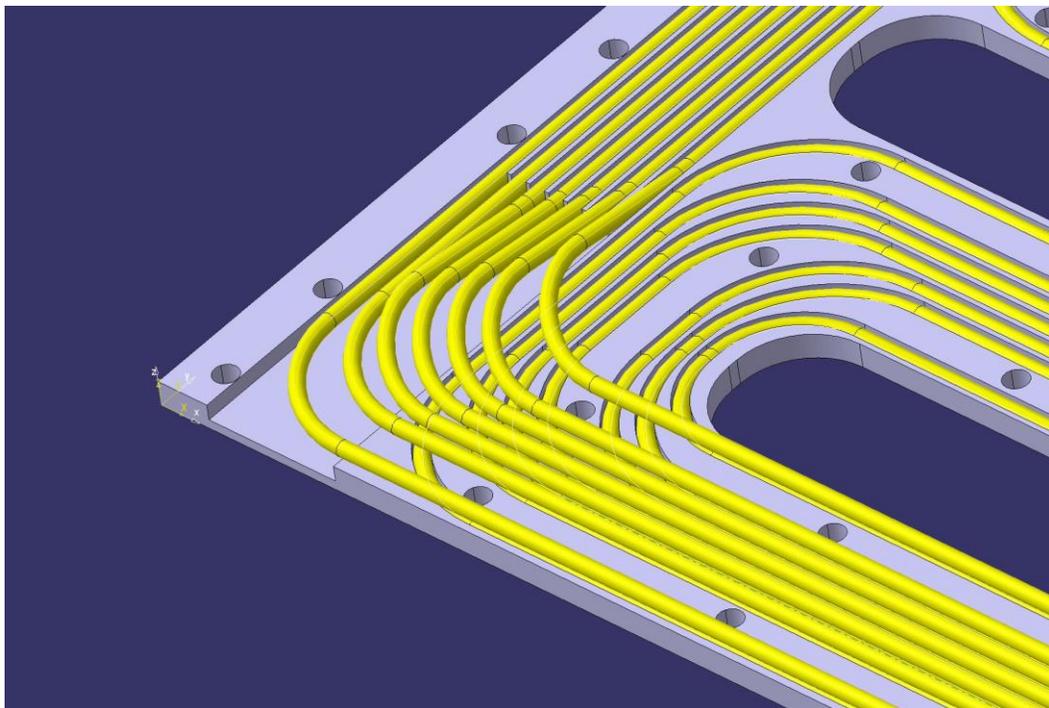


Figure 5.13.7.2.1-4 TTCS Condenser Detail

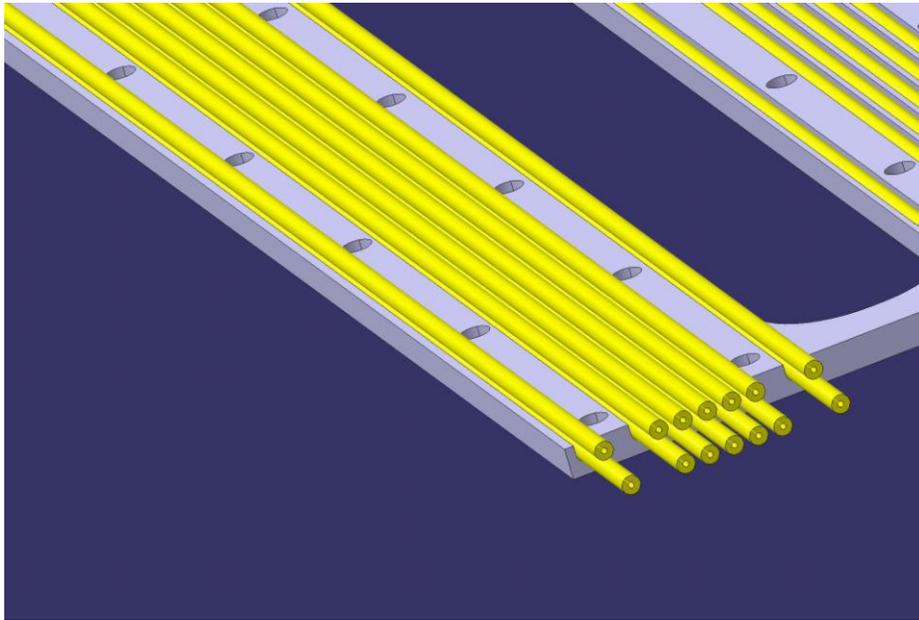


Figure 5.13.7.2.1-5 TTCS Condenser Detail

The Inconel tubing (1mm ID) runs from the condensers to manifolds mounted on the Upper Vacuum Case Interface Joints (Figure 5.13.7.2.1-7). The manifold combines the parallel flow from the 7 capillary tubes and transitions it to 2.6 mm ID stainless steel tubing (Figure 5.13.7.2.1-8). The condensers (including all capillary tubes) are designed to withstand freezing and thaw of CO₂. Heater wires are wrapped around the capillary tubes to thaw the lines in case of freezing after loss of power. All exposed tubes are covered with MLI.

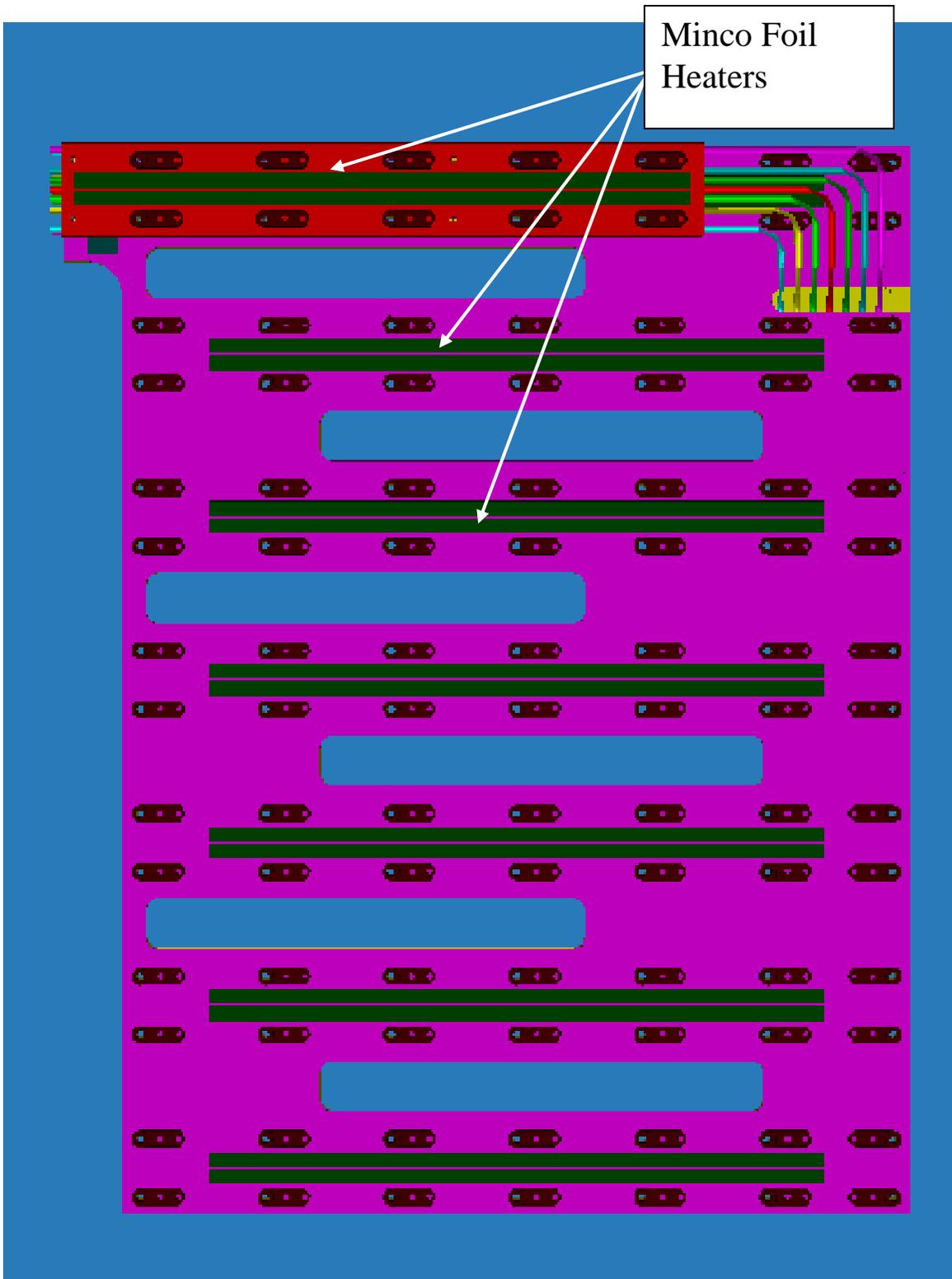


Figure 5.13.7.2.1-6 TTCS Condenser Heaters

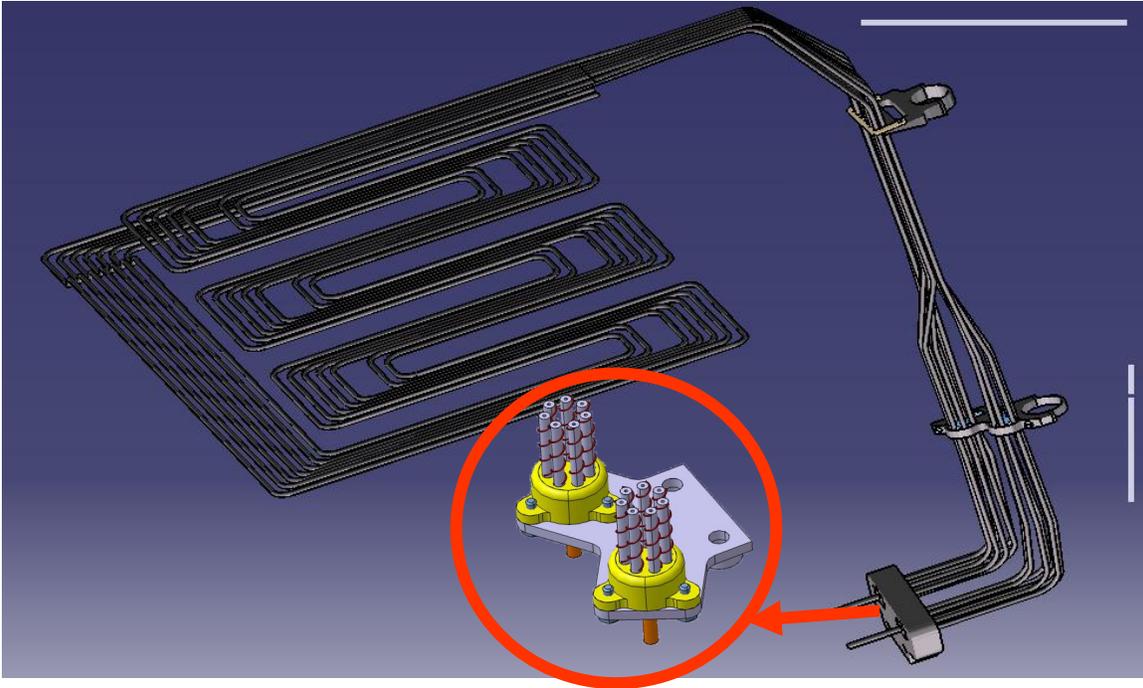


Figure 5.13.7.2.1-7 Capillary tubes from Condenser to Manifold

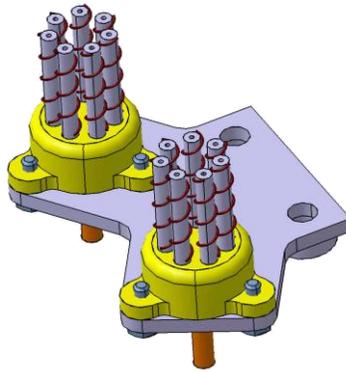


Figure 5.13.7.2.1-8 TTCS Manifolds (with heaters on tubes)

5.13.7.2.2 Pump

There are a total of 4 TTCS pumps; two for each redundant loop. The single stage centrifugal pumps are provided by Pacific Design Technologies and are similar to those successfully flown on the Mars Pathfinder mission. The rotating mass of these pumps is 0.5 inch in diameters with a maximum rotating speed of 9000 RPM. These pumps

operate in an “open” environment and are not subject to pressure differentials other than those they generate themselves.

5.13.7.2.3 Accumulator

The accumulator is a CO₂ reservoir tank used to set the evaporation temperature for Tracker cooling and account for expansion of the working fluid (Figure 5.13.7.2.3-1). There are two TTCS accumulators, one Primary and one Secondary, mounted in each of the TTCBs. The 1 liter cylindrical tanks (one for each loop) are made of 316LN CRES with an 82mm ID and 4mm wall thickness. The accumulator shell is penetrated to provide a liquid line to the TTCS CO₂ loop and by an Accumulator Heat Pipe (AHP) that traverses the interior of the accumulator along the longest axis. The heat pipe is made of 316L CRES with a 304 CRES wick and ammonia as the working fluid. Heaters are wrapped around and soldered to this heat pipe (37.5 watts x 2) are used for warming of the CO₂ within the accumulator, controlling the mix of liquid and gaseous CO₂. A series of intricate 316L CRES mesh screens are mounted inside the tanks to act as a capillary wicks to assure that the liquid CO₂ is drawn to the inner surface of the tank and to the plumbing junction to the loop (Figure 5.13.7.2.3-2 and -3). Temperature set point control of the two-phase CO₂ loop is achieved by using Peltier elements (2x Melcor CP 1.0-127—05 L2 in series) to cool the accumulators and the heat pipe with its exterior mounted heaters to heat the accumulator contents. The Peltier elements are mounted to a saddle on the tank. Each set of two Peltiers elements have a cooling power of about 20 watts, corresponding with waste heat of about 30 watts. Thermostats are mounted with copper saddles on the accumulator heat pipe and the Peltier devices to provide two-fault tolerance against heaters exceeding a thermal threshold capable of driving the TTCS loops above the established MDP (Figure 5.13.7.2.3-4). One thermostatic control device for each heater element string and Peltier element has been placed in the power return leg of the circuit. The thermostatic switches have been placed to sense as directly as possible the heat load that is generated by each of the heater/Peltier elements.

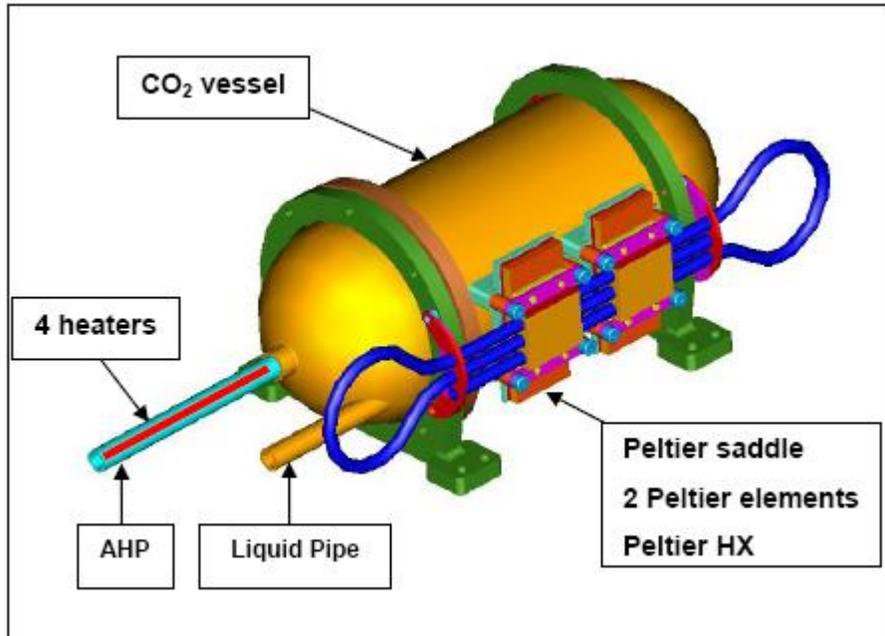


Figure 5.13.7.2.3-1 Accumulator Cross section (no wicking shown)

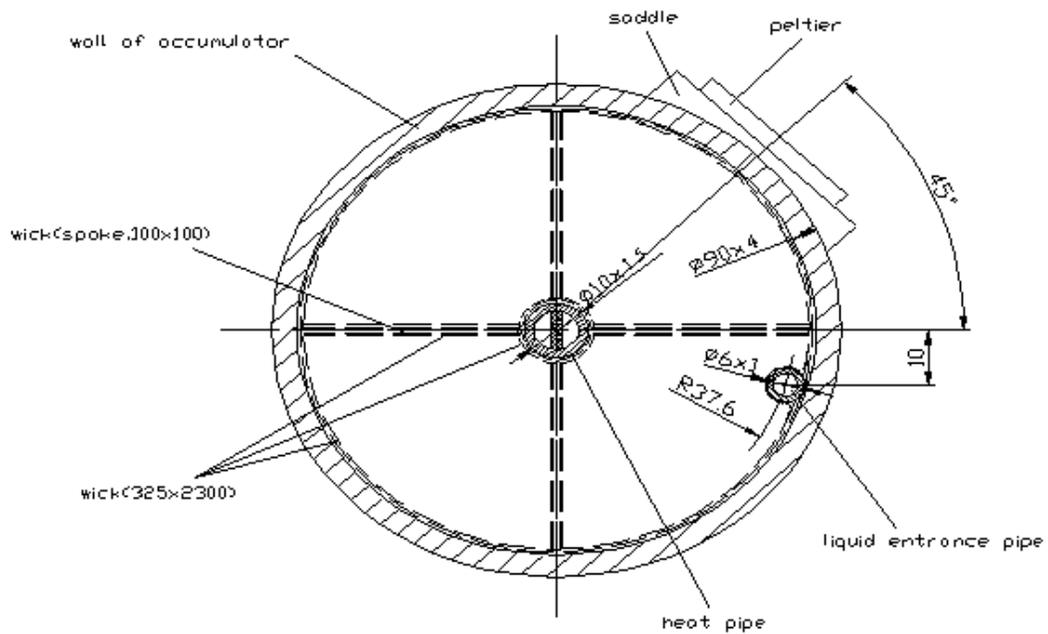


Figure 5.13.7.2.3-2 Accumulator Cross section (along heatpipe, portion of wicking shown.)



Figure 5.13.7.2.3-3 Accumulator Shell Heat Pipe And Wicking Material

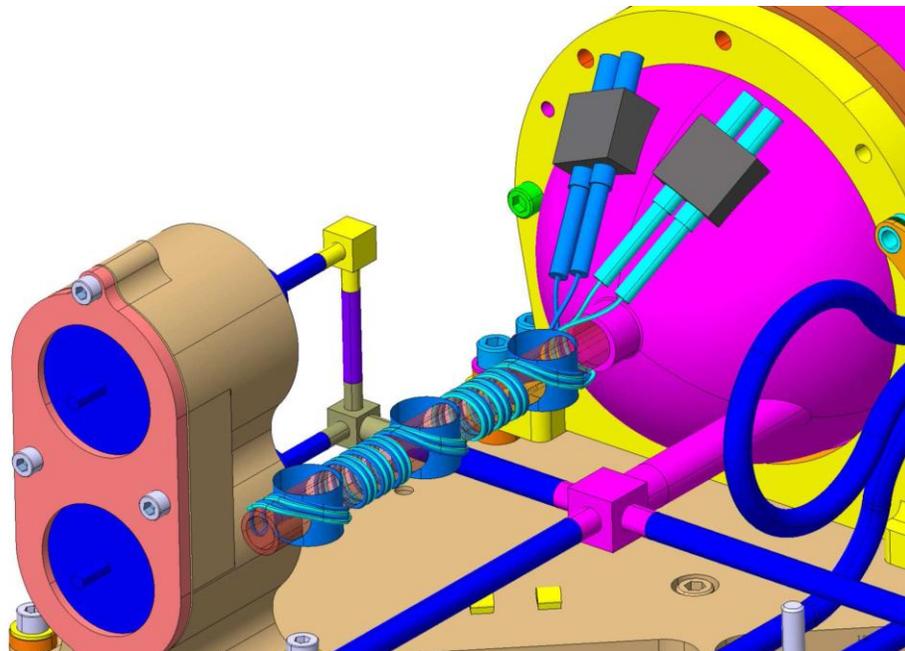


Figure 5.13.7.2.3-4 Accumulator Heat Pipe Heater and Thermostatic Control Devices

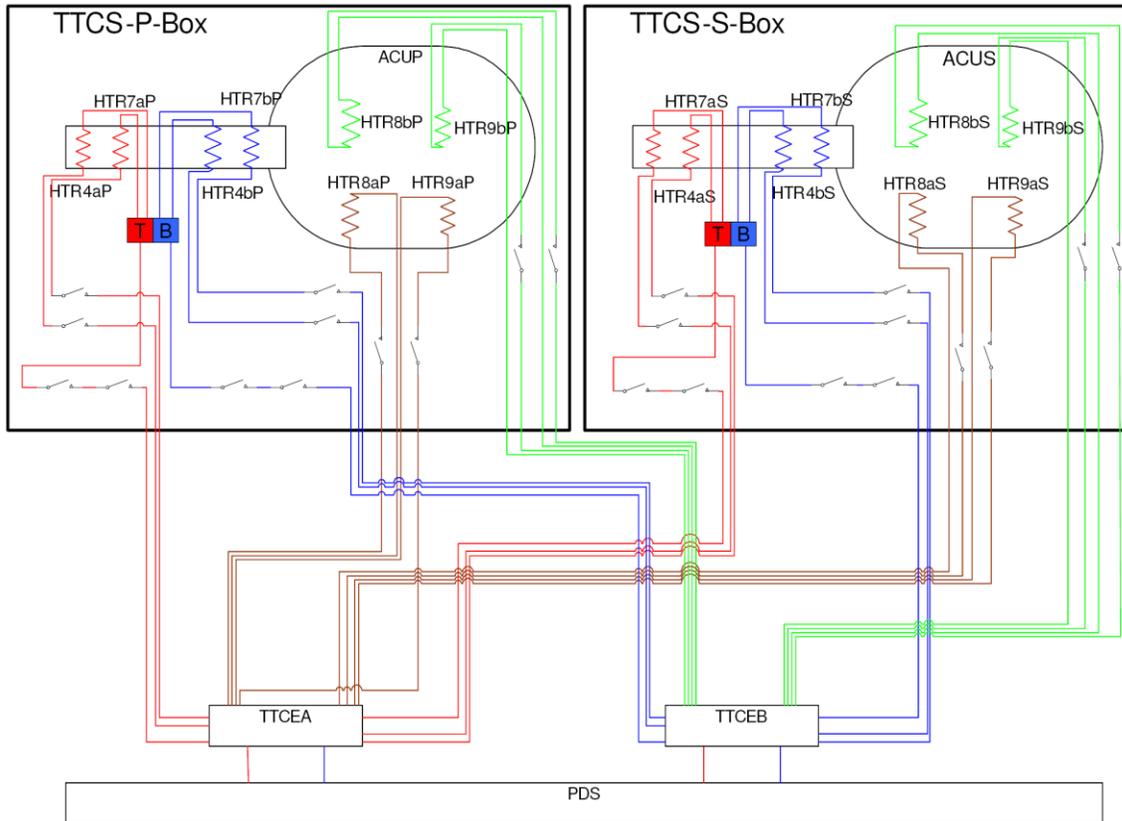
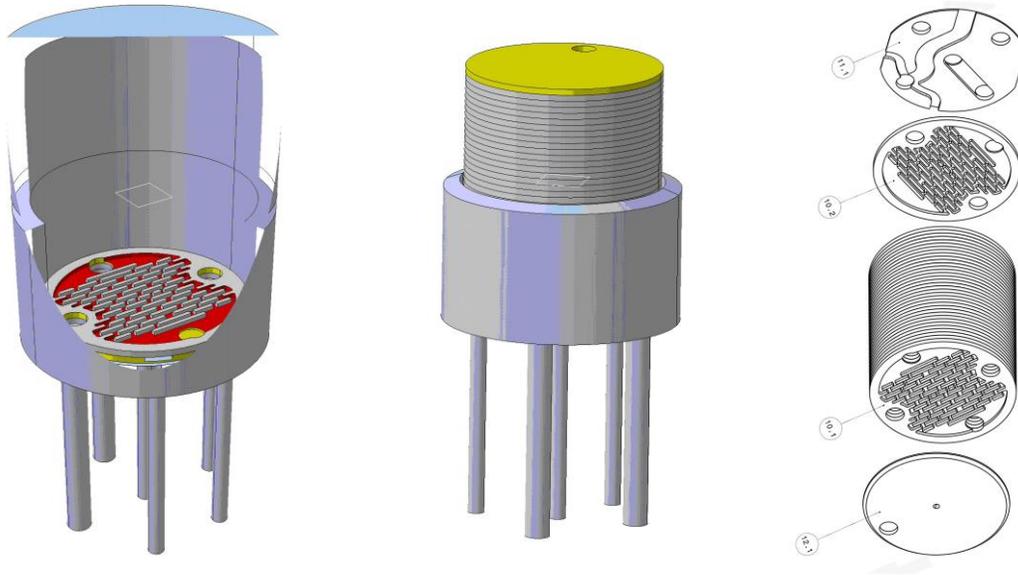


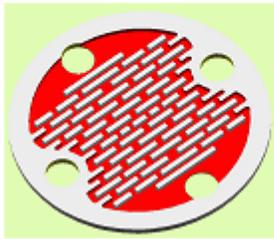
Figure 5.13.7.2.3-5 Accumulator Thermostatic Heater Control Circuitry

5.13.7.2.4 Heat Exchanger

The TTCS heat exchanger, mounted inside the TTCEB, is designed to transfer heat between the Evaporator inlet and exit. This minimizes the amount of pre-heating needed to assure that the CO₂ entering the evaporator is at the saturation temperature. The heat exchanger is a two-phase to single-phase plate type made of Inconel with 4mm wall thickness. Inside are 36 plates soldered together (Figure 5.13.7.2.4-1). Two sets of heaters (50W) are mounted on the body of the heat exchanger used for initial start-up of the TTCS, each controlled by three thermostats in series (Figure 5.13.7.2.4-2.)



36 X
18 x liquid
18 x two-phase



=

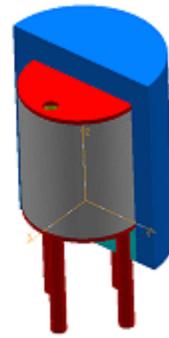


Figure 5.13.7.2.4-1 TTCS Heat Exchanger

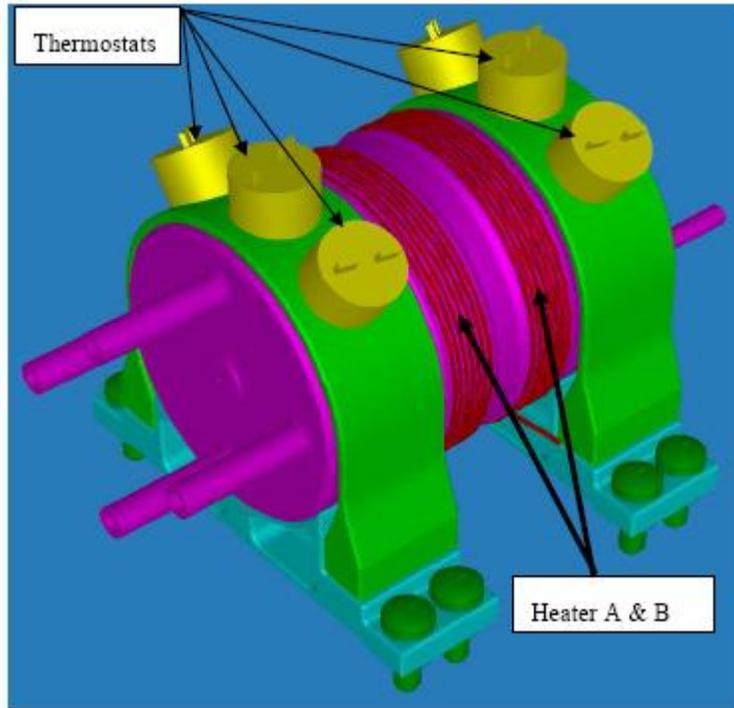


Figure 5.13.7.2.4-2 TTCS Heat Exchanger with Mounted Heaters

5.13.7.2.5 Pre-heaters

The pre-heaters are used to heat the sub-cooled liquid to the saturation point (i.e. set-point) before it enters the evaporator. Redundant, 8.9 watt heaters (Thermocoax SEA 10/150) are soldered to each of the 4 evaporator branches. Heater duty cycle will be determined by the temperature and flow rate of the liquid in each branch. The Pre-heaters are incapable of experiencing a thermal maximum condition that can drive the pressure of the TTCS above the MDP.

5.13.7.2.6 Start-up heaters

Start-up heaters, discussed in Section 5.13.7.2.4, similar to the pre-heaters are used to heat the liquid CO₂ above -20C, to avoid over cooling the Tracker electronics prior to their switch-on. Two 50 watt heaters are mounted on each TTCS heat exchanger and have the potential to drive the pressure of the TTCS system. Three thermostatic switches are included in the power circuitry to assure that excessive temperatures are not possible.

One of these thermostatic control devices has been placed in the return leg of the heater power circuitry. .

5.13.7.2.7 Cold Orbit Heaters

Cold orbit heaters are used to raise the CO₂ temperature in order to prevent freezing in the condenser during cold orbits. While the condensers are designed to survive freezing, this is not desirable for system operation. The cold orbit heaters are located in each TTCB after the exit of the heat exchanges and before the split into the Wake and Ram condenser feed lines. This is shown in Figure 5.13.7.2.7-1.

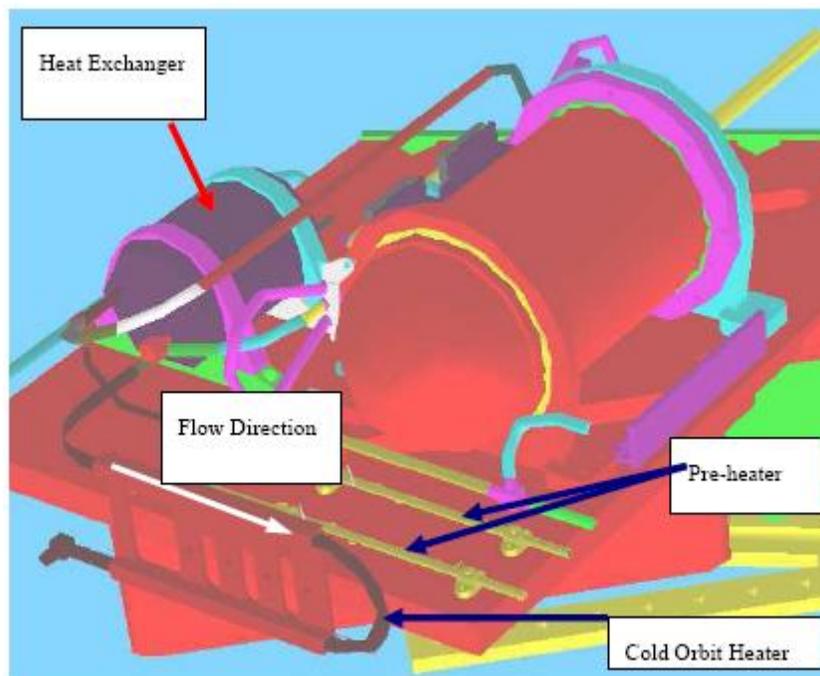


Figure 5.13.7.2.7-1 Cold Orbit Heaters on TTCB Baseplate

The cold orbit heaters include a copper structure approximately 5 x 12 cm. Wire heaters are soldered to the structure along with the liquid line from the heat exchanger. The liquid line passes two times for a total heating length of 24 cm. Each cold orbit heater provides nominal heating of 60 watts. Control is by software, these heaters are not safety critical.

5.13.7.3 CO₂ Freezing/Thawing

The TTCS is designed to reject heat generated in the Tracker as efficiently as possible. A results of this efficient design, is that when AMS experiences a loss of power the Tracker Radiators will drop in temperature rapidly. Subsequently, the TTCS condensers will also cool down to the environmental sink temperatures. In cold ISS attitudes, temperatures could drop below the freezing point of CO₂ (approximately -55°C based on fill quantity and pressure) and frozen CO₂ could accumulate in the condenser capillary tubes. By design, the condenser manifolds are mounted in a location (under MLI on the Vacuum case conical flange) which will never freeze. Line heaters (35W per condenser leg) wrapped around the capillary tubes are design to thaw the CO₂ from the manifold to the condenser after power is restored. The capillary tubes are made of extremely high strength Inconel 718 which is capable of withstanding the pressures due to uncontrolled heating of a plugged section of frozen CO₂. To measure these pressures and verify this design, testing was performed using lower strength stainless steel tubing. This test successfully measured pressures due to freezing/thawing of a plugged section (by measuring induced strain in the tubing) and showed no sign of tube failure. A more detailed description of this test can be found in the TTCS Condenser Freezing test report (NLR-Memorandum AMSTR-NLR-TN-039-Issue03, 23 August 2005).

5.13.7.4 Safety By-Pass

To avoid the possibility of entrapped volume in between the pump outlet and frozen radiators (both) without connection to the TTCS accumulator a modification has been implemented to the TTCS plumbing path. A capillary by-pass (see Figure 5.13.7.2-1) is provided to connect the potentially entrapped volume downstream the pump with the condenser return line connected to the accumulator. This capillary by-pass is located just before the RAM condenser manifold. The capillary is routed along the TTCS transport tubing on the VC Conical Flange. The capillary by-pass precludes a hazardous pressure rise of entrapped liquid. The capillary connection ($L= 3500$ mm, $D_o= 0.8$ mm, $D_i =0.4$ mm) made by a brazing connection as shown in Figure 5.13.7.4-2.

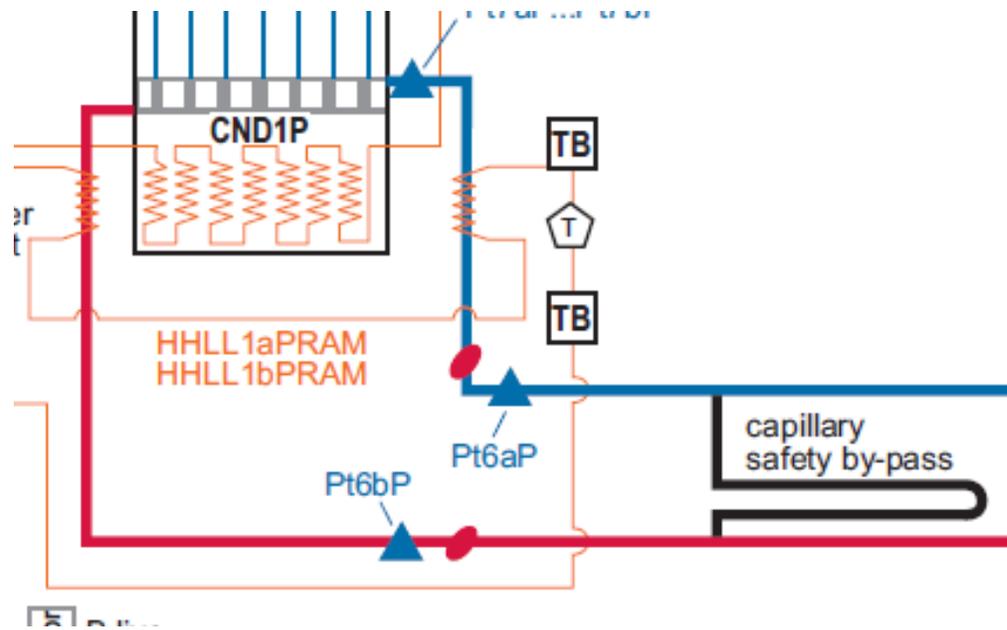


Figure 5.13.7.4-1 By-pass location near RAM condenser manifolds (red dots)

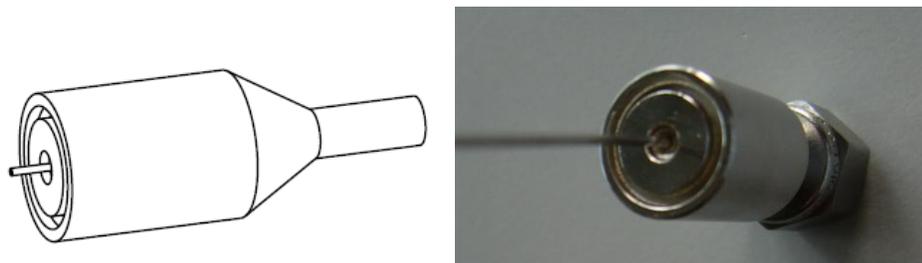


Figure 5.13.7.4-2 By-pass capillary brazed connection

5.13.8 USS Heat Pipes

Originally required for the Cryomagnet Systems thermal conditioning, the USS heat pipes have remained attached to the USS-02 with the transition to the Permanent Magnet Design. These ammonia filled heat pipes convey heat from the now removed Cryomagnet Avionics Box along the USS structural joint. Figure 5.13.8-1 shows the installation of these three pipes.

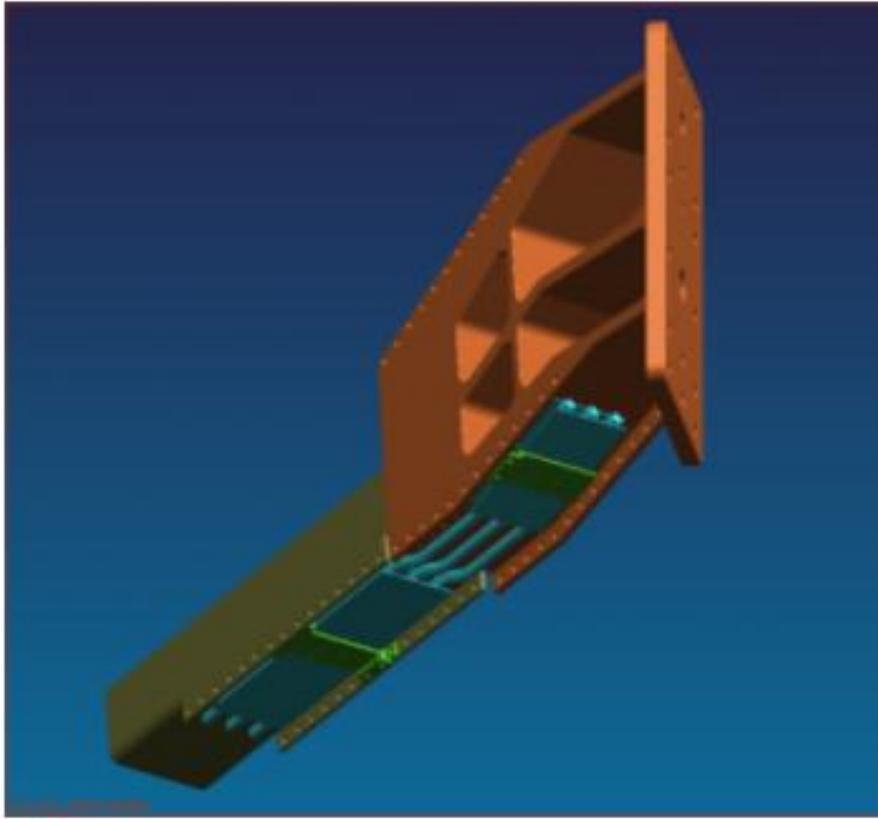


Figure 5.13.8-1 Heat Pipes on USS-02, Not Removed with Change to Permanent Magnet

5.13.9 TRD Thermal Control

The Transition Radiation Detector (TRD) has some of the most severe thermal requirements on all of AMS (Figure 5.13.9-1). In addition to component temperature limits, the entire detector needs to be isothermal within +/- 3°C. To achieve this goal the 4 main structural interfaces to the USS-02 are isolated as much as possible with titanium spacers and the Tracker Plane 1N (and its support structure 1NS) are mounted above the TRD, through the perimeter brackets to minimize heat leak. Thermal blankets are provided around the TRD and the Tracker Plane 1N/1NS. Cable and plumbing feed-throughs are also kept at a minimum and insulated to reduce heat leak. The entire detector, along with the Upper Time-of-Flight (UTOF) and the Tracker 1N/1NS layer is covered in a 10-layer MLI blanket (Figure 5.13.9-2) with a window” left open atop the 1NS structure for limited cooling of the 1N Tracker plane. Resistive heaters are glued to the M-structure (17.35 watts (4 x 3320 Ω heaters) per side x 4 sides = 69.40 watts total (using nominal 120 Vdc)) to minimize gradients and keep the entire detector within the desired temperature range.

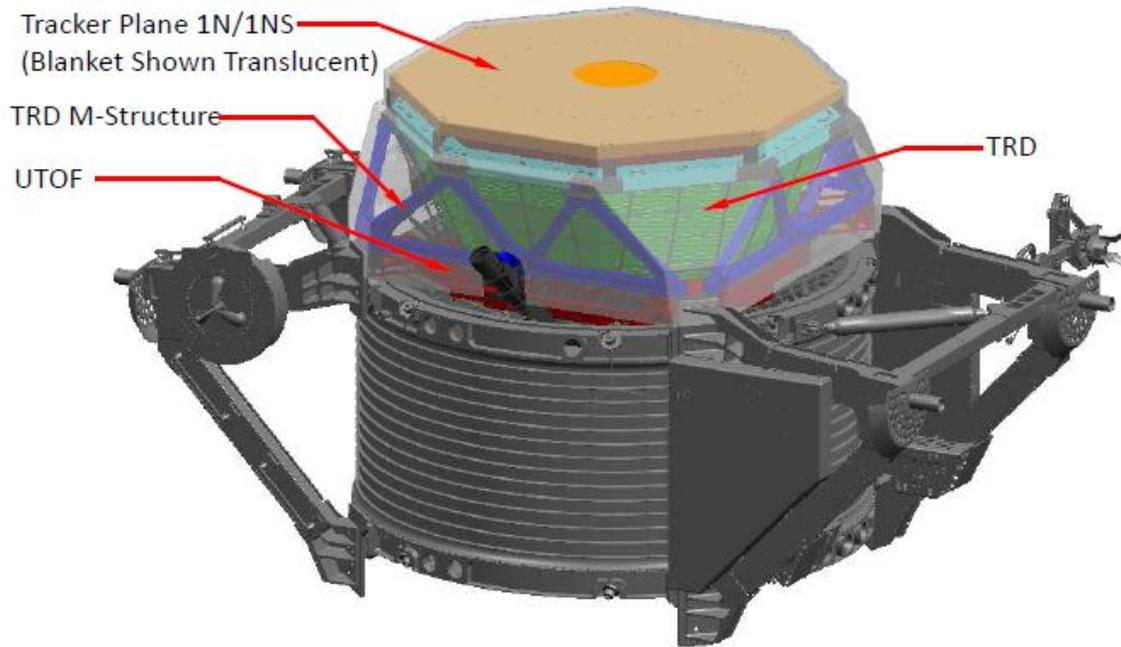


Figure 5.13.9-1 TRD on AMS-02

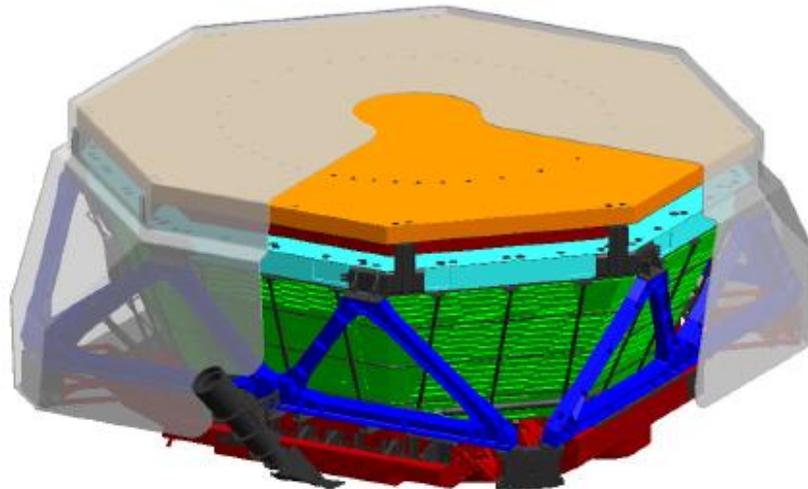


Figure 5.9.7-2 TRD MLI

Figure 5.13.9-2 TRD MLI (Tracker Plane 1N and 1NS not shown with open “window”)

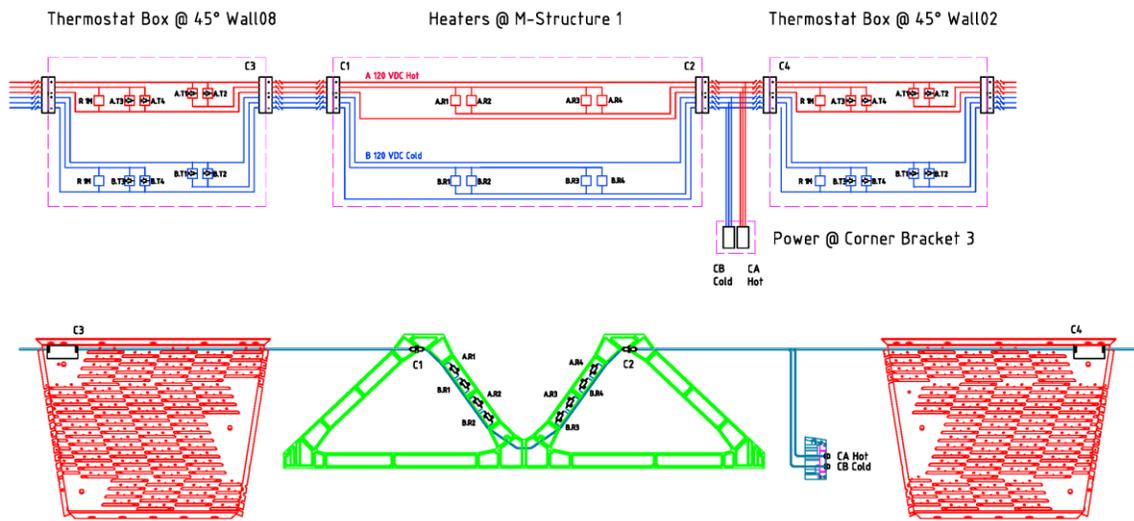


Figure 5.13.9-3 TRD M-Structure Heater Schematics

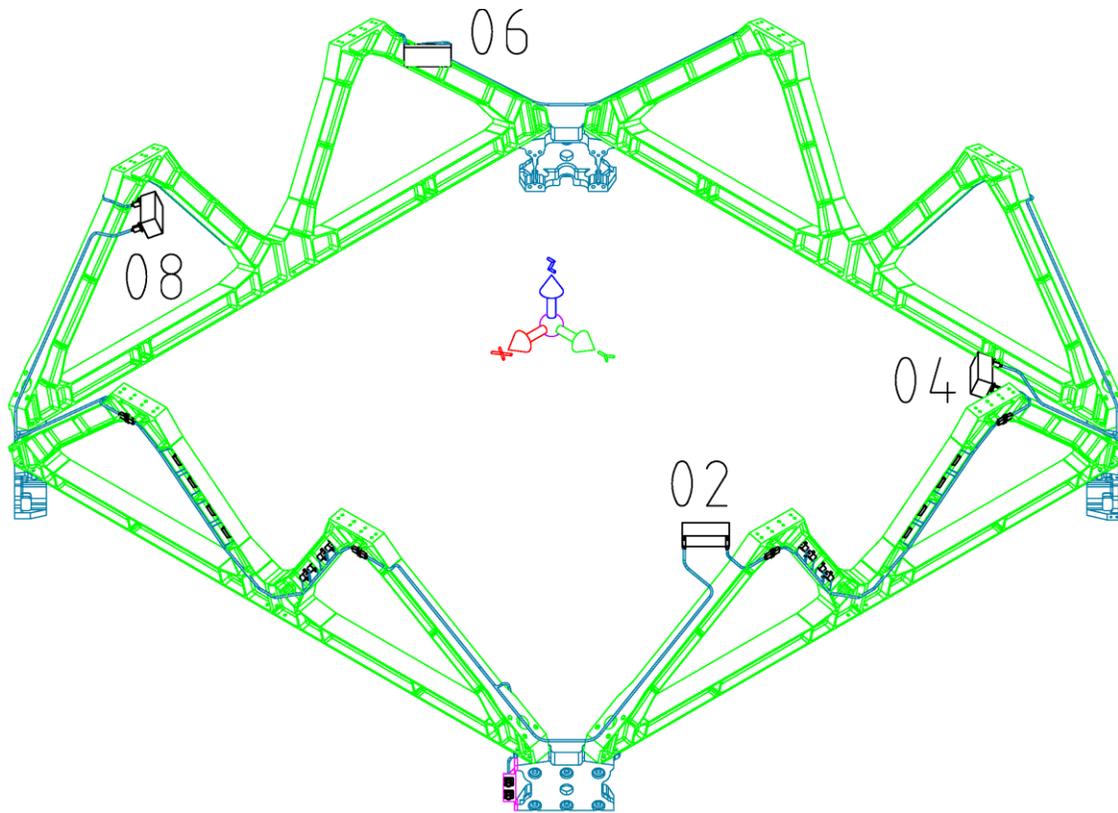


Figure 5.13.9-4 TRD M-Structure Heater Placement and Heater Cable Routing

5.13.10 TRD Gas Supply Thermal Control

The TRD Gas System (Figure 5.13.10-1) consists of two parts; the Supply (Box S) and the Control (Box C). Box S includes a high pressure Xenon tank, a high pressure CO₂ tank, a mixing tank, pre-heater volumes, sets of valves, pressure sensors and associated tubing, all mounted on an aluminum support plate. Box C includes two pumps, monitoring tubes and valves. The entire subsystem is structurally mounted to the AMS Unique Support Structure (USS-02). The thermal design of the TRD Gas System is intended to maintain components (valves, pressure sensors and pumps) above their minimum temperature limits, to heat pressure vessels above the critical point of the gasses (Xe and CO₂), and to assure that no enclosed volume will be overheated in the event of any two failures.

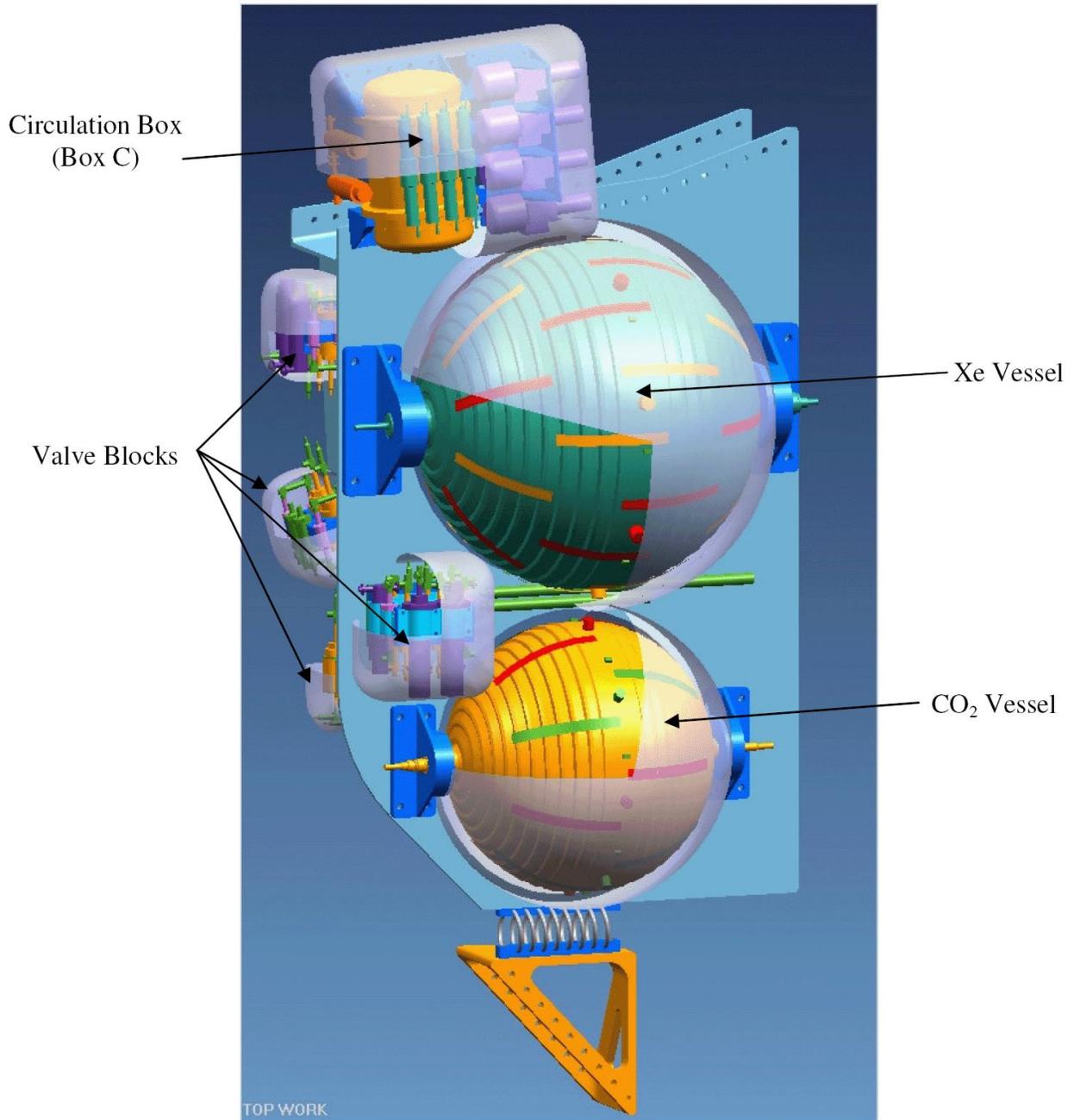


Figure 5.13.10-1 TRD Gas Supply (Box S)

Active heating is required to keep both the Xenon and CO₂ tanks above their respective saturation temperatures. This is needed in order to monitor the amount of fluid remaining in each tank by means of a pressure sensor. Due to an extremely long time constant, it is not possible to quickly warm up the fluid in the tank. The Xenon must be maintained

above 20°C and CO₂ above 34°C. Kapton foil heaters are glued to the surface of the composite over-wrapped stainless steel tanks. Two strings of eight heater patches (one for each power feed) are distributed around the tank surface (Figures 5.13.10-2). Four thermostats in series are used for each heater string to protect against overheating of the pressure vessel. There are two redundant heaters strings, one for power feed A and one for power feed B. A cloth belt provides additional support for the thermostats and thermal sensors. Engineering evaluations in thermal-vacuum were performed to quantify any temperature gradients between thermostats and heaters. Each individual tank is wrapped in multi-layer insulation (MLI) and the entire TRD Gas Supply S-box in another MLI blanket.

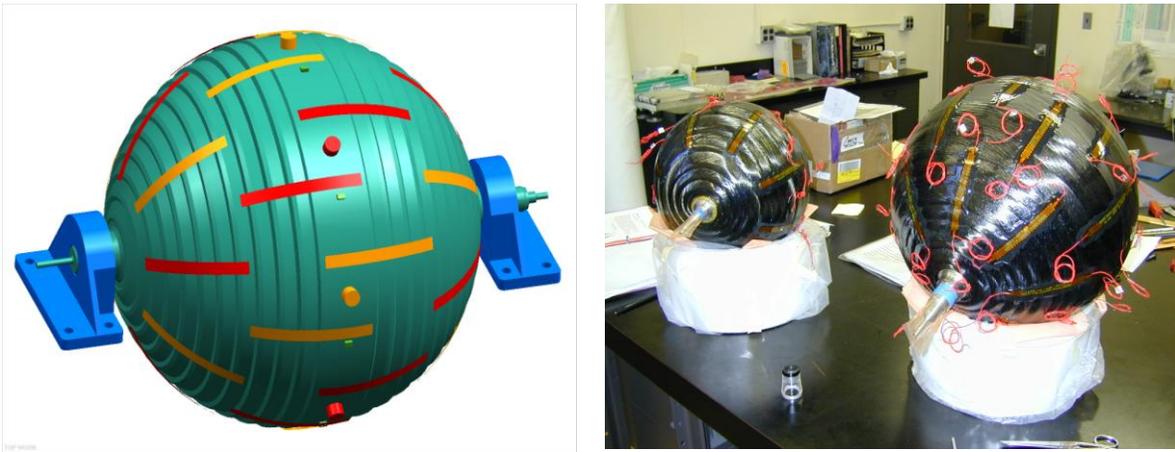


Figure 5.13.10-2 Xe and CO₂ Vessels with heaters

Box S also has 5 groups of valves mounted together with support brackets. Resistance heaters are mounted to each bracket in order to keep valves above their minimum operating temperatures limit. A single thermostat is used to control each heater. Additionally, two thermostats in series are mounted to the support plate to avoid overheating in the case of a stuck on thermostat. The brackets are bolted to the support plate using G10 spacers for insulation. Each group of valves is also enclosed within a 7-layer MLI blanket. These blankets are also made with aluminized Kapton for both the inner and outer layers.

The TRD Gas Circulation System (Box C), shown in Figure 5.13.10-3, includes pumps the low pressure gas mixture from the mixing tank into the TRD straw tubes. A pressurized canister encloses two diaphragm pumps. Heaters mounted on this can maintain the pumps above their minimum temperature limit. Resistance heaters mounted to a support bracket maintain a group of valves above their limit. Both the can and valve bracket heaters are controlled with a single thermostat. A 7-layer MLI blanket (Beta cloth on the outside) encases Box C.

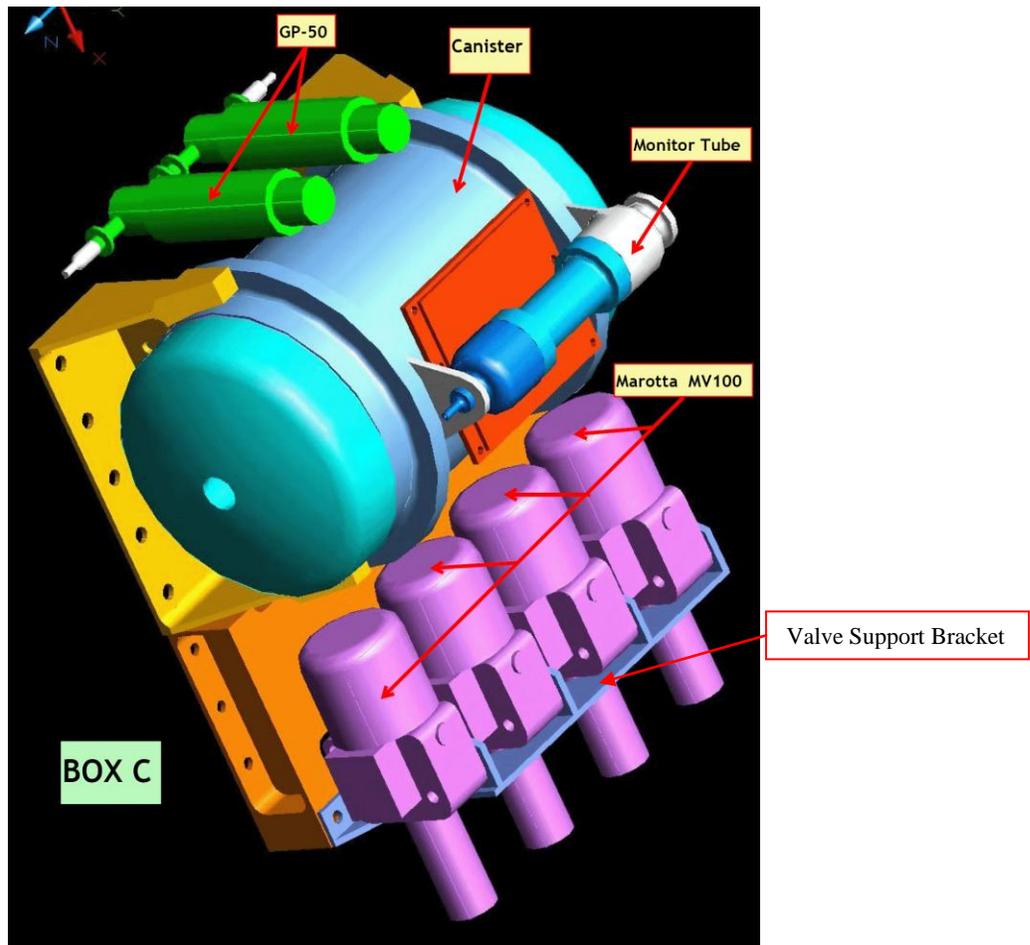


Figure 5.13.10-3 TRD Gas Circulation (Box C)

5.14 MICROMETEOROID AND ORBITAL DEBRIS (MMOD) SHIELDING

The MMOD shielding will be designed, analyzed, built and integrated by NASA/ESCG. The shielding is designed to protect the TRD pressure systems on the AMS-02 experiment according to the environments specified in SSP 30425, paragraph 8.0. These tanks include the V TRD Gas System Xe tank and CO₂ tank. The location of these components on AMS-02 is shown in figure 5.14-1.

The AMS-02 Micro Meteoroid Orbital Debris (MMOD) Shield analysis was performed using the Fortran program BUMPER-II on the original Cryomagnet configuration of the AMS-02 which included the Superfluid Helium tank and Warm Helium Gas supply. BUMPER-II was used to determine the MMOD risk assessments for AMS-02 pressure systems to a Probability of No Penetration (PNP) of .997 percent required for safety. The NASA Hypervelocity Impact Technology Facility has testing to ensure that the correct ballistic limit equations are used in the Bumper II analysis. The shields were designed to meet the ISS and STS requirements.

AMS-02 Provides two multi walled Stuffed Whipple Shield designs protecting the TRD Gas Supply (Xenon, CO₂, and Mixing Tank) and a custom fit TRD Gas internal aluminum foam debris shield.

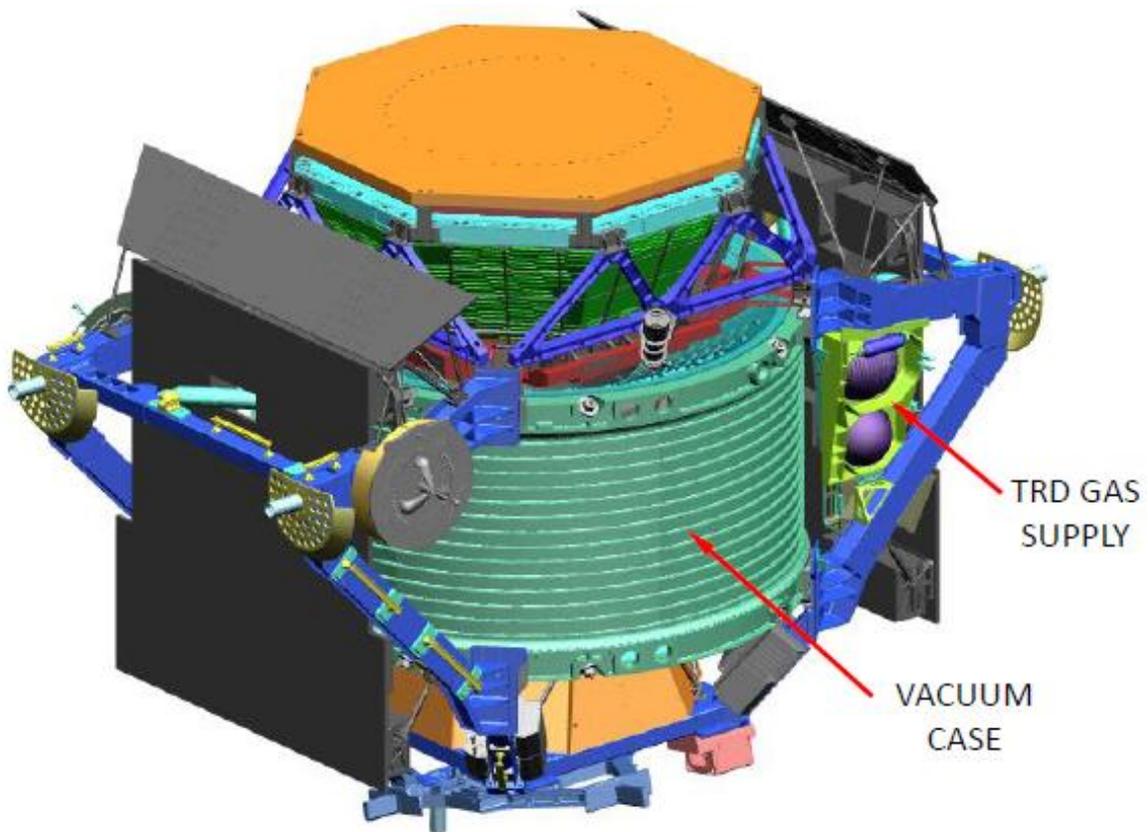


Figure 5.14-1 AMS-02 Payload Assembly

5.14.1 TRD Gas Port and Starboard Debris Shields

AMS-02 provides two debris shields on the Port and Starboard side of the payload primarily for the purpose of protecting the TRD Gas System from MMOD impacts. This MMOD shielding consisting of a 0.1 inch outer and inner aluminum sheet with a Kevlar/Nextel ballistic blanket between the two aluminum surfaces. Standoffs are used at precise distances to separate the outer aluminum sheet from the inner aluminum sheet and the ballistic blanket between the two. The shield assemblies are bolted to the Upper and Lower Trunnion Bridge Beams of the USS-02 are shown in figure 5.14-2 and 5.14-3, 5.14-4, and 5.14-5.

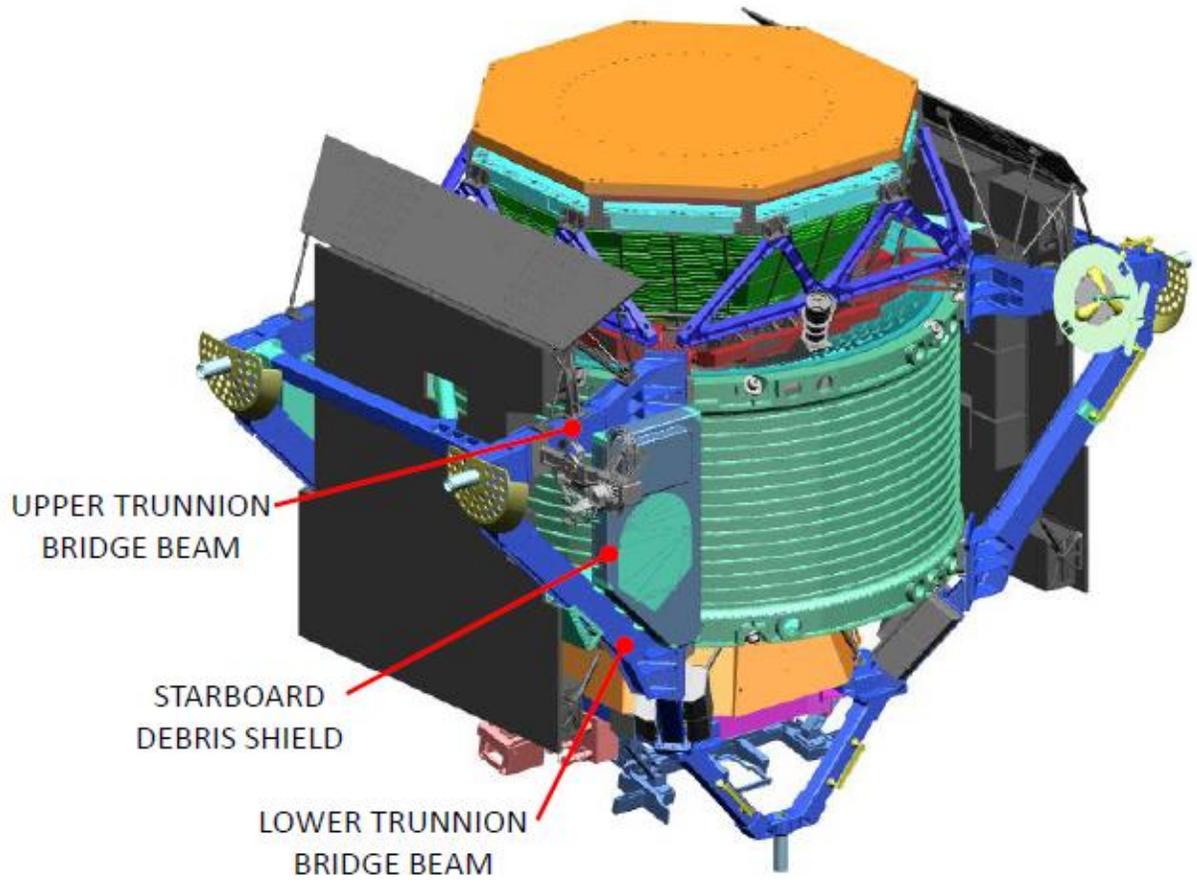


Figure 5.14-2 Starboard Debris Shield

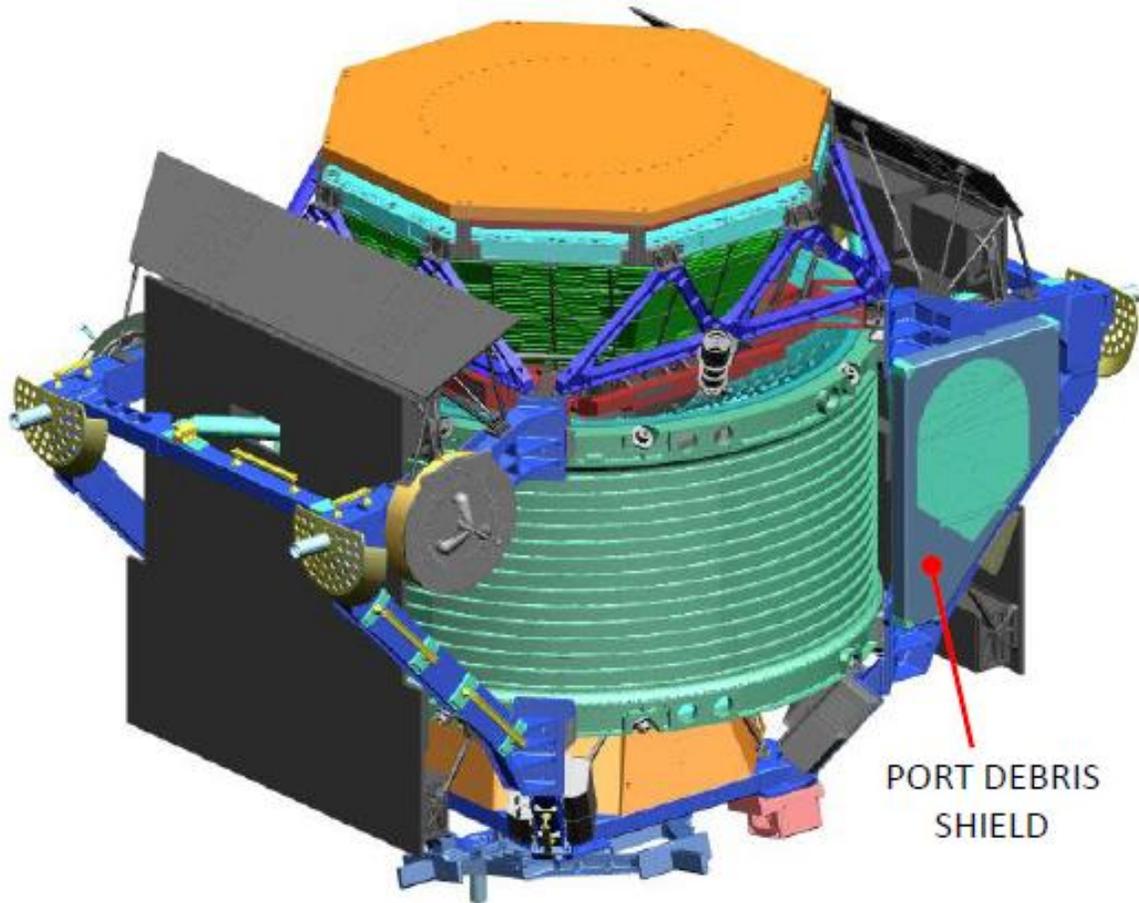


Figure 5.14-3 (TRD-Gas Supply) Port Debris Shield

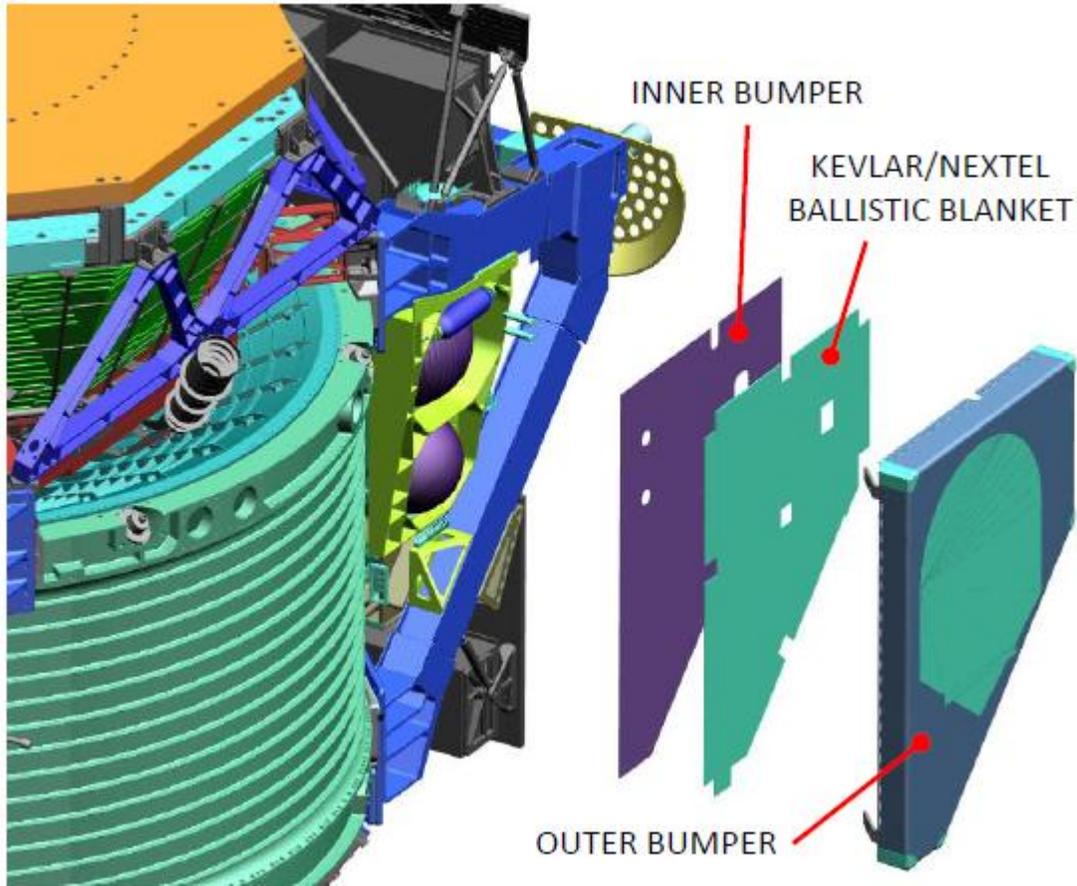


Figure 5.14-4 (TRD-Gas Supply) Port Debris Shield

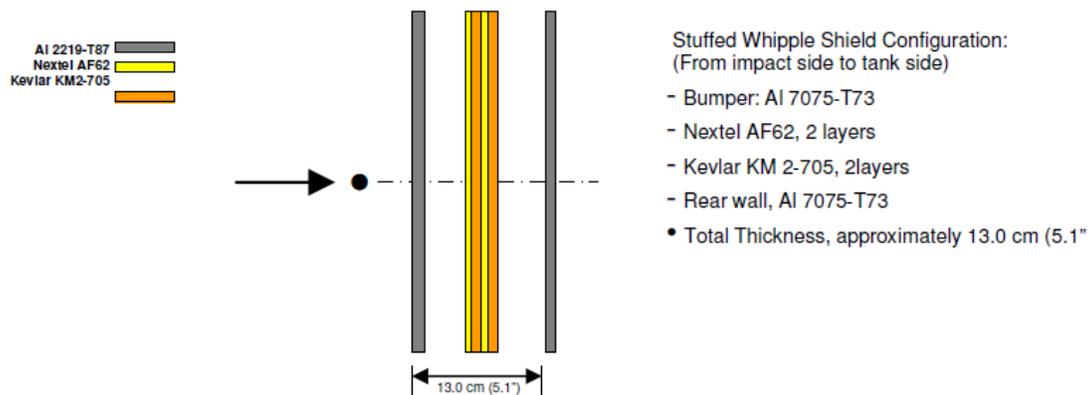


Figure 5.14-5 Port and Starboard Debris Shield Arrangement

5.14.2 TRD Gas Internal Starboard Debris Shield.

AMS-02 also provides an internal TRD Gas Debris shield to protect the Composite Overwrap Pressure Vessels (COPV) from MMOD impacts. See Figure 5.14-6 for the COPV arrangement. This shield is composed of a 0.040 inch thick outer skin, a 0.040 inch inner skin, and a 0.5 inch nominal thickness of aluminum foam. See Figure 5.14-7 and 5.14-8.

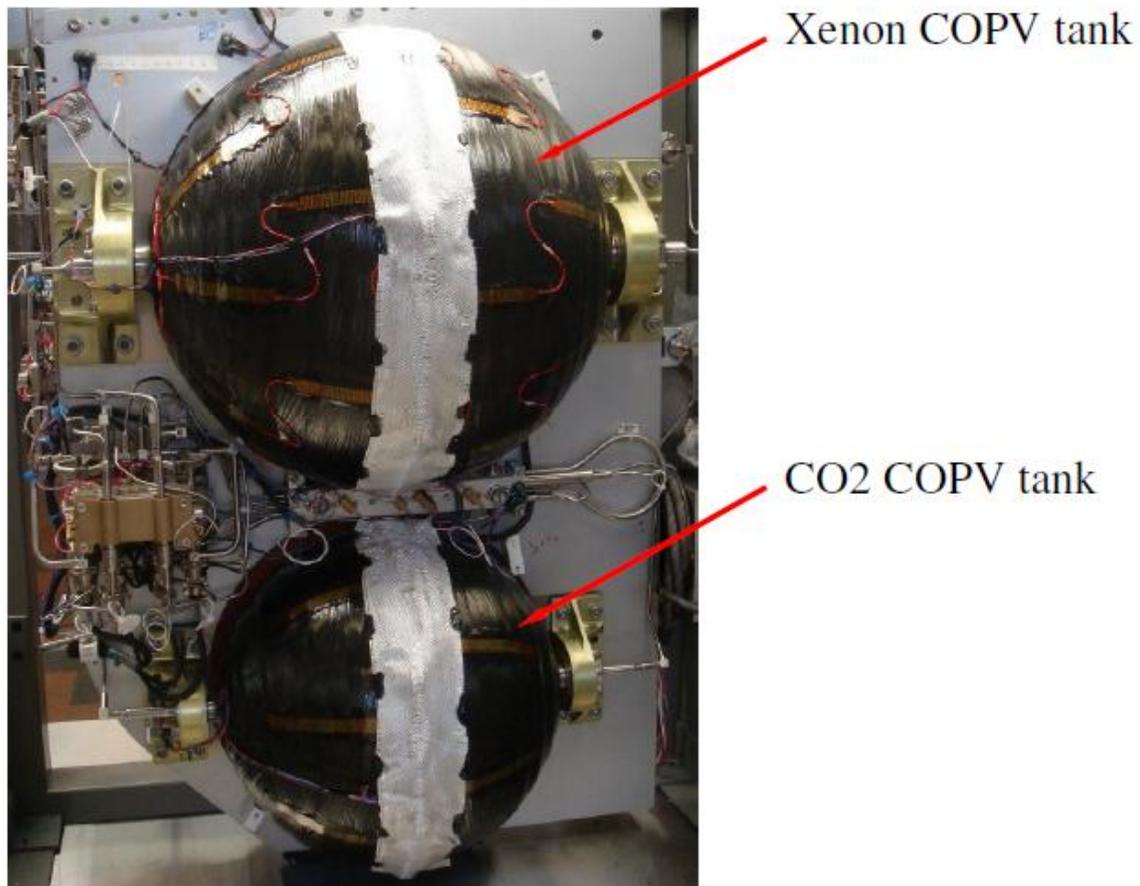


Figure 5.14-6 (TRD-Gas Supply) COPV Arrangement

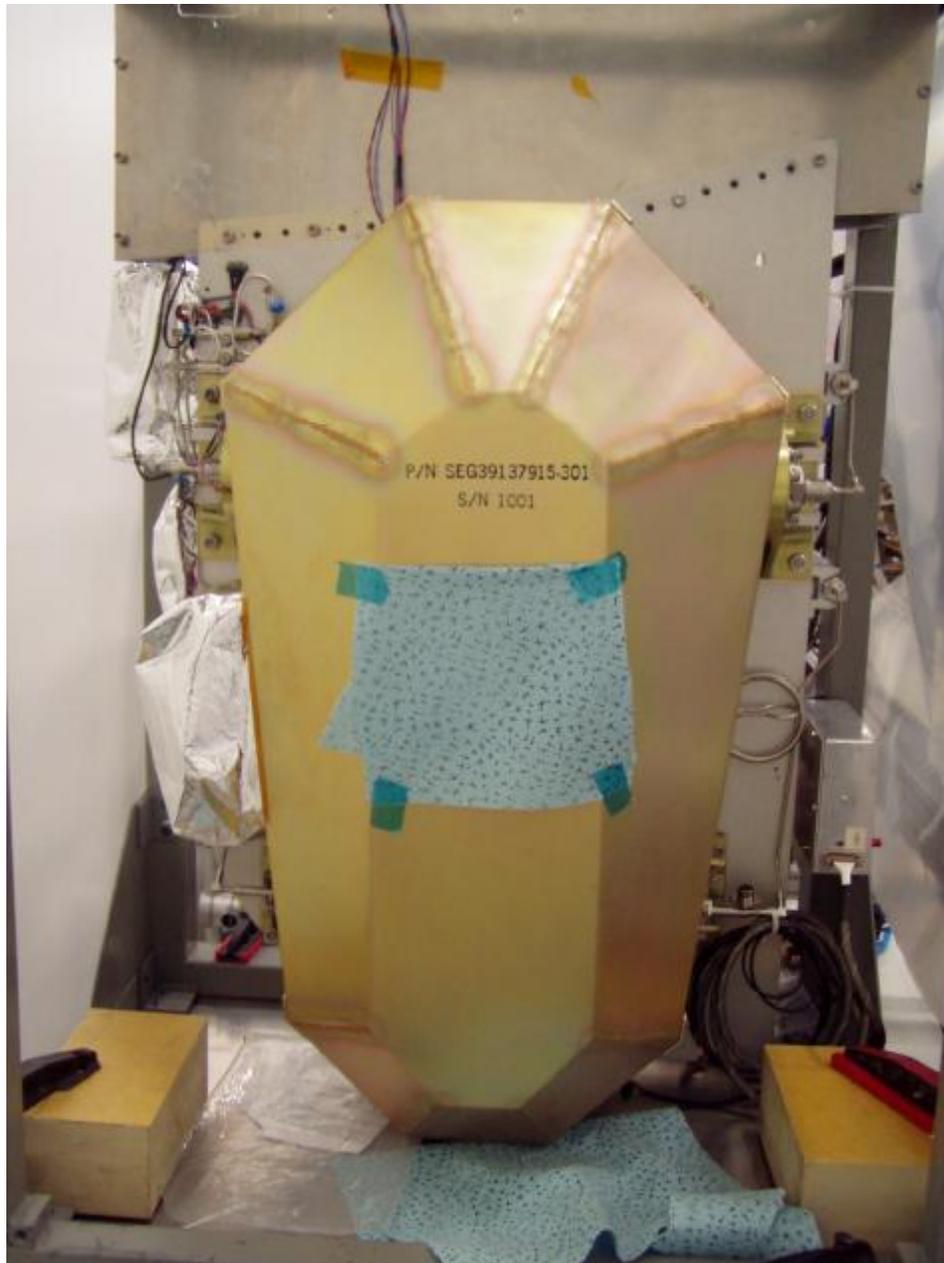


Figure 5.14-7 (TRD-Gas Supply) COPV Debris Shield

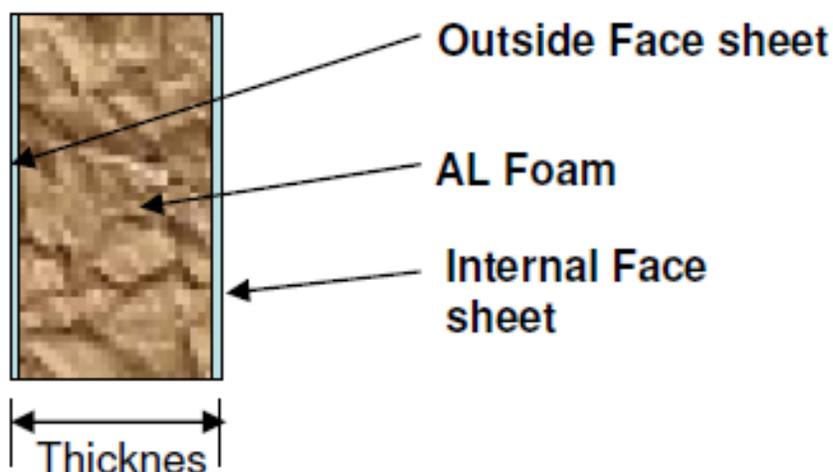


Figure 5.14-8 Aluminum Foam Debris Shield

5.14.3 MMOD Probability Of No Penetration Analysis

The PNP of this configuration has been assessed against the MMOD environment defined in SSP 30425 using the BUMPER code developed by JSC. AMS-02 is in its installed position on the ISS and the station orbit is assumed to be 400 km constant altitude at a 51.6° inclination. The station attitude is an estimate of the Torque Equilibrium Attitude (TEA) at assembly complete: a yaw of -2.99 degrees, a pitch of -3.58 degrees, and a roll of 0.33 degrees. The PNP calculations was performed on the original Cryomagnet configuration of the AMS-02, including the Superfluid Helium Tank, a vacuum within the VC and the Warm Helium Gas Supply, for each of the pressure systems listed above are given in the table below.

Pressure Vessel	Probability of No Penetration (PNP)			Critical Particle Diameter
	Meteoroid	Debris	Combined	
Vacuum Case	0.9998	0.9979	0.9977	3.97mm
Warm Helium Tank	1.0000	0.9999	0.9999	1.48mm
Xenon Tank	1.0000	1.0000	1.0000	7.5mm (Whipple) 1.37mm (Foam)
CO2 Tank	1.0000	0.9998	0.9998	
Mixing Tank	1.0000	1.0000	1.0000	

Total	0.9998	0.9976	0.9974	
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Extracting just the TRD systems that will be flying on the AMS-02 Permanent Magnet Design

Pressure Vessel	Probability of No Penetration (PNP)			Critical Particle Diameter
	Meteoroid	Debris	Combined	
Xenon Tank	1.0000	1.0000	1.0000	7.5mm (Whipple)
CO2 Tank	1.0000	0.9998	0.9998	
Mixing Tank	1.0000	1.0000	1.0000	1.37mm (Foam)
Total	1.0000	0.9998	0.9998	

As the table shows, the debris shields on the AMS-02 provide a PNP for the critical areas which more than meets the requirements of KX-06-001. The AMS-02 payload therefore does not present a risk to the ISS.

5.15 GLOBAL POSITIONING SYSTEM (GPS)

The AMS-02 utilizes an ALCATEL TOPSTAR 3000D which will be integrated into AMS by IN2P3-Montpellier. A single patch type antenna (Sextant Avionique model 3407-79) will be mounted on the Tracker Plane 1N structure (1NS) (Figure 5.15-1) on a short bracket (approximately 15 mm high). A signal from the GPS unit will be used for precision time correlation that exceeds the capabilities of the ISS to provide. The need for the GPS is to correct time drift over time within the precision timing systems that trigger the particle events.

Interface electronics within the M-Crate receive the precise time at which the timing pulse from the GPS unit was emitted and this is included, along with the value of the local timer, in the event data. To reach the required accuracy, software has been developed to include all the corrections required for low earth orbit GPS applications. The GPS operates off of the AMS-02 internal 28 VDC power bus.

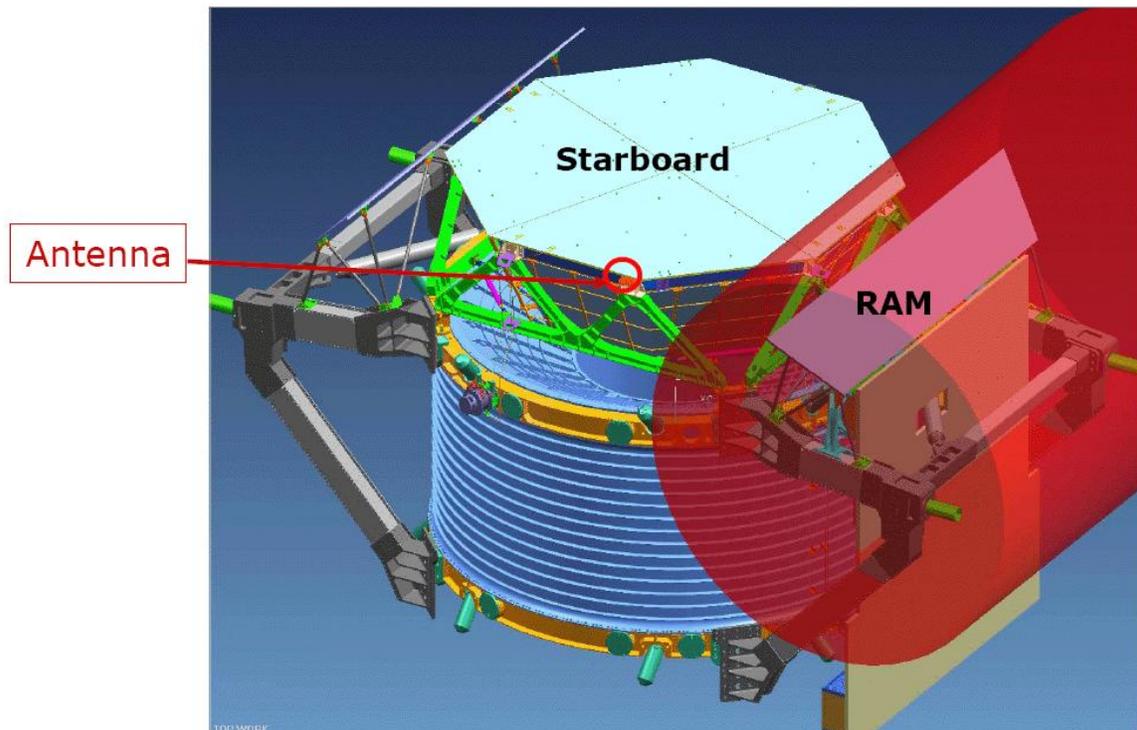


Figure 5.15-1 Location of AMS-02 GPS Antenna

6. AMS FLIGHT OPERATIONS SCENARIO

6.1 PRELAUNCH OPERATIONS

The AMS-02 requires power and data/command capability prior to launch. By utilizing AMS-02 supplied Ground Support Equipment, AMS-02 personnel monitor the 1553 Bus data for telemetry and system operating characteristics.

GSE power via the T0 umbilical is independent of Orbiter power systems and located in MLP Room 10A. T0 operations include 120 Vdc power routed to the Power Distribution System (PDS). Following installation, ~400 W is required for payload monitoring functions. Payload monitoring capability is supplied via the 1553 Bus and the high-rate data system (RS-422 protocol) routed from Shuttle Payload Data Interface Panel (PDIP1) assembly through the T0 umbilical interface to Ground Support Equipment (GSE).

As shown in Figure 6.1-1 below, low rate data (1553) is routed through T0 umbilical from Shuttle PDIP2 with the “AMS-02 1553” switch in the “T0” position, and program provided jumper installed on PDIP2 front panel “J4” connector. High rate data (RS422) is routed through T0 umbilical from Shuttle PDIP1 via payload provided cable installed between PDIP1 front panel “J103” and “J105” connectors.

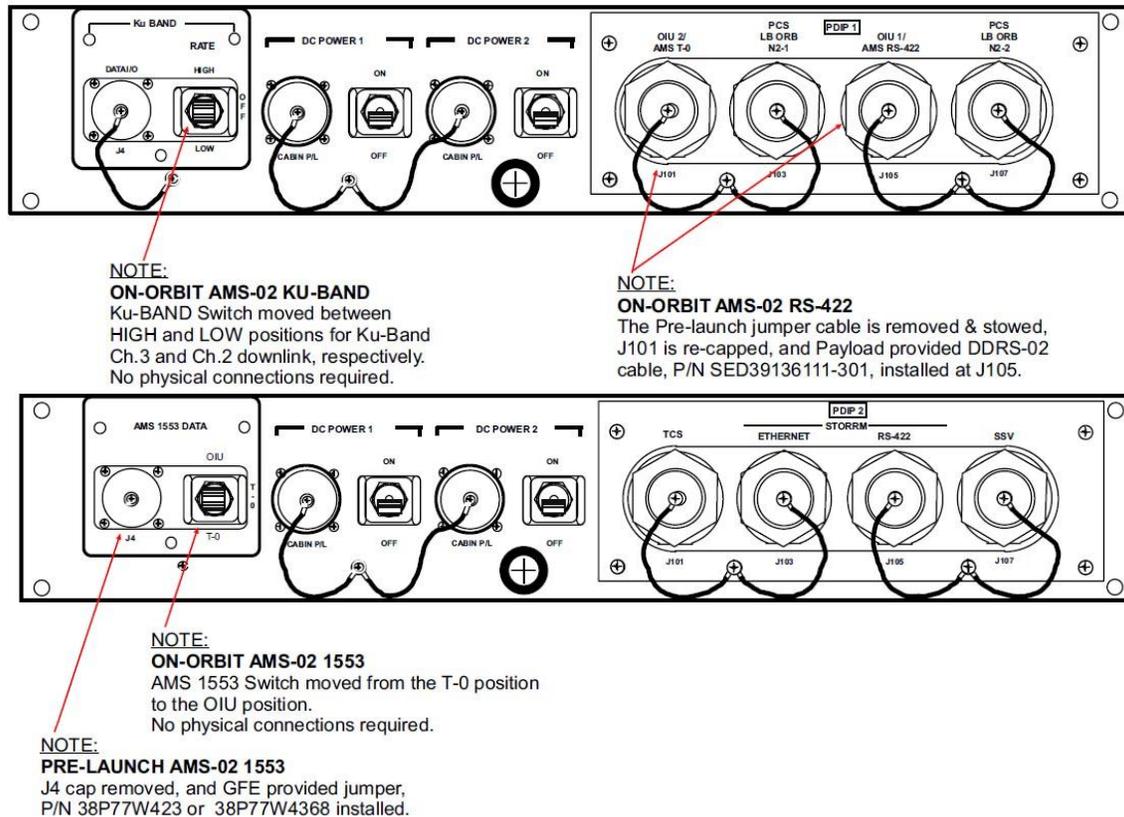


Figure 6.1.1 Payload Data Interface Panel #1 and #2 Layout

For brief periods prior to L-24H, a maximum of 2000 W may be required through the PDS for calibration and contingency troubleshooting of experiment avionics. Again, GSE allows ground controllers to access this control and data.

All payload systems will be deactivated at L-24H to ensure the T0 connection is dead-faced at lift off and all power is off for ascent without the need for creating a Launch Commit Criteria (LCC).

6.2 ASCENT

No operations are associated with the AMS-02 during the ascent phase, the payload is powered off.

6.3 ASCENT ABORT OR AMS RETURN OPERATIONS

No operations are associated with the AMS-02 payload during a contingency return / re-entry phase. The AMS-02 will be depowered for all entry phases.

6.4 ON-ORBIT OPERATIONS

6.4.1 STS On-Orbit Operations

Once on-orbit, following Post-Insertion activities, payload activation activities are expected to begin at approximately MET 00/02:30. At this time, a middeck locker stowed, STS provided, PGSC will be un-stowed, set-up, and activated on the Orbiter Aft Flight Deck (AFD). Setup includes the removal of a payload provided cable between two connectors on a Payload Data Interface Panel #1 (PDIP1) located on the AFD, and attachment of a new payload provided cable to the PDIP (Figure 6.1-1) to interface with the PGSC, as shown in Figure 6.4.1-1 . The new cable will include a built-in multiplexer to interface the RS-422 signals into a USB on the PGSC for recording. This PGSC in conjunction with the payload cable is referred to as the AMS-02 Digital Data Recording System (DDRS-02); and will be used to record all high rate data generated by AMS-02 during checkout activities. Concurrent to these activities (or prior to), the Orbiter Interface Unit (OIU) should be powered up and checked out in preparation for communication with the AMS payload via PDIP2, with “AMS-02 1553” switch in “OIU” position (Figure 6.1-1).

Next, two ISS provided Assembly Power Control Units (APCUs) are activated by the crew (SSP controlled); and then front-end data interface electronics are activated to initiate the downlink of housekeeping data; then the AMS-02 payload is activated at which point detectors and other subsystems are activated and checked out. During avionics checkout, RS-422 data is recorded on the hard-drive of the PGSC continuously., AMS-02 RS-422 data from another feed-thru on the Payload Data Interface Panel #1 (PDIP1) assembly with the “Ku-Band” switch in the “HIGH” or “LOW” position (Figure 6.1.1-1) will be down-linked via the Ku-Band via Ku Channel 3 or Channel 2, respectively, as coverage and scheduling permit.

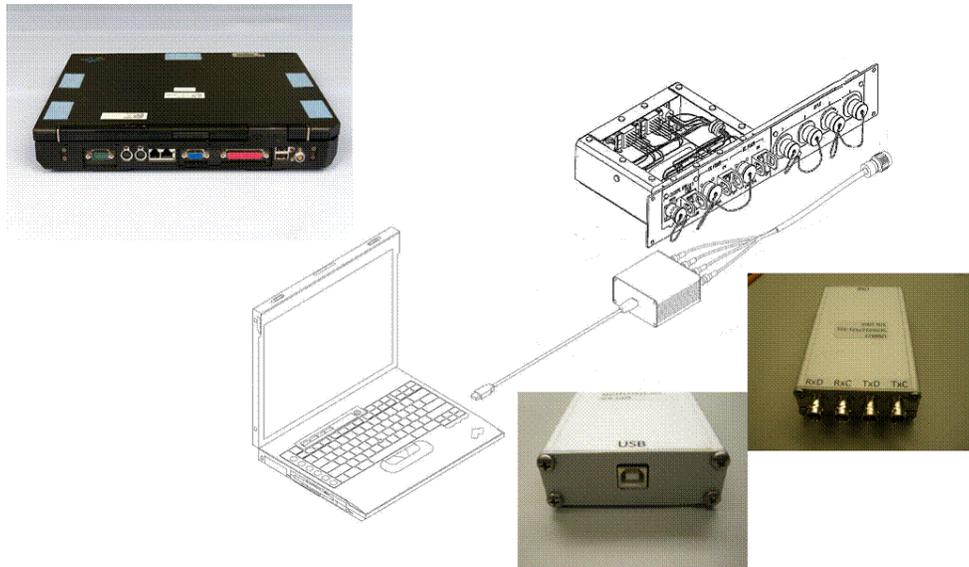


Figure 6.4.1-1 DDRS-02, PGSC to PDIP Interface

A maximum of 2 kW is required during these Orbiter operations; however, as AMS-02 heat rejection capabilities in the PLB are quite limited (primary radiators face the Orbiter sidewalls), these operations are limited by thermal constraints (dependent on attitude). All checkout activities are controlled by ground command or pre-programmed into the PGSC; crew intervention is not required. Checkout time is estimated at 40 hours with significant command uplink required.

On MET Day 3, the STS is expected to dock with the ISS. AMS-02 activities will continue as required for checkout and thermal conditioning. At the earliest opportunity, expected to be MET Day 4, the AMS-02 transfer to ISS should occur. Just prior to transfer, AMS-02 is powered down, the APCUs output is inhibited/deactivated and the DDRS-02 stowed. The SRMS is used to grapple the experiment via the FRGF (Figure 6.4.1-2, Frames 1 & 2); the Remotely Operated Electrical Umbilical (ROEU) is disconnected; the Payload Retention Latch Assemblies (PRLAs) and Active Keel Latches are opened; and the SRMS is used to remove AMS-02 from the PLB. The SRMS then moves the AMS-02 to a position (Figure 6.4.1-2, Frames 3 & 4) for the SSRMS to grapple the PVGF located on the opposing side of the AMS from the FRGF.

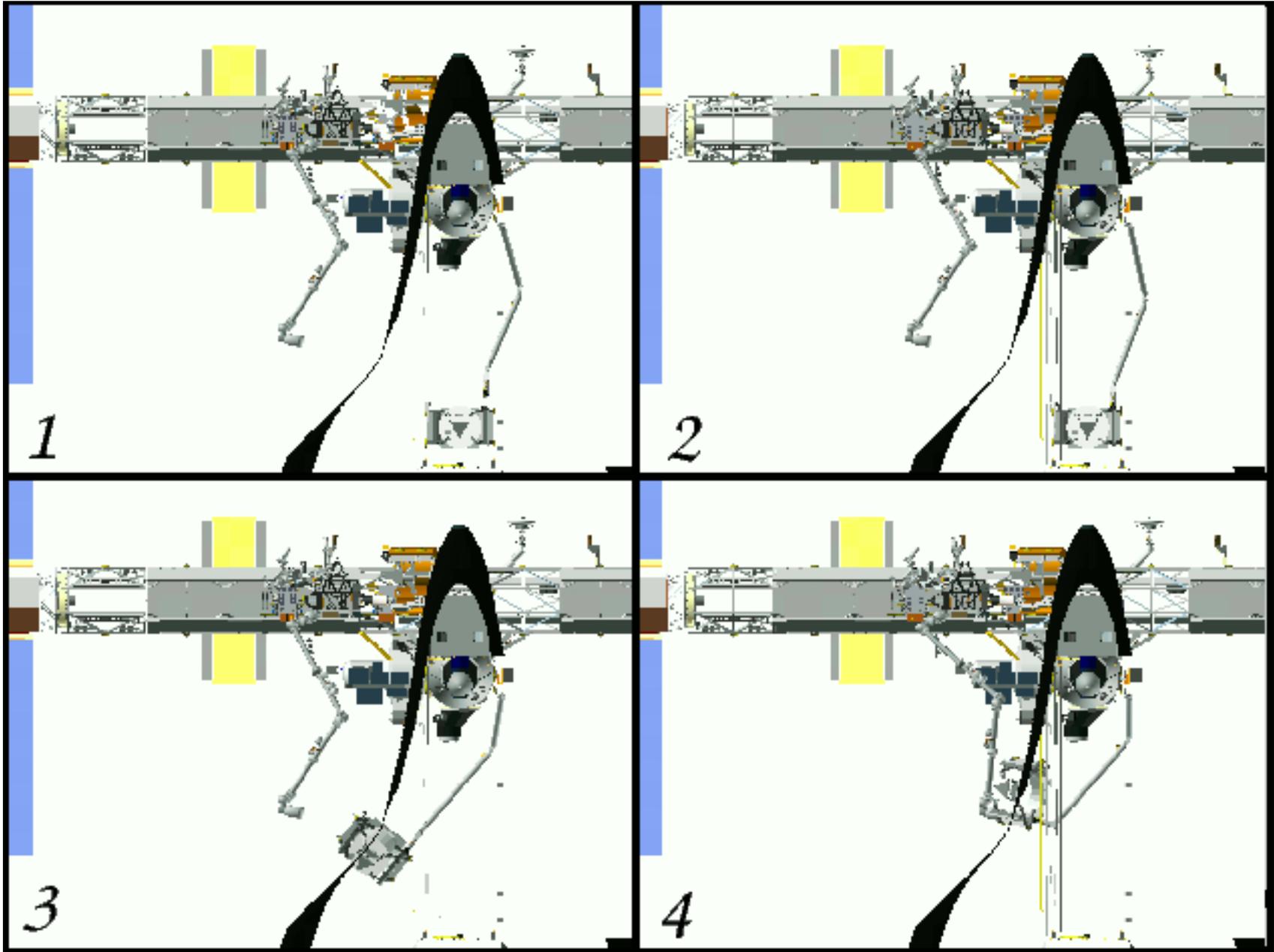


Figure 6.4.1-2 Robotic Transfer of the AMS-02 from the Orbiter the ISS (1 of 2)

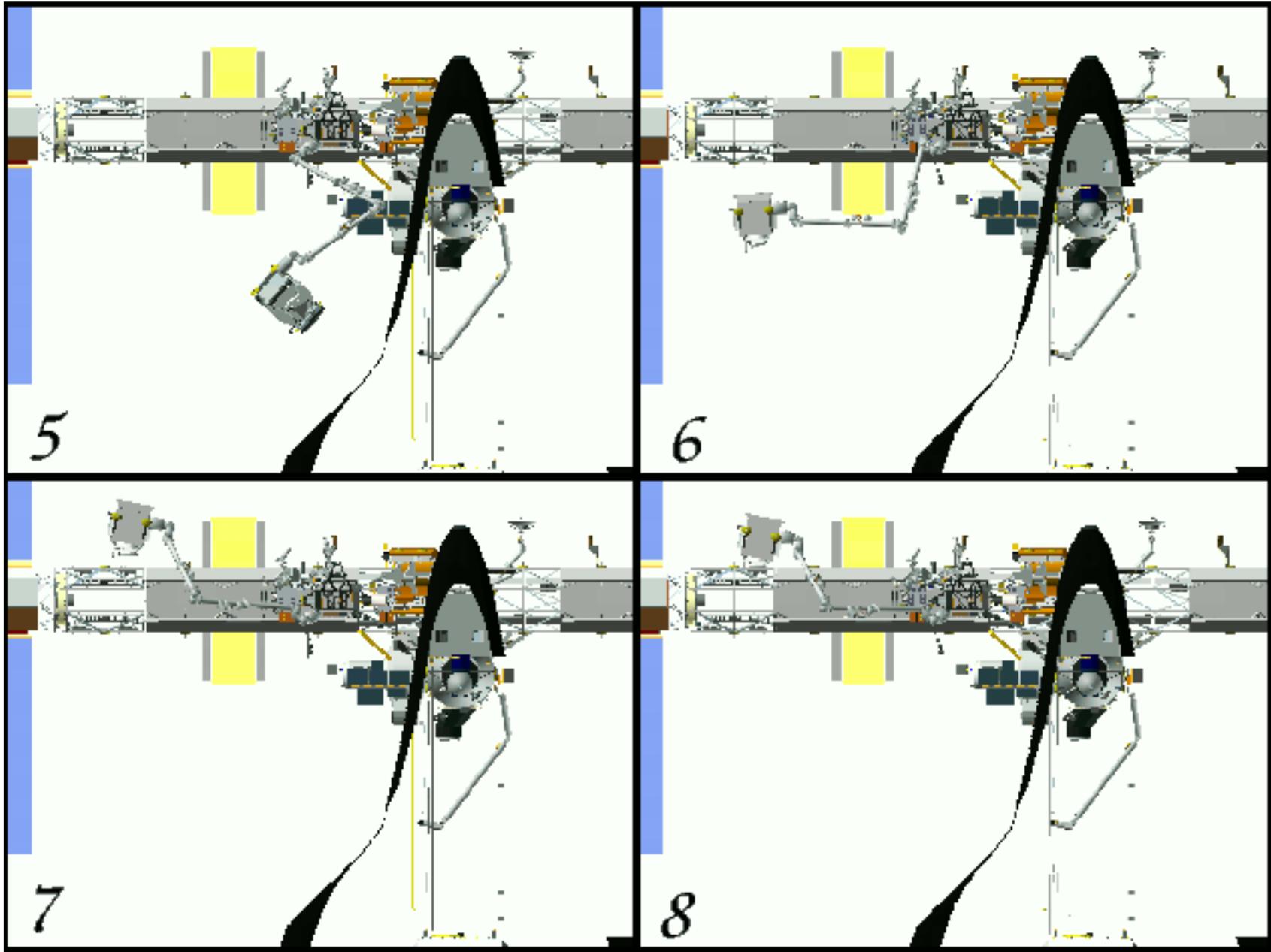


Figure 6.4.1-3 Robotic Transfer of the AMS-02 from the Orbiter the ISS (2 of 2))

6.4.1.1 EVA Operations on STS (Contingency Only)

The AMS experiment must be compatible with a Contingency EVA operation for removal of the FRGF in the event that the SRMS is unable to release the grapple fixture. The JSC EVA Analysis and Integration Team (AIT) agreed (reference Nov. 12, 2009 AIT meeting) that the contingency FRGF release EVA, as an existing STS program EVA performed from either the Orbiter sill or once the SSRMS has grappled the PVGF, can be performed without the addition of any hardware other than the existing USS mounted handrails and WIF, and no further analysis or NBL testing is required.

Another potential Contingency EVA that could be performed on the AMS experiment involves STS provided Government Furnished Equipment (GFE). This task is a standard contingency EVA planned for the contingency release of the ROEU from the PDA in the Payload Bay, in the event that the drive mechanism for the ROEU active half fails to operate. The planning for this operation is clearly performed by the EVA group at JSC. The access requirement was determined to be acceptable since the EVA could be performed from the Orbiter sill; The JSC EVA AIT agreed (reference Nov. 12, 2009 AIT meeting) that the contingency ROEU release EVA, as an existing STS program EVA performed from the Orbiter sill, can be performed without the addition of any hardware other than the existing USS mounted handrails and WIF, and no further analysis or NBL testing is required.

Finally, the AMS must be compatible with the EVA Contingency task for manually opening the PRLAs. This is also a task involving GFE that will be planned and developed by JSC EVA personnel. This task would only be performed in the event that the drive mechanism for the PRLAs failed. This is also considered standard work by the EVA group. Sill translation activities are a part of all of these Orbiter Contingency EVAs; and AMS must be compatible with that activity.

In summary, AMS must be compatible with STS EVAs that involve: translation down the Orbiter sill; EVA release and re-mate of the ROEU; release of the FRGF; and release of the PRLAs.

6.4.2 ISS On-Orbit Operations

Once the grapple is verified with the SSRMS, the SRMS releases the FRGF (Figure 6.4.1-3, Frame 5). At this time, power is applied to the Electronic Berthing Camera System (EBCS) avionics via the SSRMS through the PVGF. The EBCS is ISS provided hardware used as an aid for berthing the experiment to the Active Payload Attach System (PAS). The EBCS provides a video image of the berthing to the crewmember controlling the SSRMS and utilizes an EBCS target on the truss to facilitate final approach and payload capture in the PAS. The EBCS provides feed-thru power of up to 16.7 A for use by the payload. AMS-02 contains thermostatically controlled heaters that may utilize some or all of this power to maintain the payload temperature within design limits. The amount of power required is dependent on environmental conditions during transfer and the length of time the payload spends on the SSRMS. The 1553 bus on the SSRMS is not connected to the AMS-02 systems through the PVGF.

To complete the transfer, the SSRMS moves the AMS-02 directly above the S3 Upper Inboard attach site so that the Passive PAS on the payload is correctly oriented with the Active PAS on the truss (Figure 6.4.2-3, Frames 6 & 7). As the AMS-02 is lowered toward the capture mechanism on the truss, the EBCS is used to verify closure distance and orientation for final mechanical mating. Once the guide pins on the payload are positioned in the guide vanes of the active PAS, the Capture Latch Assembly (CLA) on the PAS is driven to grapple the capture bar on the AMS Passive PAS to a minimum load (in the $-Z$ direction) of 4900 lbs and a maximum load (in the $-Z$ direction) of 6430 lbs (Figure 6.4.2-3, Frame 8). When proper mechanical mating is verified, the power from the SSRMS to EBCS and AMS heaters is deactivated. The Umbilical Mechanism Assembly (UMA) Active half (located on the truss) is driven into the UMA Passive half (located on AMS). Following verification of mating, power is supplied from the ISS to AMS-02 via the UMA. Once power supply and data links from the Payload are verified by AMS-02 ground personnel, the PVGF is released from the SSRMS and the SSRMS is moved away from the payload.

Following installation of the AMS-02 on the truss, an avionics checkout will be conducted and science operations will begin. Due to the complexity of the experiment,

and the numerous critical subsystems that must operate nominally to achieve mission success, AMS-02 must operate for a period of time to verify that all critical systems are functioning correctly.

AMS-02 will operate continuously on the ISS for a minimum of 11-years, requiring 2.4 kW average power, and generating high-rate data at an average rate of 6 Mbps over its lifetime. AMS-02 also utilizes the ISS 1553 bus for low-rate telemetry (health and status) command/data. All of this data is down-linked via the ISS Ku-Band.

In the event of a major contingency; the AMS could be required to be returned on the same shuttle flight. If this were required, the AMS-02 would be powered off; the SSRMS would grapple the PVGF; the UMA would be disconnected, and the CLAs would be driven to release the grapple bar. The SSRMS would then maneuver AMS to a position where the SRMS can grapple the FRGF; the SSRMS would release the PVGF; and the SRMS would be used to return AMS to the payload bay. The PRLAs and active keel latch would be closed and the SRMS released. At this point the ROEU would be driven to re-mate with the PDA; and power up activities would begin again. Power/data transfer would be deactivated during De-orbit Prep activities per the standard Payload deactivation section of this document.

Minimum safe return configuration of the AMS-02 requires that all PRLAs be fully closed on the AMS-02 trunnions and the Keel Latch closed on the Keel pin. The ROEU does not need to be engaged to affect a safety return.

6.4.2.1 EVA Operations on ISS (Contingency Only)

If an Extravehicular Activity (EVA) is required for any AMS-02 contingency operation on the ISS, power from the UMA will be deactivated at the Type II Remote Power Control Modules (RPCM) upstream of the UMA prior to commencement of the EVA. In addition to this (if required) the UMA Active half can be disconnected from the UMA passive half as a secondary method of assuring fault tolerance. This is not highly desirable as it inherently creates the risk of a failure to re-mate.

The AMS-02 is designed with redundant front-end data interface hardware. In the event that 1553 or Fiber communications are disrupted due to problems with AMS-02 front end data hardware, an EVA may be performed to switch the connectors from the primary to the redundant electronics hardware. These connectors are EVA compatible and are located on the EVA Connector Panel located on the lower end of the Unique Support Structure very close to the Passive UMA (Figures 6.4.2.1-1 and 6.4.2.1-2).

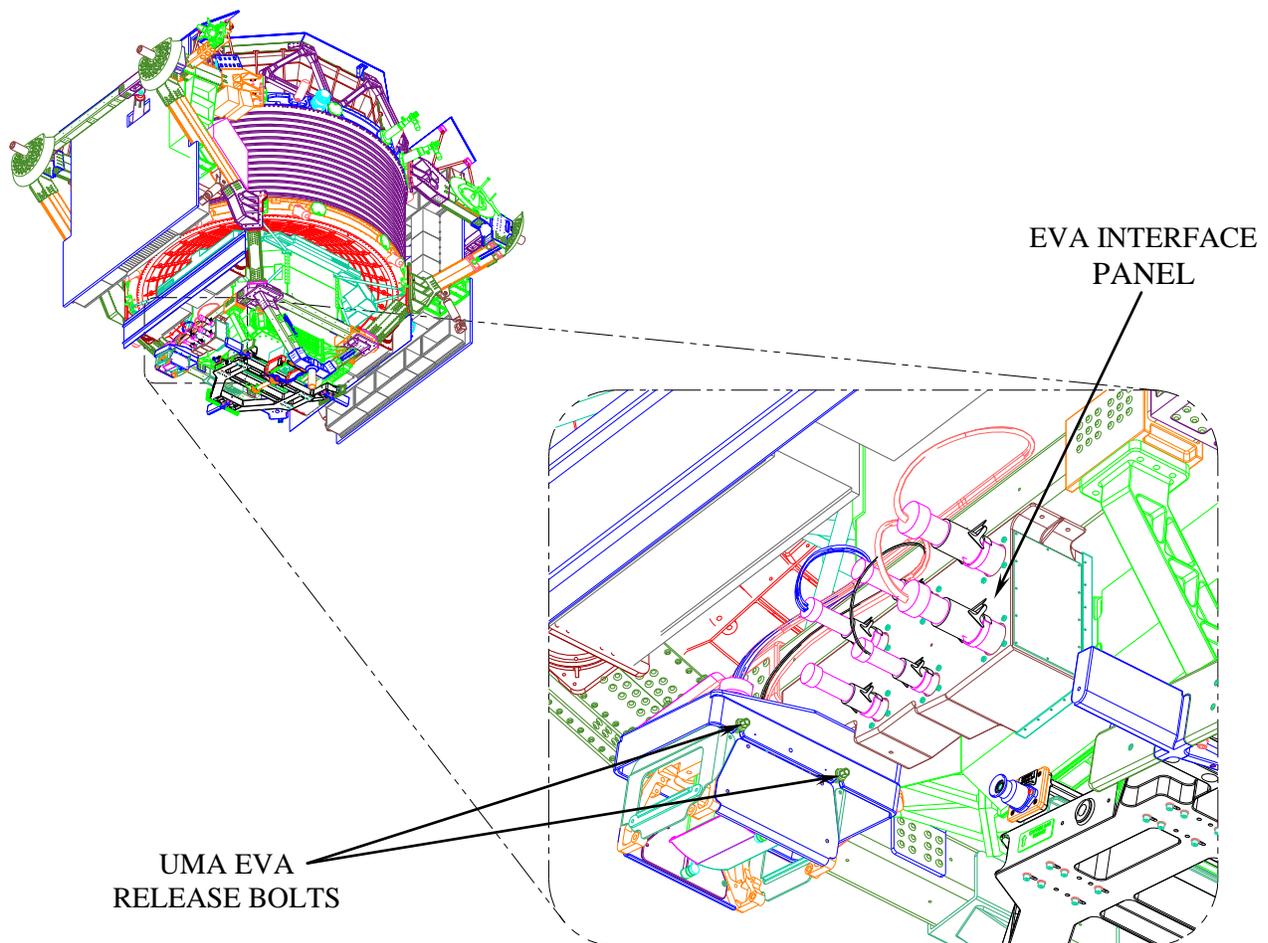


Figure 6.4.2.1-1 AMS-02 UMA (Passive Half) and EVA Interface Panel

In the event that a station contingency renders the ISS main power bus inactive at a time when the AMS-02 is experiencing a operational Bus Loss, the connectors powering payload PDS Power Bus A and Power Bus B can be interchanged at the EVA Interface Panel by a suited crewmember during a contingency EVA.

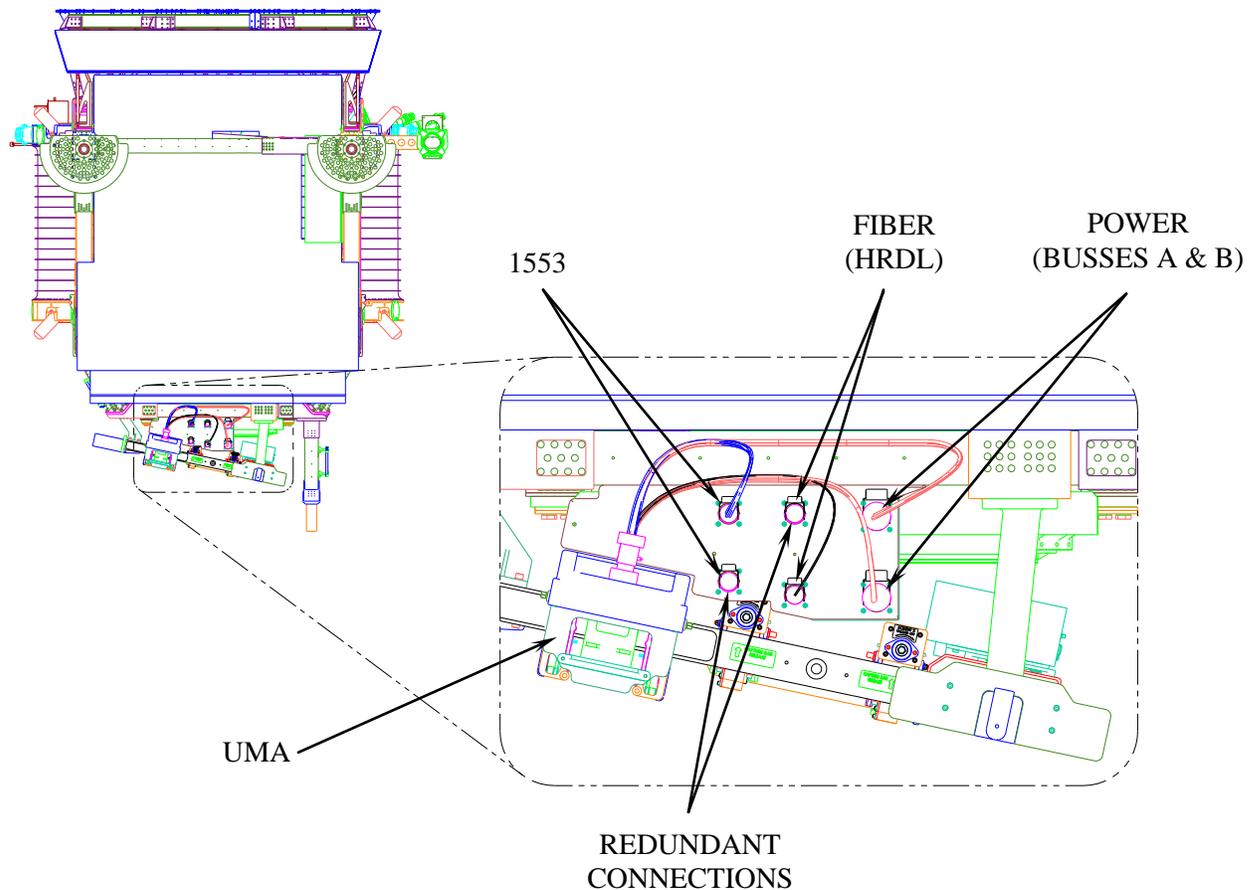


Figure 6.4.2.1-2 AMS-02 Power and Data Connectors on the EVA Interface Panel

Other AMS-02 Contingency EVA Operations include:

- UMA Removal (as required by SSP-57003) (Reference Figure 6.4.2.1-1)
- AMS-02 Passive PAS Capture Bar Removal/Replacement (Reference Figures 5.17-4, 6.4.2.1-3, 6.4.2.1-4, and 6.4.2.1-5)
- FRGF/PVGF contingency release operations (Reference Figures 6.4.2.1-6, 6.4.2.1-7, 6.4.2.1-8, and 6.4.2.1-9)

All the contingency activities and translation paths for AMS-02 on ISS EVAs, ISS Truss EVAs, and alternate Payload Attach Site EVAs were demonstrated using Worksite Analysis tools and in the NBL using a full scale AMS-02 volumetric mockup with high-fidelity EVA interfaces. Successful completion of these tests is documented in Crew Consensus Report (CCR) CB-02-129. Figures 6.4.2.1-10 illustrates an EVA translation

path from the EVA Worksite Analysis tool. Figures 6.4.2.1-11 and 6.4.2.1-12 are scenes from the NBL testing performed in November 2002.

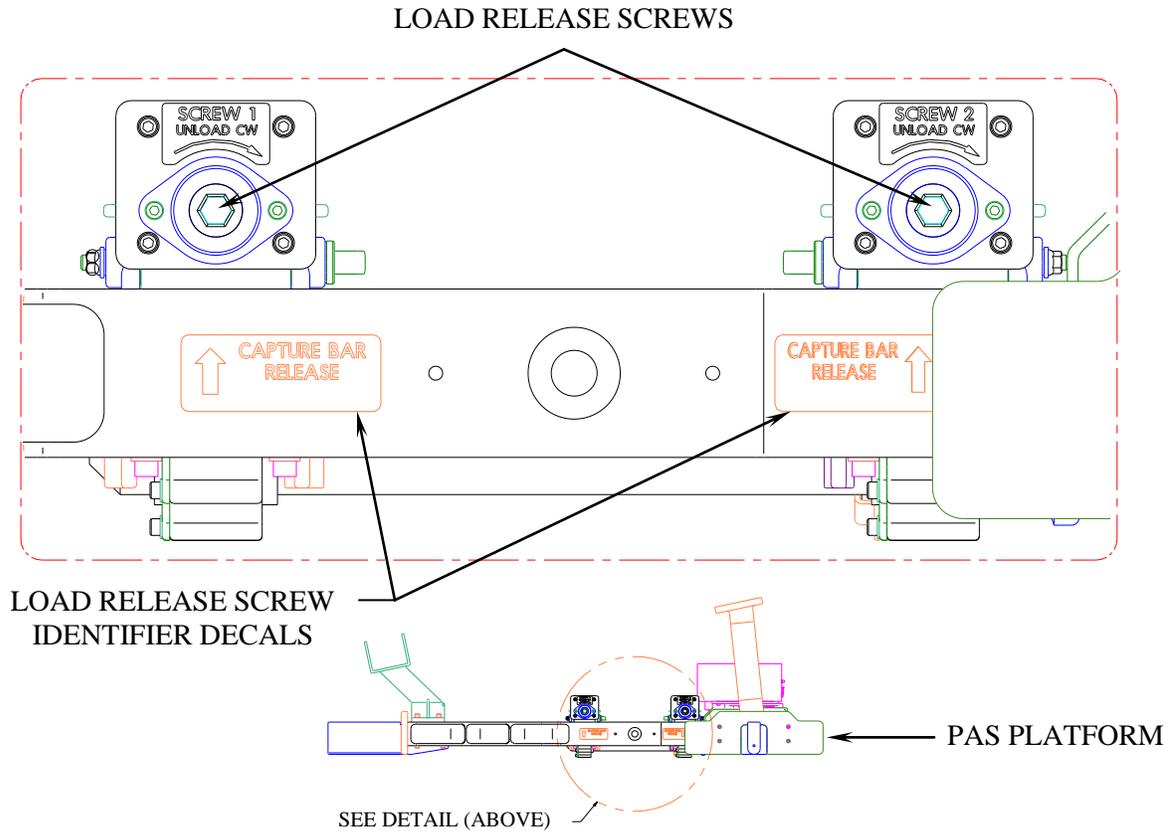


Figure 6.4.2.1-3 AMS-02 Contingency Capture Bar Release (1 of 2)

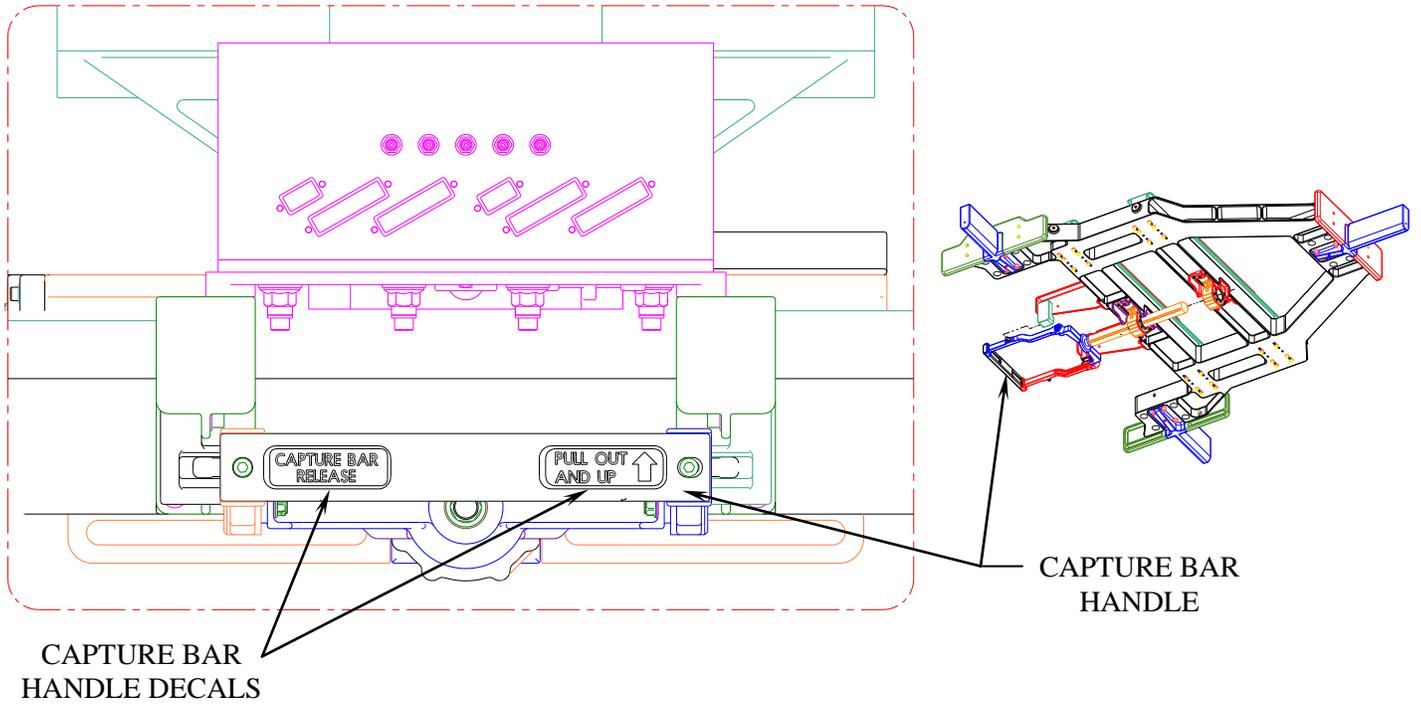


Figure 6.4.2.1-4 AMS-02 Contingency Capture Bar Release (2 of 2)

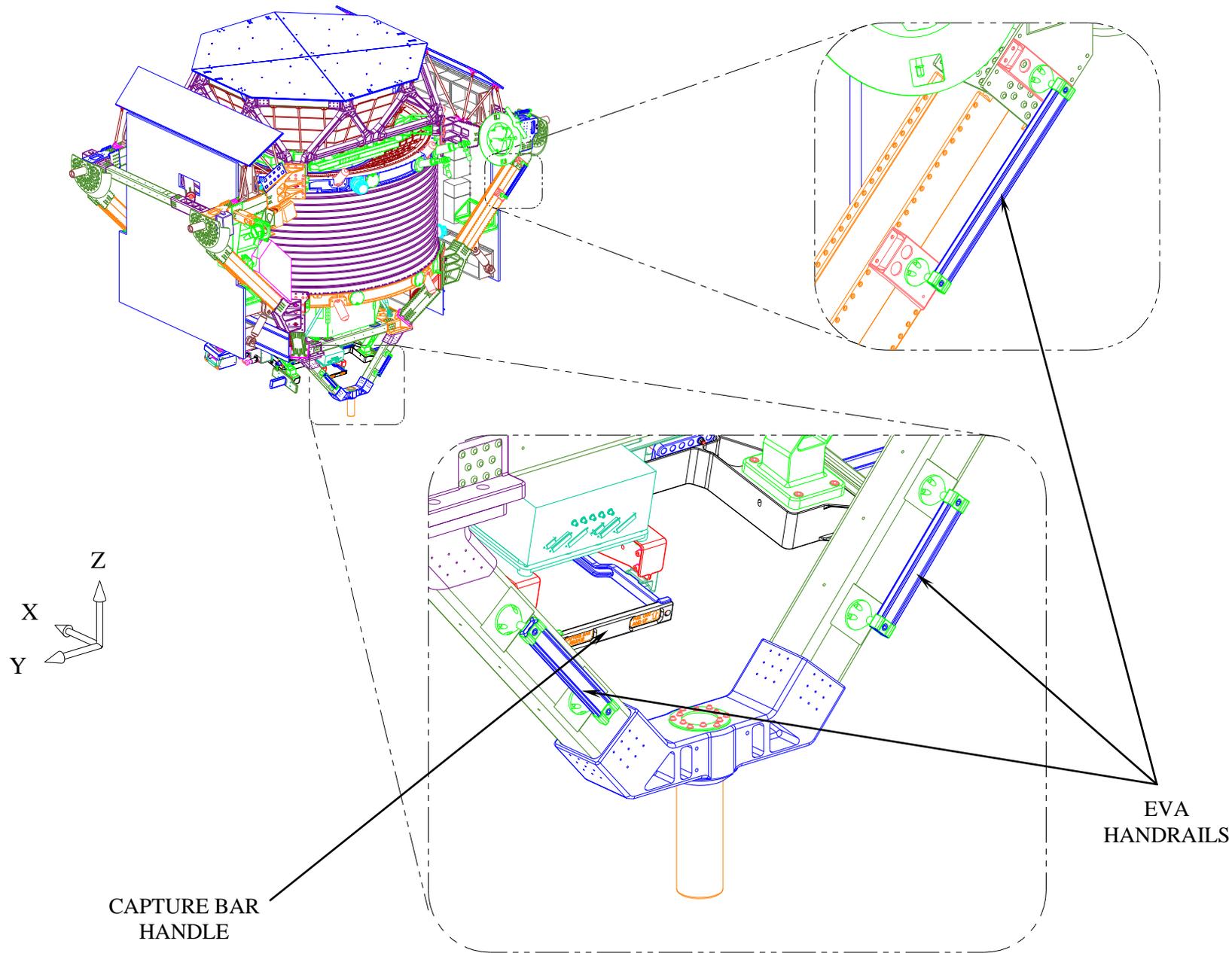


Figure 6.4.2.1-5 EVA Handrails in the Vicinity of the PAS Capture Bar Handle

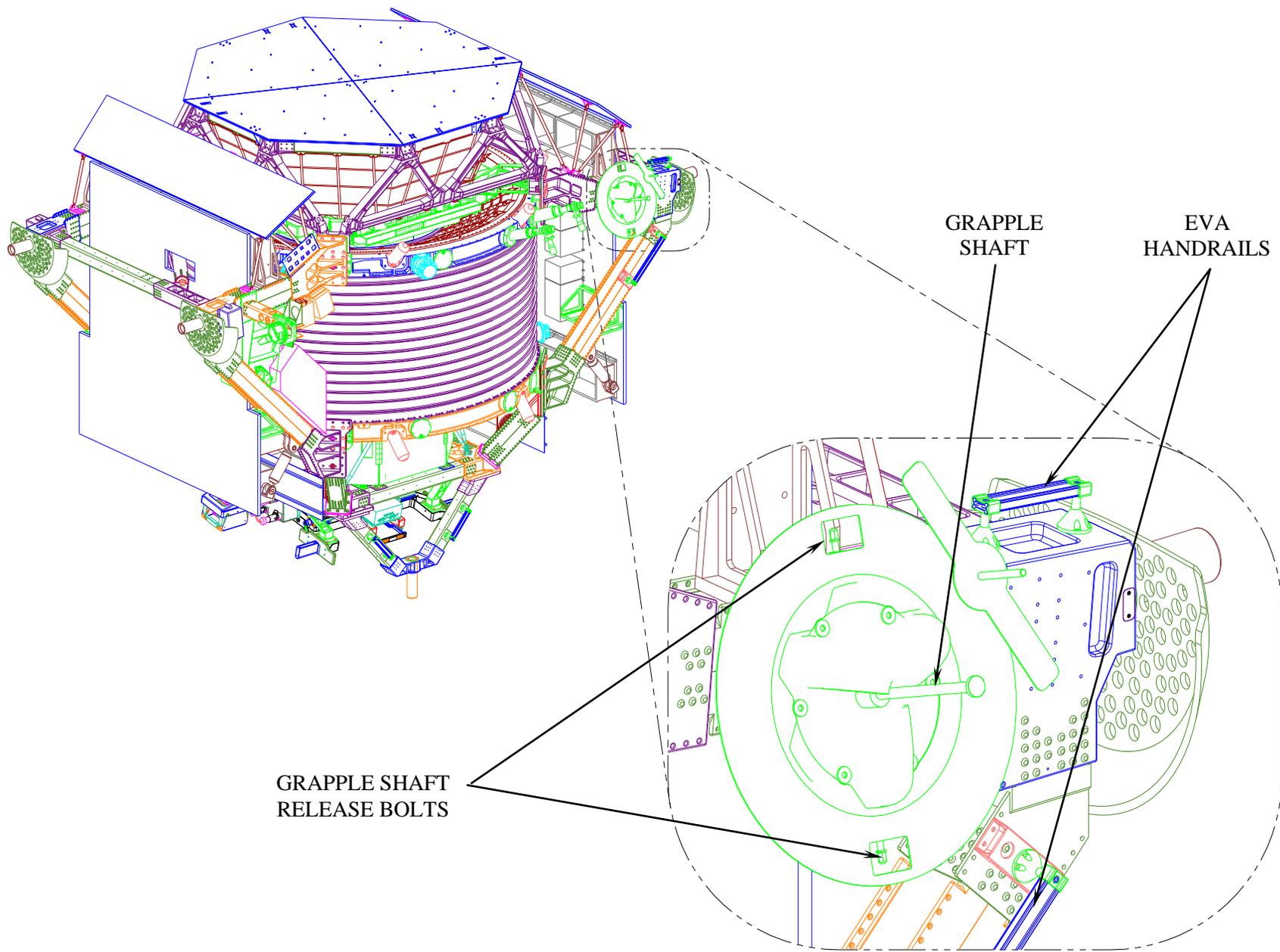


Figure 6.4.2.1-6 FRGF Grapple Shaft Contingency Release Mechanism

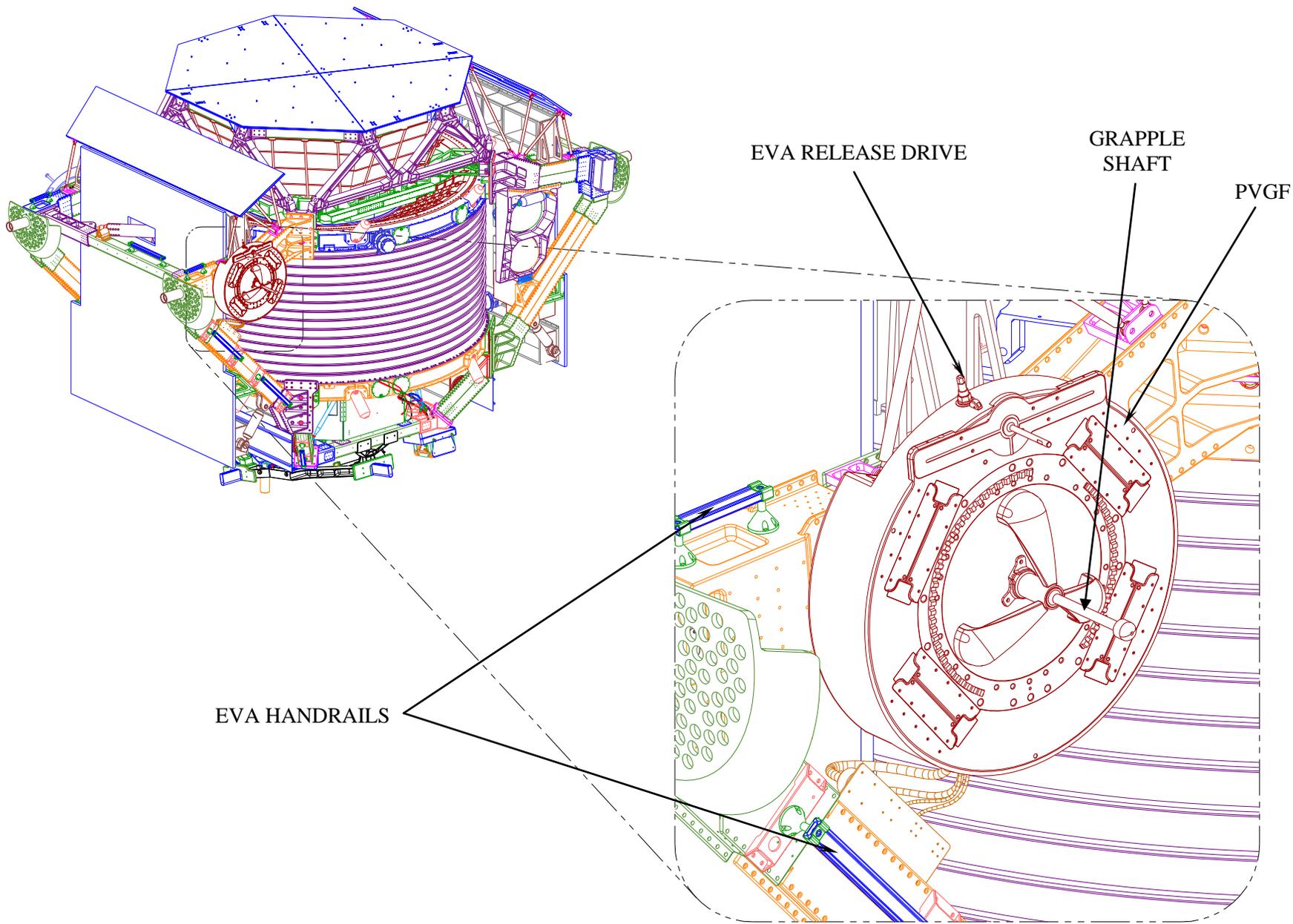


Figure 6.4.2.1-7 PVGF Grapple Shaft Contingency Release Mechanism

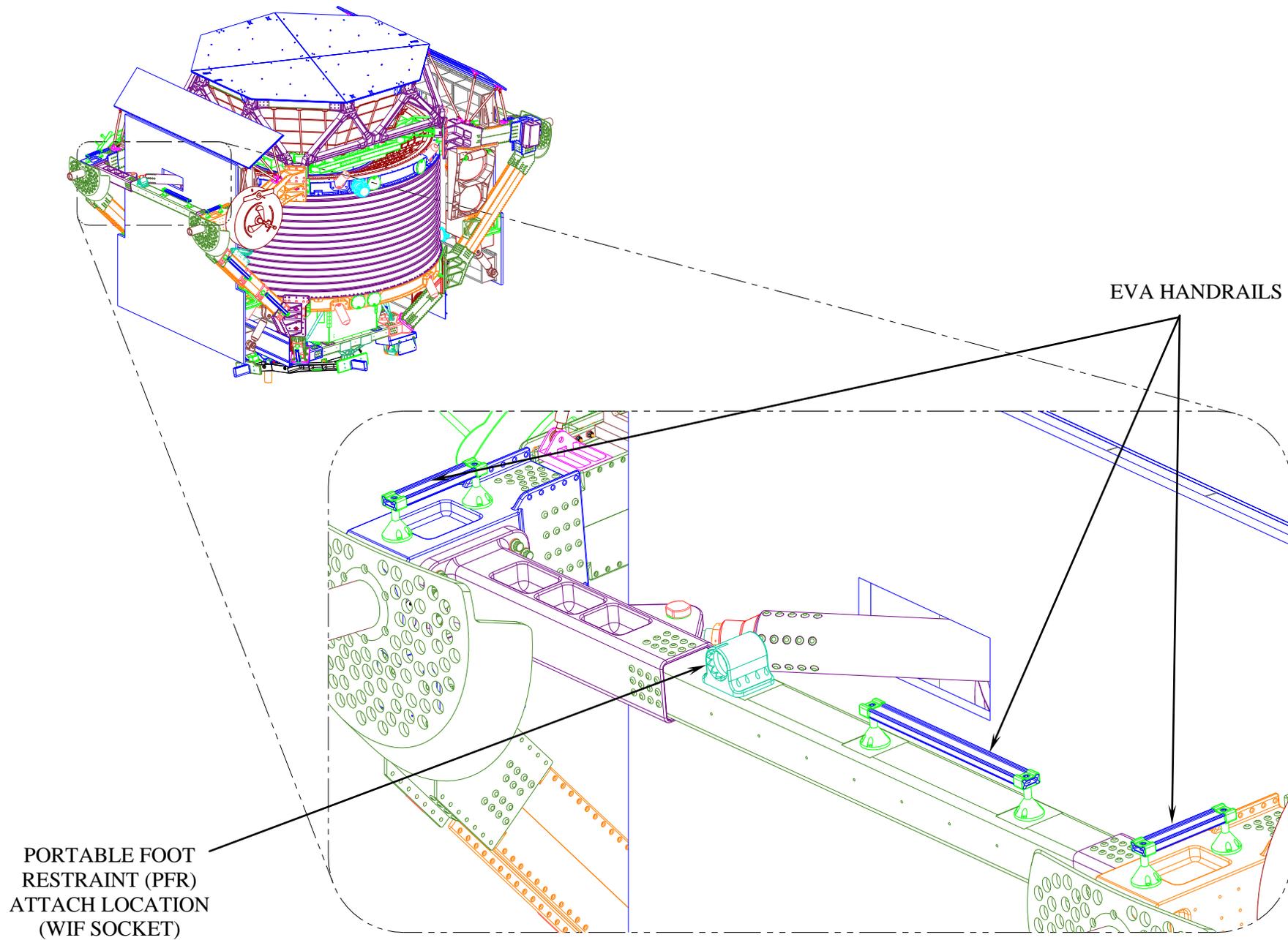


Figure 6.4.2.1-8 EVA Handrails and Worksite Interface Fixture (WIF)

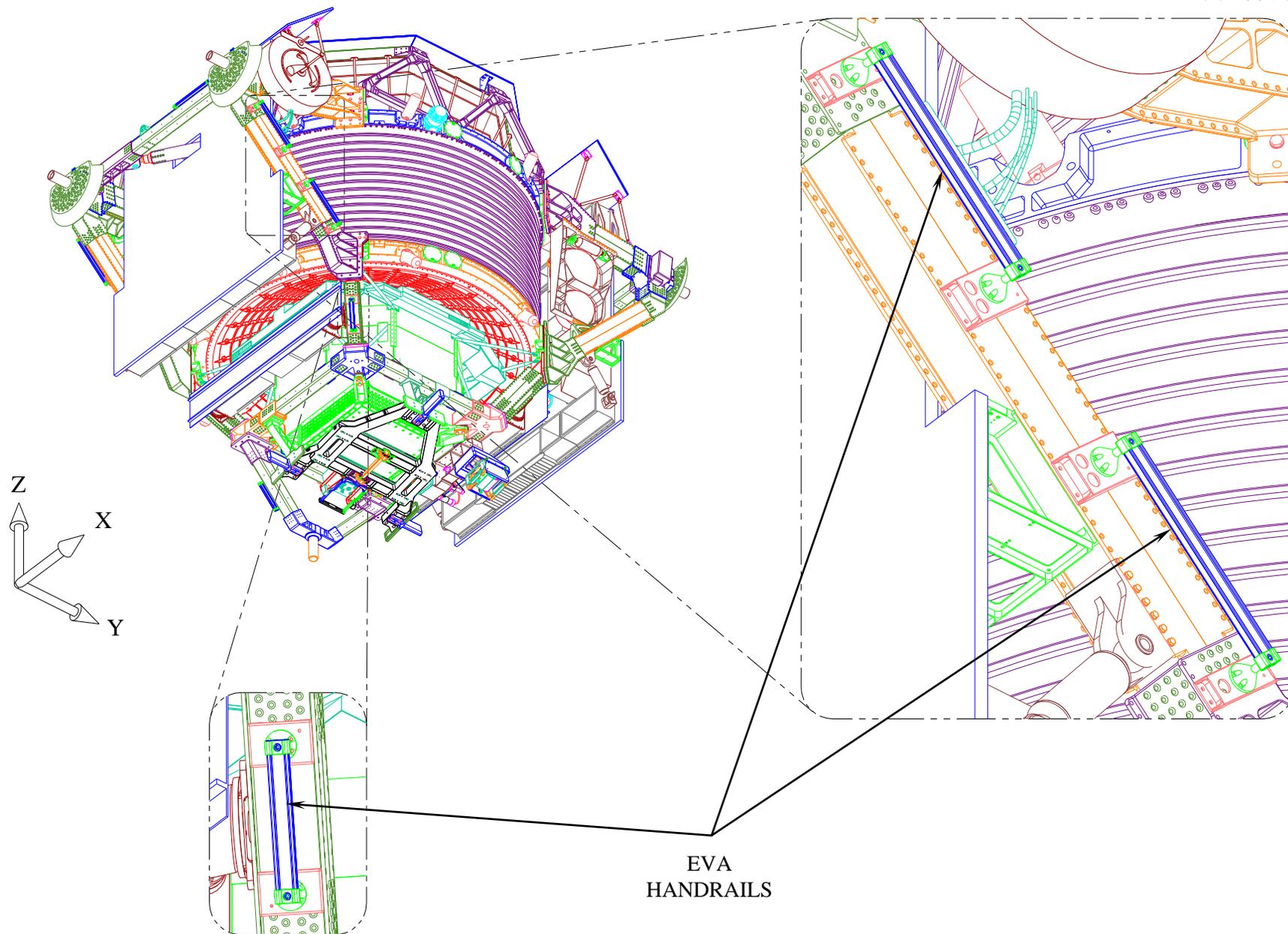


Figure 6.4.2.1-9 EVA Handrails in the Vicinity of the PVGF

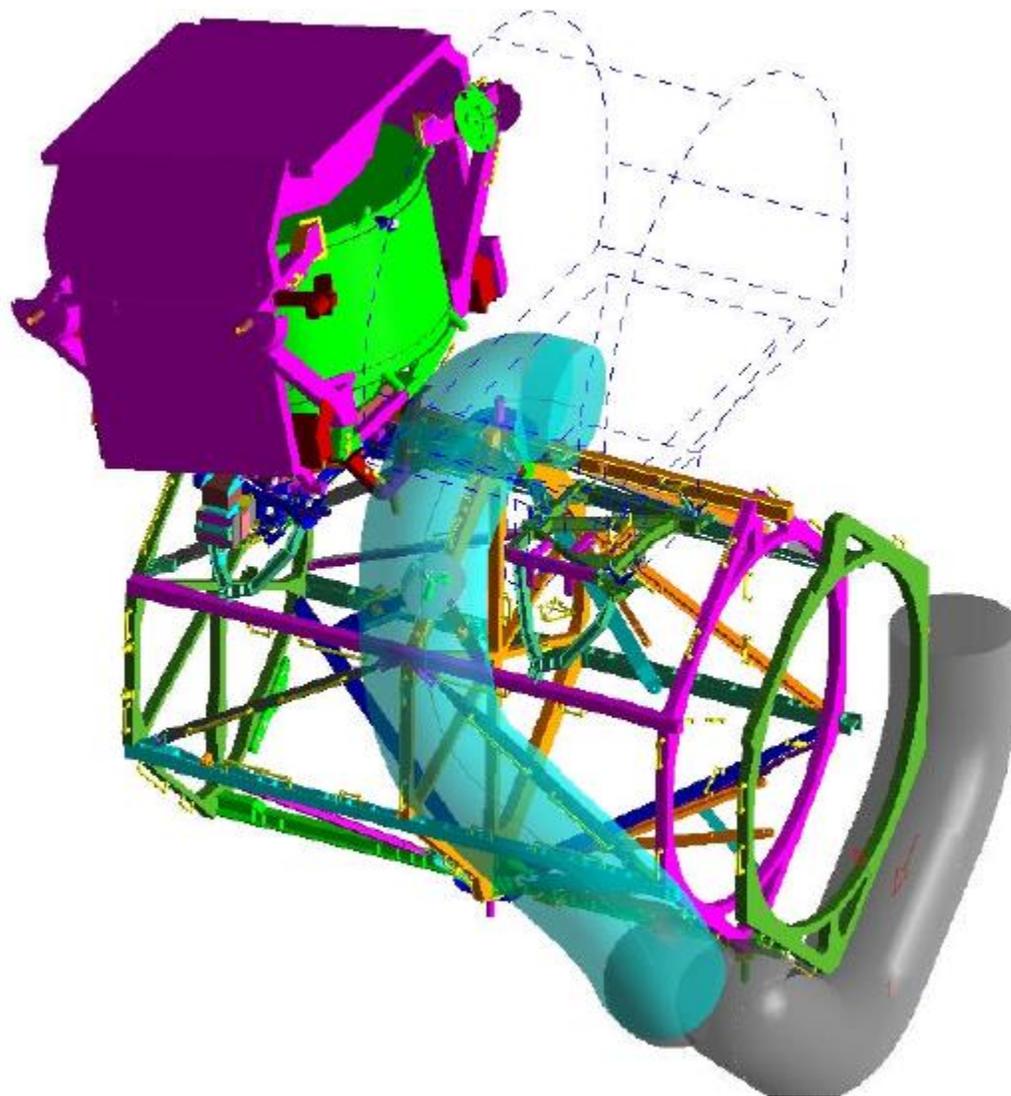


Figure 6.4.2.1-10 EVA Translation Path from Worksite Analysis



Figure 6.4.2.1-11 EVA Crewmember in NBL Testing (UMA Release Task)

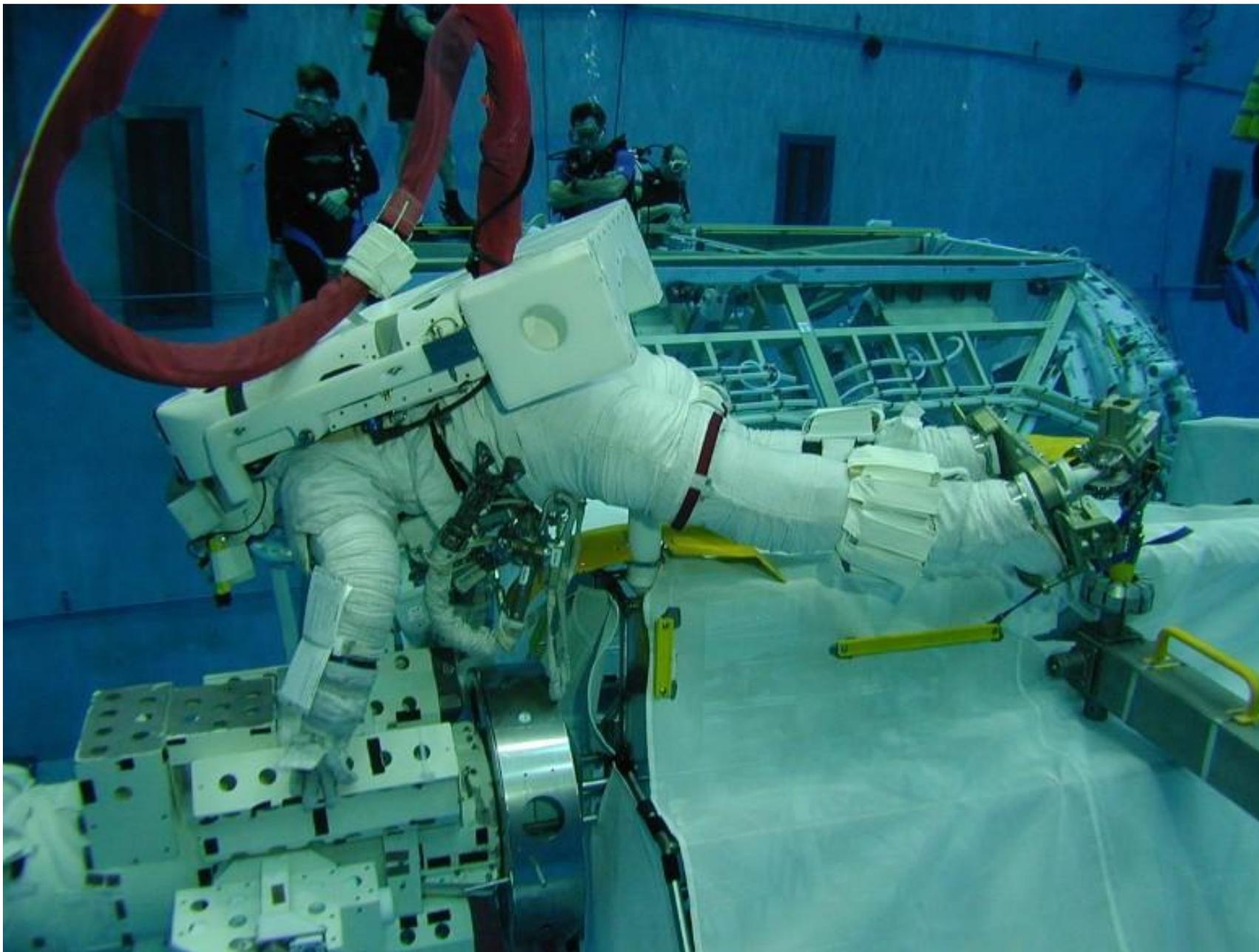


Figure 6.4.2.1-12 EVA Crewmember in NBL Testing (PVGf Release Task)

The AMS-02 Collaboration has also designed a “foldable” mounting bracket for the ROEU PDA. This was requested by OZ in response to a desire to decrease the AMS exceedance to the Standard Payload Envelope at the attach site in this particular location. Further review of the AMS-02 exceedances indicated that this folding operation was not required, thus the folding mechanism was fixed with bolts instead of pip pins. No EVA operations are to be conducted on this hardware configuration. It should be noted that a Manipulator Analysis, Graphics, and Integrated Kinematics (MAGIK) analysis was performed using the AMS model and an SSRMS with a standard payload envelope to determine if there were any contact issues. This analysis included the standard “stacked” tolerances for the arm and still did not reveal an impact concern. EVA assessments of operations on AMS-02 and the adjacent payload indicated this extension was not a concern.

7. SAFETY DISCUSSION

The AMS-02 Project has employed a methodical approach of for implementing a safe design for the AMS-02 payload. Safety has been a central focus of the Collaboration that has come together to create this international scientific instrument. With the evolution of the design of the AMS-02 since the Phase I Safety Review, held January 16, 2001, the design of the AMS-02 has undergone a renewed safety analysis to assure that all safety issues have been properly identified and addressed.

In the Phase I Safety Data Package (SDP) several systems were identified as being “re-flight” from the AMS (AMS-01) mission. Upon further review these systems were established to be sufficiently modified from the original flight design and configuration that they have now been directly addressed in the AMS-02 hazard analysis and hazard reports.

The Phase II safety review was held May 21-24, 2007, all systems were reviewed at this co-chaired review (PSRP, SRP). During the course of the review and subsequent technical interchanges, all hazard reports were either approved for Phase II or removed as valid hazard reports. Hazard report and action item dispositions are summarized in this section.

The Phase III safety data packaged was prepared for the Phase III safety review held January 12-14, 2010. At that time the number and type of open verifications precluded the approval of the majority of the AMS-02 hazard reports, plans were made to revisit the PSRP to provide updated hazard reports and verification closure plan.

In March 2010, a critical design change was implemented in the AMS-02, changing the system from a superfluid helium cooled superconducting magnet providing the magnetic field to a constant field permanent magnet that could sustain that magnetic field for the duration of the ISS orbital life. The reduction in the magnetic fields strength dictated modifications necessary in the Tracker system to extend the sensor volume to be able to detect the more subtle curvature of the particles along their path. A revision to the safety

analysis was required for the primary change and the subsequent cascade of changes that this original change required.

7.1 SAFETY ANALYSIS

The AMS-02 safety analysis considered the AMS-02 exterior elements and the interior elements that are to be utilized on the Shuttle Orbiter and the exterior elements to be berthed on the ISS. This analysis and SDP reflects the fact that the AMS-02 does not have any ISS interior elements.

The AMS-02 safety analysis and hazard reports generated consider the operations associated with the AMS-02 during the following operational phases:

- Pre-launch operations
- Launch and ascent
- On-orbit checkout of the AMS-02
- Shuttle RMS Operations
- ISS RMS Operations
- ISS PAS Installation
- ISS Operations

In addition the following contingency operations were considered in the safety analyses and hazard reports:

- Shuttle EVAs, past the AMS-02 and on Shuttle Program provided GFE (ROEU, FRGF)
- ISS EVAs past the AMS-02 and on ISS Program provided GFE (PVGF, PAS)
- AMS-02 Contingency EVA For Power Routing In-flight Maintenance (IFM)
- AMS-02 Contingency EVA For Data Routing IFM
- AMS-02 Contingency EVA For Manual Release of the PAS

The AMS-02 DDRS ISS, a data recording and interface system to be utilized within the ISS habitable volume, is not addressed in this SDP, a separate unique safety analysis will be documented for its transportation and use on the ISS. This interface has been

considered in the safety analysis of the operations of the AMS-02 as an integrated system.

7.1.1 Energy Analysis

The basic technique used to perform the safety analysis was identification of energy sources, energy transfer and energy concentration points in the AMS-02 design. This safety analysis technique utilizes the fact that in most cases, hazards cannot manifest without some form of energy existing and changing state or position. Energy can be categorized in a number of forms (generally), electricity, thermal, pressure, ionizing radiation, electromagnetic radiation, magnetic fields, chemical energy, kinetic, acoustic and organisms. By identifying these sources of energy and how they may be possibly transferred or concentrated, the fundamental hazards associated with AMS-02 have been identified.

7.1.2 Historical Comparative Analysis

In addition to the Energy Analysis technique for hazard analysis a complementary method of hazard analysis was utilized where a historical perspective of hazards addressed for payloads of the ISS and Shuttle was used to assure that there are no omissions in the AMS-02 hazard identification. This technique relied heavily on experiences of the safety and engineering community of the AMS-02 Project and an iterative approach to the design review and investigation.

7.1.3 Maintenance Hazard Assessment

The AMS-02 design does not require any regular maintenance procedures or conditional maintenance actions to be performed during the AMS-02 mission. A unique hazard analysis for maintenance operations has deemed to be unnecessary, all operations identified as nominal and contingency for the AMS-02 have been considered in the hazard analysis documented in this safety data package. During the Phase II Safety Review the PSRP provided concurrence that a unique maintenance hazard assessment was not required of AMS-02.

7.1.4 Design Revision Analysis:

As a consequence of the AMS-02 redesign to incorporate a PM and alteration of the Tracker system, Tracker Thermal Control System, structures, etc., it was necessary to review the basic hazards, causes, control and verifications. This was accomplished with a top down approach, eliminating hazards, looking for new or modified causes, establishing the validity of controls and verifications, identification of modified or new controls verifications and critical review of existing closed verifications that must be reopened because of modifications to the flight hardware. Specifically of concern is the process by which alterations have been accomplished in preparing the Permanent Magnet version of the AMS-02 for flight.

7.2 HAZARD REPORT GENERATION

The AMS-02 design was revisited with a renewed safety analysis in preparation of the Phase II Safety Data Package. As a result of the revised safety analysis the hazard reports were restructured and additional hazard reports added. To address this revision, new AMS-02 Project tracking identifiers were assigned to the hazard reports, differing from those used at the Phase I safety review. This difference is the addition of the “F” for flight in the number and a two digit numerical designator. With reorganization and additions of hazard reports, these designators may not correlate directly with previous hazard reports reviewed at Phase I. JSC Form 1230 has been used where possible to address Standard Hazards that satisfy the control and verification standards that are documented on the JSC 1230 Form. Two JSC Form 1230s had been prepared for Phase II, one for AMS-02 exterior elements (Shuttle and ISS) and one for hardware that will be present within the Shuttle crew habitable environment. It was noted in the generation of the JSC Form 1230s for the AMS-02 phase II safety review that the JSC Form 1230 does not specifically address ISS Exterior Payloads, and in cases where it was clear the form was not able to address these payloads, a unique hazard report was generated. Generic Hazard Report STD-AMS-02-F01 was deleted and its contents assigned to alternate hazard reports as directed at the Phase II safety review.

Subsequent to the Phase II safety review the hazard reports have been modified to be consistent with the natural evolution of the AMS-02 payload. Systems that have been removed from the payload, such as the radioactive source from the TRD detector, the Cryomagnet systems, have resulted in the withdrawing of hazard reports, while other changes, such as the deletion of the Oscillating Heat Pipe Experiment and the Cryocooler loop heat pipes have required only modifications to the hazard reports. These changes have been tracked and can be identified upon request. The Phase III package and hazard reports reflect the flight configuration of the AMS-02.

AMS-02 hazard reports identified by the hazard analysis have been documented on a custom hazard report form that is compliant with the documented requirements of JSC/ISS 13830. The format of the hazard report groups controls and verifications together for direct correlation of the control and the associated safety verifications. Additionally a column that parallels the controls is present to identify all flight operational controls for quick reference. Character designators identify these controls, “I” for ISS based operation, and “S” for Shuttle based operations. Preflight ground operations are not identified in this column.

A consistent numbering convention has been applied to the hazard reports using the form “aa.bb.cc”. In this format “aa” designates the Cause Number, “bb” the Control Number, and “cc” the safety verification method and status number. This methodology is maintained through the unique hazard reports, with the JSC Form 1230, the use of a slightly different numbering scheme utilizing the JSC Form 1230 letter designators required a minor deviation of the verification numbering methodology.

7.3 ACTION ITEM (AI) STATUS

The following actions were assigned at the AMS-02 Phase I Flight Safety Review held January 16, 2001.

Phase 0/I Action Items:

AI	Action	Date Due
1 Assigned to:	Continue to assess the helium venting analysis with Shuttle Integration and EP4 and develop a history of cryostat	Date: Phase II

SF3/J. Bates (Now EA2/T. Martin)	operations to determine the necessity of a Launch Commit Criteria (LCC) inside T-9 minutes to launch.	Mandatory Reviewers: PSRP
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Action item 1 was discussed in two special technical interchange meetings (TIMs) held with the PSRP on October 11 2001 and January 17, 2003. The monitoring of the Cryomagnet has been established to be an essential AMS-02 Verification Process and a Launch Commit Criteria has been established in hazard report AMS-02-F04, Overpressurization of Orbiter Payload Bay. The AMS-02 Project will seek to have this action closed at the Phase II Safety Review.

AI	Action	Date Due
2 Assigned to: SF3/J. Bates HR: AMS-02-6 (Maps to Phase II HR AMS-02-F06)	Pre-submit AMS-02 vent test data regarding TCS, warm helium supply, TRD, and the cryosystem to EP4/H. Flynn for approval; submit data to USA in April 2001 for analysis; and add results to HR AMS-02-6 for presentation at Phase II FSR.	Date: Phase II Mandatory Reviewers: PSRP

Action item 2 has been an ongoing effort to establish all possible venting rates and maximum volumes from all stored gas systems, exceeding the list of the action item. Special technical interchange meetings followed the Phase I safety review where the venting rates and thermal conductance that could lead to emergency venting of the superfluid helium as helium gas. The AMS-02 Project will seek to have this action closed at the Phase II Safety Review.

AI	Action	Date Due
3 Assigned to: NC55/S. Loyd HR: AMS-02-7 (Maps to Phase II HR AMS-02-F07)	Provide updates regarding changes to the magnetic requirements for the EMU and peripheral equipment, and status the relevant communication between the PO and EVA Project Office/XA. (PSRP may schedule a meeting with XA and AMS following review of the AI, if necessary.)	Date: February 18, 2001 Mandatory Reviewers:

This action item was closed at a special discussion meeting held by the PSRP on September 11, 2001.

Phase II Action Items:

AI	Action	Date Due
1	Confirm with JSC/Fracture Control the possibility of two	Date:

Assigned to: JSC/MSWG HR: AMS-02-F11	breaks in one PAS anti-rotation device spring as a credible failure mode and review the AMS analysis. PO POC—C. Tutt	06/15/07 Mandatory Reviewer(s): PSRP
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The AMS-02 Project was informed by JSC memorandum NE141-07-215, “Alpha Magnetic Spectrometer (AMS)-02 Phase II Action Item (AI) 1 Closure, dated August 15, 2007, that this action item had been closed and multiple breaks were deemed non-credible.

AI	Action	Date Due
2 Assigned to: JSC/OB/M. Bennett HR: N/A	Provide a limited age life requirement for AMS-02.	Date: 06/15/07 Mandatory Reviewer(s): AMS PO

The AMS-02 Project was informed by JSC Memorandum NE141-07-216, “Alpha Magnetic Spectrometer (AMS)-02 Phase II Action Item (AI) 2 Closure,” dated August 15, 2007, that action item 2 had been closed and the AMS-02 Project should conduct all limited life analyses assuming an ISS life extending to 2020.

AI	Action	Date Due
3 Assigned to: JSC\Structures HR: AMS-02-F03	Provide the acceptance rationale for the 1.5 FOS over the 2.0 requirement against burst for the SFHe tank and the VC.	Date: 06/15/07 Mandatory Reviewer(s): PSRP

The minutes of a technical interchange meeting (TIM) held between the AMS-02 Project and the Payload Safety Review Panel on October 10, 2007 document the closure of this action item. As stated in the minutes of that meeting:

The PO now meets the 2.0 FOS, so this AI is closed as it applies to the AMS-02 payload. The PSRP assigned internal AI 07-10 to investigate the continued applicability/acceptability of the NSTS 1700.7b, ISS Addendum, paragraph 208.4a requirement, which allows a safety factor of lower than 2.0 for ISS, experiment pressure vessels. Actionee: TBD (this AI to be discussed at November 2007 PSRP Internal Meeting).

No additional action items have been assigned at subsequent PSRP meetings with the AMS-02.

Phase III Action Items:

AI	Action	Date Due
1 Assigned to: AMS/ J. Heilig HR: AMS-02-F13	Determine an engineering basis to fly the cracked FETs in the Battery Management System (BMS). If the PO decides to fly cracked FETs it must provide a FMEA. Document the failure modes of these FETs and the consequence of a failure in each. Provide statistics for Failure Open versus Failure Closed for this design or for this type of FET situation.	Date: 03/01/10 Mandatory Reviewer(s): PSRP

The cracked FETs were part of the Uninterruptible Power Supply (UPS) that was integral to the operation of the Cryomagnet system. With the Cryomagnet being removed and replaced with a Permanent Magnet, the UPS was removed as well. This action item has been overcome by events and is considered closed.

AI	Action	Date Due
2 Assigned to: JSC/ES/G. Henning HR: AMS-02-F07	JSC Engineering will validate the Eddy Current Analysis in Control 3.4.	Date: 02/01/10 Mandatory Reviewer(s): PSRP

The Eddy Current Analysis was required as a consequence of the changing magnetic fields associated with charging (low impact due to time constant), discharging, and quench of the Cryomagnet system. With the replacement of the Cryomagnet system with a lower field strength constant magnetic field of the Permanent Magnet, the need for eddy current analysis is unnecessary, the field does not make rapid changes that might induce eddy currents of sufficient nature to cause electrical or structural damage. This action item has been overcome by events and is considered closed.

AI	Action	Date Due
3 Assigned to: AMS/ C. Tutt HR: AMS-02-F06	PO will confirm the continued applicability of Boeing Memo TM-990018-05, 9/12/99. Reference Hazard Verification 4.1.	Date: 03/01/10 Mandatory Reviewer(s): PSRP

Prior to the change in the AMS-02 from the Cryomagnet system to the Permanent Magnet, Boeing had indicated it had no desire to reissue the memorandum, allowing the

first to stand as the values for AMS-02 were well under those dictated in the memo. Subsequent to the change from the Cryomagnet to the Permanent Magnet, the value for the applied magnetic torques has been reduced further and this new value has been made available for ISS and Shuttle use. This action item is considered closed.

AI	Action	Date Due
4 Assigned to: AMS/ C. Tutt HR: AMS-02-F04	Assess leak size versus time to effect for the leak rates in the SFHe system.	Date: 02/01/10 Mandatory Reviewer(s): PSRP

The removal of the Cryomagnet system, with the associated superfluid helium supply and it's vacuum dewar (VC) has rendered this action item non-applicable. This action item has been overcome by events and is considered closed.

AI	Action	Date Due
5 Assigned to: AMS/ C. Tutt HR: All	Update SVTL to indicate pre- and post-KSC SVTLs.	Date: 03/01/10 Mandatory Reviewer(s): PSRP

The SVTL has been updated to provide a flag that indicates which verifications that are planned to occur at KSC. This action item is considered closed.

Special Topic TIM 3/23/2010:

AI	Action	Date Due
1 Assigned to: AMS/ C. Tutt HR: AMS-02-F07	Provide PO input that clearly defines LCC constraint to be included as a formal concurrence memo from the NASA PSRP to KSC.	Date: 04/06/10 Mandatory Reviewer(s): PSRP

With the removal of the Cryomagnet system, the subject LCC have been deleted as a project requirement. This action item is considered closed.

7.4 AGREEMENTS

The following agreements were documented in the Phase III minutes for the AMS-02 held January 12-15, 2010. Reference numbers are taken directly from the text of the minutes of the meeting.

3.1 The PO agreed to make sure the silver Teflon tape will stay on the radiators for the life of the ISS.

AMS-02 has confirmed that the Silver Teflon Tape utilized is the same tape that has been previously approved for long term usage on the ISS.

3.2 The PO agreed to update the SDP to indicate the Guard Manifolds (associated with the Weka Helimatic Valves) are not a control for a hazard.

The Guard manifold was removed from the AMS-02 with the conversion from the Cryomagnet to the Permanent Magnet. The SDP does not reflect the Guard Manifolds for this reason.-

3.3 The PO agreed to attach an inhibit diagram to 1.1 of HR AMS-02-F12, Mate/De-mate of Connectors.

The diagram was attached to the subject HR.

3.4 The PO agreed to attach the updated magnetic field strength mapping based on the 411A current input to HR AMS-02-F06.

The magnetic field mapping has been updated to reflect the Permanent Magnet field data, the data no longer being related to a Cryomagnet current level.

3.5 The PO agreed to attach an EMU Magnetic Field Testing memo to the HR AMS-02-F07.

The EMU Magnetic Field Testing Memorandums have been attached to the subject HR.

The following agreements were documented in the Post Phase III Tim minutes for the AMS-02 held March 23, 2010. Reference numbers are taken directly from the text of the minutes of the meeting.

3.1 The PO agreed to provide distances of the magnetic field so MOD can determine the keep-out zone (if Option A or C is selected).

The Magnetic Field lines of the Permanent Magnet have been provided for keep out zones for the EVA and EVR operations.

7.5 HAZARD SUMMARY

The safety analysis of the AMS-02 conducted in preparation for the Phase II safety review resulted in the generation of twenty integrated hazard reports and two unique JSC Form 1230 hazard compilation reports. Of the twenty integrated hazard reports, the previously deleted Phase I hazard report for Toxic Material Offgassing had been reopened for Phase II and although a complete nomenclature change has occurred with the hazard reports, the corresponding hazard report has been maintained with the same corresponding hazard report identifier (specifically AMS-02-2 at phase I and AMS-02-F02 for Phase II). Another hazard report has been withdrawn upon further investigation of the design and consequences of the potentially hazardous condition.

At the Phase II safety review one standardized hazard report was instructed to be broken up among the unique hazards as the 1230 form application with this complex payload that was to be both inside the orbiter payload bay and on the exterior of the ISS was confusing. Hazard Report AMS-02-F15, Thermal Extremes was deleted. These actions have been accomplished in preparation for the Phase III submittal.

Subsequent to the Phase II safety review, AMS-02-F09, Exposure of the Crew to Excessive Ionizing Radiation, was deleted when the hardware that was to contain the radioactive isotope was deleted from the AMS-02 design.

The design modification that replaced the AMS-02 Cryomagnet System with a Permanent Magnet has driven substantial changes in the hazard reports with the removal

of the variable intensity superconducting magnet, the cryogenic superfluid helium supply, the COPV sourced Warm Helium Gas Supply and the supporting electronics and systems for this hardware. The modifications to the AMS-02 to account for the reduced magnetic field strength and desire to maintain the same quality of science dictated relocated and additional Tracker planes and alterations of electronics and thermal conditioning systems. To that end significant changes were made in most hazard reports to account for the changes in hazards, causes, controls and verifications. Hazard report AMS-02-F03 was deleted in its entirety with the removal of the Cryogenic system. Hazard report AMS-02-F13 was removed with the deletion of the battery system (UPS).

7.5.1 Structural Failure of Hardware

7.5.1.1 Structural Margin

The AMS-02 hardware to be launched in the Orbiter Payload Bay, transferred via SRMS and SSRMS to the ISS PAS location has been designed to maintain positive load factors for all required loading conditions. Hazard report AMS-02-F01 has been prepared to document the AMS-02 hardware's capability to safely complete the AMS-02 mission without losing structural margins, damaging the AMS-02, the Orbiter, the ISS or these vehicles' crew or the general public.

Structural safety of the hardware to be flown and used within the Orbiter habitable volume is addressed in hazard report STD-AMS-02-F01.

Fastener back-off, which is traditionally a concern of loss of structural load path or release of masses in excess of 0.25 pounds, has been addressed in STD-AMS-02-F01 with regards to the release of any fastener or mass as a result of fastener back-off. The release of a mass which can become a co-orbiting mass that can impact the ISS, the AMS-02 or other payloads has not been established to have a mass limitation, thus all fasteners have been shown to have the requisite back off prevent or be shown to be contained and not to release a mass with any possible back-off. Only in this latter condition, containment of any released mass, has the use of chemical thread lock been approved for use on the AMS-02.

The schedule for conversion from the Cryomagnet to the permanent magnet did not allow for a full suite of static and modal testing. Instead, at the direction of the SWG, all new hardware was designed to no-test factors of safety of 2.0 to yield and 3.0 to ultimate. All of the hardware was simple, robust structure and had natural frequencies well above any range of interest. Everything showed positive margins to these new factors using the original design loads, and these results are summarized in AMS-02-F01. These margins will be reverified during the Verification Loads Analysis (VLA) and a final assessment presented at the Verification Acceptance Review (VAR).

7.5.1.2 Vented Volumes

The AMS-02 has been designed to have volumes that will equalize pressure during its mission. These volumes will either be shown to have adequate venting area for the enclosed volume or show adequate structural margin in the event that all vents are closed. This has been addressed in hazard report AMS-02-F01.

7.5.1.3 Fracture Control

The AMS-02 structural and mechanical components have been assessed for fracture control per the JSC Fracture Control plan. This is addressed in hazard report AMS-02-F01. (Pressure systems are also addressed for fracture control, and documented in hazard reports AMS-02-F03 and AMS-02-F05.)

7.5.2 Mechanism Failure

The AMS-02 makes use of one mechanical device, implemented in the AMS-02 design by mandate from the ISS program,. This is the PAS release mechanism, addressed in hazard report AMS-02-F11.

7.5.2.1 EVA PAS Release Mechanism

The EVA releasable PAS requires an excess of three failures to occur to inadvertently release the preload of the ISS PAS grapple system and allow for the withdrawal of the capture bar. The requirement for operability of the EVA releasable PAS capture bar only

requires that the system be zero fault tolerant (SSP 57021, Section 4.1.2.2.1) to add the last required means of clearing a payloads from the ISS truss.

7.5.2.2 ROEU Bracket Folding Mechanism (Removed/Deleted)

The mechanism has been fixed with bolts and is now considered structure, not a mechanism.

7.5.2.3 Unable to Berth, Collision

The AMS-02 utilizes the shuttle and ISS robotic arms for maneuvering to berthing locations in the Orbiter (for a contingency return) and on the ISS (for nominal berthing for mission.) The AMS-02 has installed grapple fixtures in appropriate locations to meet the center of gravity requirements and other ICD requirements, for robotic handling and will provide accurate models of the entire AMS-02 for the robotic motion analysis and simulators. The AMS-02 is entirely passive with regards to berthing operations, with the exception that it has integrated into its structure and avionics the Electronic Berthing Camera System (EBCS). The EBCS has been installed according to the ICD and will have its critical alignment verified prior to launch. The mounting of the grapple fixtures and installation of the EBCS have been addressed in hazard report AMS-02-F11, Mechanical Failure.

7.5.3 Rotating Equipment

The AMS-02 makes use of pumps within two of the systems that comprise the payload: TRD and TTCS. This is documented in hazard report AMS-02-F01.

7.5.4 Pressurized Systems

The AMS-02 utilizes a number of pressurized systems in accomplishing its function. These systems are addressed in a number of hazard reports. The rupture of the pressurized systems have been addressed in hazard report AMS-02-F05. The hazard of over-pressurization of the Orbiter Payload Bay has been addressed in hazard report AMS-02-F04, addressing the source potential of all fluids.

7.5.5 Excessive Thrust/Overturning Moments

The AMS-02 has identified the potential for the AMS-02 to generate forces that could affect robotic operations and vehicle stability. The presence of high pressure gaseous systems and the generation of an intense magnetic field are direct potential causes for this condition.

All pressure system vents will either be capped or provided with zero-thrust vent caps/non-directional vent that will minimize the potential for generation of resulting forces. The AMS-02 magnetic field is designed to have a minimum exterior effect in generating a torque that is perceivable to the ISS. These potential hazards and controls are addressed in hazard report AMS-02-F06.

7.5.6 Radiation/Magnetic Fields

The AMS-02 has systems that can generate radiation and strong field effects that are essential for the experiment objectives. These are addressed in the following paragraphs.7.5.6.1 Excessive Radiated Field Strengths, EMI

The AMS-02 will be complying with both Orbiter and ISS EMI/EMC requirements; compliance is documented in hazard report AMS-02-F07.

7.5.6.2 Magnetic Fields

The AMS-02 makes use of an intense magnetic field within the bore of the instrument. The permanent magnet has been designed to minimize the field external to the magnet and AMS-02 as much as possible. The EMU and standard EVA tools have been certified through a cooperative effort to show good for the maximum fields they could see why translating past the AMS-02 (when the AMS-02 use the stronger Cryomagnet). The permanent Magnet's field profile is such that an EVA crewmember or EVR equipment will not access regions where the magnetic field strength exceeds limitations.. This hazard is addressed in detail in hazard report AMS-02-F07.

7.5.6.3 High Intensity Light

The hazards from visible, infrared and ultraviolet electromagnetic energy have been established in the AMS-02 hazard analysis to have two possible sources, from an internal AMS-02 source and from an external source that is redirected. The internal source identified for AMS-02 comprises the ten laser diodes used to check the alignment of the AMS-02 Tracker and the external source the sun reflecting off of the AMS-02 thermal control features.

7.5.6.4 Exposure to Coherent Light (Lasers)

The only source of coherent light generated by lasers is within the Tracker Alignment System (TAS). The application of laser diodes (10 total) within the TAS is documented in unique hazard report AMS-02-F20. The Class IIIb laser source is contained within the source boxes and transmitted to the interior of the Tracker by fiber optic cables. The laser beam path is entirely closed from the light tight source boxes (LFCR) to the light tight tracker assembly. Even if the fibers carrying the laser illumination should be able to freely radiate, the laser power has been reduced by optical splitting of the beam into multiple fibers (individually sheathed and connected) to have a non-hazard zone (NHZ) of 2.4 cm. AMS-02-F20 is classified as catastrophic as the laser diodes are capable of emitting 80 mW at 1083 nm which could conceivably create permanent damage to human tissue and eyes. AMS-02-F20 demonstrates energy containment and design compliance with ANSI-Z 136.1.

7.5.6.5 Excessive Glare

Hazard report AMS-02-F19 was established to document the potential hazards identified in the hazard analysis associated with a highly reflective payload redirecting solar illumination. At the Phase II Safety Review the PSRP declared this to be a non-hazard and the hazard report, AMS-02-F19 was withdrawn.

7.5.6.6 Exposure of the Crew to Excessive Ionizing Radiation

All radioactive material sources have been removed from the AMS-02 Payload and this hazard is no longer applicable. Hazard Report AMS-02-F09 has been withdrawn.

During AMS-02 ground testing, the science instruments will be subjected to controlled particle beams. These particle beams will validate the science instrument operations. While this beam qualifies as a radioactive source, it cannot induce residual radioactivity in the materials of construction of the AMS-02.

7.5.7 EVA/EVR Operations Hazards

AMS-02 has been designed to be compatible with a number of contingency EVAs associated with the GFE used on the AMS-02. There are also three EVAs associated with contingency operations with AMS-02 hardware. These include the EVA rerouting of power and data cables for ISS bus connectivity, and the ISS required alternate means of releasing the AMS-02 from the PAS location. EVA compatibility issues have been addressed in hazard report AMS-02-F14. Hazards addressed in this hazard report include thermal extremes, sharp edges and corners, stored energy release, and electrical shock. Hazard associated with robotic manipulation are also included into this hazard report. A Noncompliance Report (NCR) has been generated and approved against several locations where EVA contact may occur that exceed the allowable EVA touch temperature limits documented in NSTS 07700 Volume XIV, Appendix 14 and SSP 57003. This NCR is AMS-02-NCR-01 and applicable to AMS-02-F14 hazard report.

7.5.8 High Voltages

The AMS-02 utilized a number of voltages in excess of 32 volts direct current (Vdc). The AMS-02 utilizes protection techniques, appropriate selection of cabling and grounding to preclude hazards of electrical shock, discharge and corona. These hazards are addressed in hazard report AMS-02-F08.

7.5.8.1 Electric Shock/Discharge

The AMS-02 utilizes the ISS provided 120 VDC and converts that power to a number of different voltages, some of them exceeding 1000 VDC. Hazard Report AMS-02-F08 has been developed to document this catastrophic level hazard. The controls documented in AMS-02-F08 focus on the high voltage sources and loads and the compliance with high voltage wiring, connections, potting and grounding requirements. The primary control

for exposure of EVA crew to electrical shock is the discharge of the stored energy of the Cryomagnet prior to the EVA, cessation of power application prior to an EVA and UPS battery circuit design that isolates continuously powered elements from EVA sites.

7.5.8.2 Coronal Discharge

As the AMS-02 utilizes high voltage sources and can release readily ionizable gases in the course of operations (principally from the TRD system) the AMS-02 has implemented high voltage insulation and potting protocols to limit the coronal discharge potential. AMS-02-F08 documents the techniques used to limit coronal discharge potential. Extensive testing of AMS-02 circuits and loads has shown that coronal initiation voltages for these designs are not met and the AMS-02 design. The actual coronal discharge could damage AMS-02 hardware through degradation and generate a “white noise” EMI, but there is no damage potential to the ISS directly from any conceivable coronal discharge with AMS-02 hardware.

7.5.8.3 Interaction with ISS Plasma Field

The AMS-02 does not release, emit or provide charging to particles or gases. All releases of gas will be electrically neutral. The AMS-02 does not add to the Plasma environment. The AMS-02 magnetic field will have the potential for influencing the plasma as its field drops off quickly with distance from the AMS-02 center, this may cause some distinct curvature of otherwise more random plasma field flow and it has been hypothesized that charged particle flow along field lines may be increased in a miniscule way. No hazard has been identified by the magnetic field interaction with the ISS plasma field.

7.5.9 Electrical Power Distribution Damage

The AMS-02 design protects the vehicle’s power supplies and its own internal wiring from damage due to excessive load. This is addressed in hazard report AMS-02-F17.

7.5.10 Mate/De-mate of Connectors

Nominal operations of the AMS-02 do not require the connection of any cable with the exception of the communications cable connecting the PGSC interface card to the OIU.

The AMS-02 does however have a number of contingency operations that it must support, Shuttle, ISS and its own where the de-mating and mating of connectors will occur. The mating and de-mating of connectors, by EVA, is addressed in hazard report AMS-02-F12.

7.5.11 Battery Failure

The AMS-02 battery system has been removed and the hazard report AMS-02-F13, withdrawn.

7.5.12 Ignition of Flammable Atmospheres

The AMS-02 has no power on during ascent or descent operations. The potential to ignite flammable atmospheres is addressed in hazard report AMS-02-F10

7.5.13 Flammable Materials

The hazard of fire, controlled by the use of materials which are non-flammable or possibly flammable but protected from being a significant threat, is addressed for the crew habitable volume of the Orbiter in hazard report STD-AMS-02-F02. The materials of construction of the AMS-02, the elements in the Orbiter Payload Bay, are addressed in hazard report AMS-02-F10. The AMS-02 also makes use of working fluids in the thermal control systems that can be flammable. These gaseous/liquids are addressed in hazard report AMS-02-F10.

7.5.14 Shatterable Material Release

The AMS-02 makes extensive use of photomultiplier tubes and frangible materials in order to accomplish its science objectives. The modification of the AMS-02 to support science operations with the Permanent Magnet has provided two new sources of frangible materials in the 1N and 6N Tracker planes. Hazard report AMS-02-F16 addresses each of these sources and how the materials are either contained or qualified not to break during the AMS-02 mission.

7.5.15 Toxic Material Release

AMS-02 will have hardware within the Orbiter habitable volume, these items will be assessed for off-gassing compliance. Compliance is addressed in hazard report AMS-02-F02. The AMS-02 does not make use of other chemicals within the crew habitable environment that could have a toxicological effect. No materials of construction of the exterior mounted AMS-02 will contaminate an EVA crewmember such that they may carry contaminants into the habitable environment.

7.5.16 Thermal Extremes

Previously addressed in hazard report AMS-02-F15, this hazard report has been deleted. EVA temperature extremes are documented in AMS-02-F14

7.5.17 Rapid Safing/Payload Reconfiguration

The AMS-02 has a limited number of configurations that it can be placed in physically. Hazard report AMS-02-F18 addresses the AMS-02 operations and configurations and how they do not affect the ability of the AMS-02 to safely return in the Orbiter or handle ISS loads.

There is only a single structural configuration that is divergent from the nominal as-launched configuration. This new configuration is the result of a contingency EVA where the AMS-02 has been removed from the CAS/PAS site by manually removing the AMS-02 PAS capture bar and because of operational error or some unknown condition, unable to return the bar to its nominal position after removal, the bar is free to move on the spherical bearing that retains it. In this configuration the bar can withstand potential landing loads, but may strike the EBCS box and that analysis cannot be readily accomplished. To avoid this condition that cannot be accurately analyzed for damage, an EVA “tie down” option has been pursued and shown to be viable. As a number in excess of two failures leads to this condition, it is not baselined as a contingency EVA operation.

7.6 FIRE DETECTION AND SUPPRESSION SUMMARY

The AMS-02 does not include any hardware that will be operated within the ISS habitable volume. No Fire Detection and Suppression design features are required for the AMS-02.

7.7 OPERATIONAL CONTROLS

The prepared unique hazard reports for the AMS-02 has an additional data element beyond those required by NSTS/ISS 13830 for the content of payload safety hazard reports. This additional data element is a column that indicates the use of operational controls. A control that uses an operational control has a designator in this column, an “S” for a shuttle based operation and “I” for ISS based operation. The designator (A) indicates that the procedure will be AMS-02 Project originated.

A reference list of all these designations is provided in Table 7.7-1. OCAD numbers are included in this table.

TABLE 7.7-1 OPERATIONAL PROCEDURE CONTROLS

HR/OCAD	I/S	Verif.	Control
AMS-02-F08 OCAD 67864	S	2.6.1	2.6 CONTROL: The Orbiter side of the ROEU (GFE hardware) will be depowered for the disconnect operation and remain unpowered once the umbilical is separated from the AMS-02. Any EVA subsequent to this separation could come in contact with this connector. AMS-02 procedures will call out the removal of power for disconnecting the ROEU and will not include any procedures that will require power to be resumed to the connector without reconnection of the ROEU to the ROEU-PDA. Design of the ROEU connector is certified GFE and is being used within its certification. NOTE: If power is to be reapplied to the ROEU for some reason, a Shuttle based Flight Rule to enact a keep out zone would be implemented independent of AMS-02 operational requirements.
AMS-02-F08 OCAD 67865	S	3.1.2	3.1 CONTROL: During ascent and entry, high voltage sources will not be powered.
AMS-02-F11 OCAD 67866	S	1.3.2	1.3 CONTROL: The AMS-02 is safe to return only with all PRLAs and the Active Keel (latch) Assembly closed.
AMS-02-F11 OCAD 67868	I	4.3.5	4.3 CONTROL: To assure that the appropriate preload is present when the AMS-02 is interfaced with the active PAS, a travel limiting screw is adjusted prior to flight to provide the appropriate placement of the capture bar, utilizing the 10° ramp to raise and lower the capture bar. When positioned correctly the capture position of the latch and the required displacement of the bar generated the preload. This travel limiter (with two forms of backout prevention (locking nut and locking insert with preload torque) allows for the EVA crew to readily replace the capture bar once it is removed and make the passive PAS of the AMS-02 capable of being installed in a functioning active PAS. Reinstallation of the mechanism is the reversal of the removal process with the restoration/reinsertion of the capture bar and handle then reversing the EVA bolt rotation using the release bolt counts to establish appropriate rotations to drive to hardstops (driving to hardstops, if past the original counts is preferred cessation point).

HR/OCAD	I/S	Verif.	Control
AMS-02-F12 OCAD 67860	I	1.1.1	<p>1.1 CONTROL: A contingency EVA operation is provided for in the AMS-02 design to be able to switch the routing of power to the AMS-02 to swap the internal AMS-02 buses between the two ISS supplies. To accomplish this EVA task and provide the required two upstream inhibits to preclude arcing/sparking during connector demate/mate power provided by Utility Rail S3 2B3A 3A (DDCU P1-3A) and Utility Rail S3 1A4B 4B (DDCU S1-4B) must be inhibited. Each of these power sources is routed through RPCMs to control power to the individual PAS locations. The power will be switched (on/off) at RPCM S3-3A-E(A2) and RPCM S3-4B-E (A9) (respective) to inhibit power availability to the AMS-02. The second inhibit will involve the remote retraction of the UMA connection to provide physical isolation of the AMS-02 from the ISS power sources. AMS-02 does not have the means of removing or limiting downstream loads to meet the low power option of MA2-98-170.</p>
AMS-02-F12 OCAD 67861	I	1.5.3	<p>1.5 CONTROL: Nominally, the SSRMS will demate power connections from the AMS-02 prior to engaging the UMA in order to preclude power (high) lines from one power source on the ISS to be interconnected with the output of another power source. In the event of the situation where the SSRMS has delivered the AMS-02 to the PAS location and the UMA is connected while the SSRMS is still connected, power from the UMA (or the SSRMS) will be switched off and a diode protection included in the AMS-02 circuitry will prevent power, originating from the UMA, from being present in the PVGF. NOTE: Control of SSRMS power supply through the arm is a standard GFE procedure as indicated in preceding NOTE (following Control 1.1).</p>

HR/OCAD	I/S	Verif.	Control
AMS-02-F14 OCAD 67862	I, S	3.1.3	3.1 CONTROL: The AMS-02 is designed to eliminate sharp edges, corners, protrusions and any mechanism that could be a pinch or scissor location. The AMS-02 meets the requirements of NSTS 07700, Vol XIV, Appendix 7 for all accessible surfaces and structures, with the exception of the two Star Tracker optical baffles, which by the nature of the optical properties of the baffle, has thin metal edges that do not comply with the rounding of edges. The Star Tracker baffles will be noted as “no touch areas”. There has been no identified need for the EVA crew to operate in the immediate vicinity of the Star Tracker baffles. To access these thin sheet edges, the EVA crewmember would have to reach to the interior of the Star Tracker baffle. (Reference Page A14-34 for figure showing Star Tracker Location, “STAR TRACKER BAFFLE –EVA No Touch Area.”) Note: Silver Teflon Tape was used to cover edges that were not properly finished in accordance with NSTS 07700 Vol XIV, Appendix 7.“)
AMS-02-F14 OCAD 67863	I	5.2.5	5.2 CONTROL: The EVA release mechanism for the PAS passive mechanism releases stored energy (5650 lb preload) by the operation of the two EVA operated release mechanisms, each using a screw driven ramp that slowly releases the tension of latched capture bar. Two mechanisms must be released fully to allow for the capture bar to clear interference brackets that preclude the attempts to extract the bar prior to full release of the preload. The SSRMS will be put into a limp mode to preclude a build up of loads that could be released with the removal of the bar.

HR/OCAD	I/S	Verif.	Control
AMS-02-F17 OCAD 67911	I	2.4.1	2.4 CONTROL: During robotic operation involving the AMS-02 while it is connected to the truss berthing location, the electrical source (RPCM) of the SSRMS and the electrical source (RPCM) of the UMA will be different, per SSP 57003 these two sources may not be interconnected. To avoid this condition the procedures for engaging the AMS-02's power while on the truss will require a specific sequence that precludes the UMA to be connected when the PVGF is electrically connected to the SSRMS. The UMA must be demated prior to electrical mating of SSRMS LEE to PVGF and the PVGF must be electrically demated prior to UMA engagement for installation on the ISS. This separation of connectors will preclude any interconnection of the power sources.
AMS-02-F18 OCAD 67910	S	1.5.2	1.5 CONTROL: The AMS-02 is safe to return only with all PRLAs and the Active Keel (latch) Assembly closed.

7.8 FLIGHT SAFETY NONCOMPLIANCES

The AMS-02 Project has identified one noncompliance to NSTS 1700.7B and/or NSTS 1700.7B ISS Addendum. AMS-02-NCR-01 – AMS-02 Payload EVA Touch Temperature. A worst case thermal analysis of AMS payload shows a Debris Shield reaching -183 degrees F (violating Incidental contact temperatures and heat rates), a Flight Releasable Grapple Fixture (FRGF) reaching 258 degrees F (violating unlimited contact temperature and heat rates) and an EVA Connector Panel reaching 174 degrees F (violating unlimited contact temperature and heat rates). This NCR is applicable to AMS-02-F14 and has been approved by the PSRP chairman as equivalently safe on January 6, 2009.

7.9 HAZARD REPORT LIST

Table 7.9-1 provides a listing of all AMS-02 hazard reports with title and current Phase III status. All hazard reports presented at Phase II were approved with modifications at that time, with the exception of AMS-02-F15 which was deleted by the PSRP at the Phase II Meeting. The Withdrawn status of AMS-02-F19 was confirmed at that time as

well. STD-AMS-02-F01 as requested was removed for Phase III and the information placed appropriately in unique hazard reports. Hazard Report AMS-02-F09 was deleted when the radioactive material source was removed from the AMS-02 payload.

At Phase III the following hazard reports were review and approved, STD-AMS-02-F02, AMS-02-F02, AMS-02-F16, and AMS-02-F20.

Subsequent to the change of the AMS-02 to a Permanent Magnet Design, two hazard reports were deleted as no longer being applicable, AMS-02-F03 for the Cryosystem, and AMS-02-F13 for battery related hazards. Previously closed hazard reports AMS-02-F16 for frangible materials was reopened with alterations in the containment of silicon tracker ladders and AMS-02-F20 because the laser system was modified. STD-AMS-02-F02 and AMS-02-F02 both dealt exclusively with the DDRS-02 which was unmodified by the change from Cryomagnet to Permanent Magnet.

7.10 SAFETY VERIFICATION TRACKING LOG (SVTL)

The AMS-02 SVTL is provided as Appendix G of this document. Appendix G will become a free standing deliverable to the PSRP subsequent to the completion of the Phase III safety review and its updates will not nominally be reflected in updates to the baseline JSC 49978 prior to launch.

TABLE 7.9-1 AMS-02 HAZARD REPORT LIST

HR ID	Hazard Report Title	Phase II Status	Phase III Approval Date
STD-AMS-02-F01	Flight Payload Standard Hazard Report – Exterior Elements	Approved	Deleted
STD-AMS-02-F02	Flight Payload Standard Hazard Report – Interior Elements	Approved	8/20/2010
AMS-02-F01	Structural Failure of Hardware	Approved	1/21/2011
AMS-02-F02	Toxic Material Off-gassing	Approved	8/6/2010
AMS-02-F03	Rupture of Superfluid Helium Tank, Vacuum Case and/or Pressurized System	Approved	Deleted
AMS-02-F04	Over-pressurization of Payload Bay	Approved	8/6/2010
AMS-02-F05	Rupture of AMS-02 Pressurized Systems: TRD Gas System (Xe & CO ₂), Cryomagnet Warm Helium Gas System, Tracker Thermal Control System, Thermal Control System, Cryocooler	Approved	1/21/2011
AMS-02-F06	Excessive Thrust/Overturning Moments	Approved	1/21/2011
AMS-02-F07	Excessive Radiated Field Strengths, EMI, Magnetic	Approved	1/21/2011
AMS-02-F08	Electric Shock/Discharge	Approved	8/6/2010
AMS-02-F09	Exposure of the Crew to Excessive Ionizing Radiation	Approved	Deleted
AMS-02-F10	Flammable Materials in the Payload Bay	Approved	1/21/2011
AMS-02-F11	Mechanism Failure	Approved	8/6/2010
AMS-02-F12	Mate/De-mate of Connectors	Approved	8/6/2010
AMS-02-F13	Battery Failure	Approved	Deleted
AMS-02-F14	EVA/EVR Hazards	Approved	8/6/2010
AMS-02-F15	Thermal Extremes	Deleted	Deleted
AMS-02-F16	Shatterable Material Release	Approved	8/6/2010
AMS-02-F17	Electrical Power Distribution Damage	Approved	1/21/2011
AMS-02-F18	Rapid Safing/Payload Reconfiguration	Approved	8/6/2010
AMS-02-F19	Excessive Glare	Withdrawn	Deleted
AMS-02-F20	Crew Exposure to Coherent Light	Approved	8/6/2010